# Using Neural Networks for Time-Series Prediction

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### **Outline**

- 1. Introduce problem
- 2. Phrase problem as an ML problem
- 3. Collect and apply data
- 4. Select features
- 5. Train the model
- 6. Improve the model
- 7. Tips

### Who am I?



- Works with storage and manipulation of time series data
- Integrates third-party data sets

### The Problem



### **Elements**



Figure 1: A hit circle

### **Elements**



Figure 1: A hit circle



Figure 2: A slider

### **Elements**



Figure 1: A hit circle



Figure 2: A slider



Figure 3: Mouse cursor

### Scoring

300 points if on the beat

### Scoring

- 300 points if on the beat
- 100 points if slightly off the beat

### Scoring

300 points if on the beat

100 points if slightly off the beat



### Scoring

300 points if on the beat

100 points if slightly off the beat



50 points if really off the beat

### Scoring

- 300 points if on the beat
- 100 points if slightly off the beat



50 points if really off the beat



### Scoring

- 300 points if on the beat
- 100 points if slightly off the beat



50 points if really off the beat



0 points for missing entirely

### Scoring

300 points if on the beat

100 points if slightly off the beat



50 points if really off the beat



0 points for missing entirely



Sample
\$ mpv videos/osu-example.avi

Improve my rank quickly

Improve my rank quickly Many new songs a week

Improve my rank quickly Many new songs a week Particular playstyle

Improve my rank quickly Many new songs a week Particular playstyle Arbitrage opportunity?

### Phrasing the Problem

Predict my score on a beatmap

### Predict my score on a beatmap

Need to compute accuracy %

### Predict my score on a beatmap

Need to compute accuracy %

Temporal Accuracy

### Predict my score on a beatmap

Need to compute accuracy %

Temporal Accuracy

Aim Accuracy

### **Machine Learning Models**

### **Classifiers**

Label a sample as a member of one of a finite set of classes.

### **Machine Learning Models**

**Regressors** Approximate a numerical function.

### **LSTM Models**

Order dependent data

### **LSTM Models**

Order dependent data
Sequence of observations

### **LSTM Models**

Order dependent data
Sequence of observations
Uses windows of time-sorted observations

### **Our Problem**

For each hit-object, predict..

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## **Classifier** A label.

- 300
- 100
- 50
- 0 (miss)

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For each hit-object, predict..

## **Classifier** A label.

- 300
- 100
- 50
- 0 (miss)

### Regressor

A numeric error metric.

- 1. Aim Error ((x, y) error)
- 2. Accuracy Error (punctuality)

### **Data Collection**

### **Beatmaps**

Hit objects in (x, y, time) space.

### **Beatmaps**

Hit objects in (x, y, time) space. Circle Size (CS)

### **Beatmaps**

Hit objects in (x, y, time) space.

Circle Size (CS)

Approach Rate (AR)

### **Beatmaps**

Hit objects in (x, y, time) space.

Circle Size (CS)

Approach Rate (AR)

Overall Difficulty (OD) (score thresholds)

#### Raw Data

#### **Beatmap**

```
[HitObjects]
103,272,52926,6,0,L|111:176,1,67.5000025749208
93,95,53279,1,2,0:3:0:0:
194,131,53455,2,0,B|263:160|264:100|337:135,1,135.000005149
437,204,53985,2,0,L|432:286,1,67.5000025749208
394,105,54338,6,0,L|399:17,1,67.5000025749208
286,62,54690,1,2,0:3:0:0:
177,54,54867,2,0,B|110:74|110:30|41:53,1,135.000005149842,0
70,213,55396,2,0,L|77:132,1,67.5000025749208
161,215,55749,6,0,P|175:273|247:314,1,135.000005149842,0|2
341.286.56279.1.0.0:0:0:0:
308,183,56455,2,0,P|268:201|245:238,1,67.5000025749208,0|2
```

• Hard Rock (HR)

- Hard Rock (HR)
- Double Time (DT)

- Hard Rock (HR)
- Double Time (DT)
- Hidden (HD)

- Hard Rock (HR)
- Double Time (DT)
- Hidden (HD)
- etc...

Time series of...

Time series of...

