

Jierui (Jerry) Zhang

E-mail: jieruiz@seas.upenn.edu | TEL: +1 347 272 5815

EDUCATION

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- University of Pennsylvania, School of Engineering and Applied Science**, Philadelphia, PA *Sept 2020 – May 2022*
- Master of Science in Engineering (Robotics)
 - Cumulative GPA: 3.75/4.0
 - Courses taken / taking:
Introduction to Robotics; Control System Design; Applied Machine Learning; Big Data Analytics
- New York University, Tandon Engineering School**, New York, NY *Sept 2016 – May 2020*
- Bachelor of Science in Computer Science, minor in Mathematics
 - Cumulative GPA: 3.92/4.0
 - Honors & Awards: Summa Cum Laude *May 2020*
 - HackNYU: 3rd prize *Feb 2019*

RESEARCH & PROJECTS

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- GTSRB Traffic Sign Recognition**, UPenn *April 2021*
- Built and tested various CNN architectures using PyTorch to classify traffic sign images from the GTSRB dataset. Achieved a test accuracy of 95%.
 - Performed PCA on the dataset for the purpose of visualization and better understanding of the underlying informative structures in the traffic sign images.
- Robot Arm Project**, UPenn *Nov 2020*
- Co-designed a strategy for a 5 DoF robot arm to perform the task of grabbing static and dynamic cubic objects from a turntable and platforms and stack these cubes onto each other. Applied forward and inverse kinematics and inverse velocity kinematics in the design.
 - Programmed the robot arm in Python and tested it in Gazebo simulation.
- Soft Robotics Exoskeleton Project**, NYU Tandon, *Undergraduate Researcher* *Sept 2019 – May 2020*
- Co-designed a lower-body exoskeleton actuated by pneumatic artificial muscles that powers the user's legs to help the user move forward.
 - Designed a system that measures accelerations at the exoskeleton's joints and controls the air flow through pneumatic artificial muscles based on the measurements; implemented the system with rotary encoders and solenoid valves.
 - Developed the system in C.
- Soft Robotics Gripper Project**, NYU Tandon, *Undergraduate Researcher* *Sept 2018 – Sept 2019*
- Built a pneumatically actuated three-finger gripper using silicone rubber gel to fetch objects of certain shapes.
 - Tested different materials: silicone rubber gel, gecko materials, shape-memory alloy.
 - Co-designed the gripper mold and the robot arm structure and 3D printed both items.
 - Studied and applied H-bridge motor driver circuit, stepper motor and microstepping, and DC motor.
 - Programmed in C to support moving the gripper.
- Embedded System Project: Robot Car Relay**, NYU Tandon, *Team Leader* *Nov 2019 – Dec 2019*
- Enabled P2P communication between two cars using HC05 Bluetooth.
 - Programmed in Arduino to autonomously navigate a robot car toward the next car based on the received Bluetooth signal strength and ultrasonic feedback; attached an IMU sensor to track the car's orientation.
 - Applied event-driven programming to handle different kinds of input signals.
 - Led a team of ten members through assigning tasks, organizing discussions, and executing a project plan.
- Senior Design Project: NYU Marketplace**, NYU Tandon *Sept 2019 – Dec 2019*
- Co-worked to deploy a web application to help members of NYU community trade used items.
 - Implemented backend API using Python Flask, connected to Remote MySQL database, and deployed the application on Heroku.
- Machine Learning Project: Predicting Heart Disease**, NYU Tandon *Apr 2019 – May 2019*
- Applied a neural network with variations in regularization methods, hidden layers, number of neurons, and activation functions (ReLU, Leaky ReLU, tanh) to predict if a patient has heart disease.
 - Programmed in Python using Pandas, Scikit-Learn, and Keras to build and test the neural network.

INTERNSHIP

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- Shanghai DIST Co., Ltd.**, Shanghai, China, *Data Analyst* *June 2017 – Aug 2017*
- Participated in data collection for a big data analysis project that aimed at alleviating traffic congestion in Chongqing.
 - Used Python XML and URL modules to acquire climate data from Chongqing's weather forecast website and organize useful information into readable output files.
 - Applied Python JSON module to acquire Chongqing's bus schedule and route information.

SKILLS

Programming: Python, C, C++, SQL;
Others: Arduino, MATLAB