

Intuitive and Efficient Roof Modeling for Reconstruction and Synthesis

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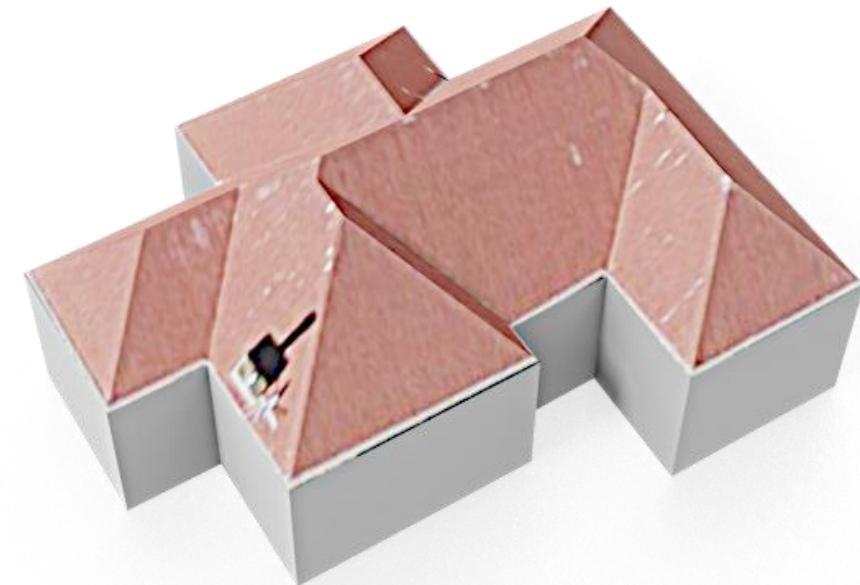


Introduction

Problem Formulation



Input

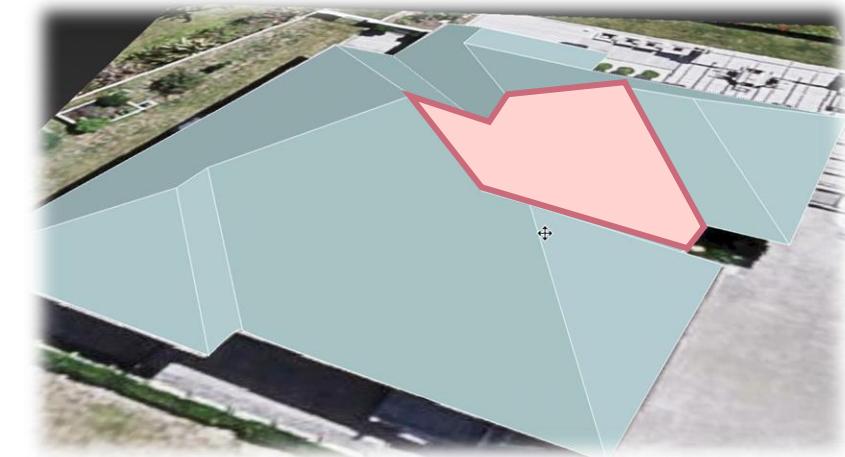
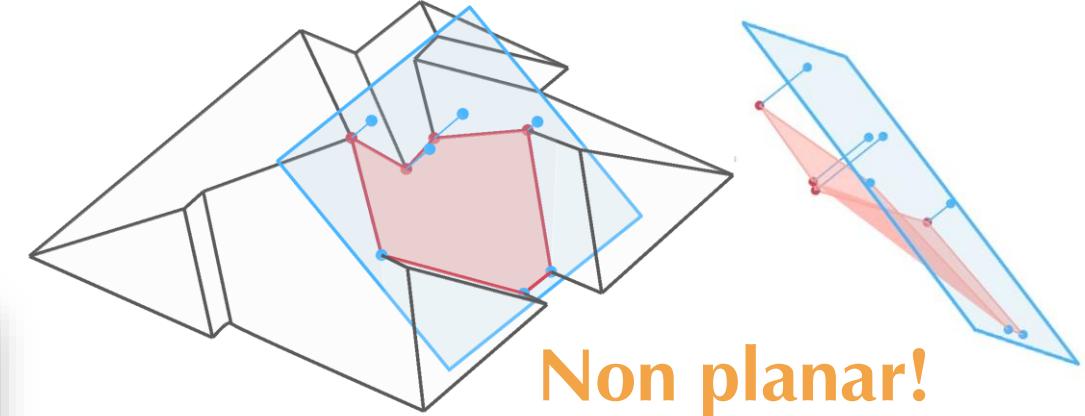
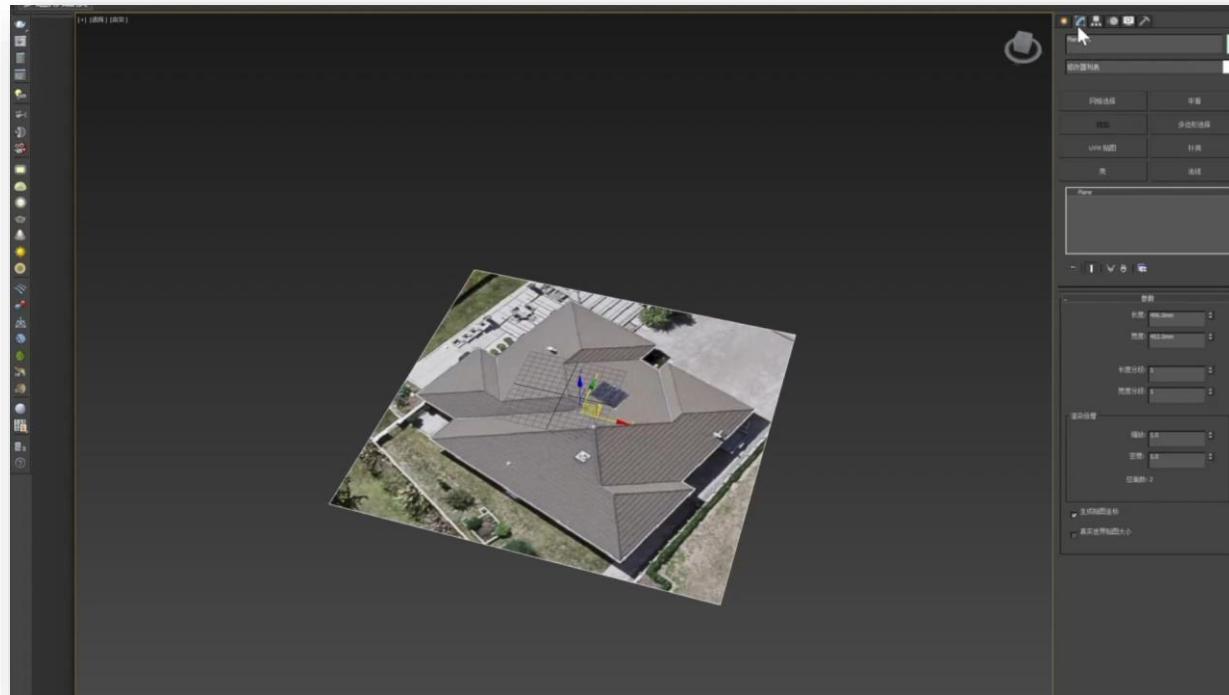


Output

Existing Methods

Commercial Software: 3ds Max

Modeling time 3ds Max: 7min, Ours: 2min



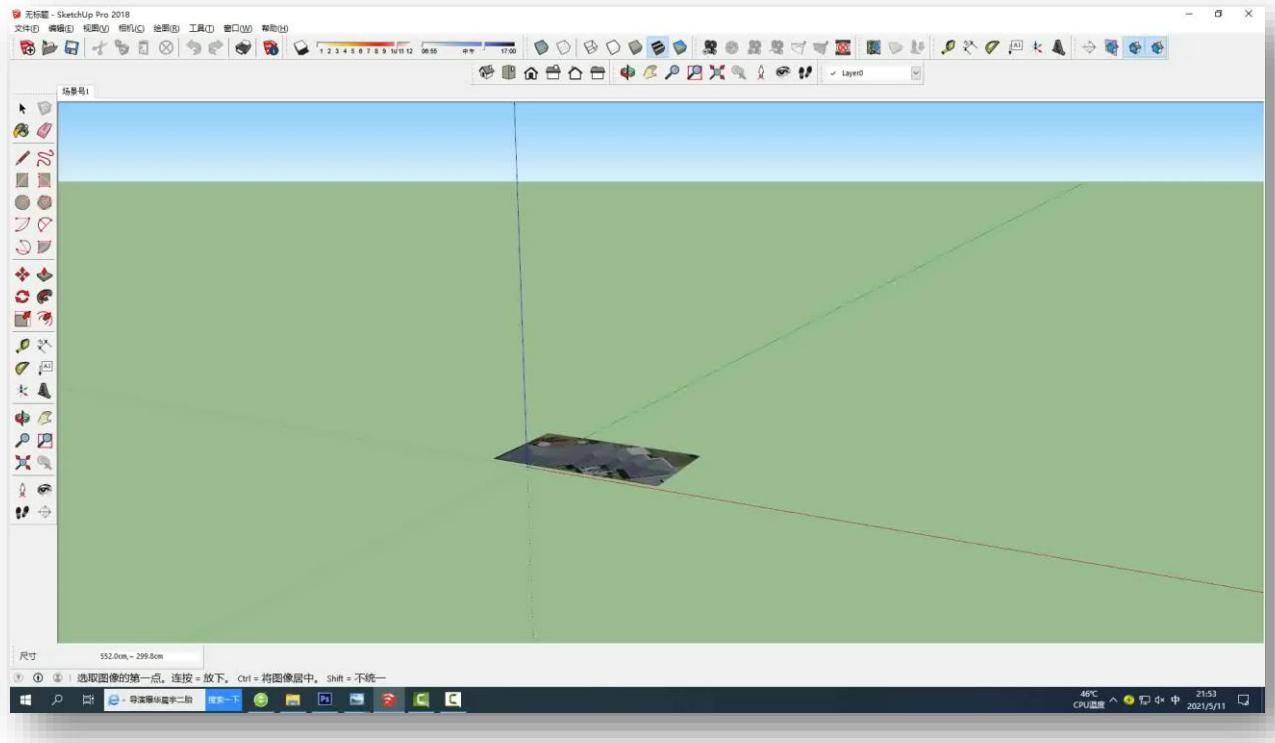
Modeling Operations

- Add vertex
- Add face
- Cut faces
- Move vertex

Existing Methods

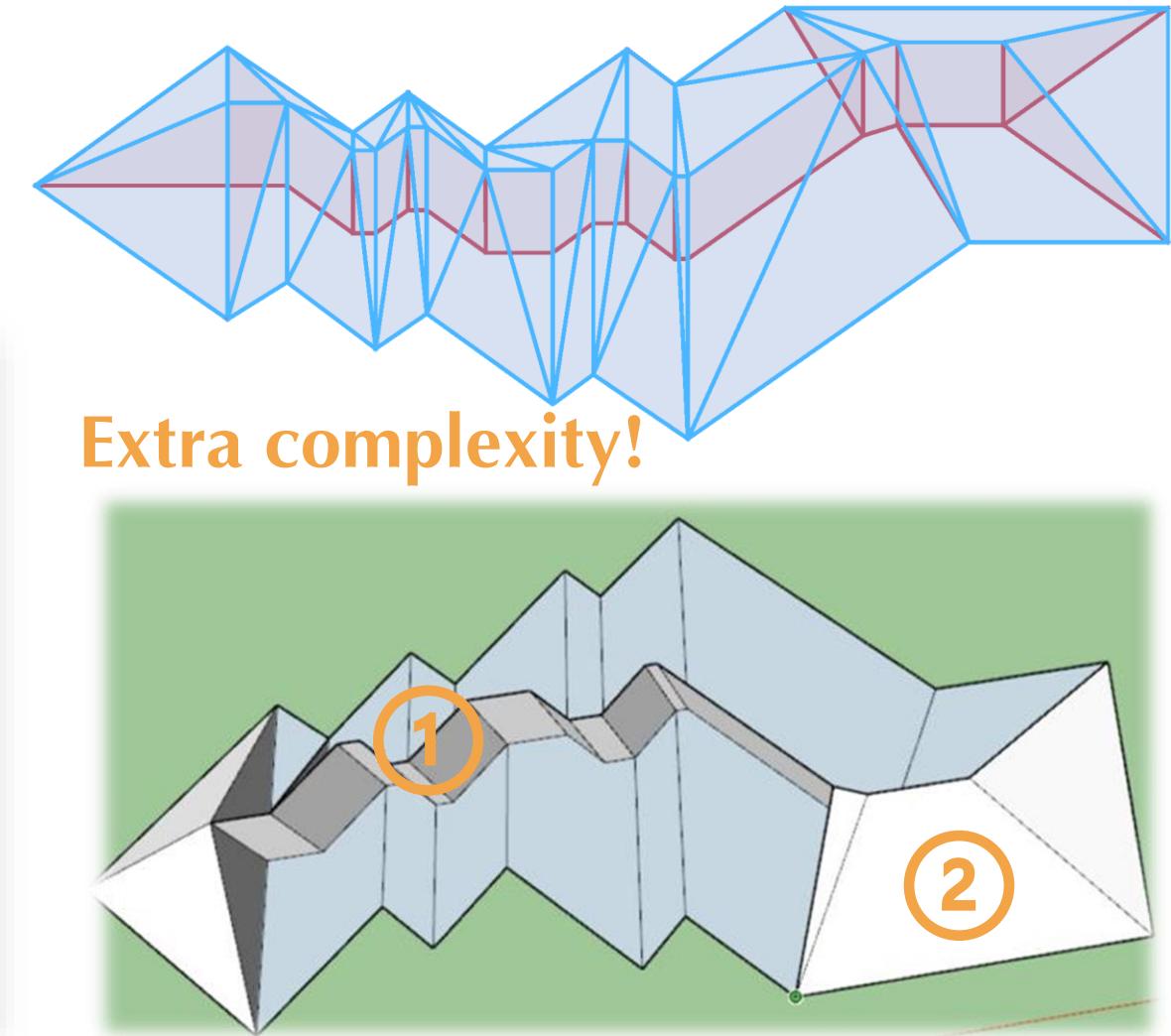
Commercial Software: SketchUp

Modeling time SketchUp: 25min, Ours: 2min



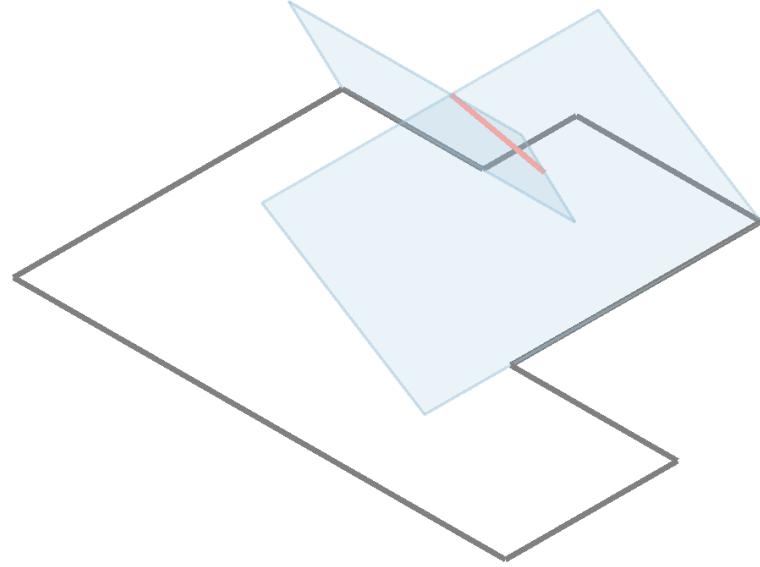
Modeling Operations

1. Build roof beams
2. Add planar roof tops



Existing Methods

Straight Skeleton Based Methods



Input 2D roof outline

Output a roof embedded in 2D

Method solve for the **roof topology** & **roof embedding** at the same time

- Blue planes: stemming from the outlined edges
- Red structure: formed by intersection among blue planes

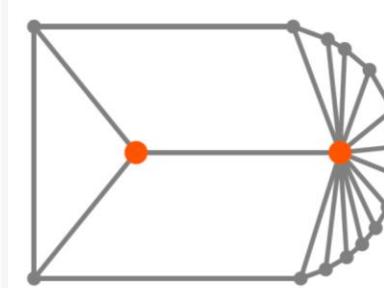
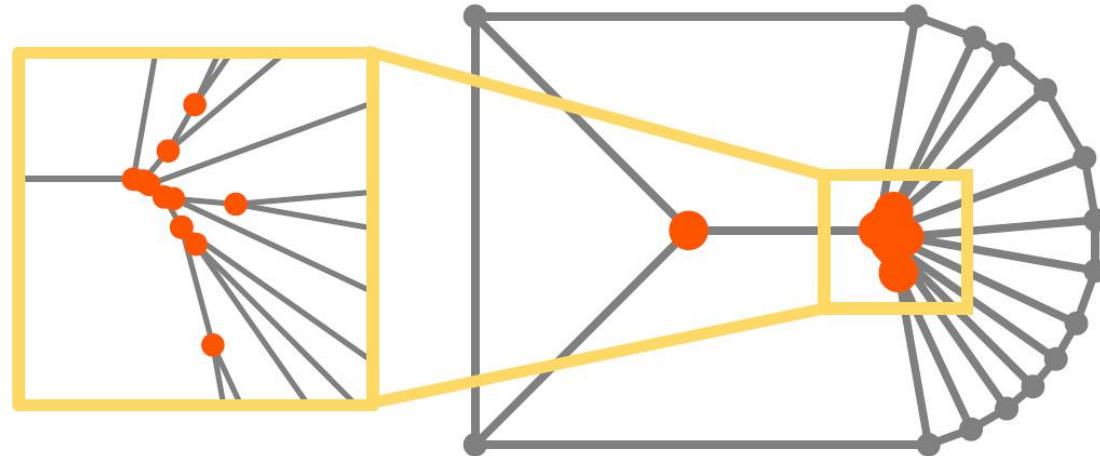
Reference:

