

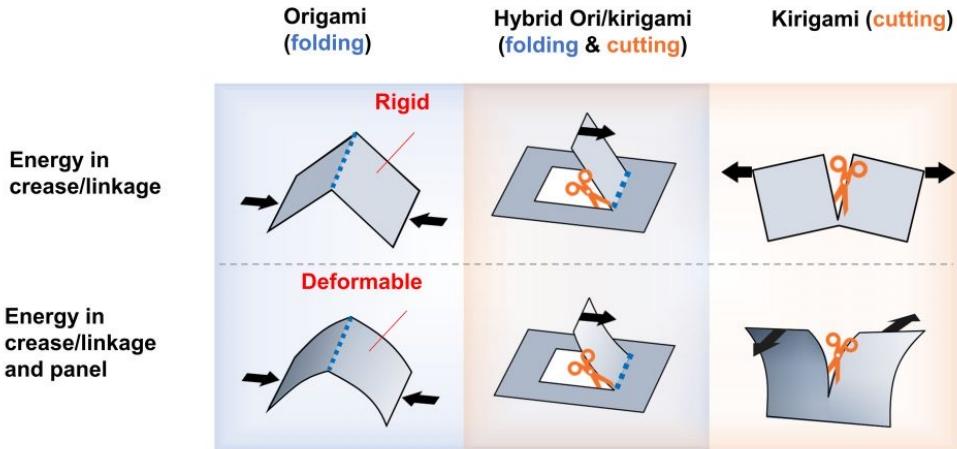


الحمد لله رب العالمين

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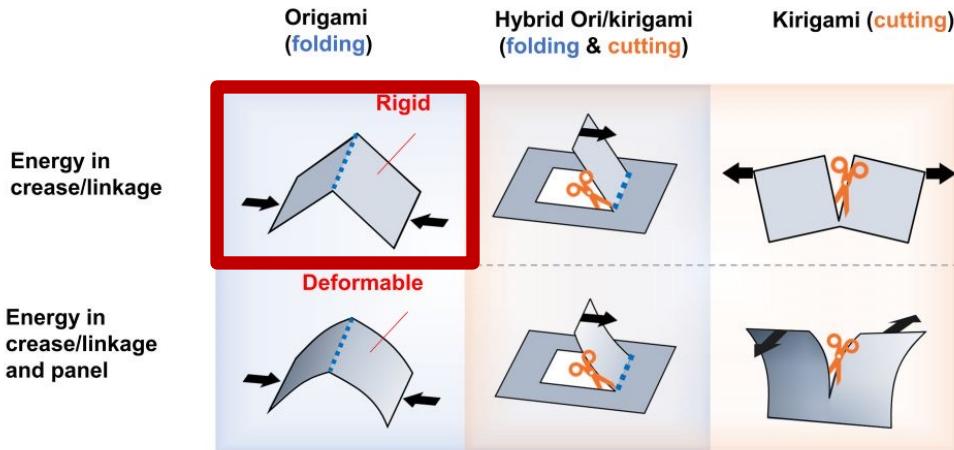
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# Kirigami



“Mechanical metamaterials based on origami and kirigami”, Zhai et al., 2021

# Kirigami

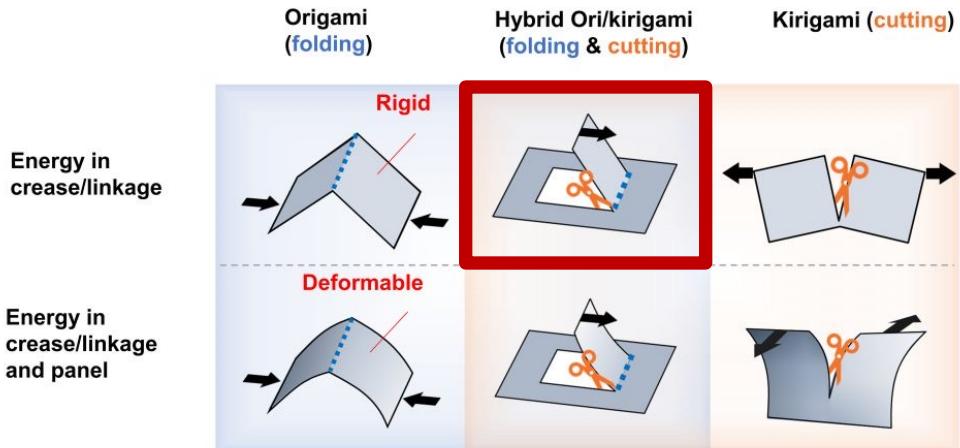


“Mechanical metamaterials based on origami and kirigami”, Zhai et al., 2021

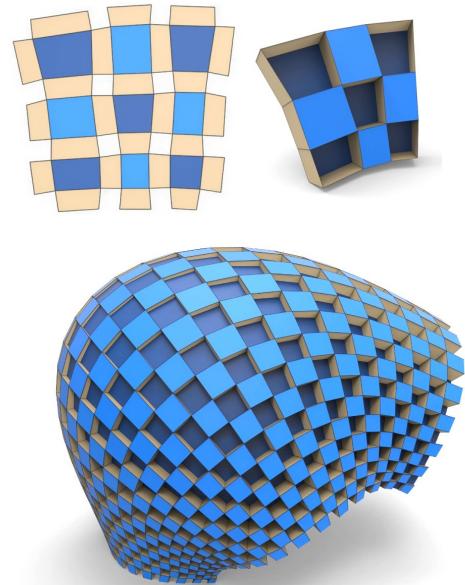


“Inkjet 4D print: self-folding tessellated origami objects by inkjet uv printing”,  
Narumi et al. SIGGRAPH 2023

# Kirigami

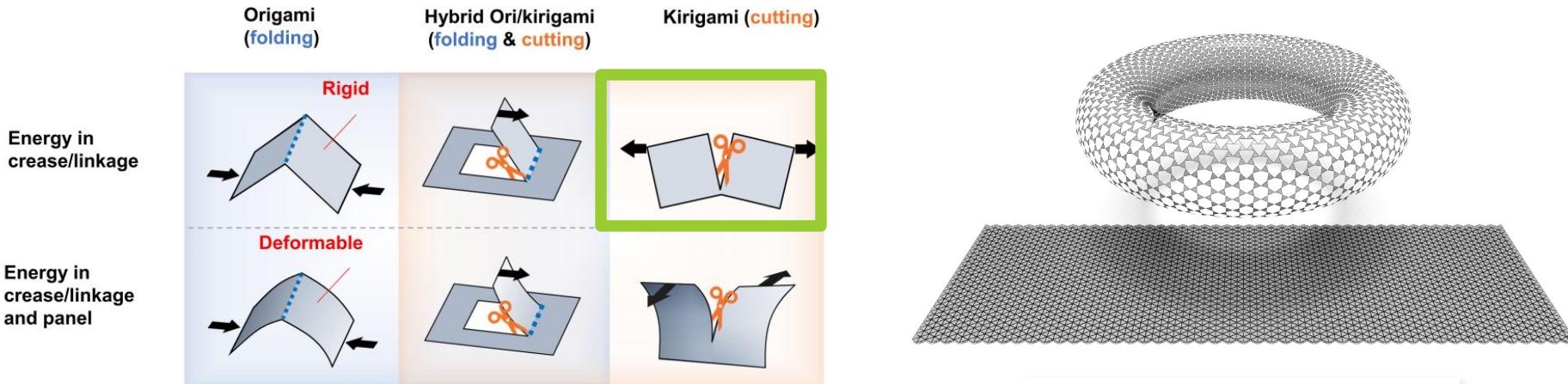


“Mechanical metamaterials based on origami and kirigami”, Zhai et al., 2021



“Freeform quad-based kirigami”,  
Jiang et al. SIGGRAPH 2020

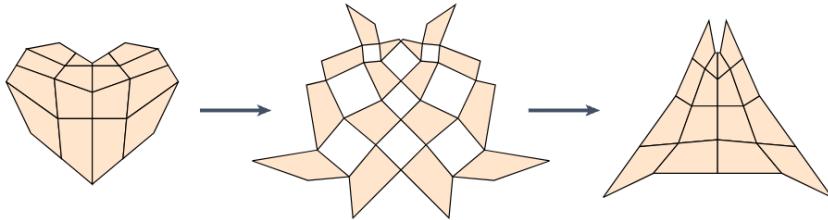
# Kirigami



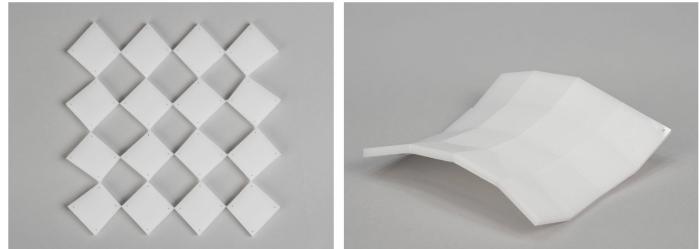
“Mechanical metamaterials based on origami and kirigami”, Zhai et al., 2021

“Beyond developable: computational design and fabrication with auxetic materials”, Konaković-Luković et al. SIGGRAPH 2016

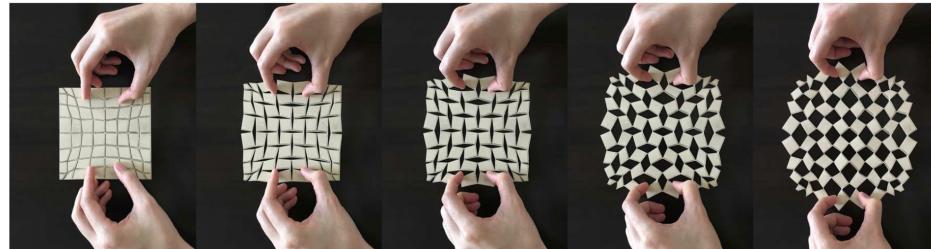
# Hinged kirigami



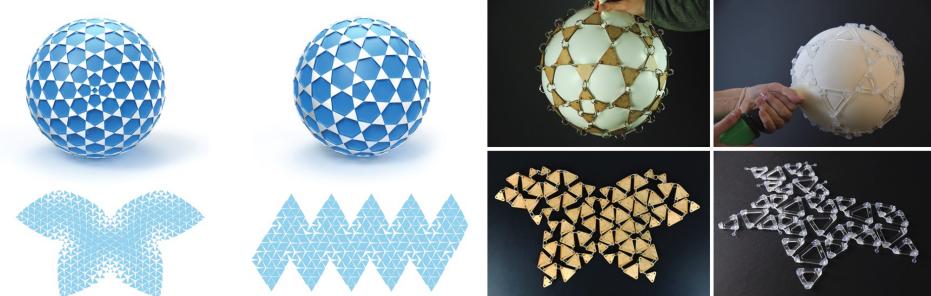
"An additive framework for kirigami design", Dudte et al., 2023