Cursor location

#### Time series of...

- Cursor location
- Keyboard state

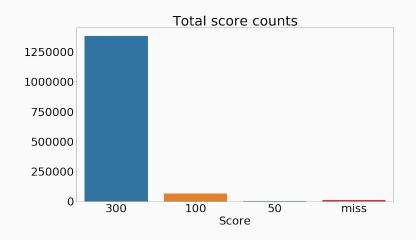
I had about seven years of replays laying around!

### **Understanding our data**

# Accuracy thresholds (milliseconds)

| OD | 300  | 100   | 50    |
|----|------|-------|-------|
| 1  | 73.5 | 131.5 | 189.5 |
| 2  | 67.5 | 123.5 | 179.5 |
| 3  | 61.5 | 115.5 | 169.5 |
| 4  | 55.5 | 107.5 | 159.5 |
| 5  | 49.5 | 99.5  | 149.5 |
| 6  | 43.5 | 91.5  | 139.5 |
| 7  | 37.5 | 83.5  | 129.5 |
| 8  | 31.5 | 75.5  | 119.5 |
| 9  | 25.5 | 67.5  | 109.5 |
| 10 | 19.5 | 59.5  | 99.5  |

# **Understanding our data (cont.)**



Joining Data

#### **Joining Data**

Find all clicks by taking times where key state changes

#### **Joining Data**

- Find all clicks by taking times where key state changes
- Match click with the nearest hit object (ignores hit locking!)

### **Accuracy Error**

Absolute difference in time.

#### **Accuracy Error**

Absolute difference in time.

Comparable across different OD

#### **Aim Error**

Euclidean distance between click and center of circle.

#### **Aim Error**

- Euclidean distance between click and center of circle.
- Comparable across different CS

## Feature Selection

Numeric inputs to the ML model

Numeric inputs to the ML model

What are we observing

Numeric inputs to the ML model

What are we observing

Focus the model on aspects of the data

Numeric inputs to the ML model

What are we observing

Focus the model on aspects of the data

Chance to use domain knowledge

#### Raw Data

#### **Beatmap**

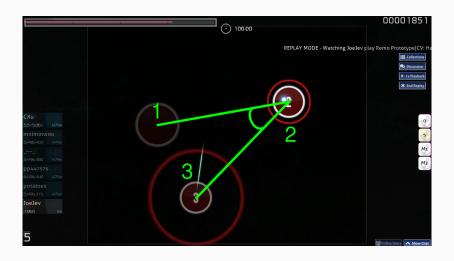
```
[HitObjects]
103,272,52926,6,0,L|111:176,1,67.5000025749208
93,95,53279,1,2,0:3:0:0:
194,131,53455,2,0,B|263:160|264:100|337:135,1,135.000005149
437,204,53985,2,0,L|432:286,1,67.5000025749208
394,105,54338,6,0,L|399:17,1,67.5000025749208
286,62,54690,1,2,0:3:0:0:
177,54,54867,2,0,B|110:74|110:30|41:53,1,135.000005149842,0
70,213,55396,2,0,L|77:132,1,67.5000025749208
161,215,55749,6,0,P|175:273|247:314,1,135.000005149842,0|2
341.286.56279.1.0.0:0:0:0:
```

308,183,56455,2,0,P|268:201|245:238,1,67.5000025749208,0|2

### **Simple Features**

absolute\_x
absolute\_y
absolute\_time

### **Domain Specific Features**



| time      | X   | У   |
|-----------|-----|-----|
| 00:37.366 | 372 | 94  |
| 00:37.763 | 447 | 205 |
| 00:38.027 | 217 | 299 |
| 00:38.291 | 229 | 171 |
| 00:38.424 | 274 | 358 |
| 00:38.688 | 149 | 221 |
| 00:38.952 | 330 | 186 |
| 00:39.217 | 233 | 127 |
| 00:39.481 | 233 | 127 |
| 00:39.613 | 198 | 303 |

| time      | X   | У   |
|-----------|-----|-----|
| 00:37.366 | 372 | 94  |
| 00:37.763 | 447 | 205 |
| 00:38.027 | 217 | 299 |
| 00:38.291 | 229 | 171 |
| 00:38.424 | 274 | 358 |
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| 00:38.952 | 330 | 186 |
| 00:39.217 | 233 | 127 |
| 00:39.481 | 233 | 127 |
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| time      | X   | У   |
|-----------|-----|-----|
| 00:37.366 | 372 | 94  |
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| 00:38.424 | 274 | 358 |
| 00:38.688 | 149 | 221 |
| 00:38.952 | 330 | 186 |
| 00:39.217 | 233 | 127 |
| 00:39.481 | 233 | 127 |
| 00:39.613 | 198 | 303 |

