

Syntax code:

```
from controller import Robot
```

```
def run_robot(robot):
    time_step = 32
    max_speed = 6.28

    # Motors
    left_motor = robot.getMotor("left wheel motor")
    right_motor = robot.getMotor("right wheel motor")
    left_motor.setPosition(float("inf"))
    right_motor.setPosition(float("inf"))
    left_motor.setVelocity(0.0)
    right_motor.setVelocity(0.0)

    # Enable IR sensors
    left_ir = robot.getDistanceSensor("ir0")
    right_ir = robot.getDistanceSensor("ir1")
    left_ir.enable(time_step)
    right_ir.enable(time_step)

    # Start simulation
    while robot.step(time_step) != -1:
        # Read IR sensors
        left_ir_value = left_ir.getValue()
        right_ir_value = right_ir.getValue()

        print("left: {}, right: {}".format(left_ir_value, right_ir_value))

        left_speed = max_speed * 0.25
        right_speed = max_speed * 0.25

        if (left_ir_value > right_ir_value) and (6 < left_ir_value < 15):
            print("Go left")
            left_speed = -max_speed * 0.25
        elif (right_ir_value > left_ir_value) and (6 < right_ir_value < 15):
            print("Go right")
            right_speed = -max_speed * 0.25

        left_motor.setVelocity(left_speed)
        right_motor.setVelocity(right_speed)

if __name__ == "__main__":
    my_robot = Robot()
    run_robot(my_robot)
```

Proto code:

```
#VRML_SIM R2023b utf8
```

```
PROTO TrackOne [
    field SFVec3f translation 0 0 0
    field SFRotation rotation 0 1 0 0
]
{
    Solid {
        translation IS translation
        rotation IS rotation
    }
}
```

```

scale 0.0075 0.0075 0.0075
children [
  Solid {
    name "obj_0"
  }
  Solid {
    children [
      Shape {
        appearance PBRAppearance {
          baseColor 0.16862746 0.18039216 0.19215687
          roughness 1
          metalness 0
          name "color_2829873"
        }
        geometry IndexedFaceSet {
          coord Coordinate {
            point [
              33.284 0.995 -28.532, 37.862 0.995 -29.631, 33.871 0.995 -26.727, 29.797 0.995 -25.04, -
              69.175 0.995 -13.52, -66.715 0.995 -17.534, -65.18 0.995 -16.418, -62.316 0.995 -19.772, -63.658
              0.995 -21.113, -7.025 0.995 -14.904, -13.891 1.005 -16.553, -13.891 0.995 -16.553, 0.115 0.995
              16.357, -6.628 0.995 16.888, 0.115 0.995 14.46, -6.925 0.995 15.014, 7.154 0.995 15.014, 6.858 0.995
              16.888, 26.4612 1.005 22.9949, 26.4612 0.995 22.9949, 26.4635 0.995 22.9918, 26.4635 1.005
              22.9918, 29.797 1.005 -25.04, 33.871 1.005 -26.727, -60.078 0.995 -24.171, -58.963 0.995 -22.636,
              60.189 1.005 -24.271, 56.175 1.005 -26.73, 59.073 1.005 -22.736, -56.065 0.995 -26.63, -55.203 0.995
              -24.94, 42.555 0.995 -30, 47.248 0.995 -29.631, 46.951 0.995 -27.757, 42.555 0.995 -28.103, 38.159
              0.995 -27.757, 62.426 1.005 -19.872, 55.313 1.005 -25.04, 51.825 1.005 -28.532, -42.445 1.005 -
              28.003, -38.049 1.005 -27.657, -42.445 1.005 -29.9, -47.138 1.005 -29.531, -46.841 1.005 -27.657,
              6.758 0.995 -16.778, 13.334 0.995 -18.357, 13.921 0.995 -16.553, -51.715 0.995 -28.432, -51.129
              0.995 -26.627, 65.29 1.005 -16.518, 66.825 1.005 -17.634, 7.054 0.995 -14.904, 67.594 1.005 -12.758,
              69.285 1.005 -13.62, 63.768 1.005 -21.213, -6.728 0.995 -16.778, 0.015 0.995 -14.35, 0.015 0.995 -
              16.248, -20.415 0.995 -19.255, -72.445 0.995 0.1, -70.547 0.995 0.1, -70.201 0.995 4.496, -70.976
              1.005 -9.171, -72.075 1.005 -4.593, -69.172 1.005 -8.584, 69.282 1.005 -8.684, 71.087 1.005 -9.271,
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              0.995 -12.658, -70.976 0.995 -9.171, -72.075 0.995 -4.593, -69.172 0.995 -8.584, -70.201 0.995 -4.296,
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              65.29 0.995 16.518, 66.825 0.995 17.633, -20.315 0.995 19.365, -55.203 1.005 -24.94, -56.065 1.005 -
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              6.628 1.005 16.888, -6.925 1.005 15.014, 60.189 0.995 24.27, 59.073 0.995 22.735, 13.921 1.005 -
              16.553, 42.555 0.995 28.102, 56.175 0.995 26.73, 55.313 0.995 25.039, -28.825 0.995 -26.63, -28.825
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              28.532, -33.174 1.005 -28.432, -26.3078 0.995 23.0683, -26.3232 0.995 23.0468, -70.201 1.005 -4.296,
              -72.445 1.005 0.1, -70.547 1.005 0.1, 38.159 0.995 27.756, -33.174 0.995 -28.432, 6.858 1.005 16.888,
              7.154 1.005 15.014, 13.334 1.005 -18.357, 6.758 1.005 -16.778, -37.752 0.995 -29.531, -37.752 1.005 -
              29.531, 38.159 1.005 27.756, -42.445 0.995 30.1, -42.445 1.005 30.1, -47.138 1.005 29.73, -47.138
              0.995 29.73, 72.186 0.995 4.693, 70.311 0.995 -4.396, -24.953 0.995 24.4254, -42.445 0.995 -29.9, -
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              -22.9366, -26.4229 1.005 -22.9366, 0.015 1.005 -16.248, -6.728 1.005 -16.778, 0.015 1.005 -14.35,
              7.054 1.005 -14.904, -7.025 1.005 -14.904, -29.687 0.995 25.139, -24.9373 0.995 24.4474, 19.583
            ]
          }
        }
      }
    ]
  }
]

```

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]

}

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