"Shape-morphing mechanical metamaterials", Jiang et al., 2022

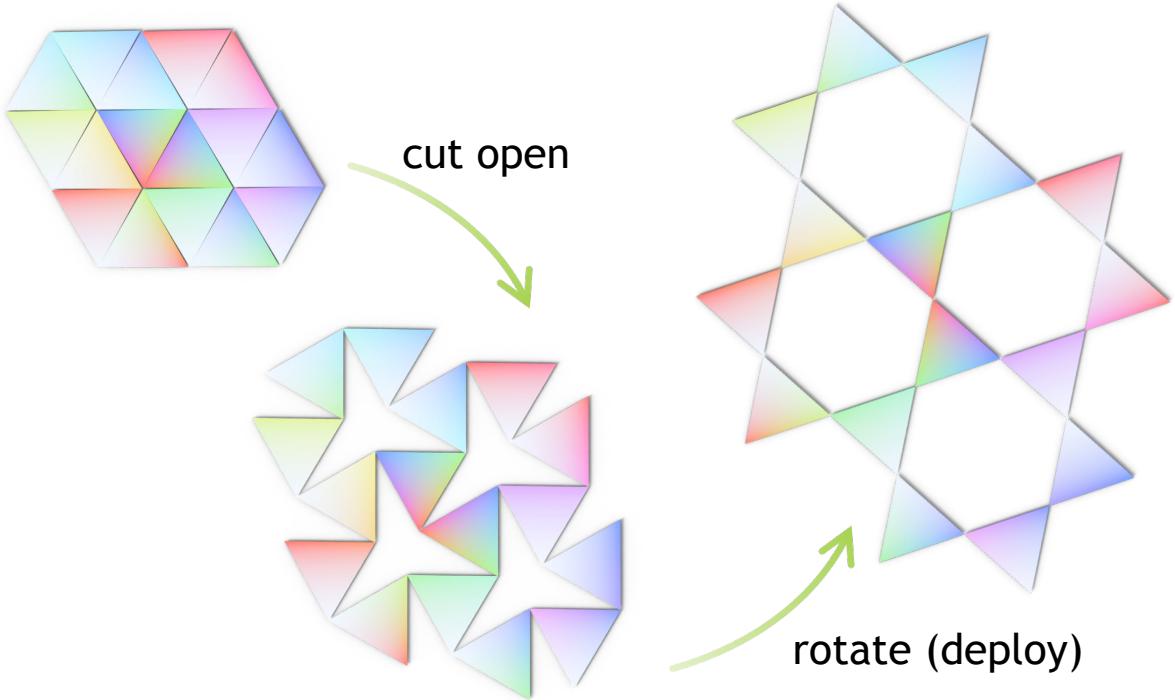
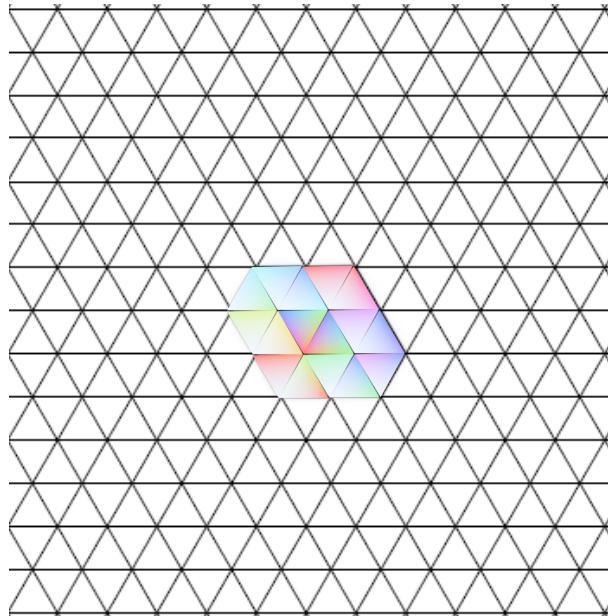


"Programming shape using kirigami tessellations", Choi et al., 2019

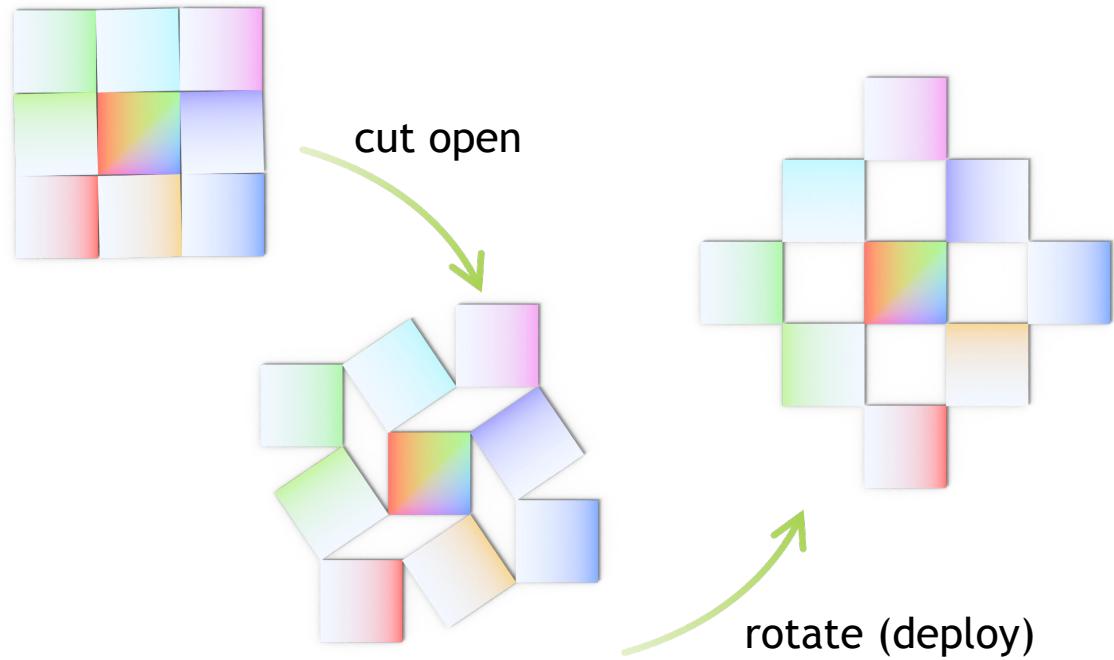
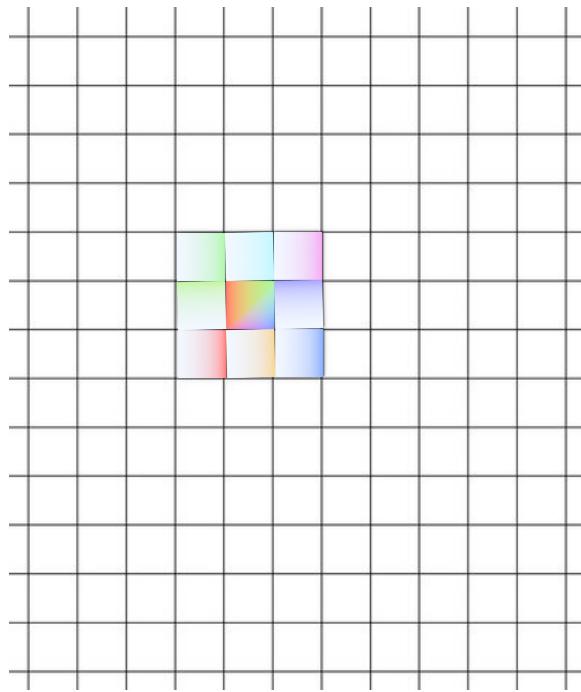


"Rapid deployment of curved surfaces via programmable auxetics", Konaković-Luković et al., 2018

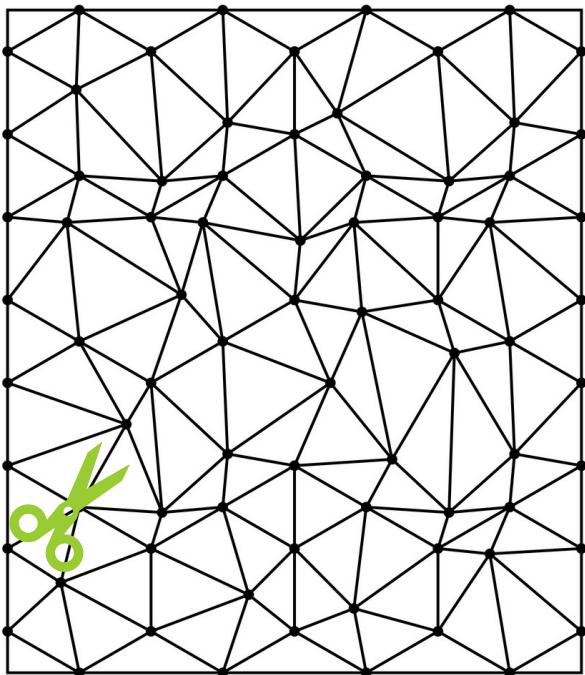
# Patterns from triangular tilings



# Patterns from quad tilings



# Generalized kirigami patterns?

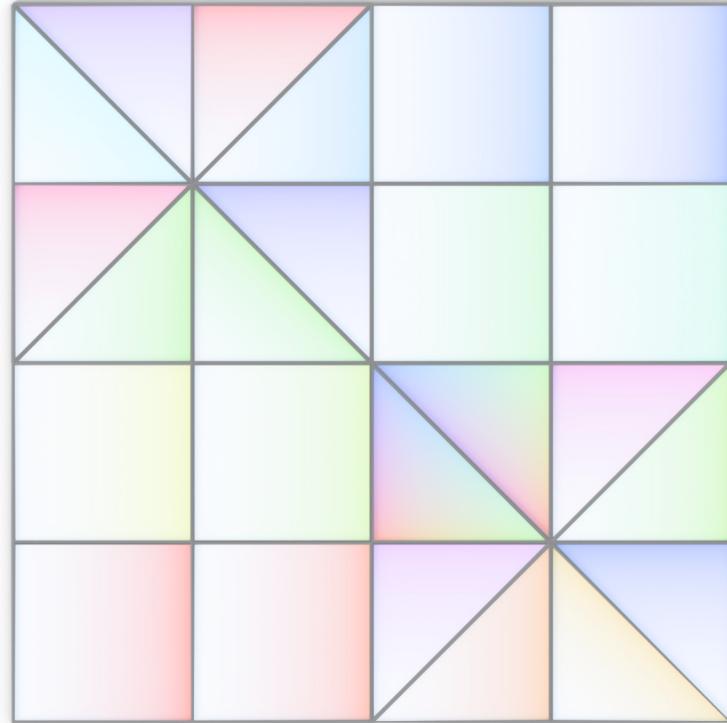


For an arbitrary planar tiling (2D manifold polygonal mesh with disk topology contains no holes)

- ❖ Can we **cut** it into a **valid** hinged kirigami structure?
- ❖ Is it **deployable**?
- ❖ How can we mathematically characterize its **rotational deployment** process?