1. Aichholzer and Aurenhammer, "Straight Skeletons for general polygonal figures in the plane", 1996

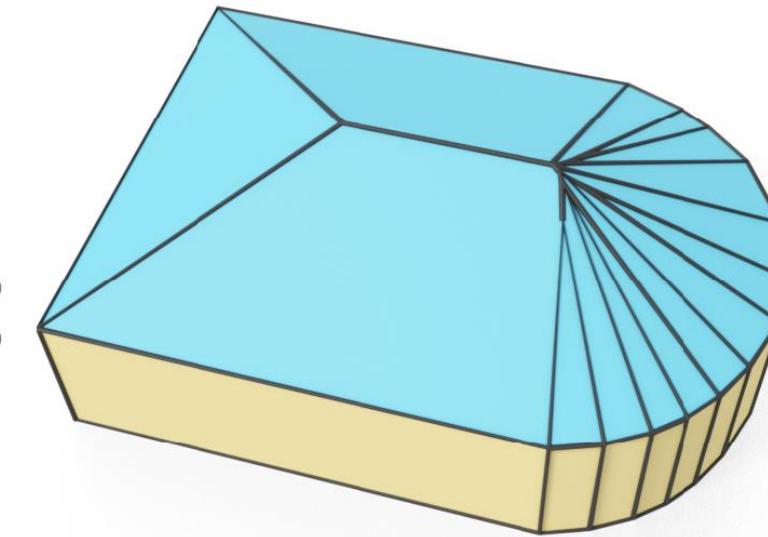
2. Eppstein and Erickson, "Raising roofs, crashing cycles, and playing pool: Applications of a data structure for finding pairwise interactions", 1999

Existing Methods

Straight Skeleton Based Methods



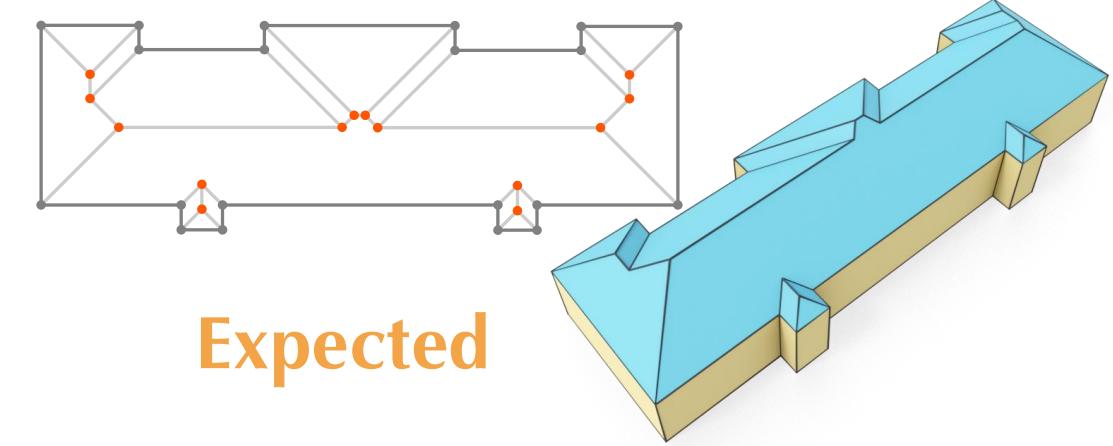
Expected



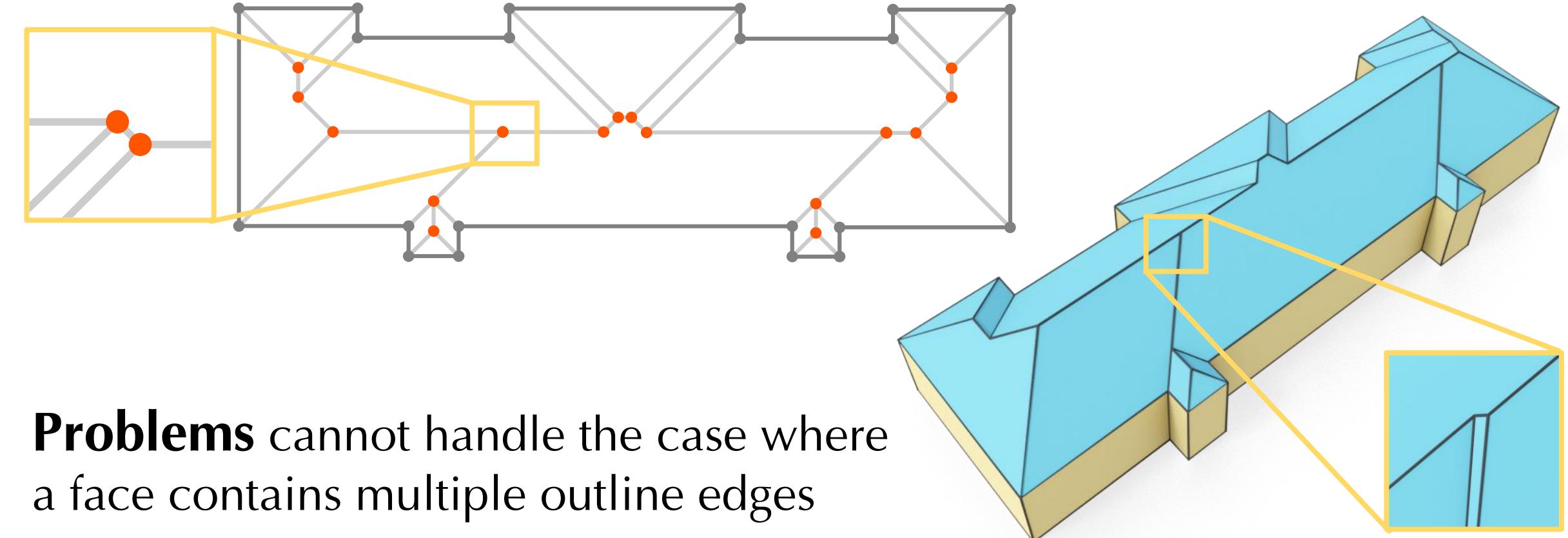
Problems wrong (and much more complicated) roof topology with spurious additional vertices

Existing Methods

Straight Skeleton Based Methods



Expected



Problems cannot handle the case where
a face contains multiple outline edges

Existing Methods

	Commercial software	Straight skeleton	Our goal
<u>Topologically correct</u>			
<u>Interactive editing</u>			
<u>Robust to noisy input</u>			
<u>Light user input</u>			
<u>Efficient for roof construction</u>			
<u>Easy to use for beginners</u>			

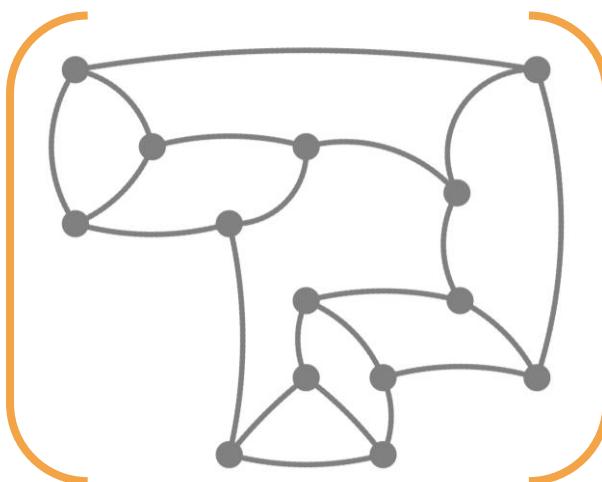
Methodology

Overview

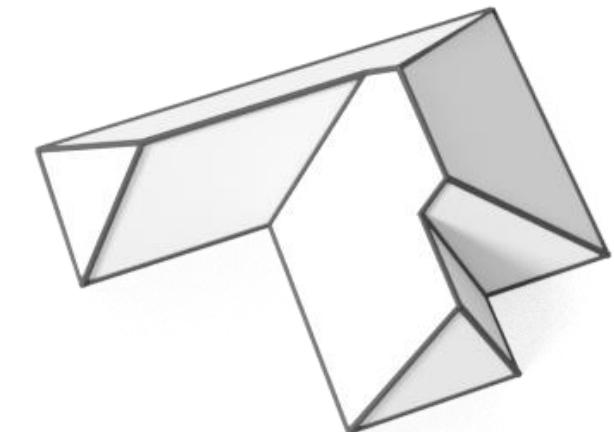
Q1 How to **model** a roof?

Q2 How to describe whether a 3D roof is **planar**?

Q3 How to design **different regularizers** for different use cases?

$$\operatorname{argmin}_X \textbf{Roof Planarity} + \textbf{Regularizers}$$


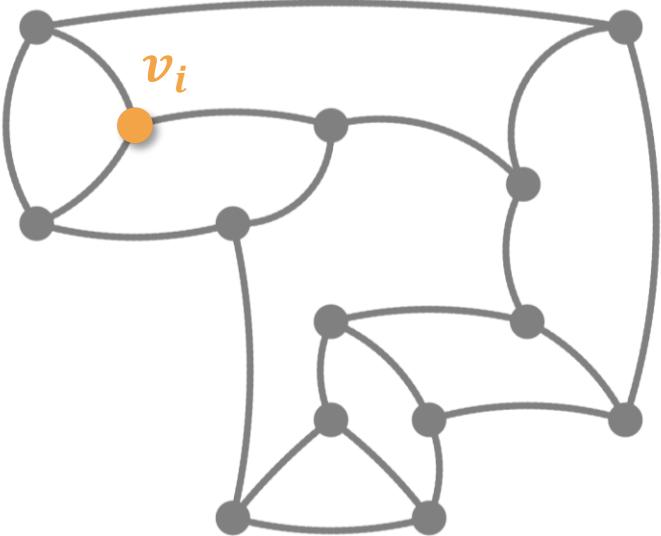
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Methodology

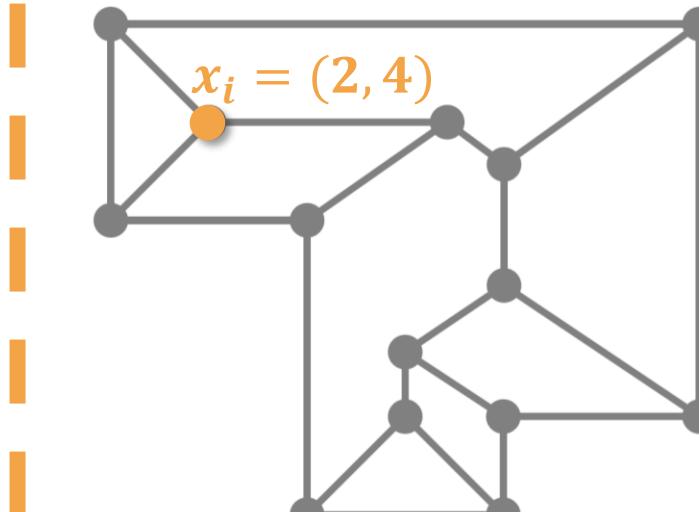
Notations

Roof Topology

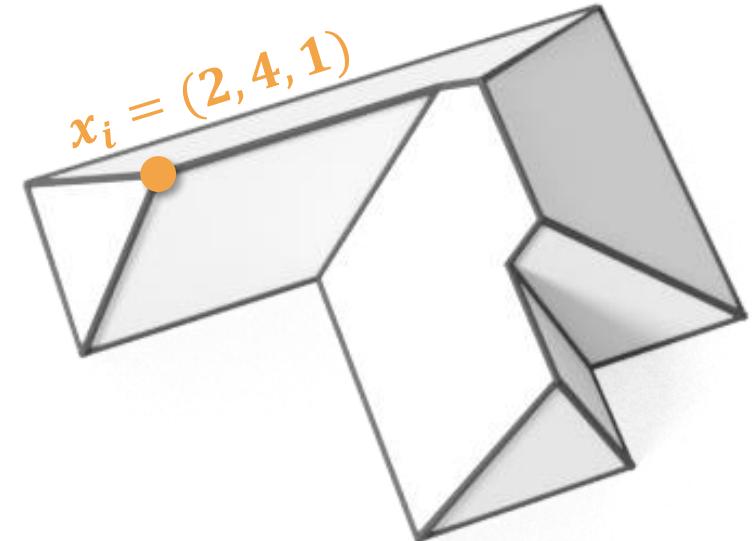


Graph (V, F)
 $|V| = n$

Roof Embedding



2D embedding:
 $(V, F, X \in R^{n \times 2})$

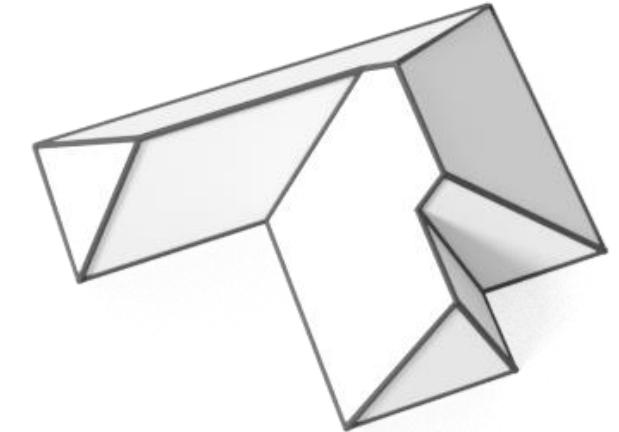


3D embedding:
 $(V, F, X \in R^{n \times 3})$

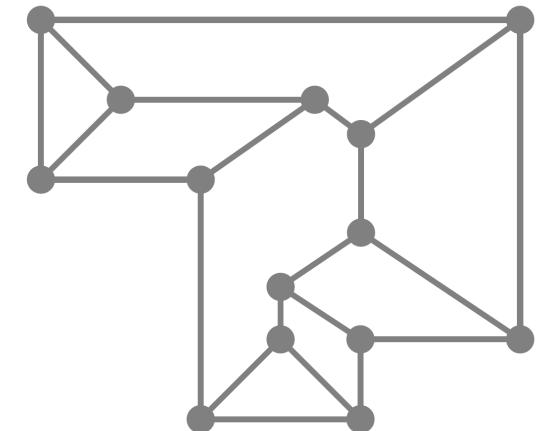
Methodology

Notations

DEFINITION 1 We call a 3D embedding of a roof graph **valid** if each 3D roof face is **planar** and the roof has **non-zero height**.

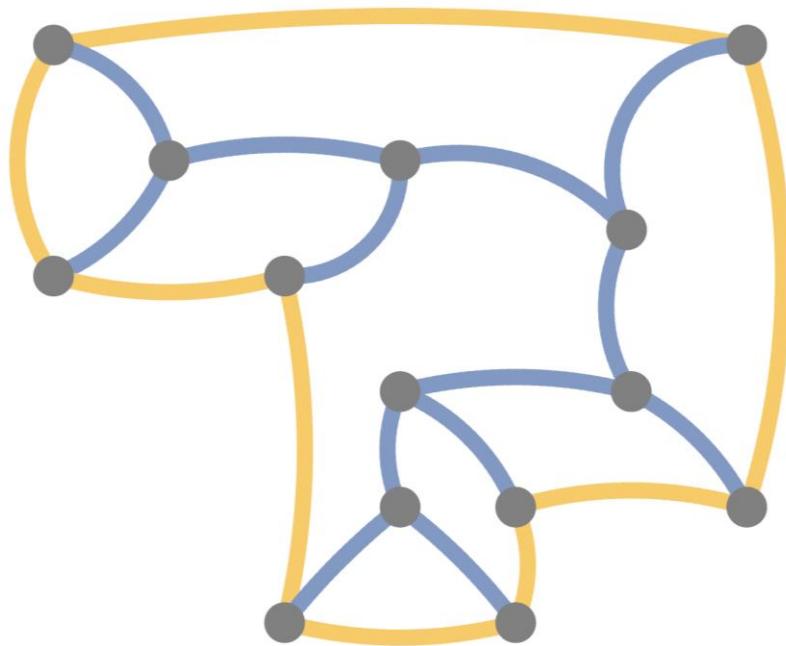


DEFINITION 2 We call a 2D embedding of a roof graph **valid** if there exists a **valid 3D embedding** such that the projection of the 3D embedding in the xy plane is exactly the same as the 2D embedding.