| time      | ×   | у   | relative x | relative y |
|-----------|-----|-----|------------|------------|
| 00:37.366 | 372 | 94  | -          | -          |
| 00:37.763 | 447 | 205 | 298        | -16        |
| 00:38.027 | 217 | 299 | 68         | 78         |
| 00:38.291 | 229 | 171 | 80         | -50        |
| 00:38.424 | 274 | 358 | 125        | 137        |
| 00:38.688 | 149 | 221 | 0          | 0          |
| 00:38.952 | 330 | 186 | 181        | -35        |
| 00:39.217 | 233 | 127 | 84         | -94        |
| 00:39.481 | 233 | 127 | -          | -          |
| 00:39.613 | 198 | 303 | -          | -          |

| time      | Х   | у   | relative x | relative y |
|-----------|-----|-----|------------|------------|
| 00:37.366 | 372 | 94  | -          | -          |
| 00:37.763 | 447 | 205 | -          | -          |
| 00:38.027 | 217 | 299 | -113       | 113        |
| 00:38.291 | 229 | 171 | -101       | -15        |
| 00:38.424 | 274 | 358 | -56        | 172        |
| 00:38.688 | 149 | 221 | -181       | 35         |
| 00:38.952 | 330 | 186 | 0          | 0          |
| 00:39.217 | 233 | 127 | -97        | -59        |
| 00:39.481 | 233 | 127 | -97        | -59        |
| 00:39.613 | 198 | 303 | -          | -          |

| time      | X   | у   | relative x | relative y |
|-----------|-----|-----|------------|------------|
| 00:37.366 | 372 | 94  | -          | -          |
| 00:37.763 | 447 | 205 | -          | -          |
| 00:38.027 | 217 | 299 | -          | -          |
| 00:38.291 | 229 | 171 | -4         | 44         |
| 00:38.424 | 274 | 358 | 41         | 231        |
| 00:38.688 | 149 | 221 | -84        | 94         |
| 00:38.952 | 330 | 186 | 97         | 59         |
| 00:39.217 | 233 | 127 | 0          | 0          |
| 00:39.481 | 233 | 127 | 0          | 0          |
| 00:39.613 | 198 | 303 | -35        | 176        |

#### Osu! Features

- absolute\_x
- absolute\_y
- absolute\_time
- relative\_x
- relative\_y
- relative\_time

- is\_slider\_tick
- approach\_rate
- distance\_from\_previous
- distance\_to\_next
- pitch
- roll
- yaw

# **Training**

```
Feature array shape

( , , , )
```

```
Feature array shape
( , number of features, )
```

```
Feature array shape

( , window length, number of features, )
```

#### Feature array shape

```
( number of windows, window length, number of features, )
```

```
Feature array shape

( number of windows, window length, number of features,

Label array shape
( number of windows, )
( number of windows, )
```

#### Keras

```
input_ = keras.layers.Input(
    shape=(window_length, len(features))
)
```

#### Keras

```
input_ = keras.layers.Input(
    shape=(window_length, len(features))
)
lstm = keras.layers.LSTM(lstm_layer_size)(input_)
```

```
input_ = keras.layers.Input(
    shape=(window_length, len(features))
lstm = keras.layers.LSTM(lstm_layer_size)(input_)
aim_error = keras.layers.Dense(
    1,
    activation='linear',
    name='aim_error',
)(lstm)
```

```
input_ = keras.layers.Input(
    shape=(window_length, len(features))
lstm = keras.layers.LSTM(lstm_layer_size)(input_)
aim_error = keras.layers.Dense(
    1,
    activation='linear',
    name='aim_error',
)(lstm)
accuracy_error = keras.layers.Dense(
    1,
    activation='linear',
    name='accuracy_error',
)(lstm)
```

```
model = keras.models.Model(
    inputs=input_,
    outputs=[aim_error, accuracy_error],
)
```

```
model = keras.models.Model(
    inputs=input_,
    outputs=[aim_error, accuracy_error],
)
model.compile(
    loss='mse',
    optimizer='rmsprop',
)
```

```
# compute features, aim_error, accuracy_error
model.fit(
    features,
    {
        'aim_error': aim_error,
        'accuracy_error': accuracy_error,
    },
)
```

```
# compute features, aim_error, accuracy_error
model.fit(
    features,
        'aim_error': aim_error,
        'accuracy_error': accuracy_error,
    },
model.predict(features)
```