# Generalized kirigami patterns?

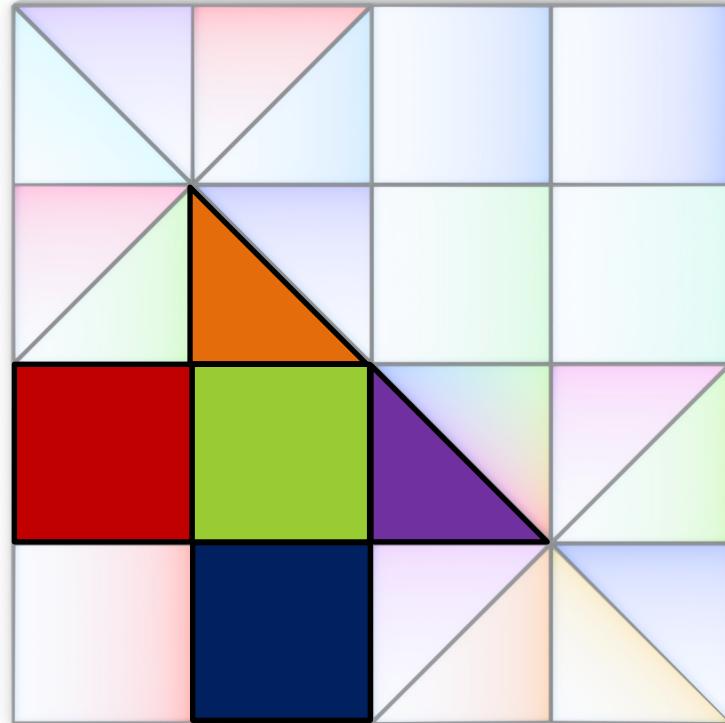
Cutting rules:



# Generalized kirigami patterns?

Cutting rules:

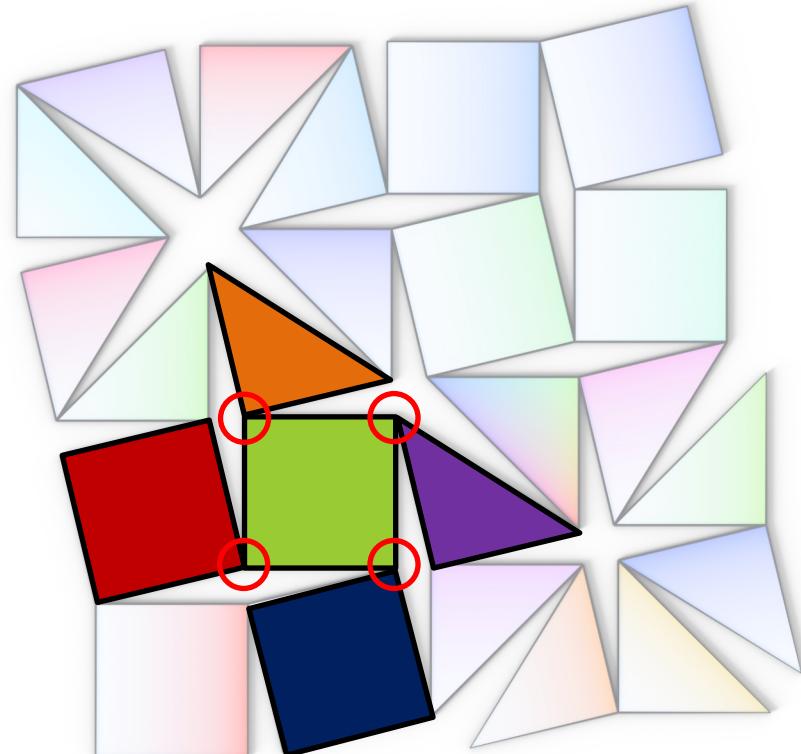
- ❖ Adjacent faces share a hinge



# Generalized kirigami patterns?

Cutting rules:

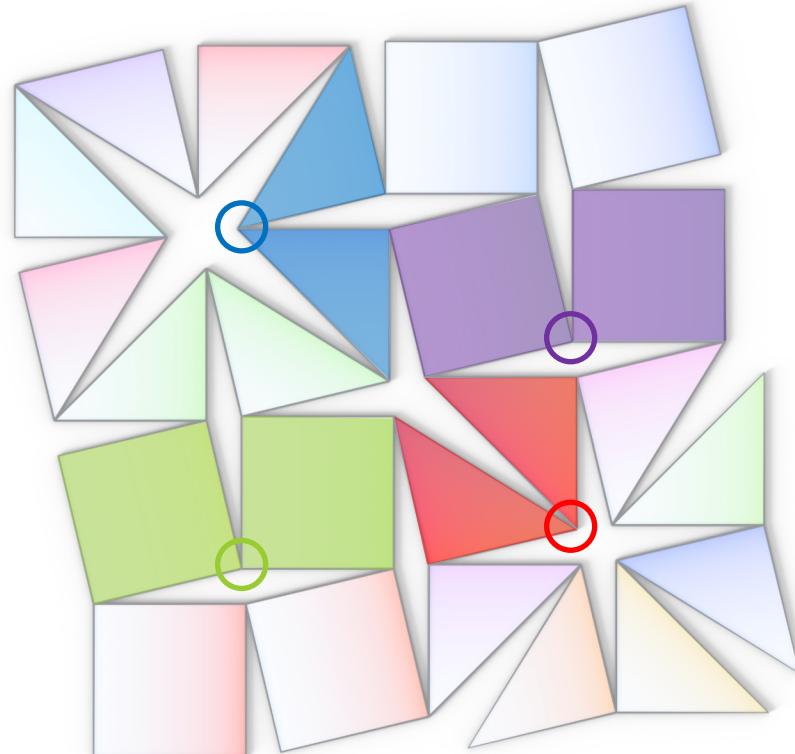
- ❖ Adjacent faces share a hinge



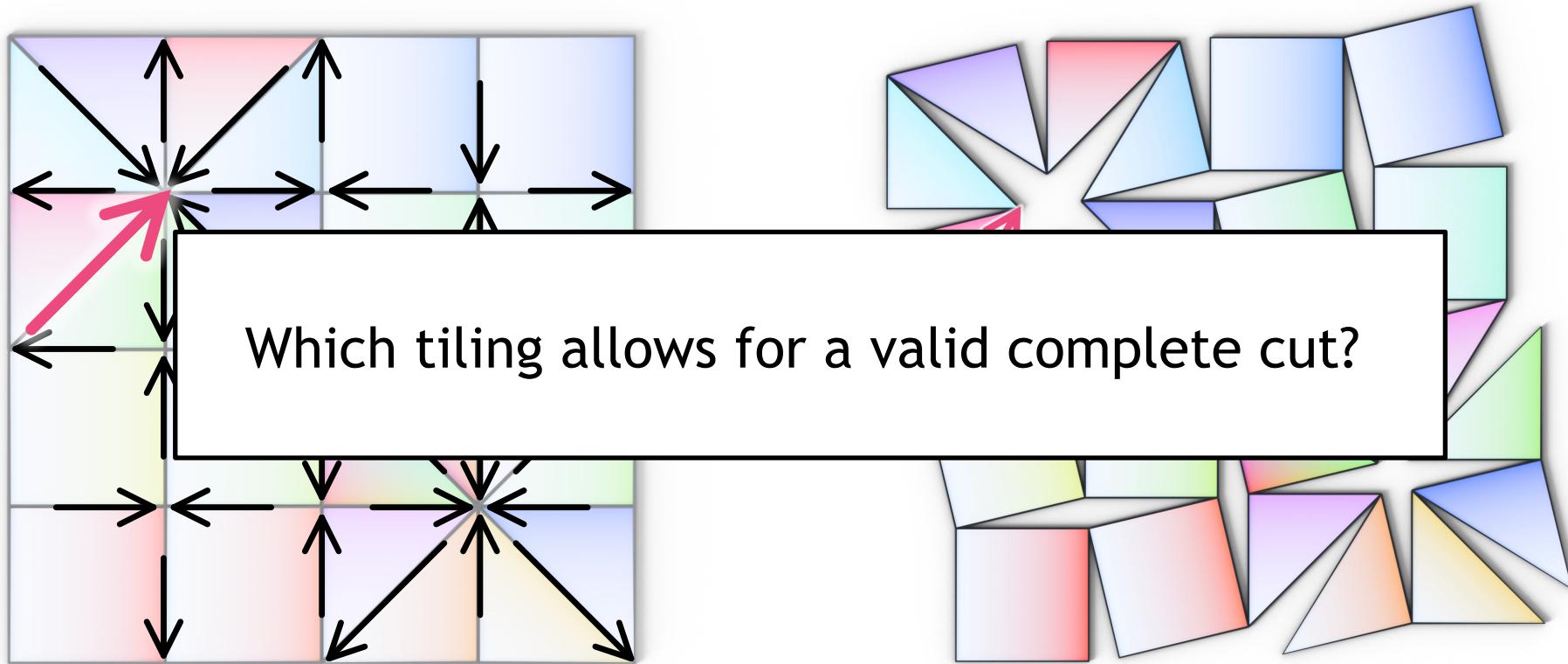
# Generalized kirigami patterns?

Cutting rules:

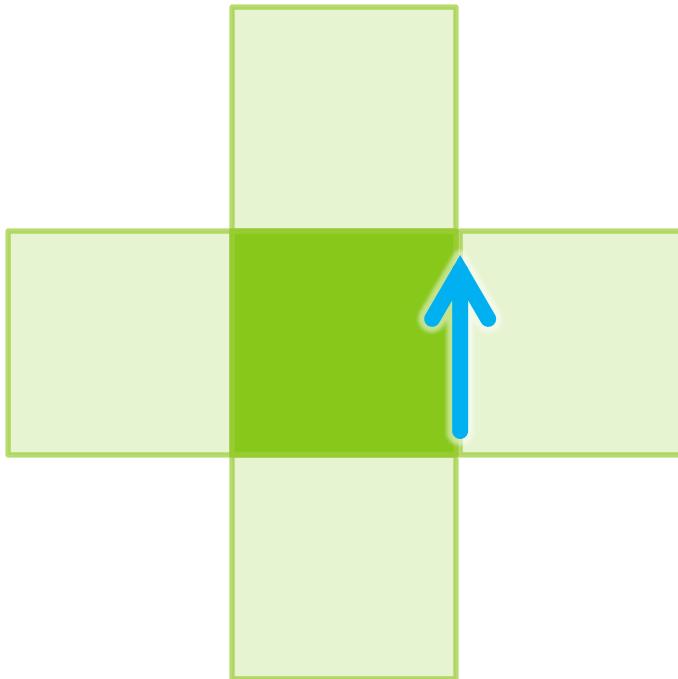
- ❖ Adjacent faces share a hinge
- ❖ Each hinge vertex is shared by exactly two faces