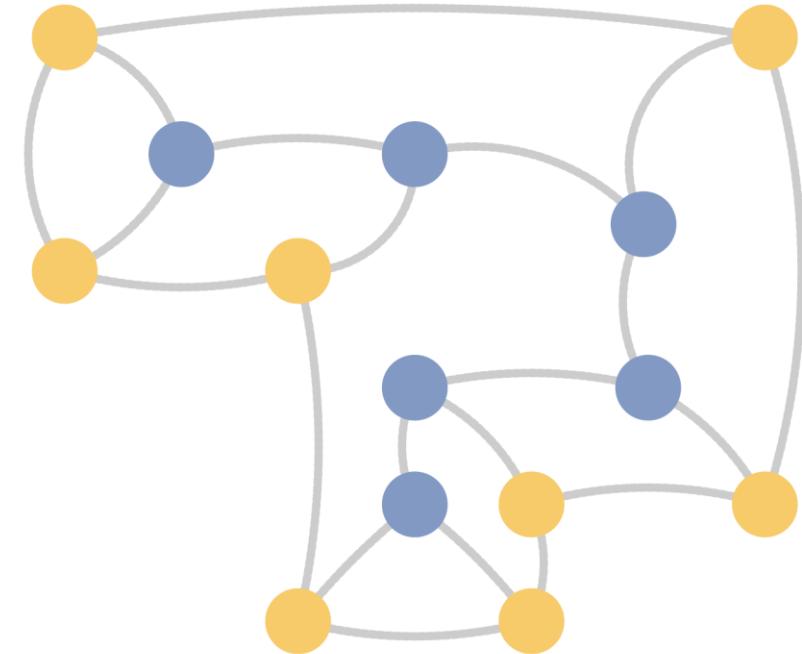


Methodology

Notations



— Roof Edge
— Outline Edge

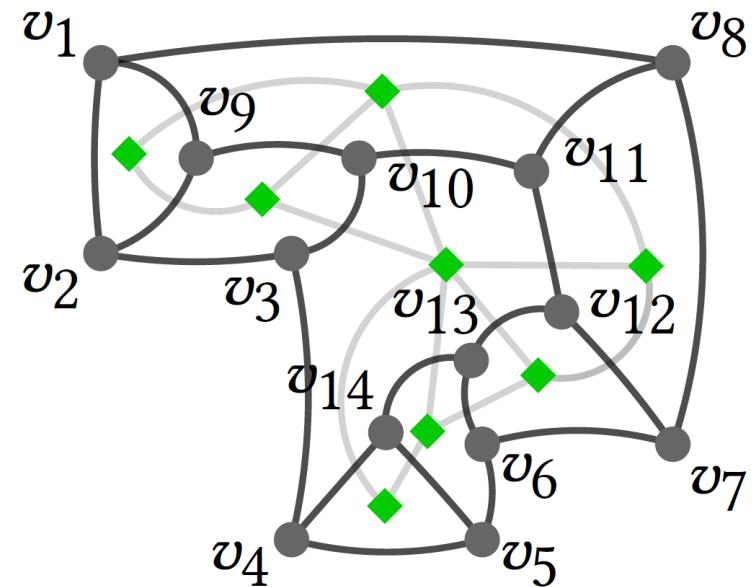


● Roof Vertex
● Outline Vertex

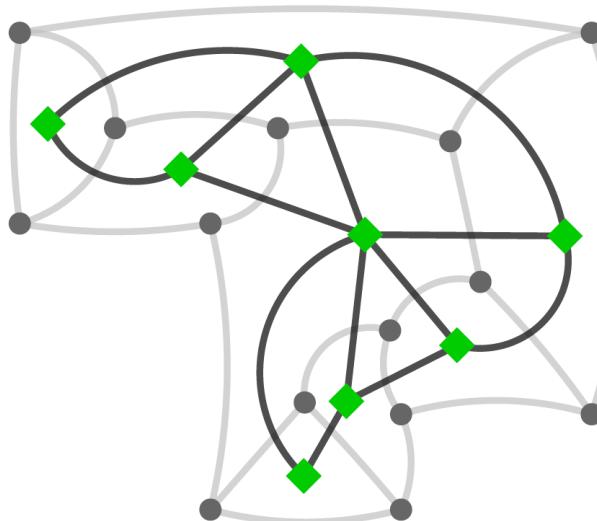
Methodology

Notations

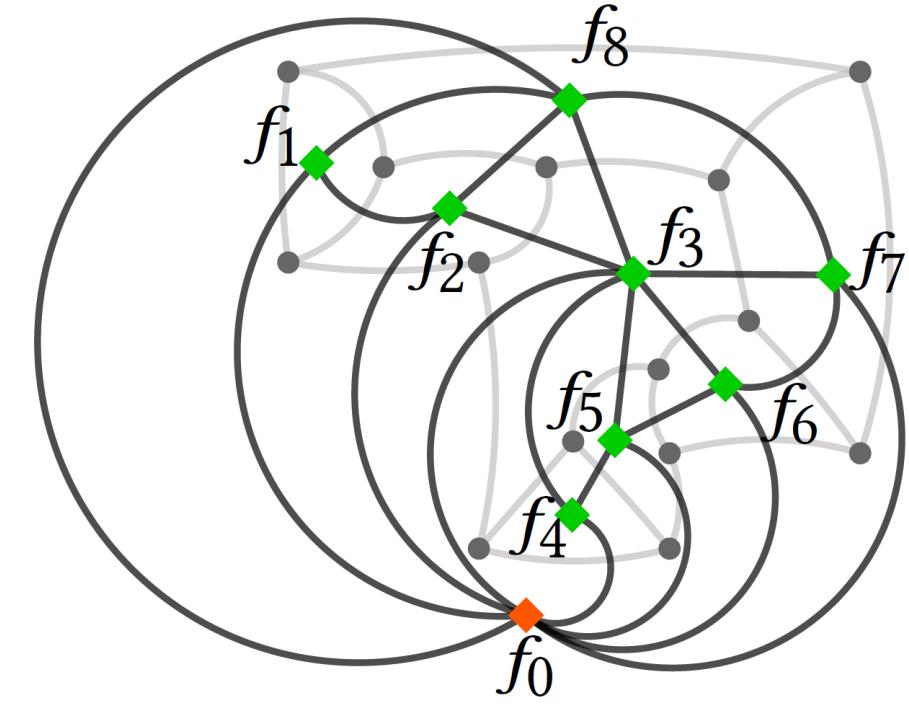
Roof Graph



Dual Graph



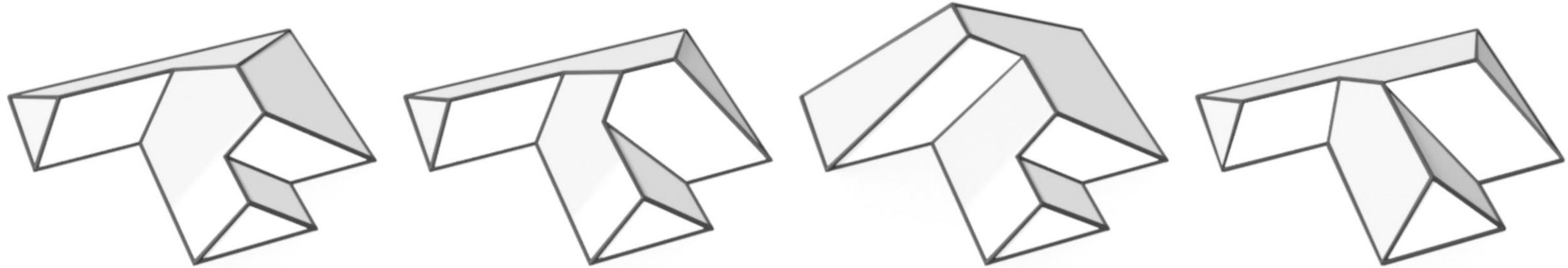
Complete Dual Graph



Equivalent topology representation primal graph \leftrightarrow dual graph

Methodology

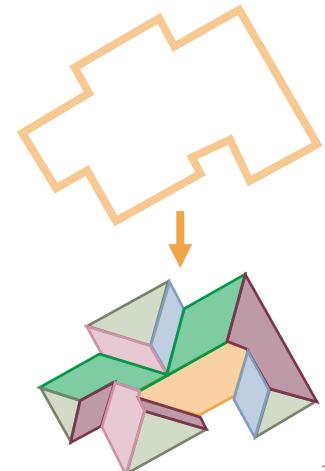
Observations



Observation roof outline → roof topology is NOT injective

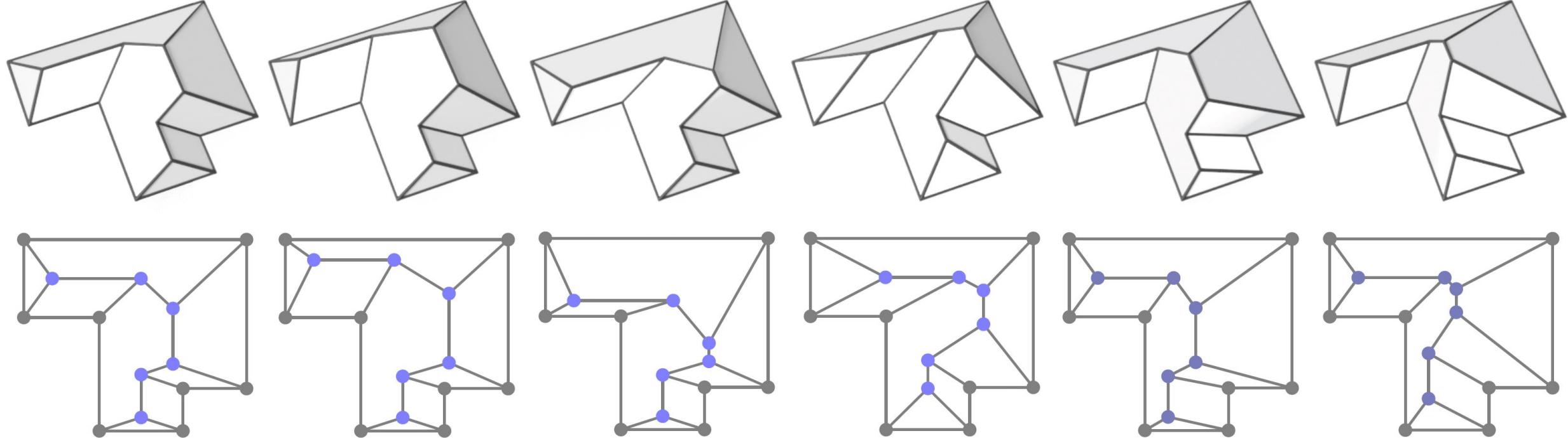
- Roofs with **different style** (topology) can have the **same outline**

Solution **outline + adjacency** to specify the roof topology



Methodology

Observations



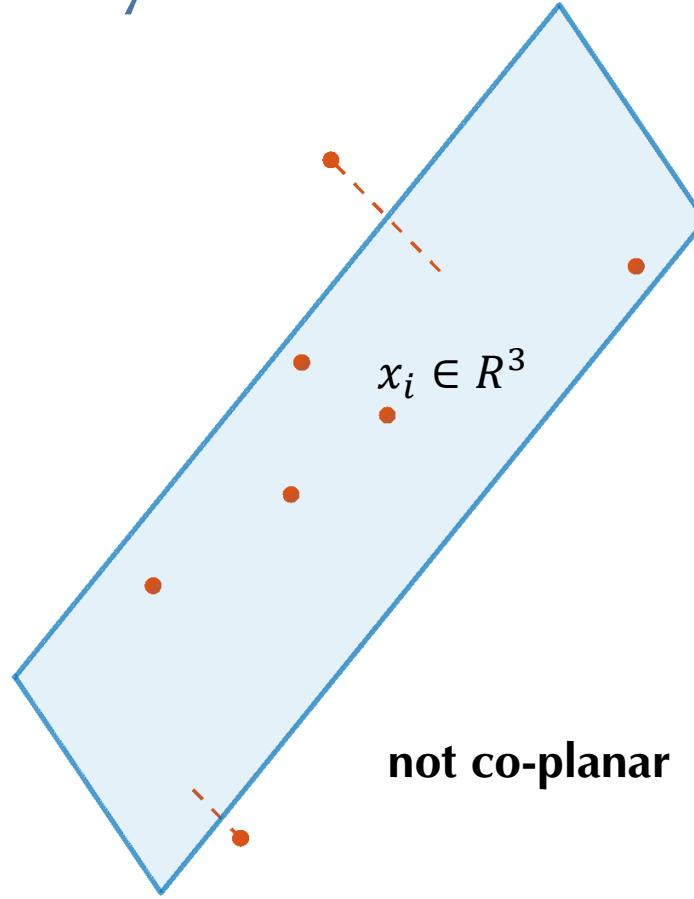
Observation multiple valid roof embeddings exist

- Roofs with the **same topology** can have **different embeddings**

Solution **regularizers** to rule out undesirable embeddings

Methodology

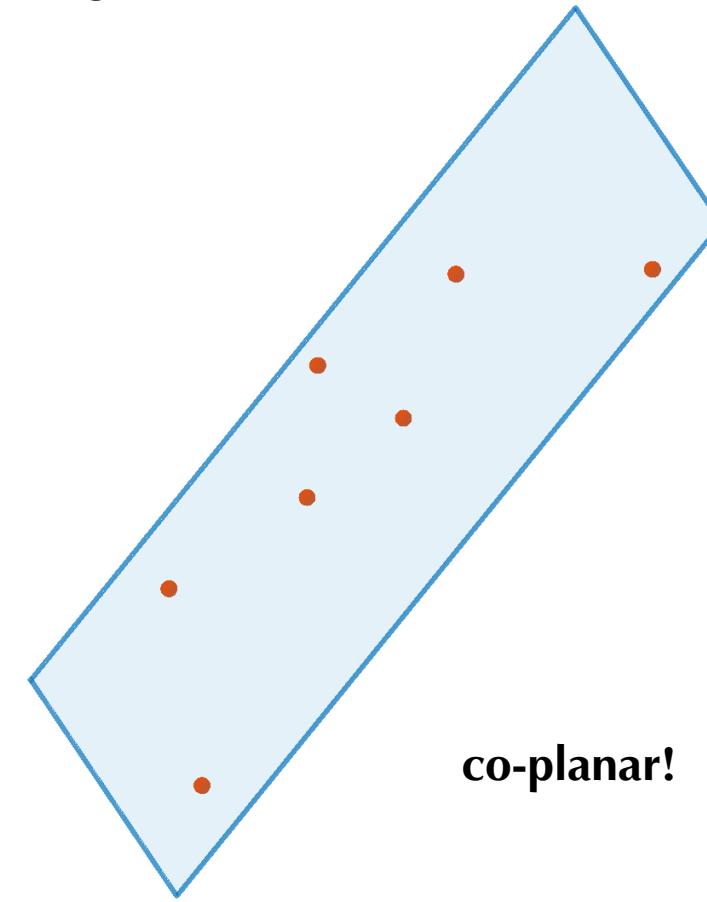
Co-planarity Metric



Covariance matrix $\text{Cov}(X)$ full rank
 $\Rightarrow \sigma_1(\text{Cov}(X)) > 0$

Covariance $\text{Cov}(X) = (X - \text{mean}(X))^T (X - \text{mean}(X))$

- Symmetric & Positive semi-definite
- Smallest eigenvalue ≥ 0



Covariance matrix $\text{Cov}(X)$ loses 1 DOF
 $\Rightarrow \sigma_1(\text{Cov}(X)) = 0$

Summary $\sigma_1(\text{Cov}(X))$ measures the co-planarity error of a point set X

Methodology

Validity Formulation

- ❖ $\text{Cov}(X)$: covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face

Input roof outline + topology (primal/dual graph)