### How does it look?

### How does it look?

bad

## **Feature Scaling**

Sensitive to input ranges

### **Feature Scaling**

```
Sensitive to input ranges
(data - data.mean()) / data.std()
```

### Feature Scaling

```
Sensitive to input ranges
(data - data.mean()) / data.std()
Save the mean and std of the training data!
```

### Data (again)

```
features:
    absolute_x:
      mean: 256.93
      std: 581144.54
     min: -26.25
      max: 42978020236964152.0
    absolute_y:
      mean: 188.67
      std: 96280.10
     min: -12.20
      max: 10754663190171874.0
```

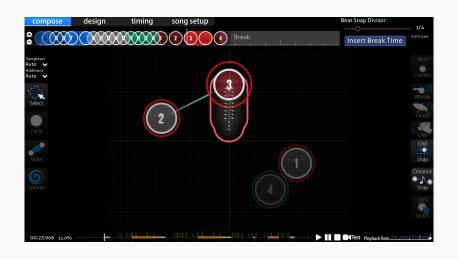
### Data (again)

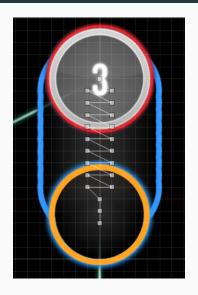
```
features:
    absolute_x:
      mean: 256.93
      std: 581144.54
     min: -26.25
      max: 42978020236964152.0
    absolute_y:
      mean: 188.67
      std: 96280.10
     min: -12.20
```

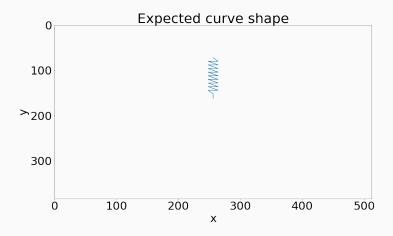
max: 10754663190171874.0

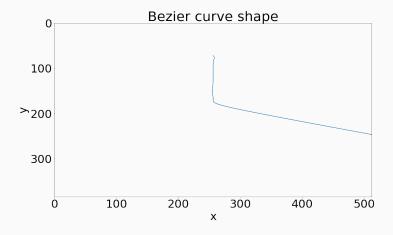
31

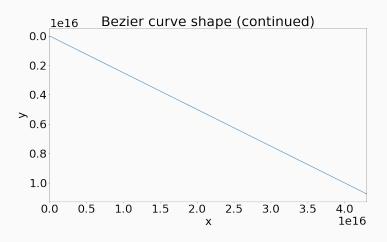
osu! playfield: (512, 384)









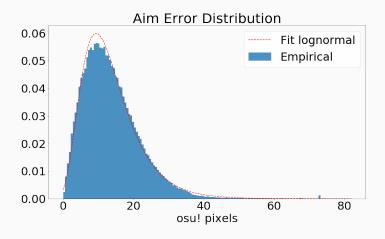


### **Understanding our data**

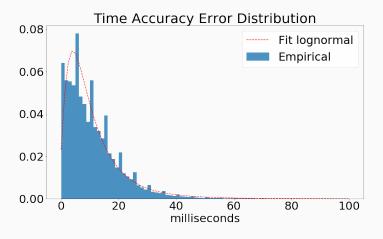
# Accuracy thresholds (milliseconds)

| OD | 300  | 100   | 50    |
|----|------|-------|-------|
| 1  | 73.5 | 131.5 | 189.5 |
| 2  | 67.5 | 123.5 | 179.5 |
| 3  | 61.5 | 115.5 | 169.5 |
| 4  | 55.5 | 107.5 | 159.5 |
| 5  | 49.5 | 99.5  | 149.5 |
| 6  | 43.5 | 91.5  | 139.5 |
| 7  | 37.5 | 83.5  | 129.5 |
| 8  | 31.5 | 75.5  | 119.5 |
| 9  | 25.5 | 67.5  | 109.5 |
| 10 | 19.5 | 59.5  | 99.5  |