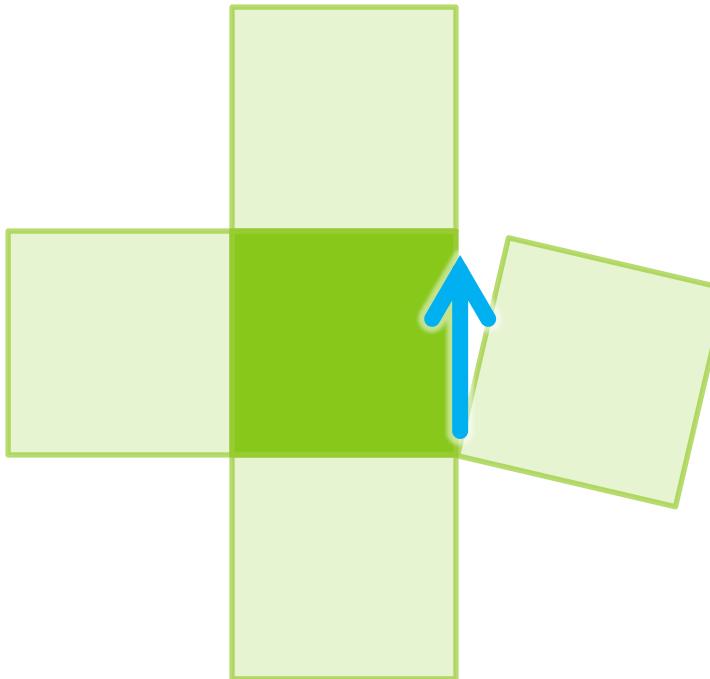
# Definition : complete cut of a tiling



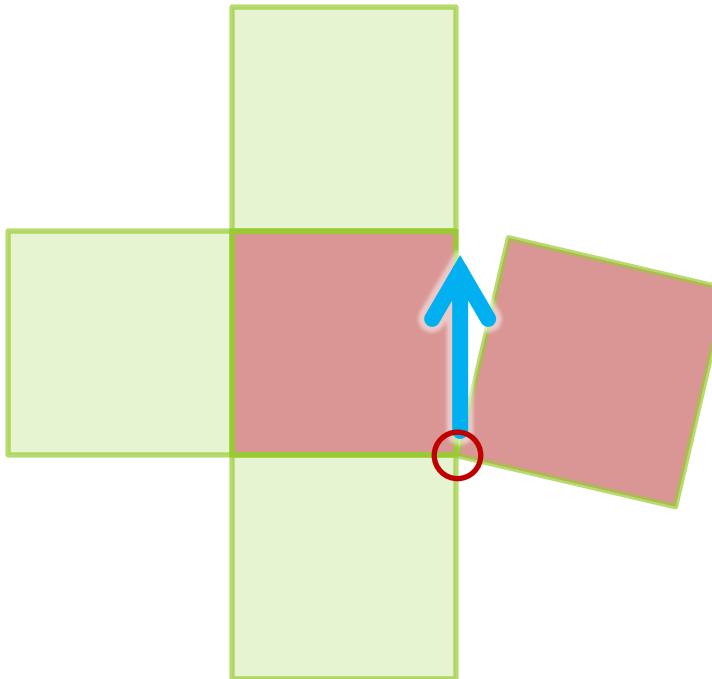
# Combinatorial condition



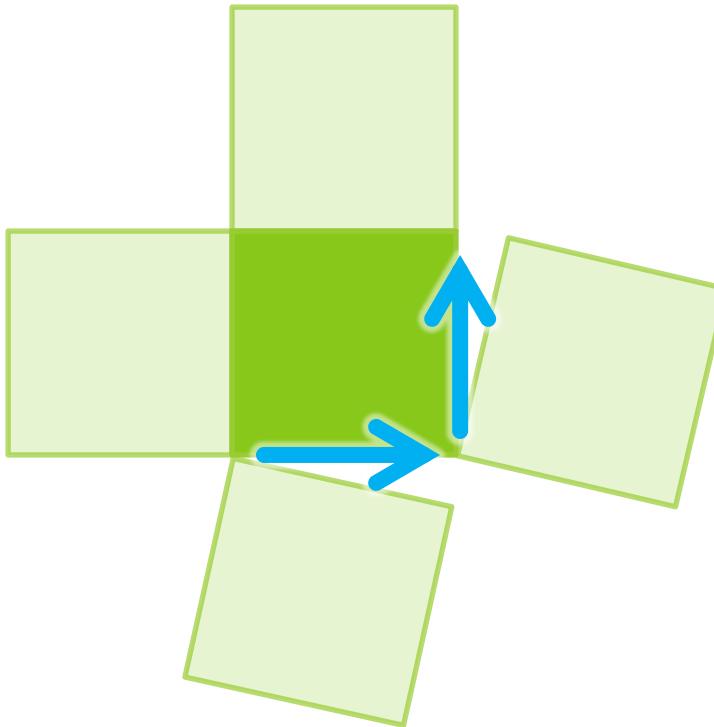
# Combinatorial condition



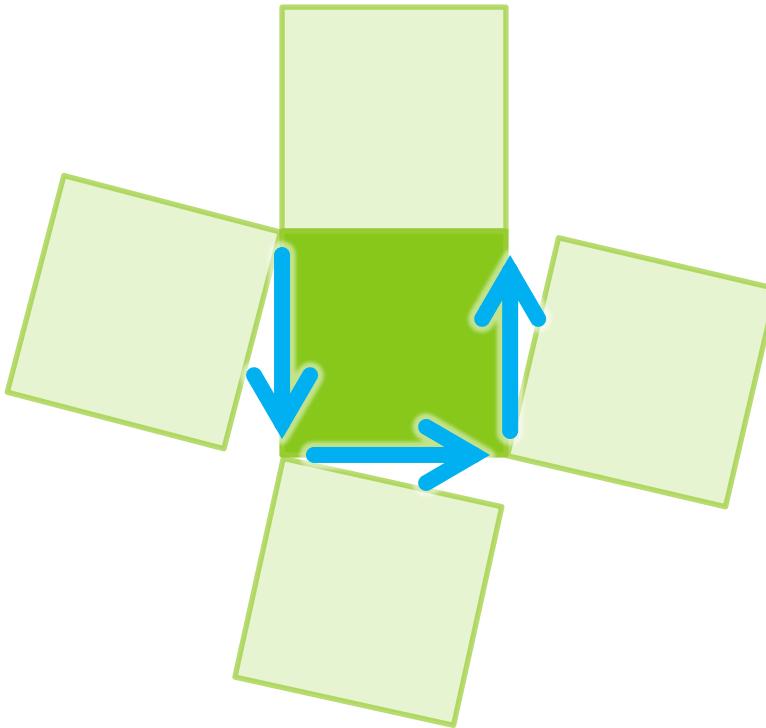
# Combinatorial condition



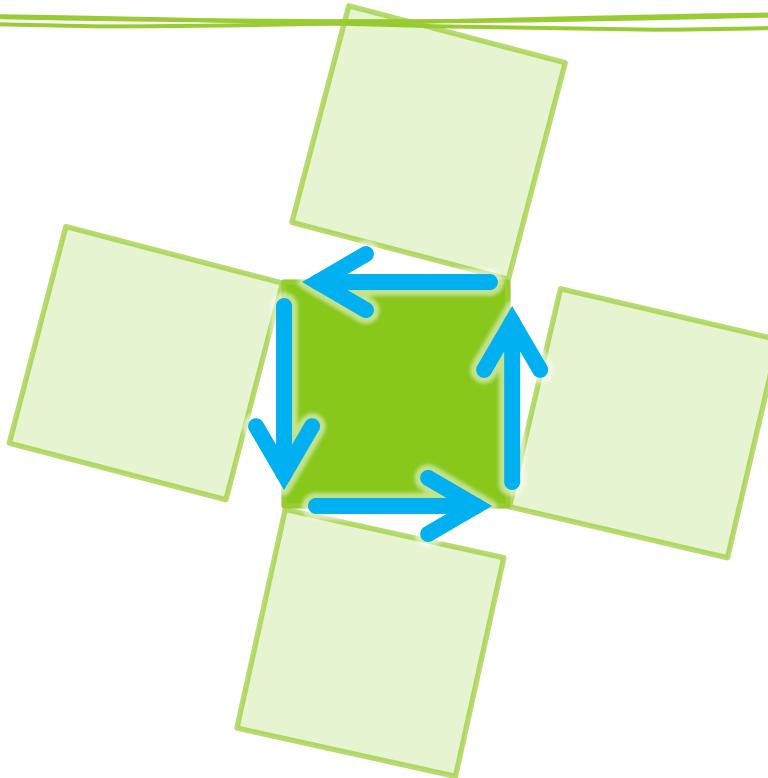
# Combinatorial condition



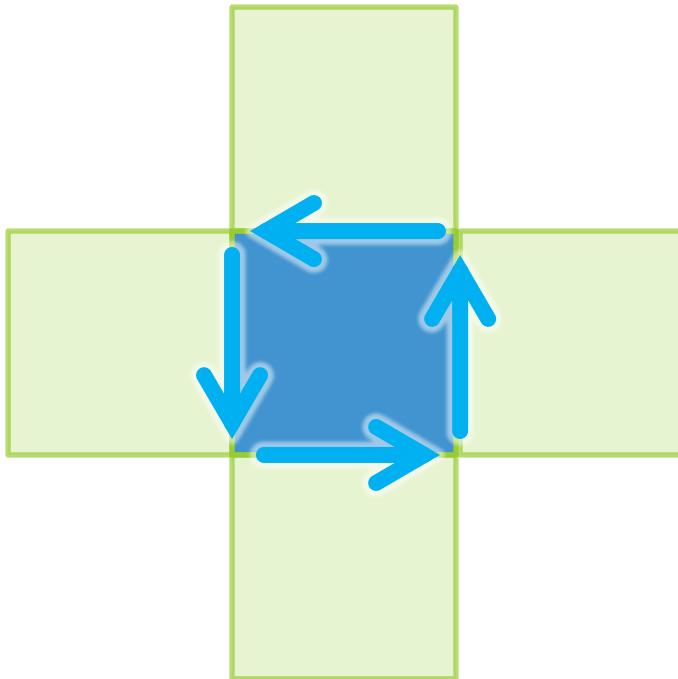
# Combinatorial condition



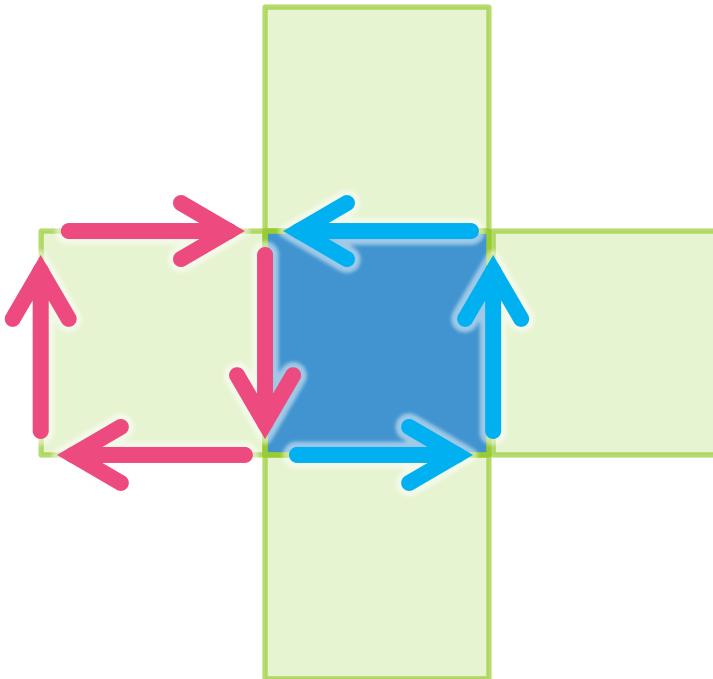
# Combinatorial condition



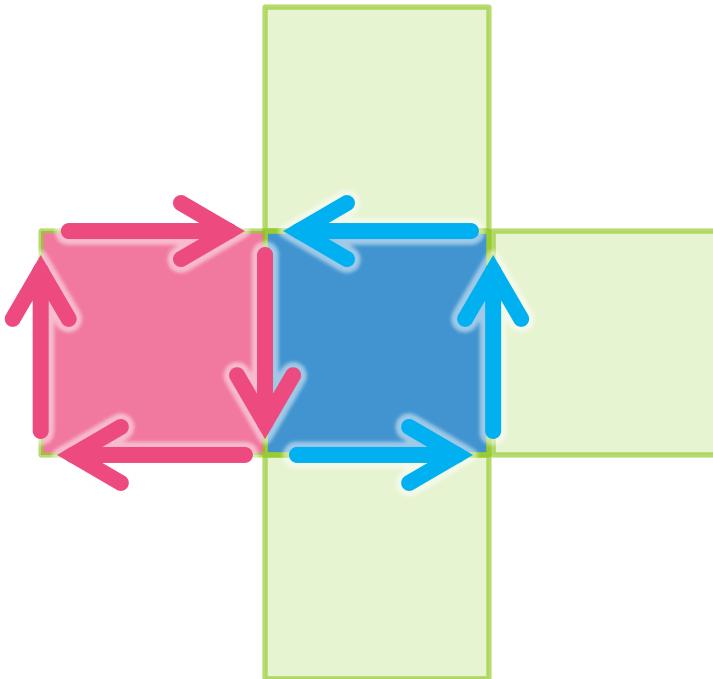
# Combinatorial condition



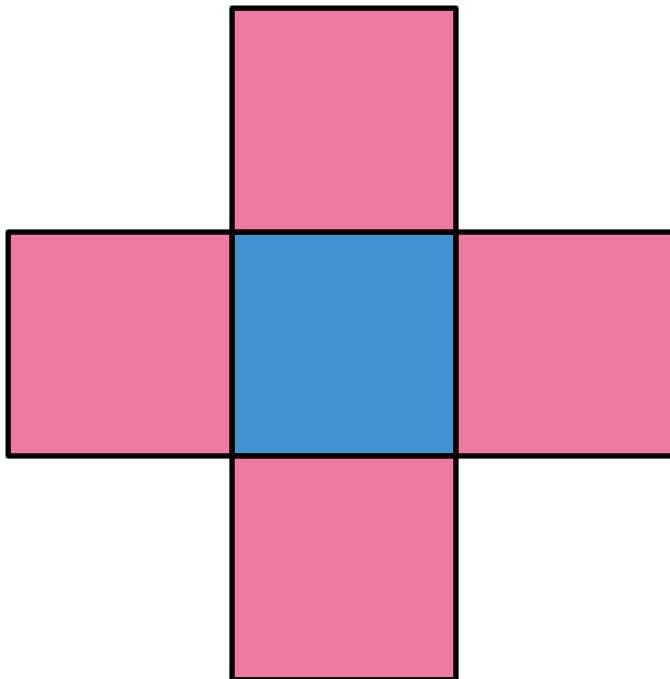