Output a **valid** 3D roof embedding

- ❖ valid: each 3D roof face is planar

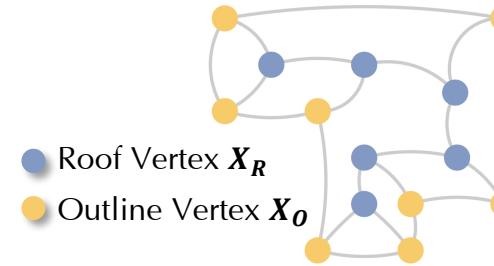
Solution optimization-based formulation

- ❖ **variables**: the 3D positions for each vertex
- ❖ **objective**: the vertices in each face are co-planar

$$E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$$

Methodology

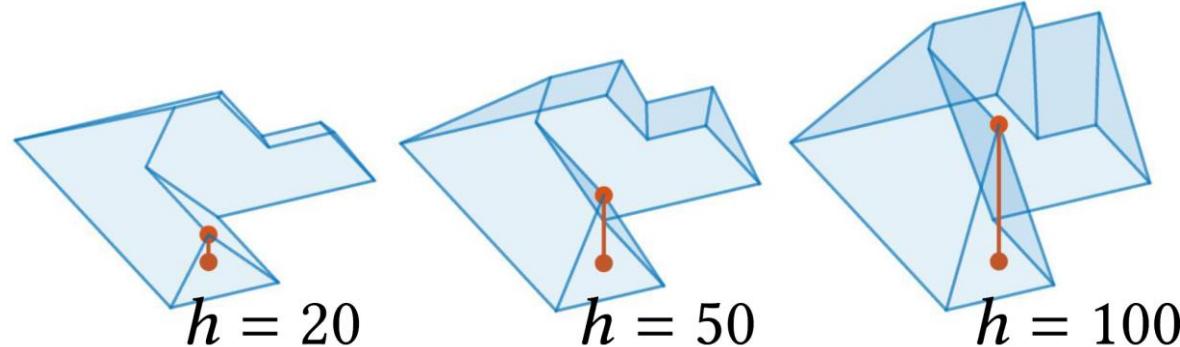
Planarity Optimization



- ❖ $\text{Cov}(X)$: covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face
- ❖ $E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$

$$\min_{X_R} E_{\text{planarity}}(X)$$

$$x_z^* = h$$



Variables 3D positions for roof vertices X_R

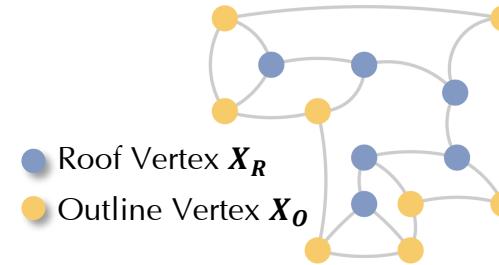
- ❖ Fixed outline: same setting as straight skeleton based methods

Hard constraint avoid zero-height roof

- ❖ Hyper-parameter h allows us to control the overall height of the constructed roof

Methodology

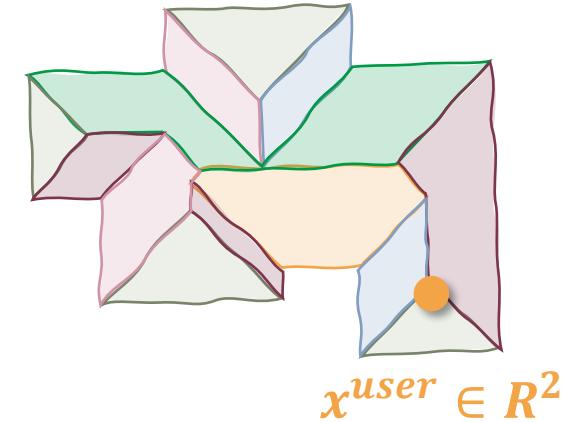
Planarity & User Input



- ❖ $\text{Cov}(X)$: covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face
- ❖ $E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$
- ❖ \bar{X} : the 2D projection of X

$$\min_{X_R} E_{\text{planarity}}(X) + \|\bar{X}_R - \bar{X}_R^{\text{user}}\|_F^2$$

$$x_z^* = h$$



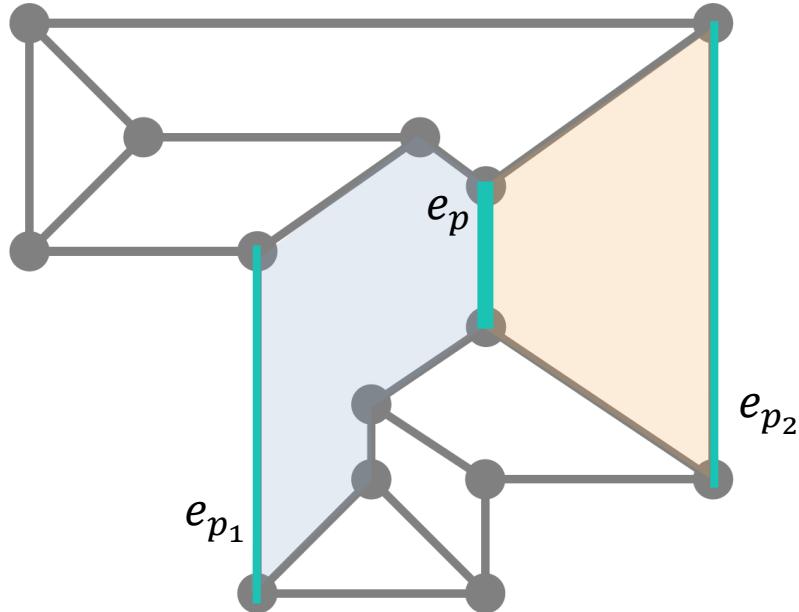
User input not valid but provides good initial locations

- ❖ enforce 2D projections of X to be close to user input

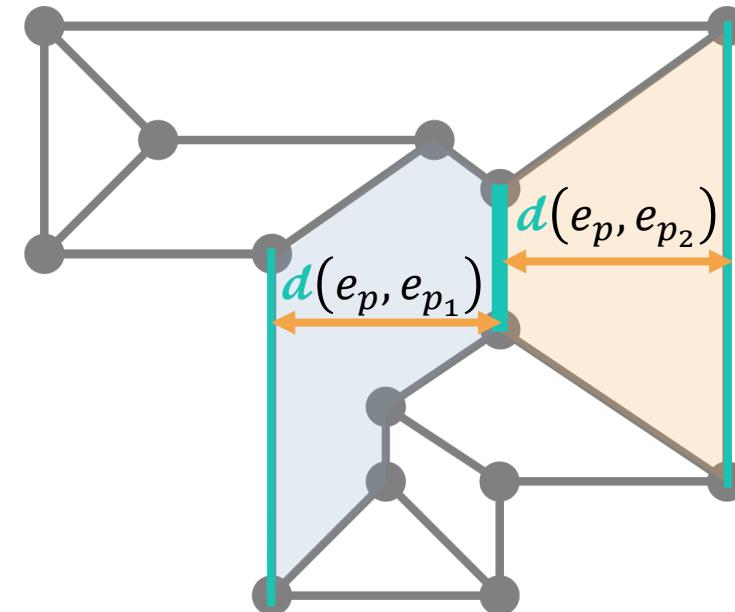
Methodology

Planarity & Aesthetic Constraints

- ❖ Cov(X): covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face
- ❖ $E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$
- ❖ $d(e_p, e_q)$: **distance** between two parallel vectors



Parallel $e_p \parallel e_{p_1} \parallel e_{p_2}$

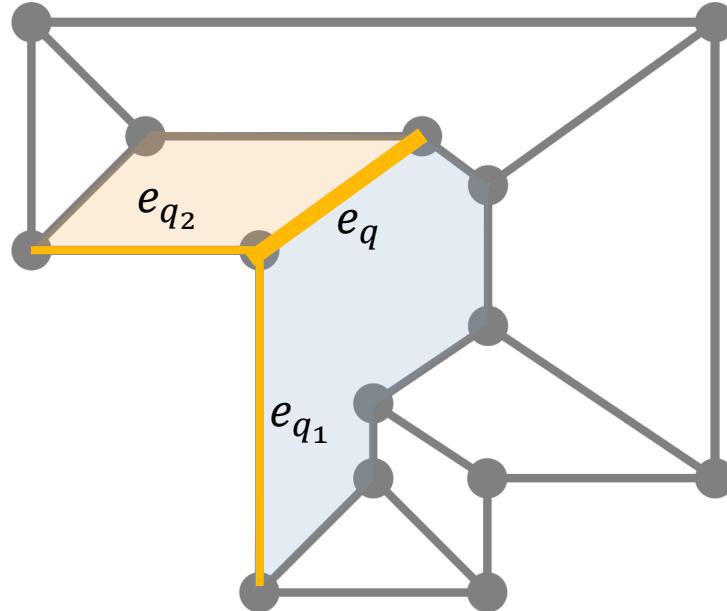


$$E = \|d(e_q, e_{q_1}) - d(e_q, e_{q_2})\|_F^2$$

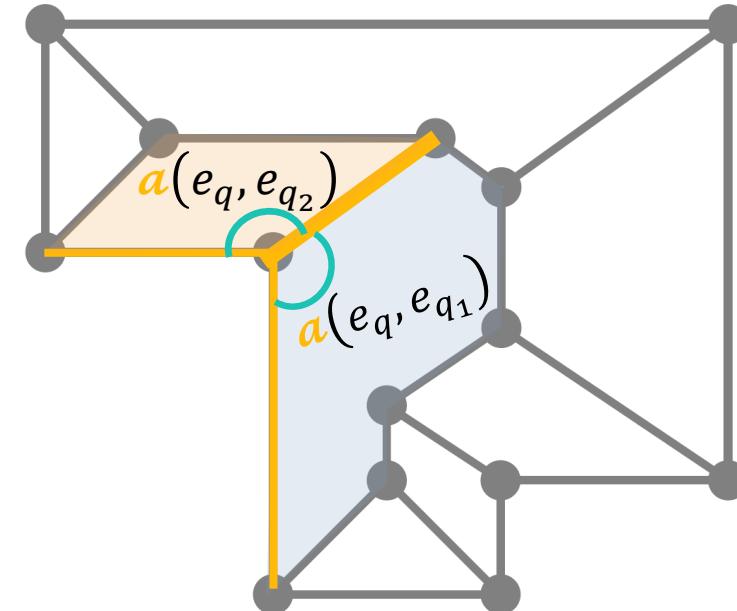
Methodology

Planarity & Aesthetic Constraints

- ❖ $\text{Cov}(X)$: covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face
- ❖ $E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$
- ❖ $a(e_p, e_q)$: angle between two parallel vectors



Intersecting $e_q \wedge e_{q_1} \wedge e_{q_2}$



$$E = \|a(e_q, e_{q_1}) - a(e_q, e_{q_2})\|_F^2$$

Methodology

Planarity & Aesthetic Constraints

- ❖ $\text{Cov}(X)$: covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face
- ❖ $E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$

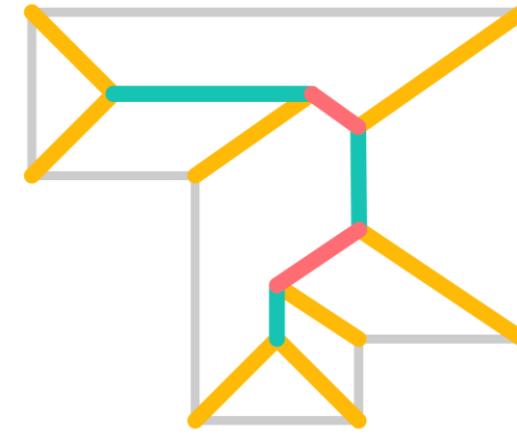
$$\min_{X_R} E_{\text{planarity}}(X) + E_{\text{aesthetic}}(X)$$

$$x_z^* = h$$

$$E_{\text{aes.}}(X) = \sum_{p \in \{\text{I}\}} \|\textcolor{orange}{a}(e_p, e_{p_1}) - \textcolor{orange}{a}(e_p, e_{p_2})\|_F^2 +$$

$$\sum_{q \in \{\text{II}\}} \|\textcolor{teal}{d}(e_q, e_{q_1}) - \textcolor{teal}{d}(e_q, e_{q_2})\|_F^2$$

- ❖ $a(e_p, e_q)$: angle between two vectors
- ❖ $d(e_p, e_q)$: distance between two parallel vectors



Aesthetic constraints more plausible local minima

- ❖ Yellow edges: angle bisectors
- ❖ Green edges: equal distance to the parallel outline edges

Methodology

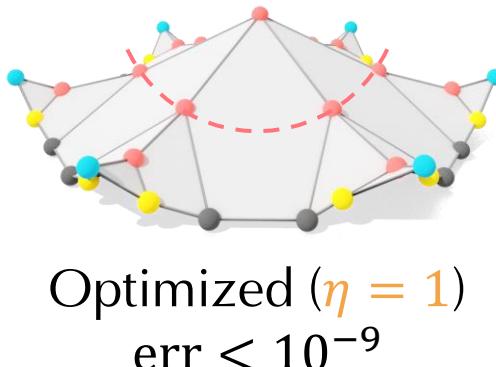
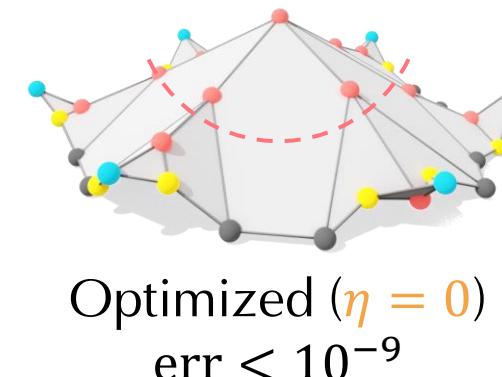
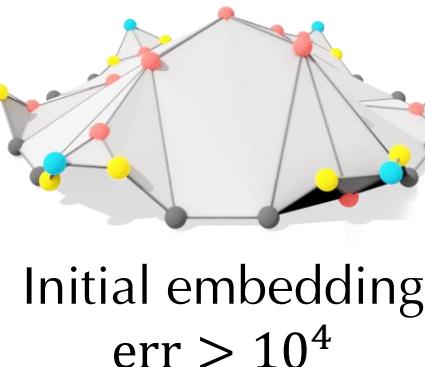
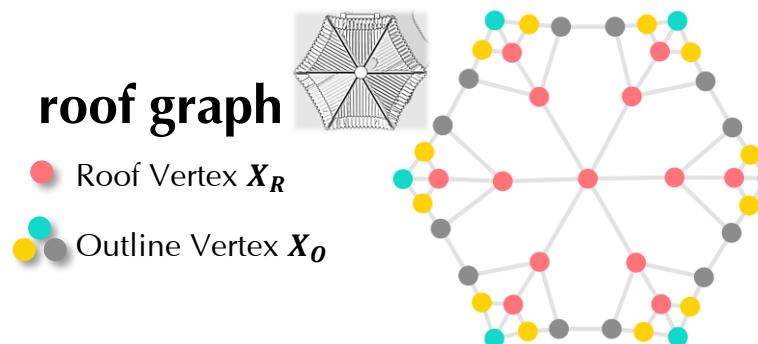
Planarity & Free Outlines

- ❖ $\text{Cov}(X)$: covariance matrix of X
- ❖ $\sigma_1(A)$: the smallest eigenvalue of A
- ❖ X_{f_i} : vertex positions of the f_i -th face
- ❖ $E_{\text{planarity}}(X) = \sum_{i=1}^{n_f} \sigma_1(\text{Cov}(X_{f_i}))$
- ❖ $\text{Var}(x)$: variance of a vector x

$$\min_{x_{xyz}, x_z} E_{\text{planarity}}(X) + \eta \text{Var}(x_z^{\text{red}}) + \eta \text{Var}(x_z^{\text{yellow}})$$
$$x_z^* = h$$

Set outline vertices as free variables

- ❖ Add extra constraints: subset of outline vertices in similar height

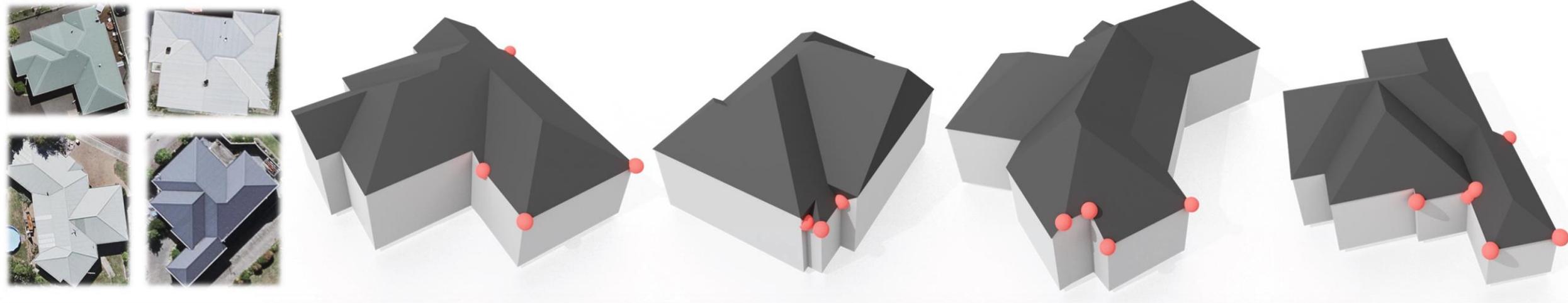


Hexagonal Pavilion



Methodology

Planarity & Free Outlines

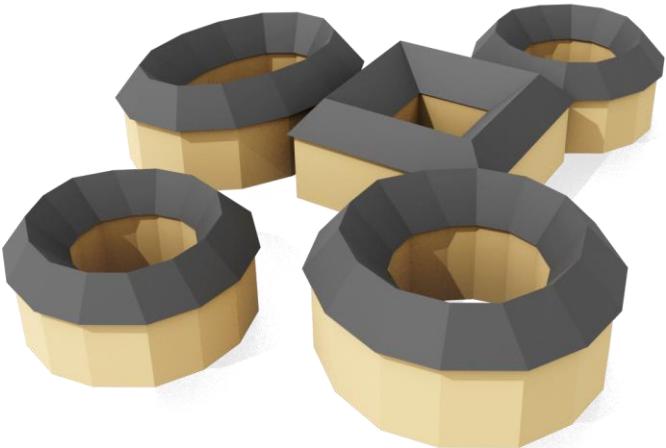


Set outline vertices as free variables

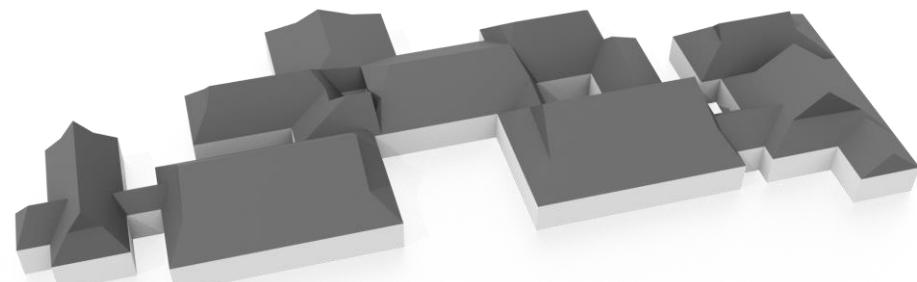
- ❖ red: outline vertices with non-zero height