## Data (again)



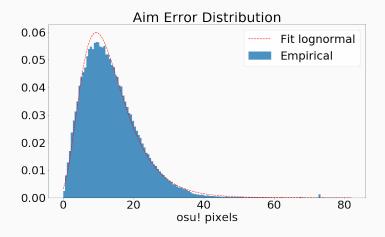
### Data (again)



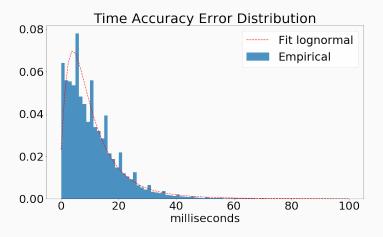
### Fit a distribution

lain/lstm.py:605

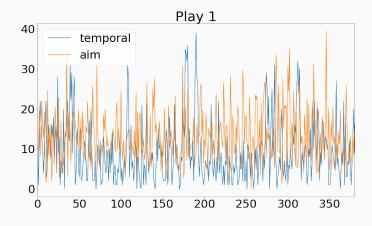
### **Sample Weights**

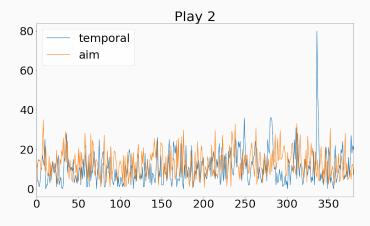


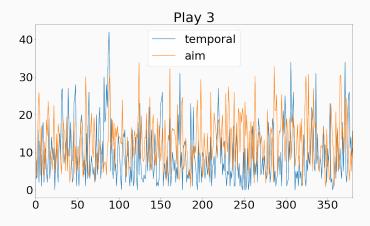
### **Sample Weights**

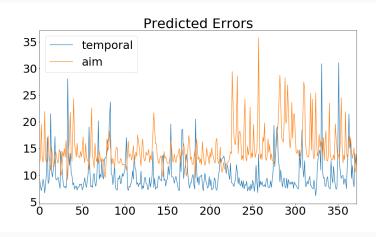


### Sample Weights (cont.)









# **Example Output (cont.)**

| Prediction | Actual | Stars |
|------------|--------|-------|
| 99.85%     | 99.13% | 5.34  |
| 99.85%     | 99.08% | 5.34  |
| 99.85%     | 98.51% | 5.34  |
| 95.95%     | 96.57% | 6.03  |
| 98.30%     | 97.09% | 6.24  |

# **Tips**

## **Understanding the process**

 ${\tt verbose} \ {\sf flags} \ {\sf that} \ {\sf log} \ {\sf information}$ 

### **Understanding the process**

verbose flags that log information
progress indicators (click.progressbar)

## **Understanding the process**

verbose flags that log information
progress indicators (click.progressbar)
print summary statistics early in process

Group code into a domain-aware Model class.

Group code into a domain-aware Model class.

feature extraction

Group code into a domain-aware Model class.

feature extraction

feature scaling

Group code into a domain-aware Model class.

feature extraction

feature scaling

label extraction

Group code into a domain-aware Model class.

- feature extraction
- feature scaling
- label extraction
- managing keras

save models to disk

save models to disk train on ec2 and use locally

save models to disk train on ec2 and use locally train locally then deploy

save models to disk train on ec2 and use locally train locally then deploy supported by keras

## **Key Points**

1. Most of the work is before or after keras

#### **Key Points**

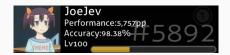
- 1. Most of the work is before or after keras
- 2. Understand the data and the data collection processes

#### **Key Points**

- 1. Most of the work is before or after keras
- 2. Understand the data and the data collection processes
- 3. Osu! is a fun game

#### Thank You

#### Questions?



#### github.com/llllllllll (10 lowercase L's)

- /lain (model implementation)
- /slider (tools for working with osu! data and API)
- /combine (irc server running lain-as-a-service)