# Combinatorial condition



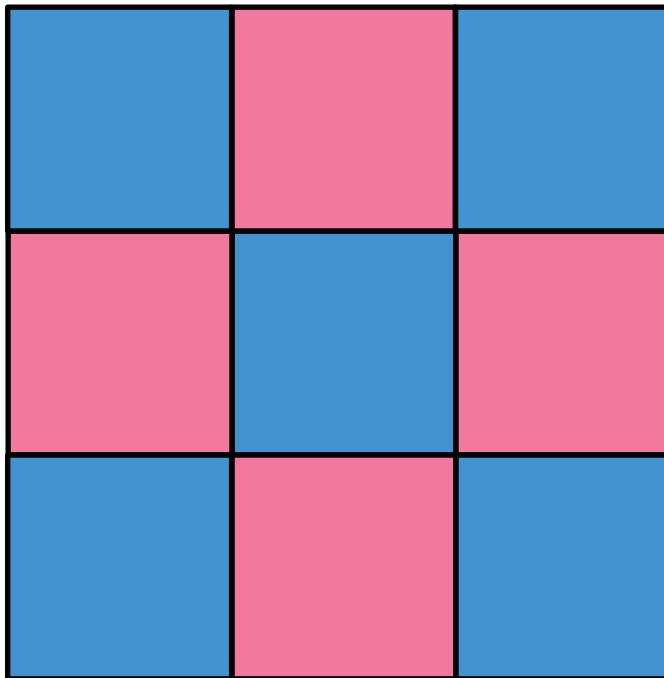
# Combinatorial condition



# Combinatorial condition



# Combinatorial condition

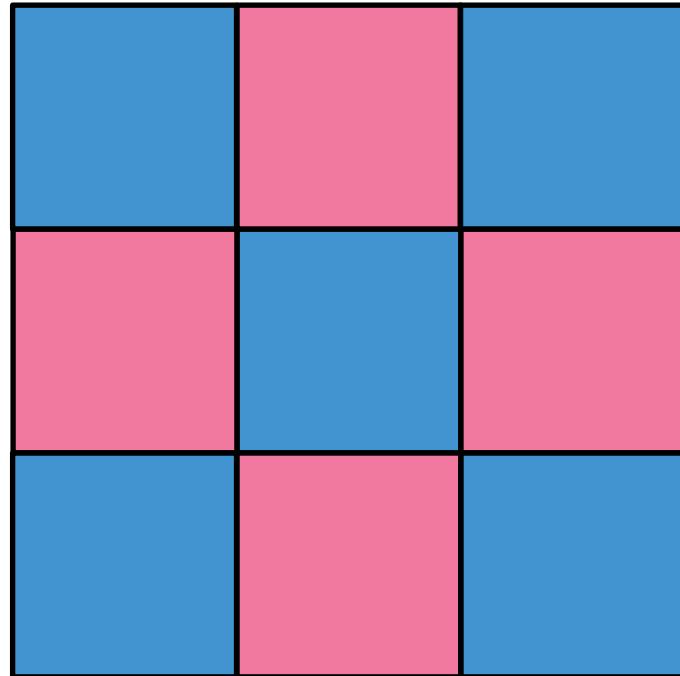


# Combinatorial condition

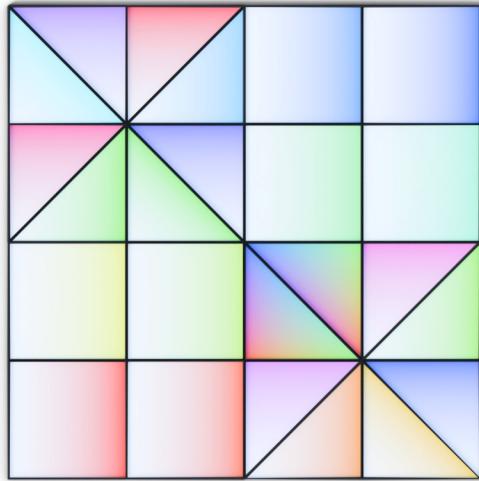
The cutting pattern can be applied if the tiling is  
2-face colorable



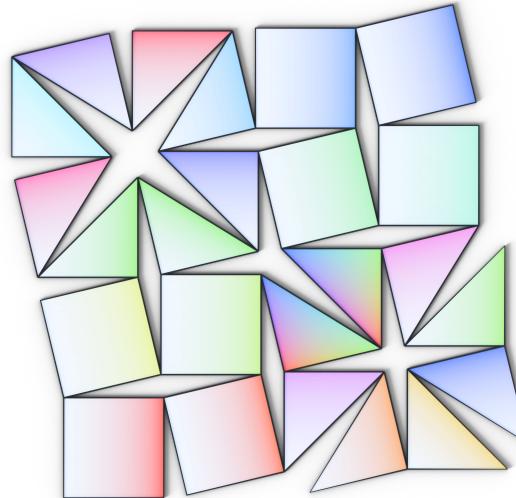
Each interior vertex has even valency



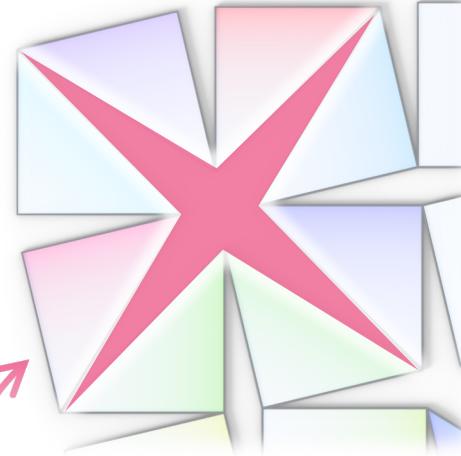
# Geometric condition



apply the valid  
complete cut



Is the resulting hinged kirigami  
pattern **deployable** in 2D?

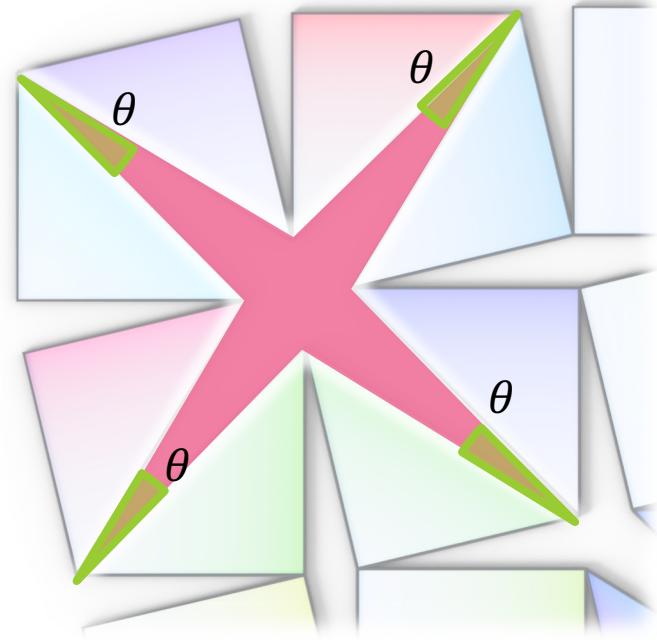


can this hole shape be  
embedded in 2D?