Results

Hakka Tulou, China



Nagoya Castle, Japan



Temple



Hexagonal
Pavilion



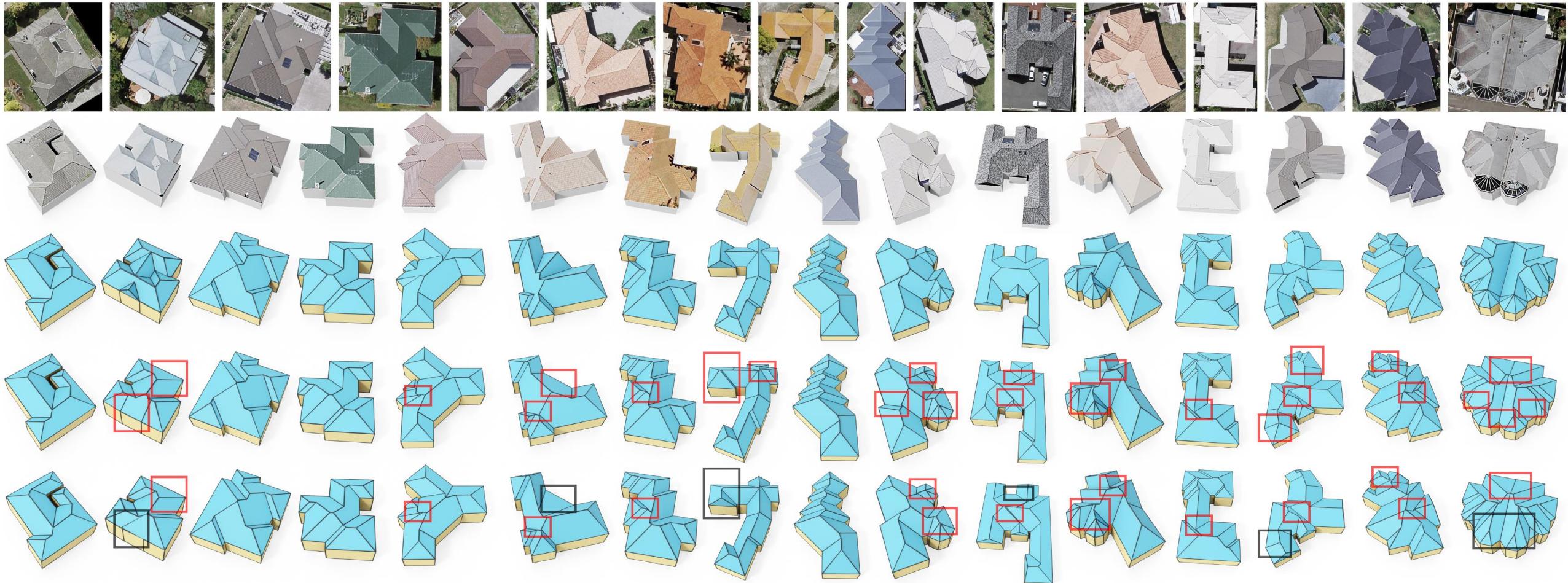
(Reference images from internet)

Feasibility model roofs with different styles:

- ✓ Approximate **curved roofs**
- ✓ Roofs with **vertical facades**
- ✓ Roofs with **inner courtyards**
- ✓ Outline edges in **different height**

Results

Compare to Straight Skeleton Based Methods



Each Row

1. Input aerial images
2. Our reconstructed roofs (texture)

3. Our reconstructed roofs (geometry)
4. Straight Skeleton
5. Weighted Straight Skeleton (wss)

■ Inconsistencies

■ Error introduced by wss

Results

Compare to Straight Skeleton Based Methods

More expressive!

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	<i>GT roof complexity</i>	
n_v	22	24	25	25	27	27	32	33	33	33	34	35	36	39	39	51		
n_f	12	17	14	14	15	16	17	20	18	20	18	21	19	22	21	38		
Ours	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
#err	ss	0	2	0	0	1	2	1	2	0	3	2	2	1	3	2	4	<i>visual inconsistencies</i>
	wss	0	2	0	0	1	2	1	1	0	2	2	2	1	2	2	2	
Ours	22	24	25	25	27	27	32	33	33	33	34	35	36	39	39	51		
\bar{n}_v	ss	22	22	26	26	30	28	34	40	34	38	38	40	38	40	44	50	<i>number of vertices on the constructed roofs</i>
	wss	22	22	26	26	30	28	34	40	34	38	38	40	38	40	44	50	
Ours	12	17	14	14	15	16	17	20	18	20	18	21	19	22	21	38		
\bar{n}_f	ss	12	12	14	14	16	15	18	21	18	20	20	21	20	21	23	26	<i>number of faces on the constructed roofs</i>
	wss	12	12	14	14	16	15	18	21	18	20	20	21	20	21	23	26	
t (s)	Ours	89.4	115	153	97.9	114	92.9	151	145	155	167	148	158	179	199	178	284	
	ss	16	20	24	18	20	16	28	29	27	33	32	35	31	33	38	38	<i>runtime</i>
	wss	-	300	-	-	60	180	180	300	-	120	180	60	60	480	180	360	

Baselines

- Straight Skeleton (ss)
- Weighted Straight Skeleton (wss)

Results

Compare to Commercial Software

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	
Ours	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	
valid	3D	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	
SU	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	
Ours	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
#err	3D	9	12	10	11	12	12	16	15	15	11	16	15	16	18	17	20
SU	20	16	21	19	16	27	33	21	25	38	28	30	33	33	29	42	
poly (%)	Ours	75	65	71	79	67	69	82	75	83	60	72	57	79	73	71	42
3D	75	62	71	79	75	67	87	75	83	52	76	60	80	72	74	56	
SU	0	24	2.6	3.3	20	2.3	2.0	22	7.0	10	11	9.8	3.8	15	14	0	
\bar{n}_v	Ours	22	24	25	25	27	27	32	33	33	33	34	35	36	39	39	51
3D	22	31	37	26	28	28	44	34	34	35	44	35	36	40	39	53	
SU	22	29	26	25	28	30	36	45	33	52	39	40	37	46	42	58	
\bar{n}_f	Ours	12	17	14	14	15	16	17	20	18	20	18	21	19	22	21	38
3D	12	21	14	14	16	18	18	20	18	21	21	25	20	25	23	36	
SU	32	33	35	33	31	43	50	41	43	58	46	51	52	55	50	82	
t (min)	Ours	1.5	1.9	2.6	1.6	1.9	1.6	2.5	2.4	2.6	2.8	2.5	2.6	3.0	3.3	3.0	4.7
3D	6	7	7	6	6	12	12	11	7	14	6	9	10	8	10	23	
SU	12	16	15	12	22	20	21	22	21	25	19	32	22	14	25	36	

3ds Max allows non-planar faces!

Manually triangulate faces to enforce planarity in SU!

More efficient

Baselines

- 3ds Max (3D)
- SketchUp (SU)

Is roof planar?

Topological errors

Ratio of the polygon faces in the roof

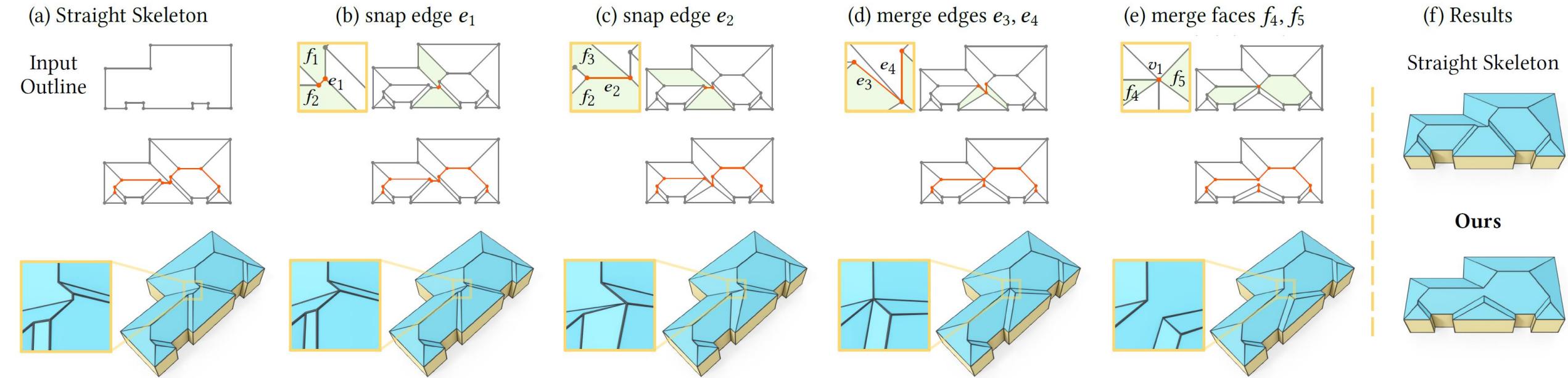
number of vertices on the constructed roofs

number of faces on the constructed roofs

runtime

Applications

Interactive Editing



Editing Operations optimization-based formulation allows **interactive editing**

- ✓ Move a vertex
- ✓ Move an edge
- ✓ Snap an edge
- ✓ Merge two faces
- ✓ Split a face
- ✓ Force two faces to be adjacent

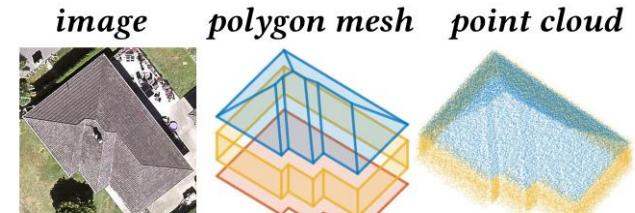
Applications

Roof-Image Paired Dataset

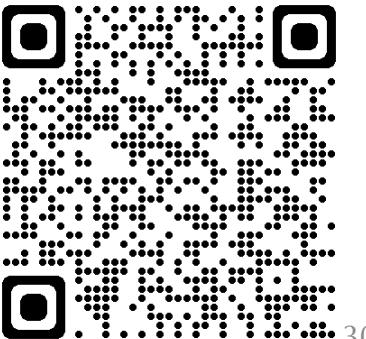


Dataset polygonal roof meshes paired with images

- ✓ >3K .obj
- ✓ Texture coordinates
- ✓ Face labels
- ✓ Roof synthesis
- ✓ Roof segmentation
- ✓ Roof detection



https://github.com/llorz/SGA21_roofOptimization/tree/main/RoofGraphDataset

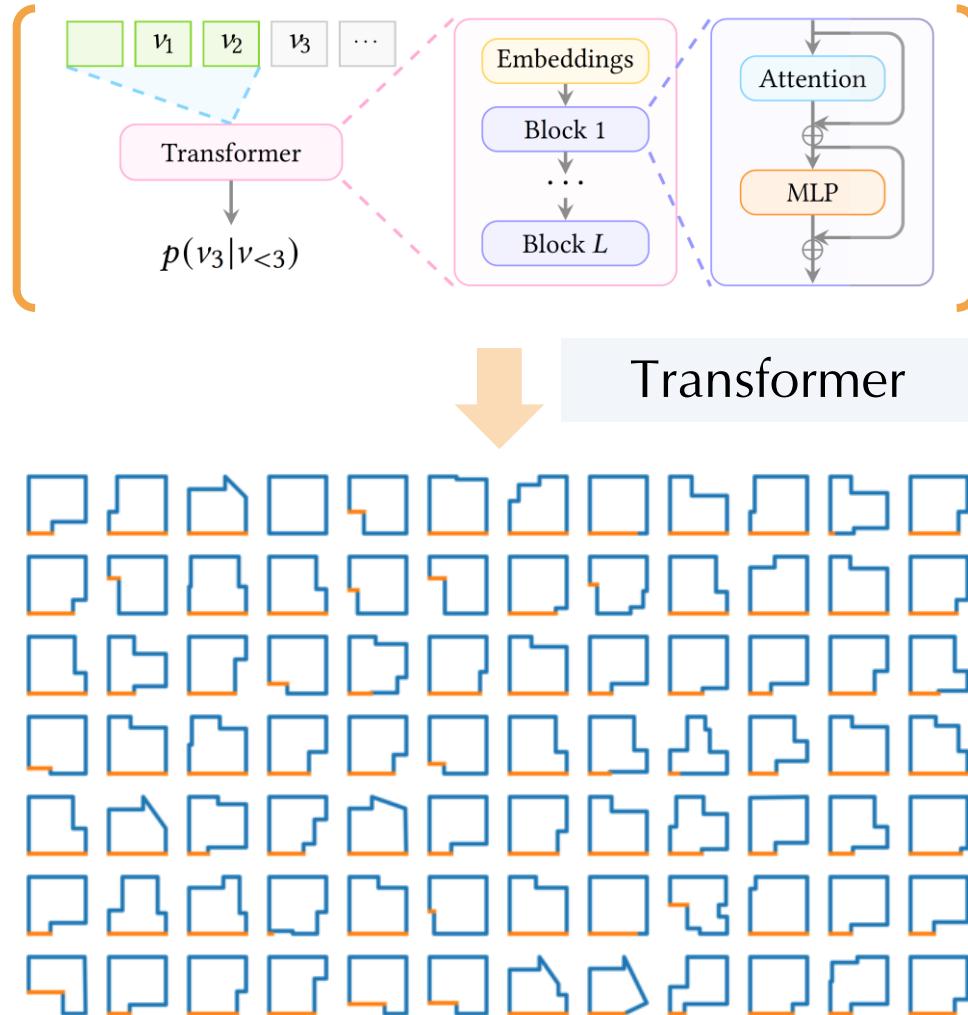


Applications

Roof Synthesis from Scratch

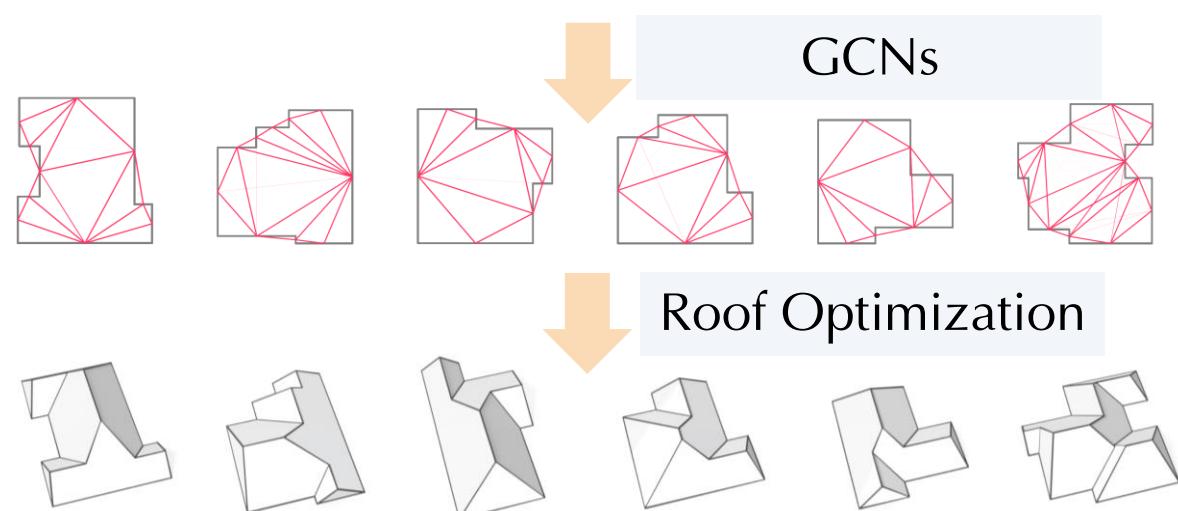
Training set: 2105 samples, Testing set: 210 samples

Roof Outline Generation



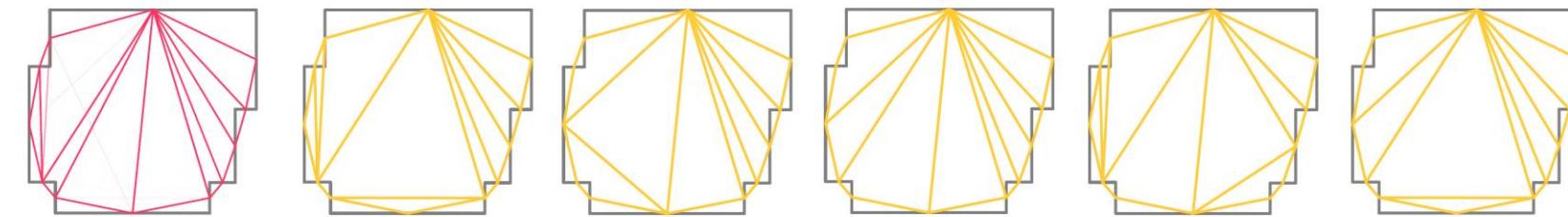
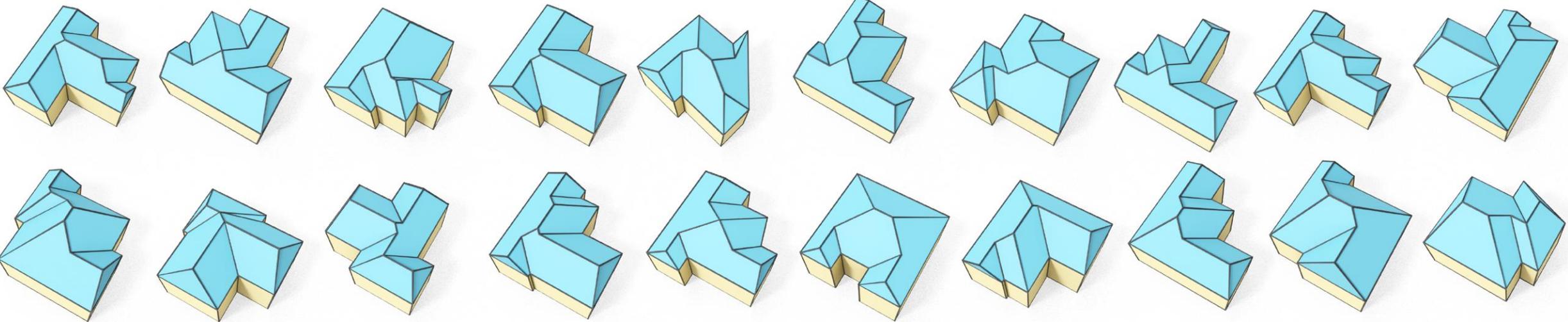
Face Adjacency Prediction

$$\text{MLP} \left[\max \left(\frac{\bar{f}_i^{(l-1)}, \bar{f}_j^{(l-1)}}{n_O} \right) \right] \oplus \bar{f}_{i,j}^{(l-1)} \oplus g^{(l-1)} = \bar{f}_{i,j}^{(l)}$$
$$\text{MLP} \left[\frac{n_O}{\text{mean}} \left(\frac{\bar{f}_{i,j}^{(l)}}{n_O} \right) \right] \oplus \bar{f}_i^{(l-1)} \oplus g^{(l-1)} = \bar{f}_i^{(l)}$$
$$\text{MLP} \left[\frac{n_O}{\text{mean}} \left(\frac{\bar{f}_i^{(l)}}{n_O} \right) \right] \oplus g^{(l-1)} = g^{(l)}$$

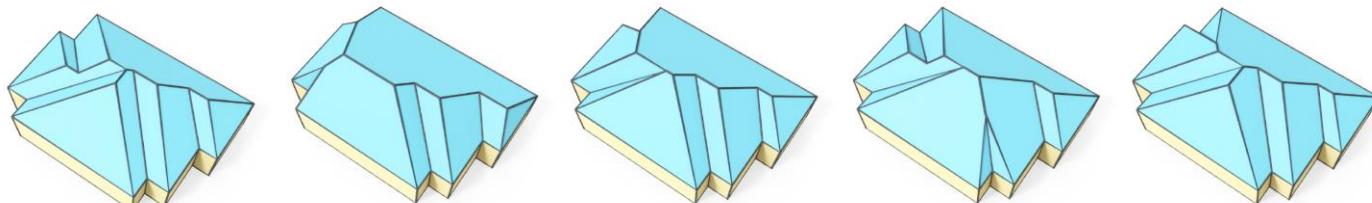


Applications

Roof Synthesis from Scratch



Learned
Adjacency



- ✓ Synthesize roofs from scratch
- ✓ Synthesize roofs with different styles with the same outline

Summary

Goal roof modeling + roof embedding

Baselines commercial software & straight skeleton based methods

Our Solution roof graph representation + optimization-based construction

- Efficient & Flexible
- Interactive editing
- Image-Roof paired dataset
- Automatic roof synthesis: outline generation + adjacency prediction

Limitations & Future Work

Limitations

- Cannot directly handle curved roofs including stadiums and skyscrapers
- Did not model roof textures
- Did not touch on automatic reconstruction from images

Future Work

- End-to-end roof reconstruction from images
- Practical constraints for roof fabricability
- Roof texture synthesis
-

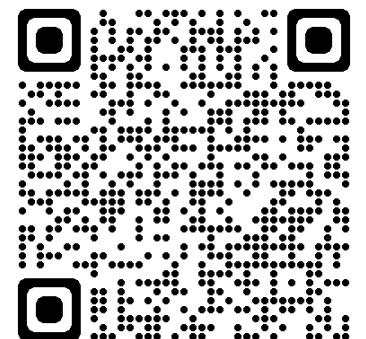
Intuitive and Efficient Roof Modeling for Reconstruction and Synthesis

Jing Ren^{1,2}, Biao Zhang¹, Bojian Wu², Jianqiang Huang², Lubin Fan², Maks Ovsjanikov³, Peter Wonka¹

¹KAUST, ²Alibaba Group, ³Ecole Polytechnique, IP Paris

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Code & Data https://github.com/lorz/SGA21_roofOptimization

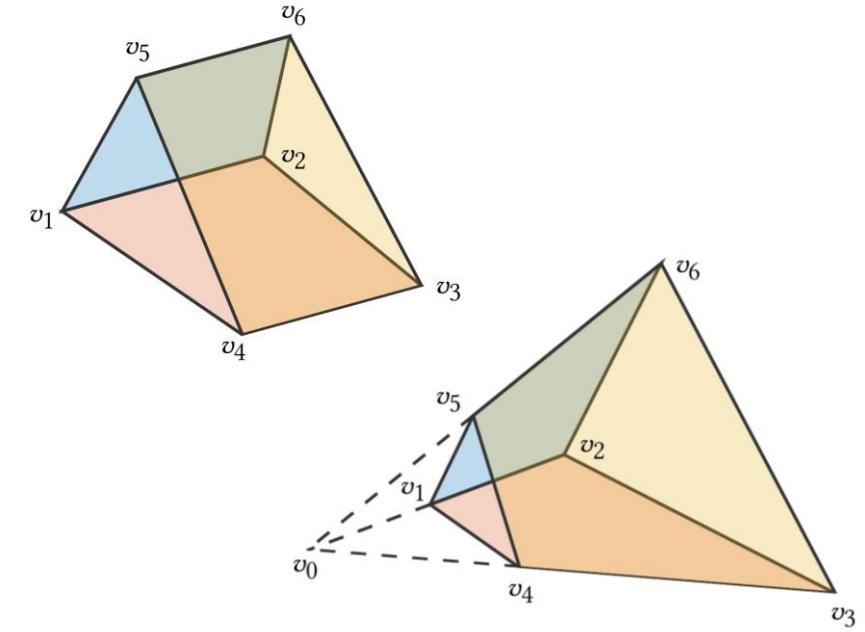


Supplementary materials

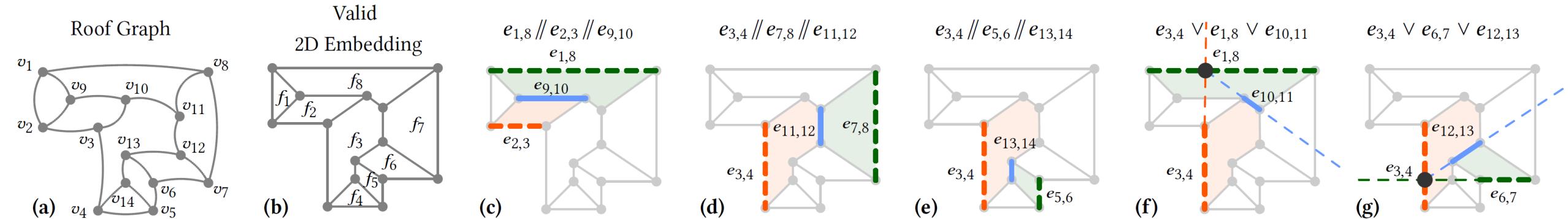
Introduction

Notations

REMARK 1 The intersecting line of two adjacent 3D planar faces with fixed outline edges, is either parallel to both outline edges, or intersects the two outline edges at the same point. The same conclusion holds when we project the 3D planar faces to xy -plane



Use Remark 1 to check if a 2D embedding is valid or not

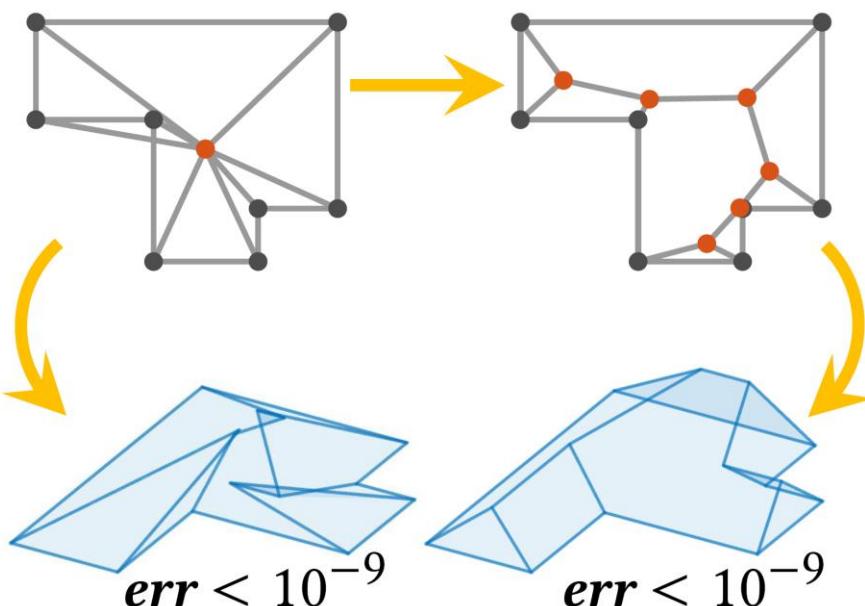


Methodology

Spectral Initialization

- ❖ \bar{X}_O : 2D position of the outline vertices
- ❖ \bar{X}_R : 2D position of the roof vertices
- ❖ A_V : vertex adjacency matrix of the roof graph, $A_V(i, j) = 1$ iff $v_i \sim v_j$
- ❖ \mathcal{L}_V : graph Laplacian of the roof graph, $\mathcal{L}_V = \text{diag}(\mathbf{1}^T A_V) - A_V$

$$\min_{\bar{X}_R} \left\| \begin{pmatrix} \bar{X}_O \\ \bar{X}_R \end{pmatrix}^T \mathcal{L}_V \begin{pmatrix} \bar{X}_O \\ \bar{X}_R \end{pmatrix} \right\|_F^2$$

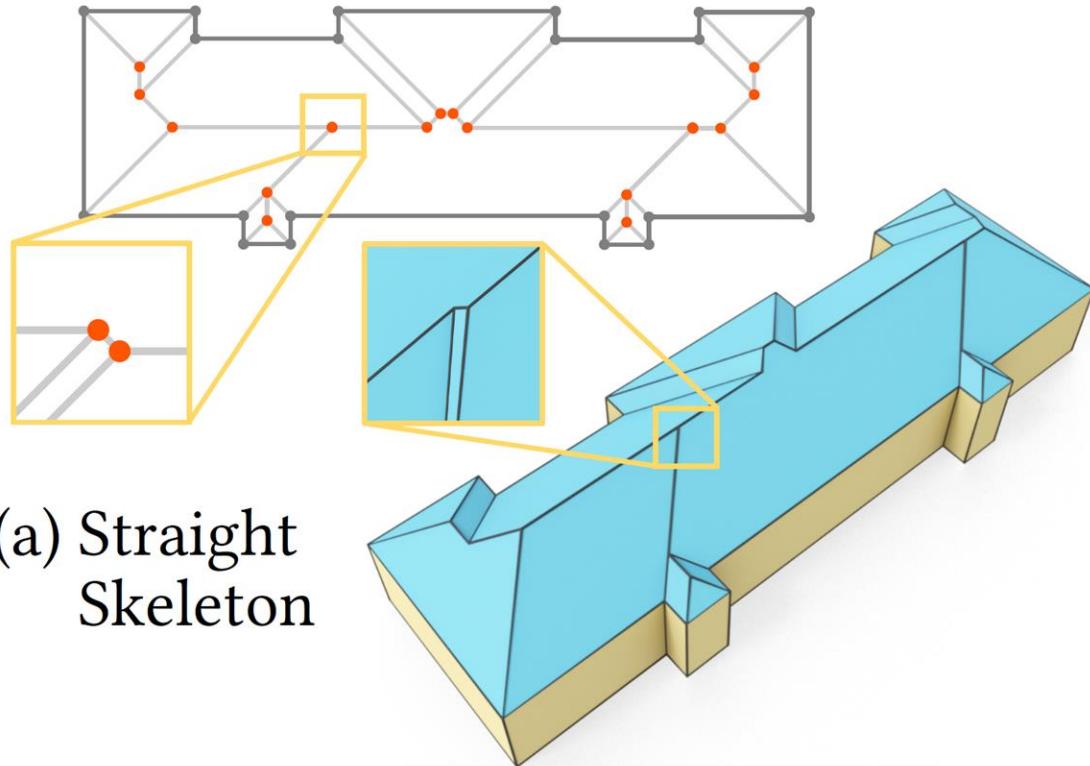


No user input as initial embedding

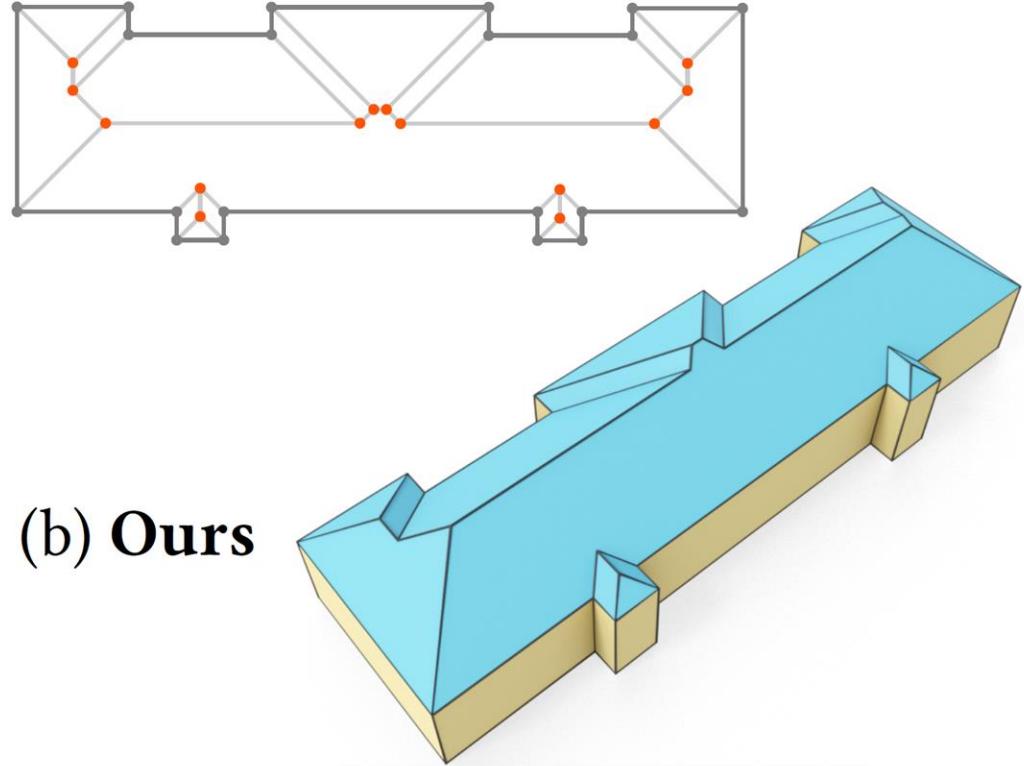
- ❖ **Random/Zero initialization** can lead to undesirable global minima
- ❖ **Spectral initialization** can avoid self-intersections

Results

Face with Multiple Outline Edges



(a) Straight
Skeleton



(b) Ours

More expressive

- ❖ Primal graph: can model this case directly
- ❖ Dual graph: the face adjacency matrix can be modified to model this case

(a)

A primal graph with 8 faces labeled f_1 through f_8 . The graph structure is as follows:

- f_1 is connected to f_2 , f_8 , and f_3 .
- f_2 is connected to f_1 , f_3 , f_4 , and f_7 .
- f_3 is connected to f_1 , f_2 , f_4 , and f_5 .
- f_4 is connected to f_2 , f_3 , f_5 , and f_6 .
- f_5 is connected to f_3 , f_4 , and f_6 .
- f_6 is connected to f_4 , f_5 , and f_7 .
- f_7 is connected to f_2 , f_6 , and f_8 .
- f_8 is connected to f_1 and f_7 .