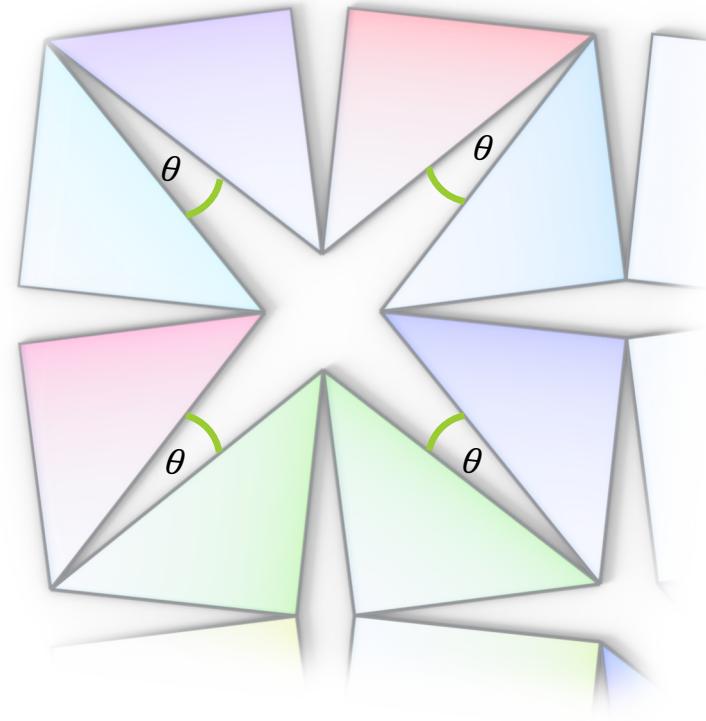
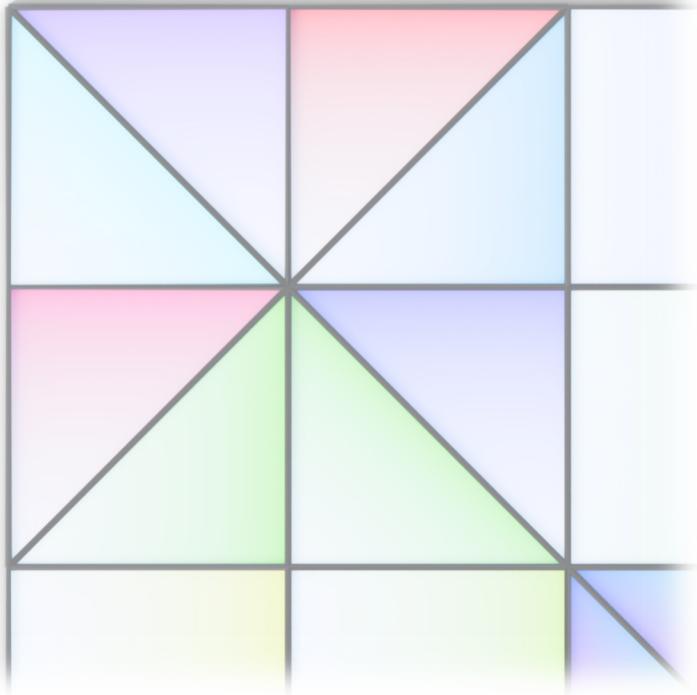
# Geometric condition

Is the resulting hinged  
kirigami pattern  
**uniformly deployable** in 2D?

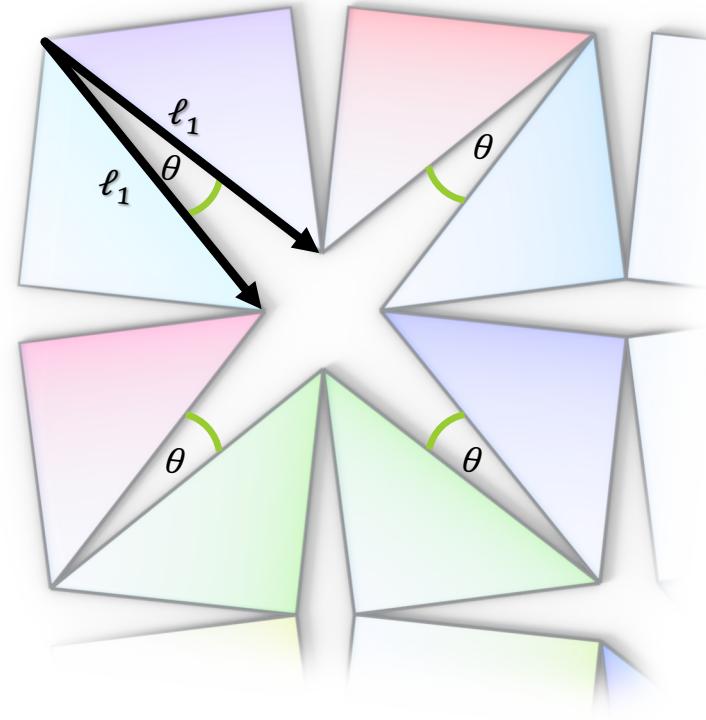
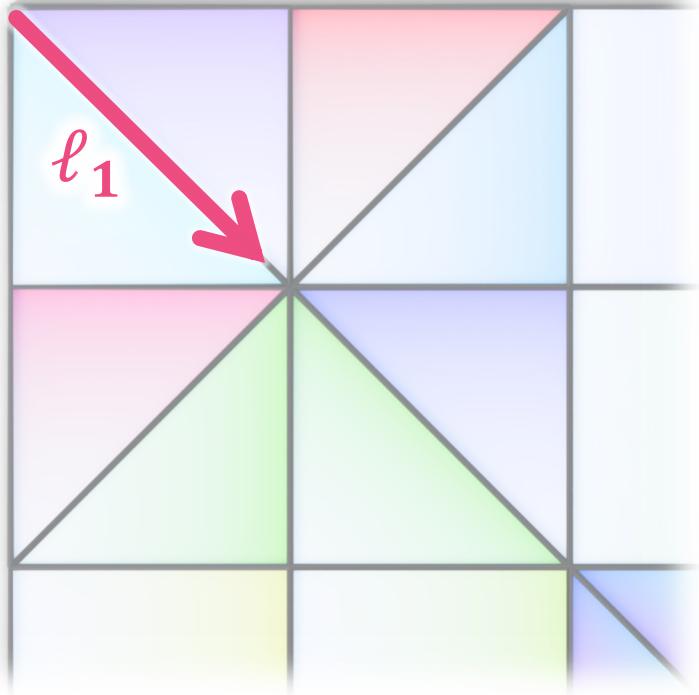
Each hinge rotates at the same speed



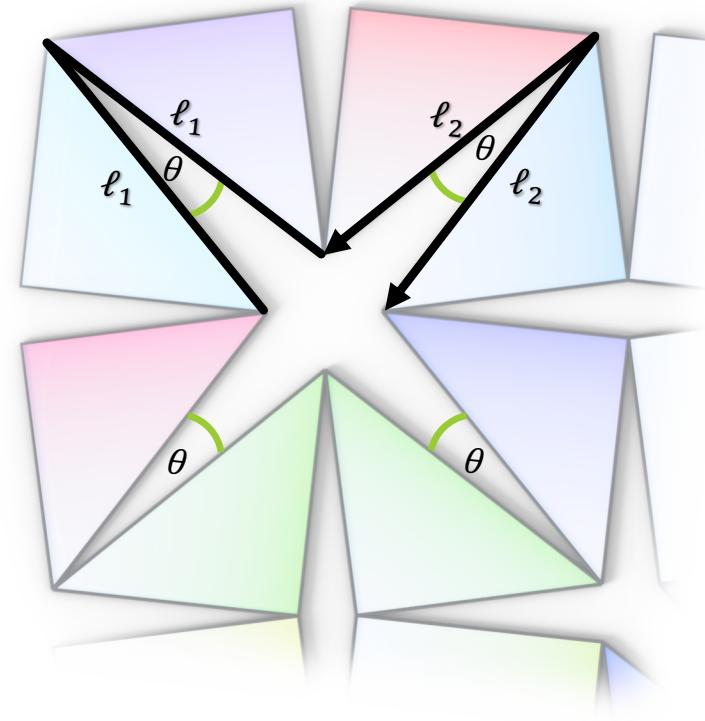
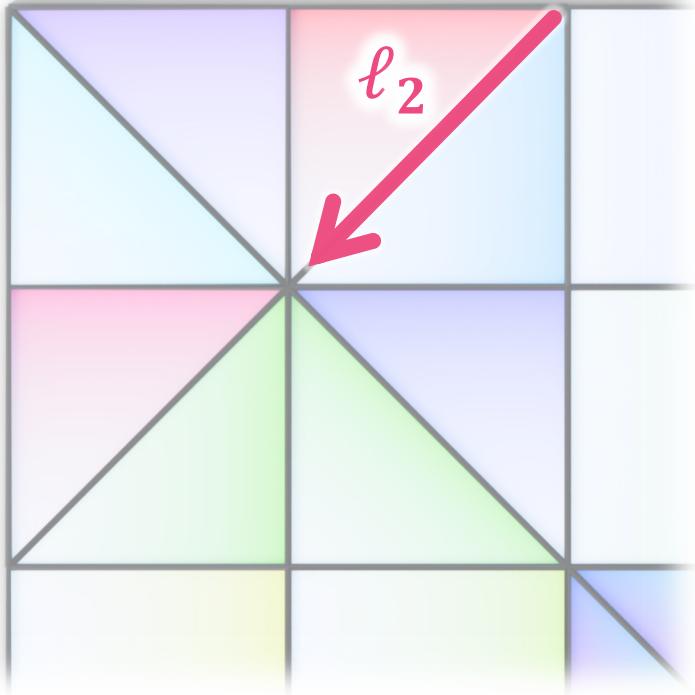
# Geometric condition



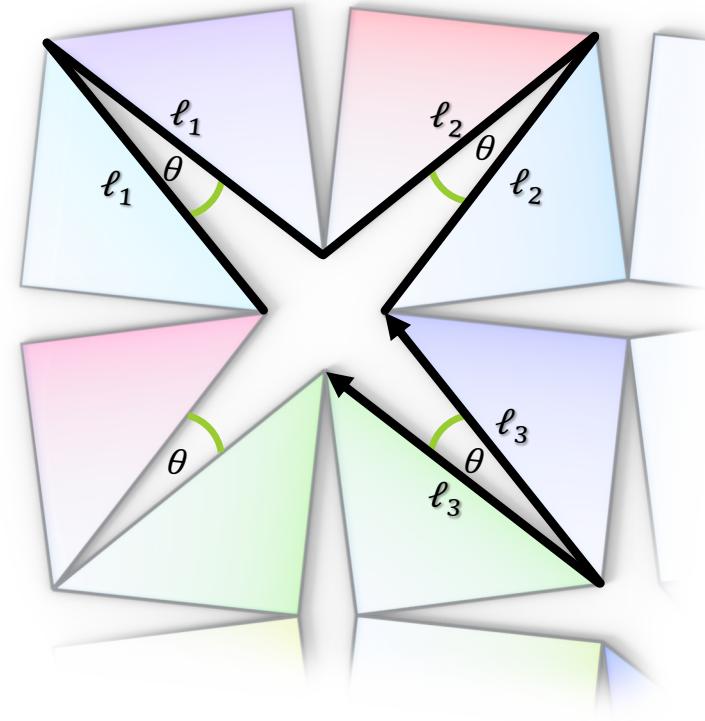
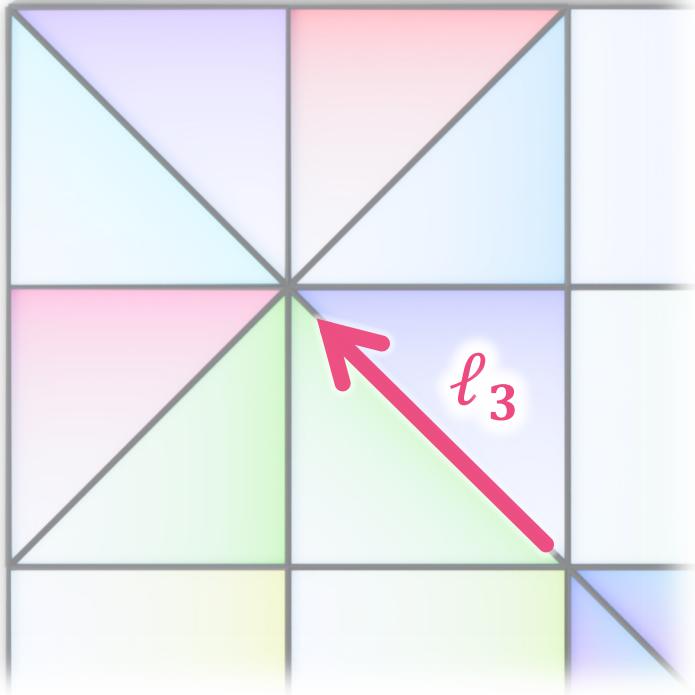
# Geometric condition



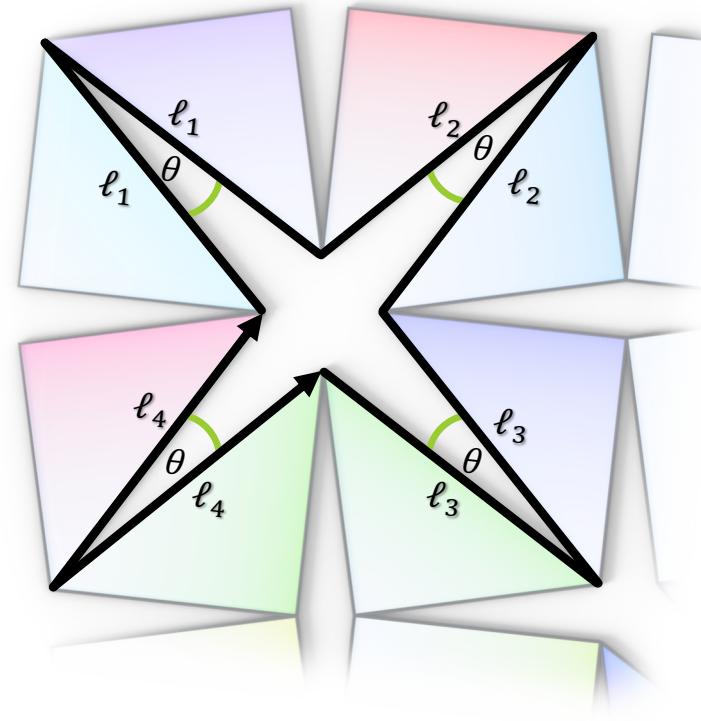
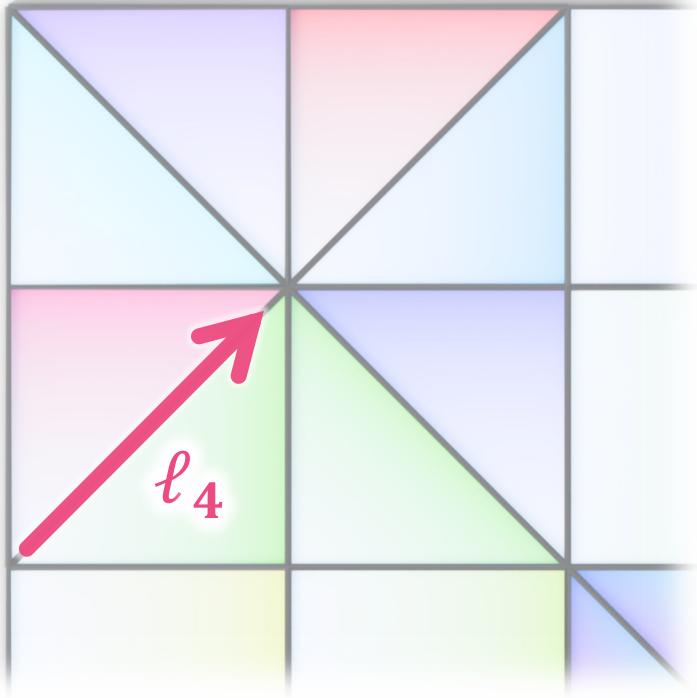
# Geometric condition



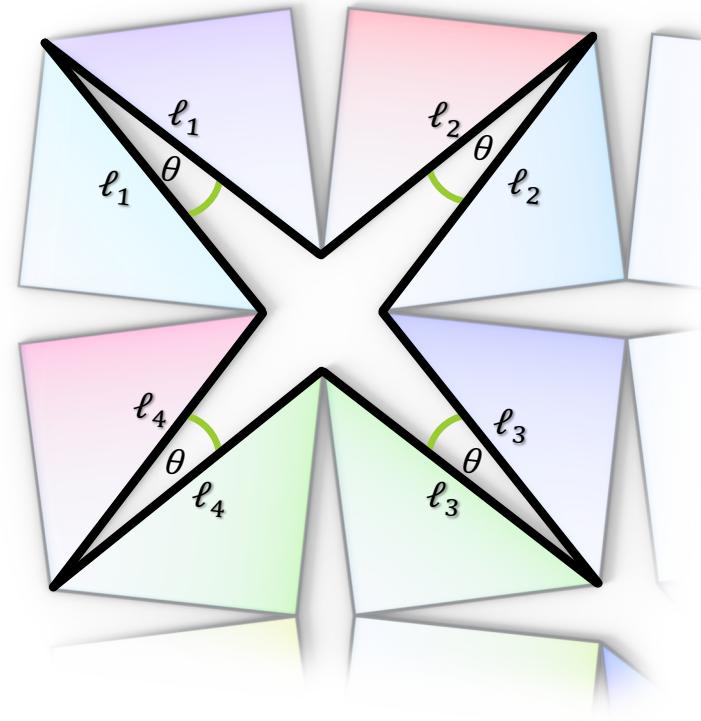
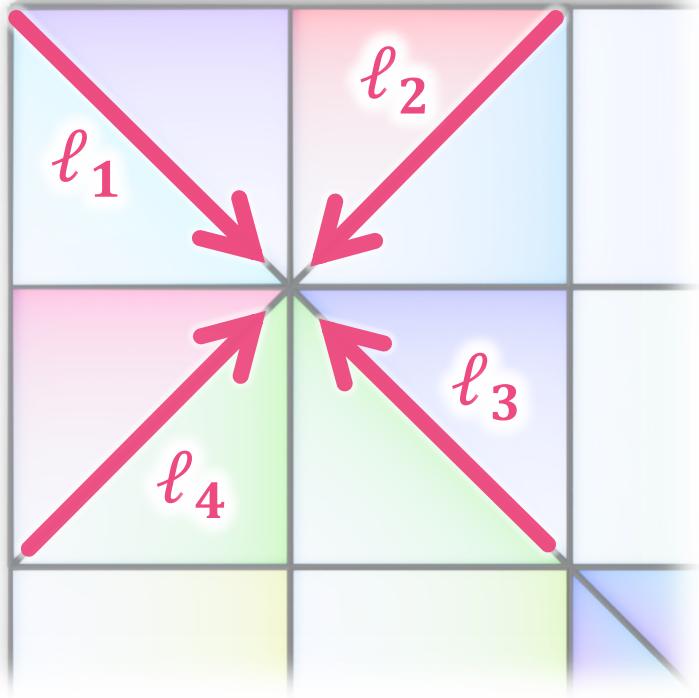
# Geometric condition



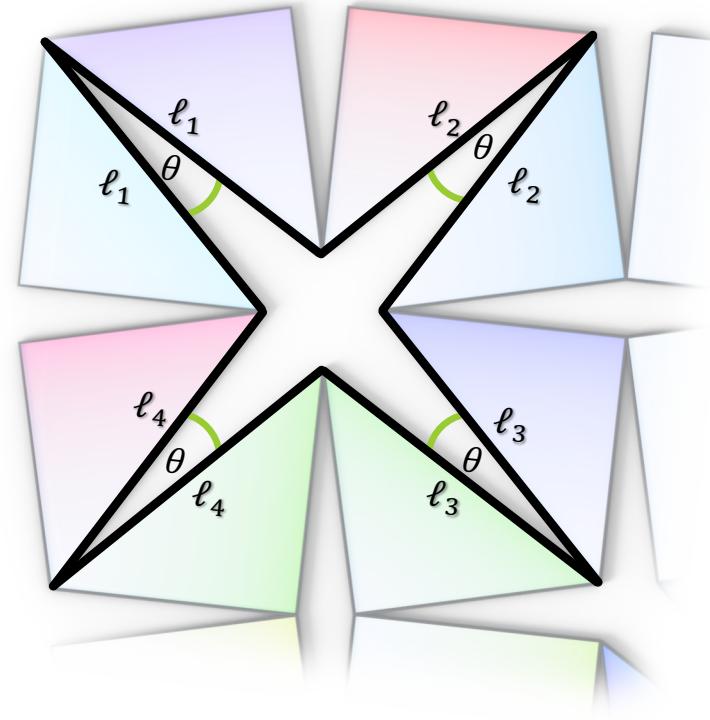
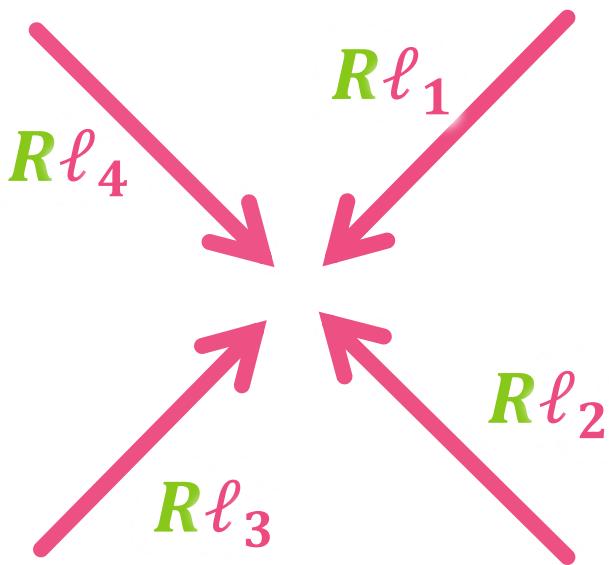
# Geometric condition