(b)

A dual graph where each face from (a) is represented by a node. The nodes are arranged in a horizontal chain: f_1 , f_2 , f_3 , $f_4(f_8)$, f_5 , f_6 , f_7 , and f_8 . The connections between nodes represent the adjacencies between faces in (a). A red box highlights the edge between f_4 and f_8 .

(a) Face adjacency matrix:

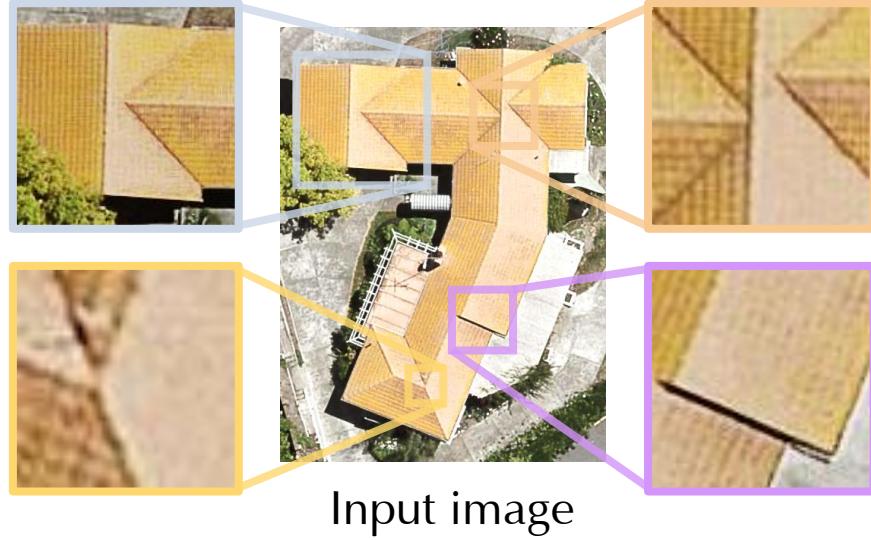
$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

(b) Modified face adjacency matrix:

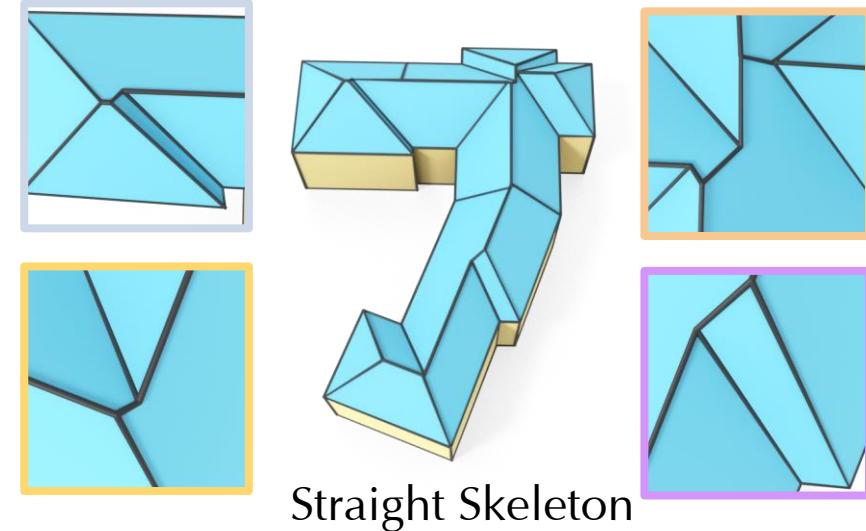
$$\begin{pmatrix} 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Applications

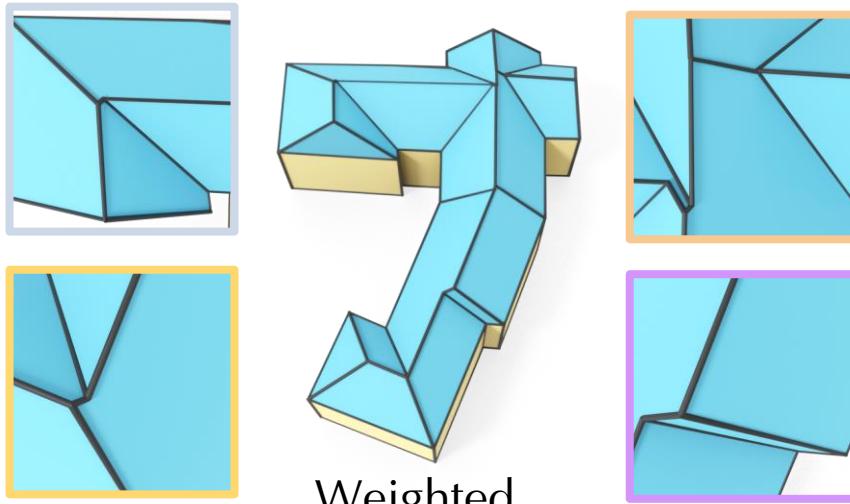
Interactive Editing



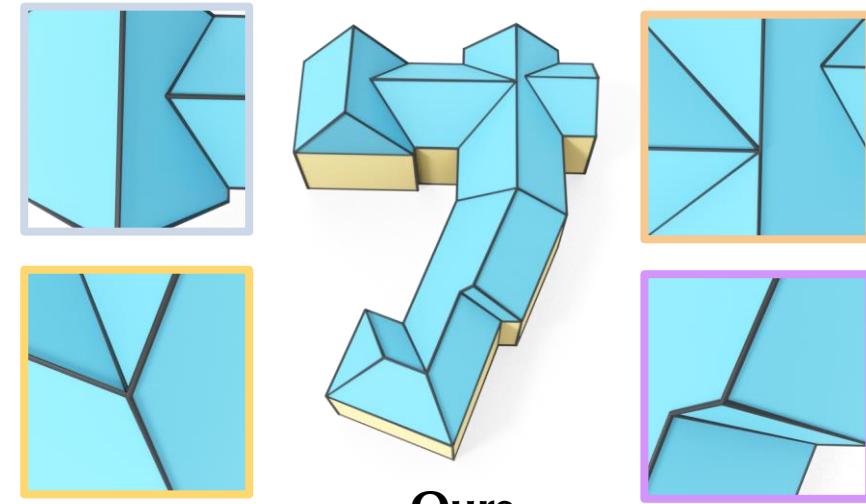
Input image



Straight Skeleton



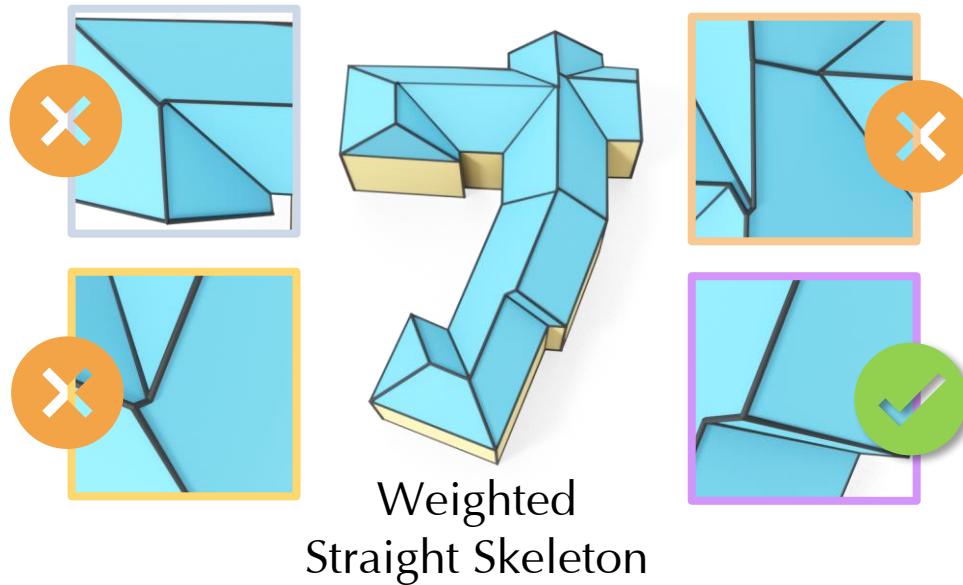
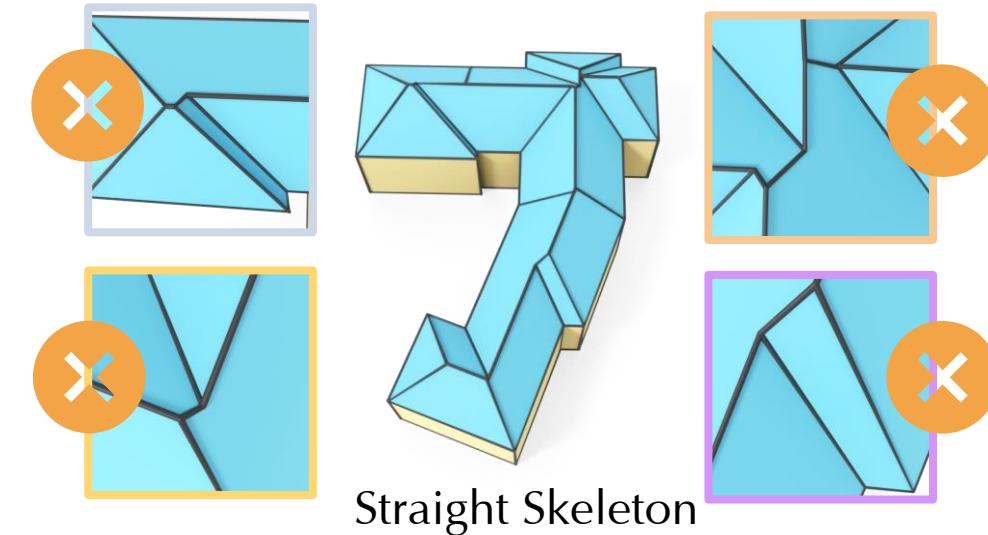
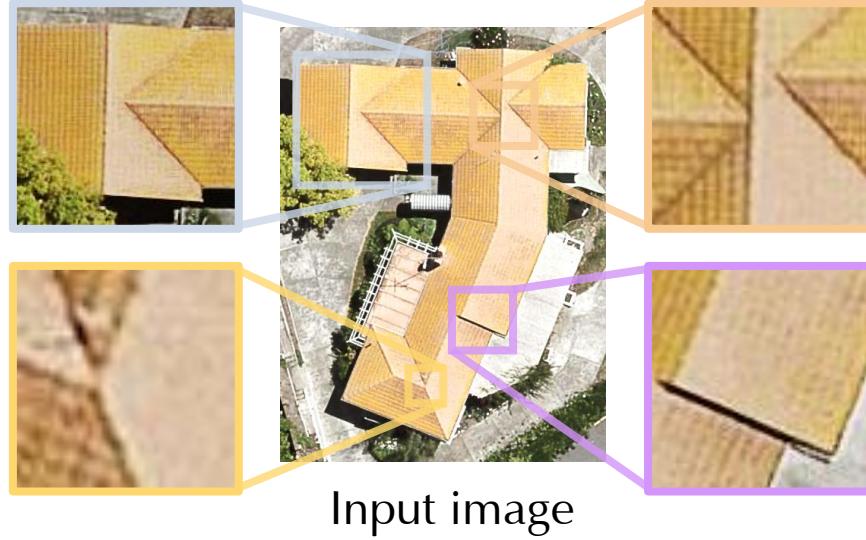
Weighted
Straight Skeleton



Ours

Applications

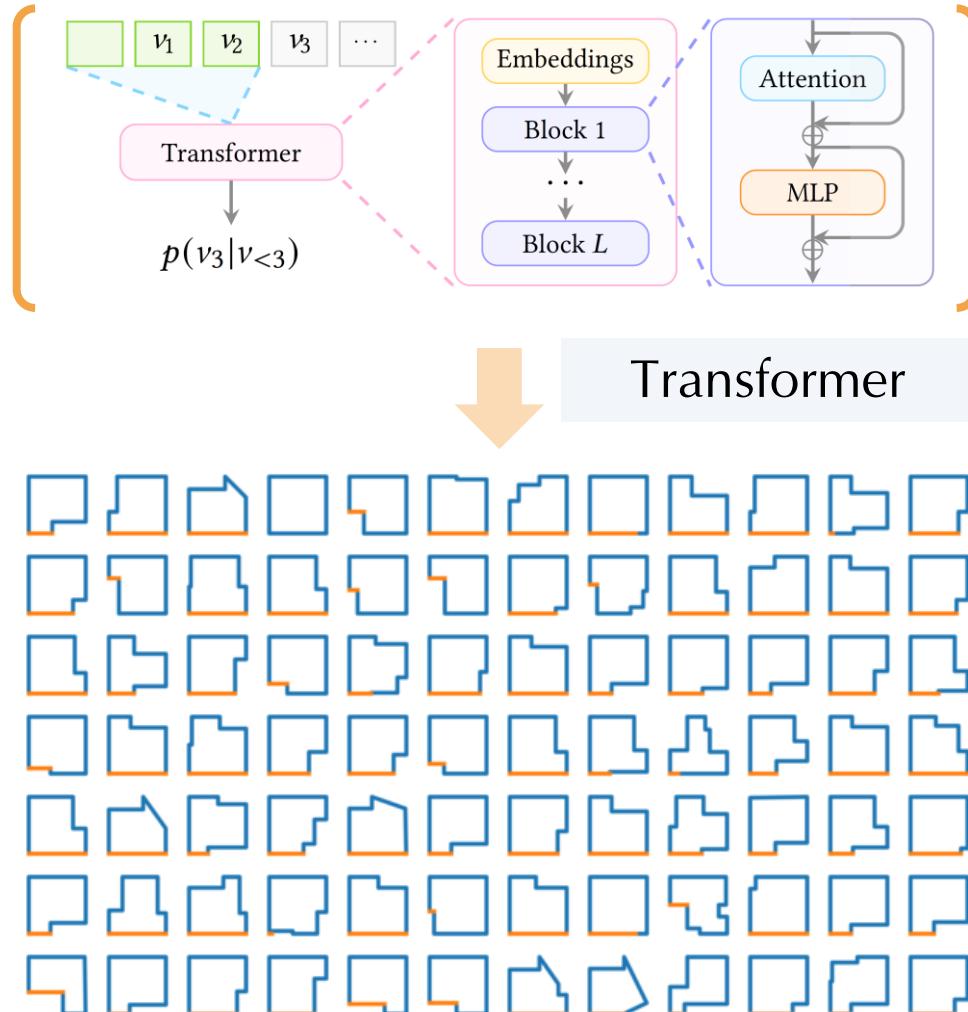
Interactive Editing



Applications

Roof Synthesis from Scratch

Roof Outline Generation



Input nothing

Output a 2D outline as a sequence of vertices $\{v_1, v_2, \dots, v_n\}$

Tokenization (flattened) vertex position values belong to $\{1, 2, \dots, 2^b\}$

Architectures

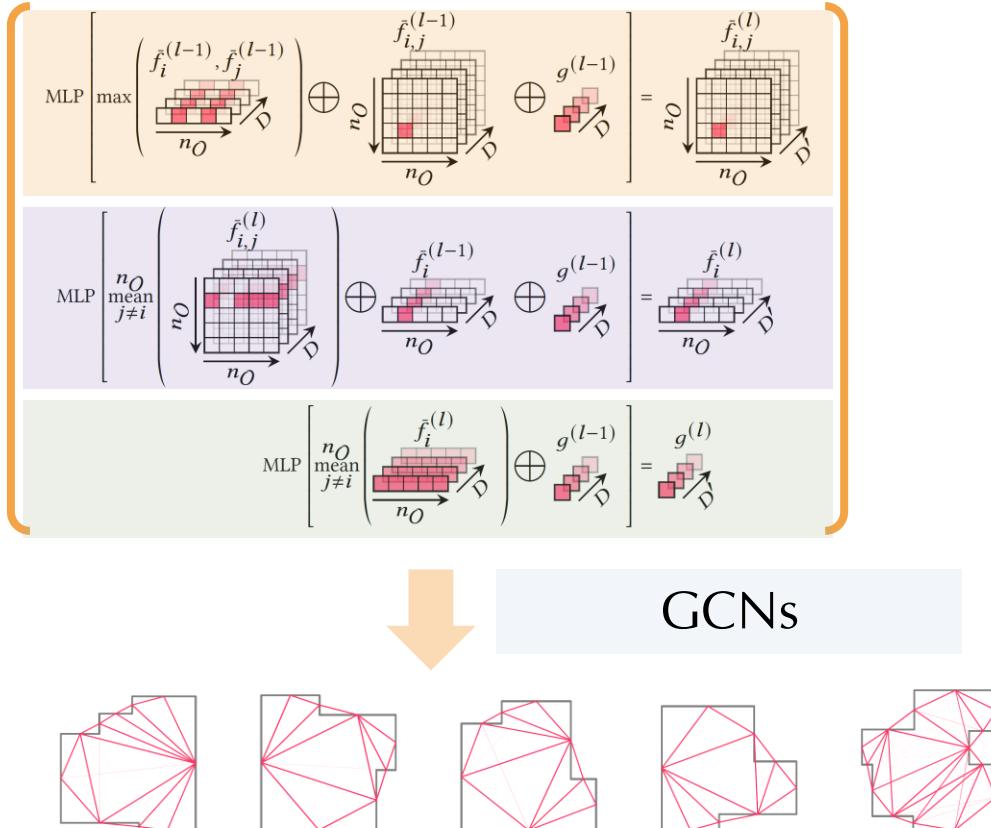
- 6 blocks: self-attention + MLP
- Embedding dimension = 384
- Self-attention: 12 heads
- MLPs: hidden dimension = 1536

token:	v_1	v_2	v_3	v_4	\dots	v_{2n_O-1}	v_{2n_O}	s
position:	1	1	2	2	\dots	n_O	n_O	$n_O + 1$
coord:	1	2	1	2	\dots	1	2	1

Applications

Roof Synthesis from Scratch

Face Adjacency Prediction



Input outline $\{v_1, v_2, \dots, v_n\}$

Output probability p_{ij} of the face f_i being adjacent to the face f_j

Architectures we stack following basic building blocks 4 times

- Adjacency block
- Edge block
- Global block

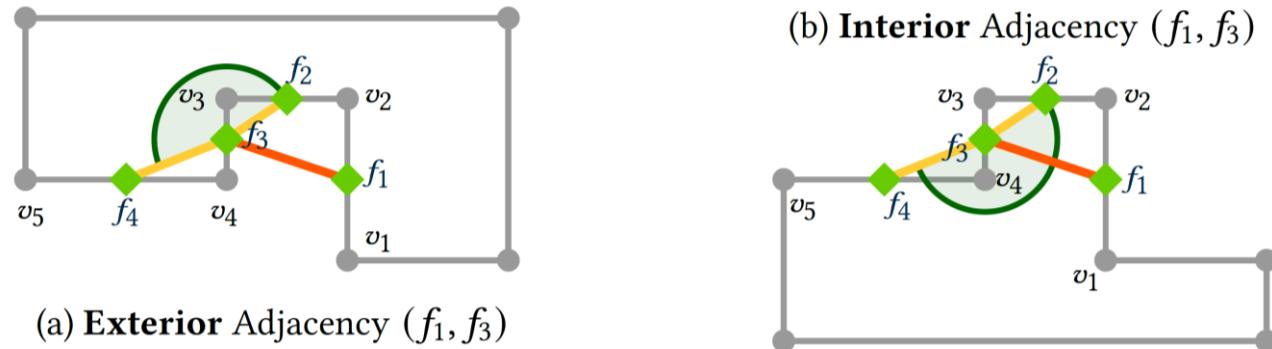
Each block updates representation vectors (adjacency, edge, global).

Loss objective binary cross entropy

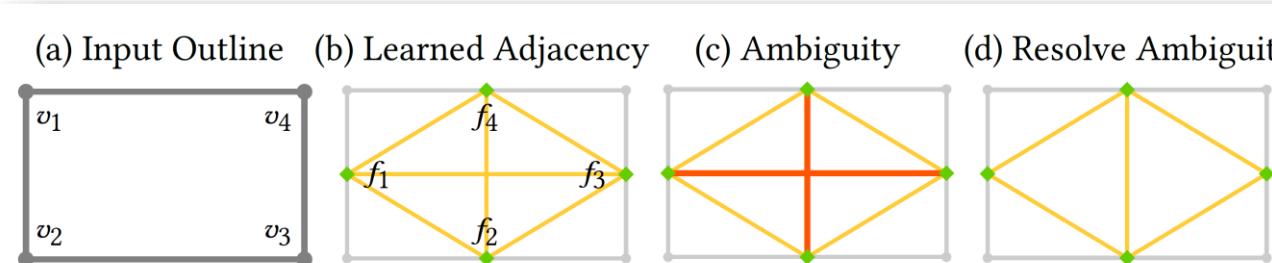
Applications

Roof Synthesis (Resolve Ambiguities in Predicted Adjacencies)

Case 01 interior vs. exterior region



Case 02 conflicting adjacencies



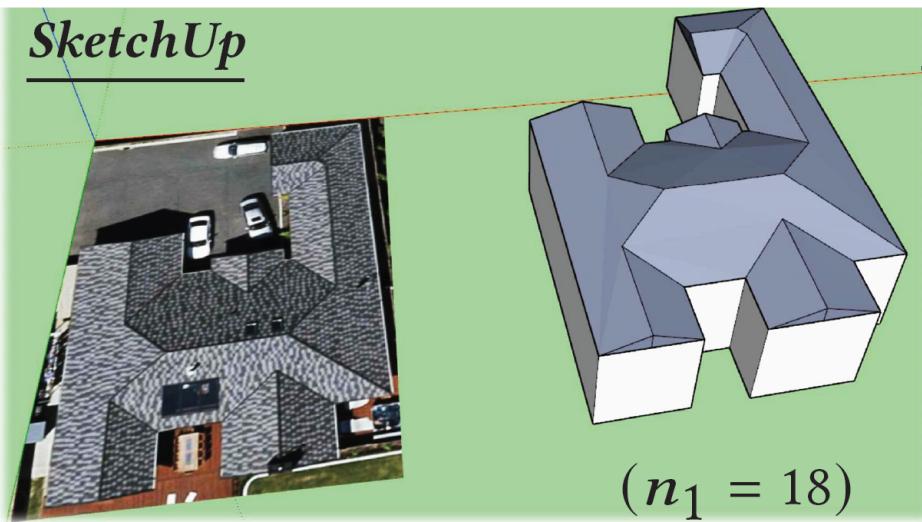
Algorithm extract valid dual graph

1. Resolve ambiguity 01: check if each edge in the dual graph (adjacency) lies in the **interior** of the roof
2. Resolve ambiguity 02: detect **edge intersections** in the dual graph, then remove the confliction by
 - ❖ Greedy (most likely one)
 - ❖ Sampling (all possible ones)

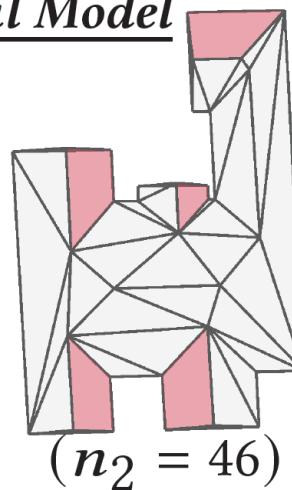
Results

Evaluate SketchUp

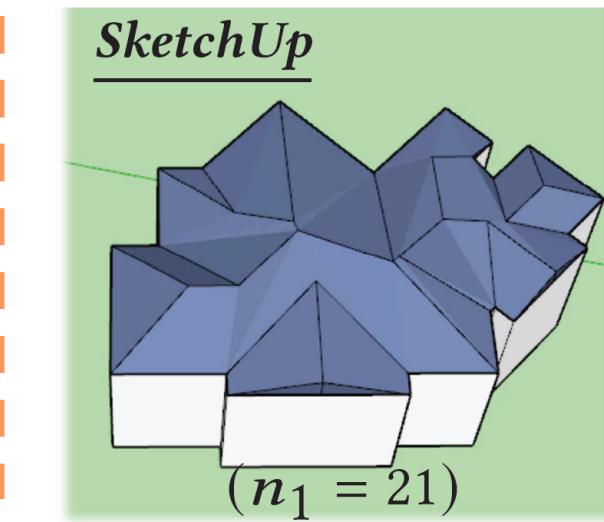
ERR = 28



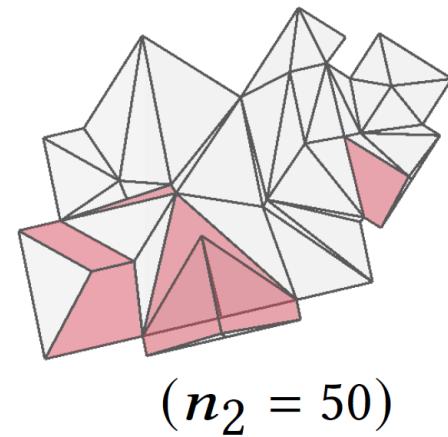
Real Model



ERR = 29



Real Model



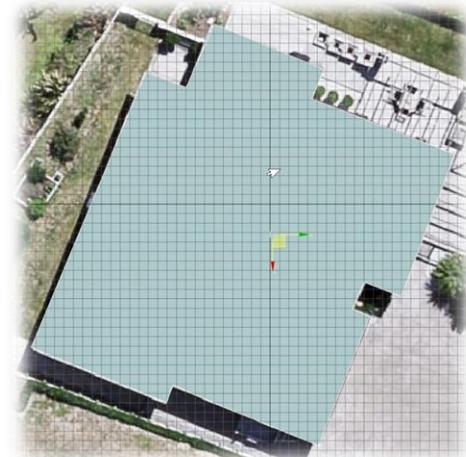
- ❖ The artist hid some edges to make the constructed roof visually consistent with the input image.
 n_1 reports the number of faces that are visible
- ❖ n_2 reports the actual number of faces that were created
- ❖ $\text{ERR} = n_2 - n_1$
- ❖ Red: polygonal faces in the created roof mesh

Existing Methods

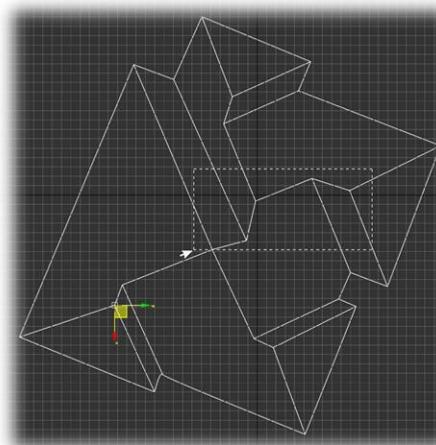
Commercial Software: 3ds Max



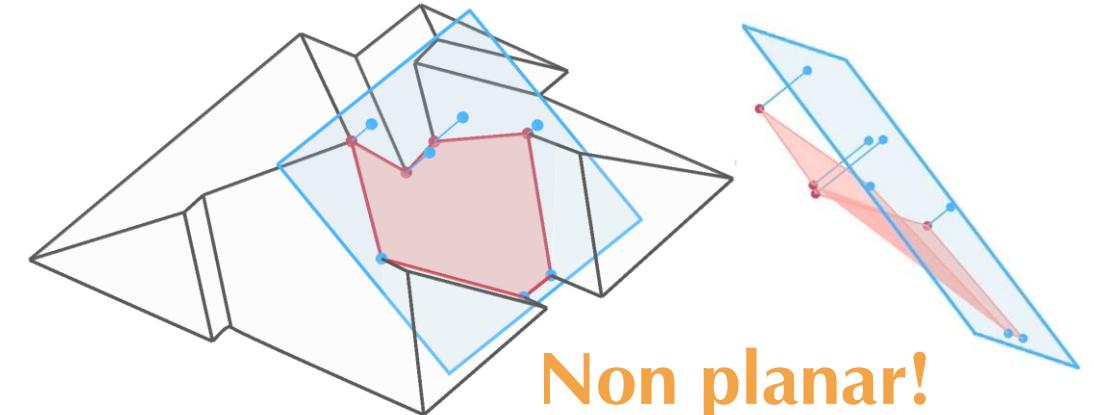
Input



- Add vertex
- Add face



- Cut faces
- Move vertex



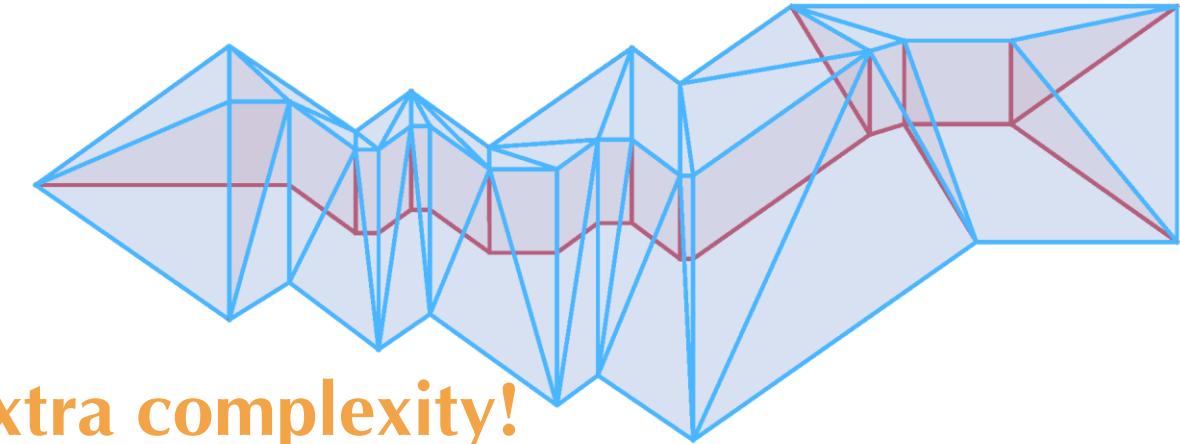
Non planar!



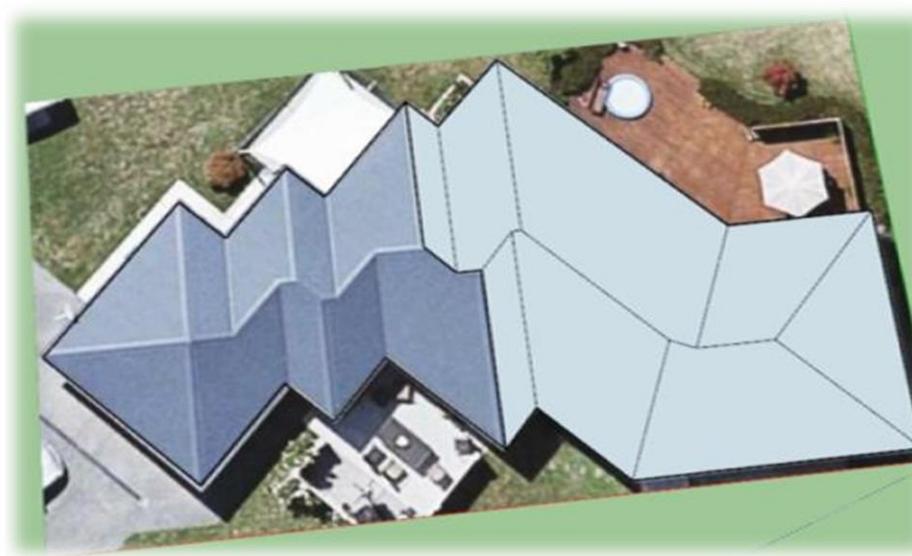
- Move vertex

Existing Methods

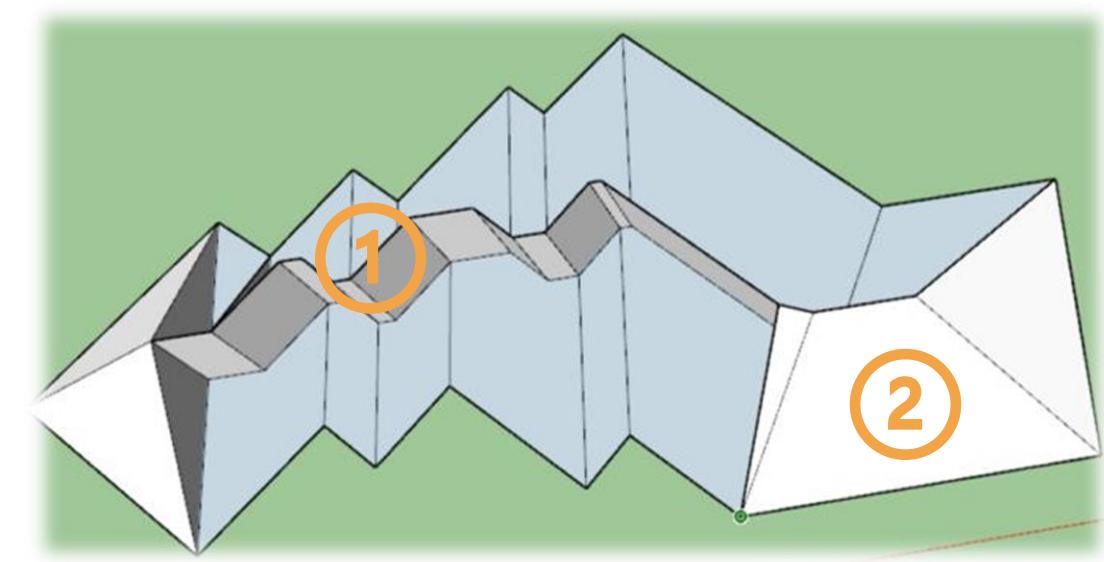
Commercial Software: SketchUp



Input



Specify roof topology



1. Build roof beams
2. Add planar roof tops