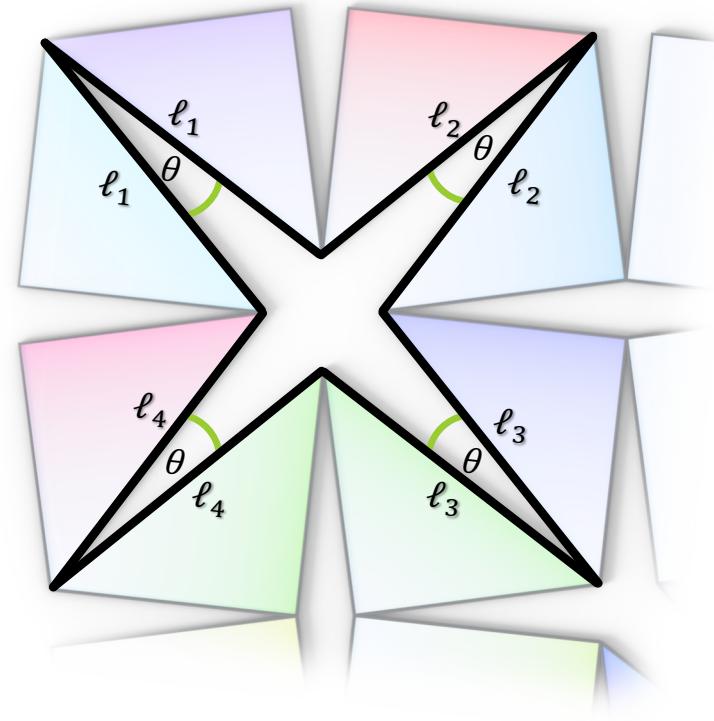
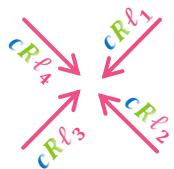
# Geometric condition



# Geometric condition



# Geometric condition



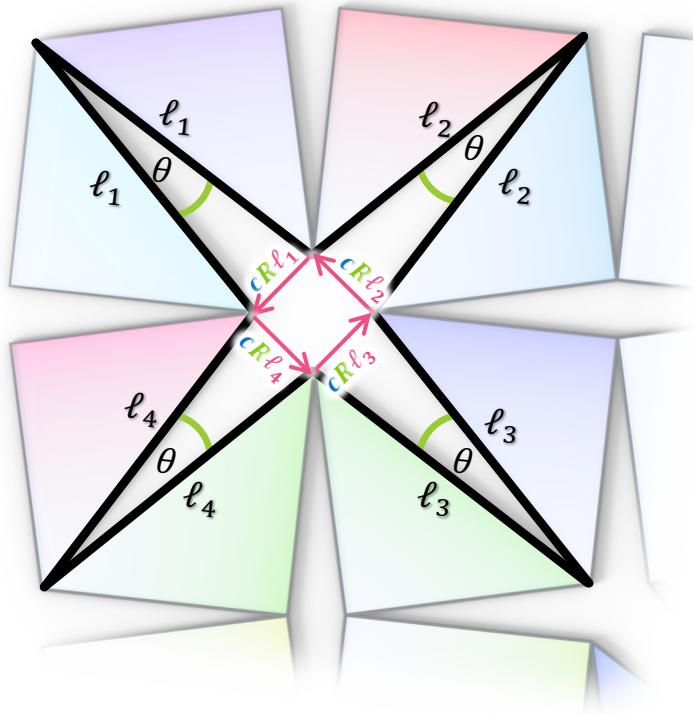
# Geometric condition

Can be rigidly embedded if

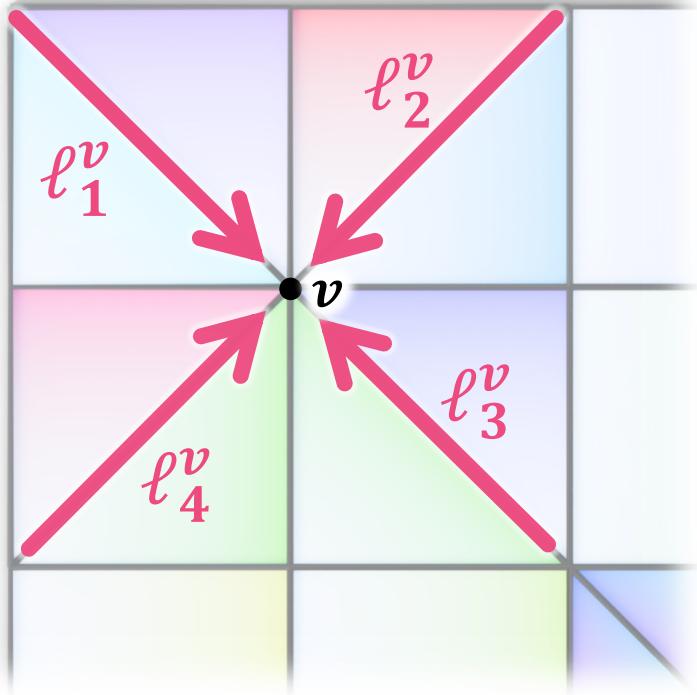
$$\sum_i \textcolor{blue}{c} \textcolor{green}{R} \vec{\ell}_i = \vec{0}$$



$$\sum_i \vec{\ell}_i = \vec{0}$$



# Geometric condition



A vertex  $v$  is deployment-friendly if

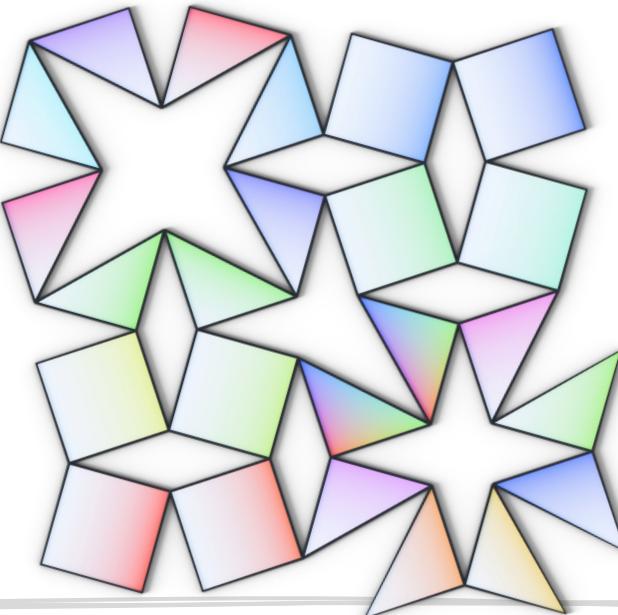
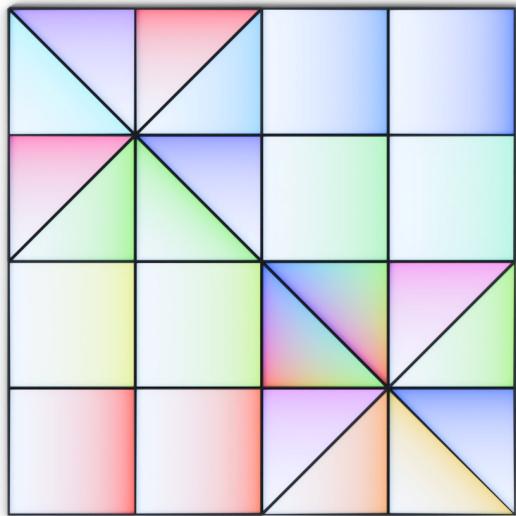
$$\sum_i \vec{\ell}_i^v = \vec{0}$$

# necessary & sufficient conditions

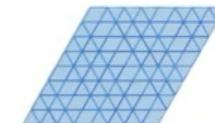
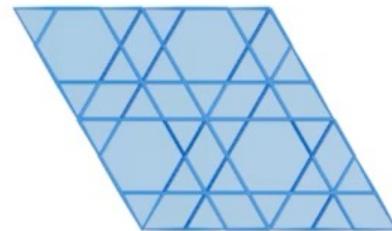
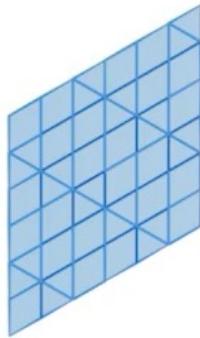
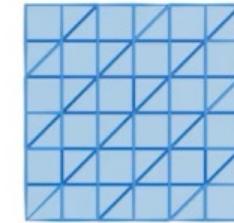
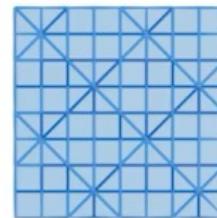
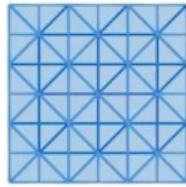
“every interior vertex is deployment-friendly”



“the resulting kirigami is uniformly deployable”

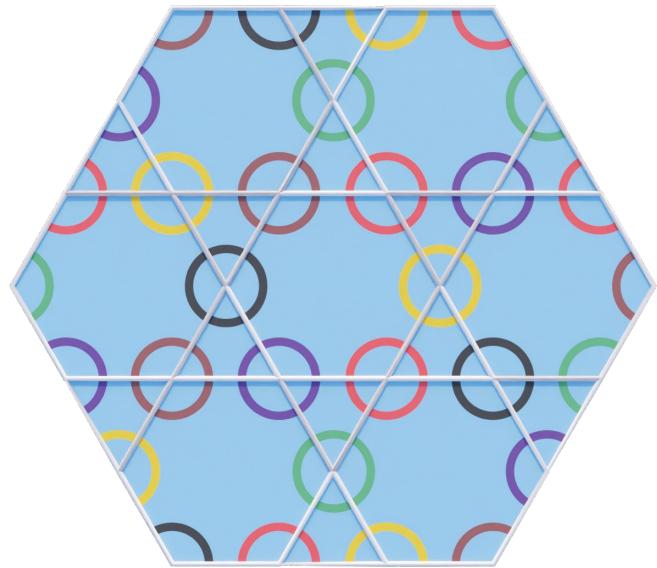


# Deployable patterns

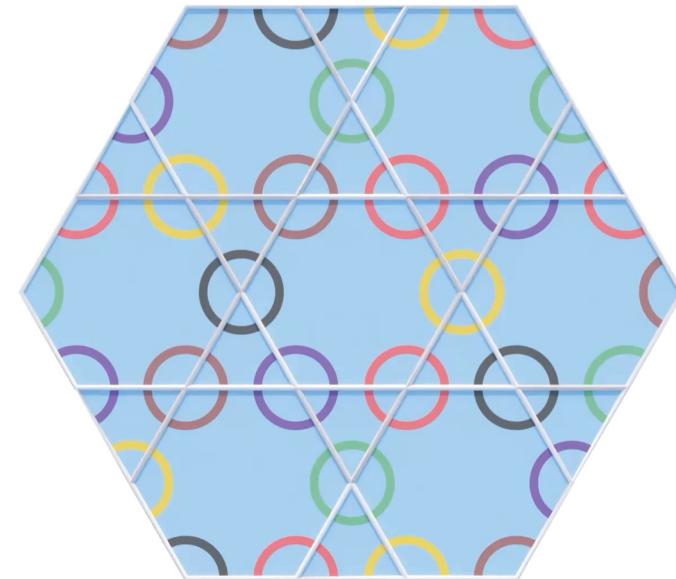


# Inverse design

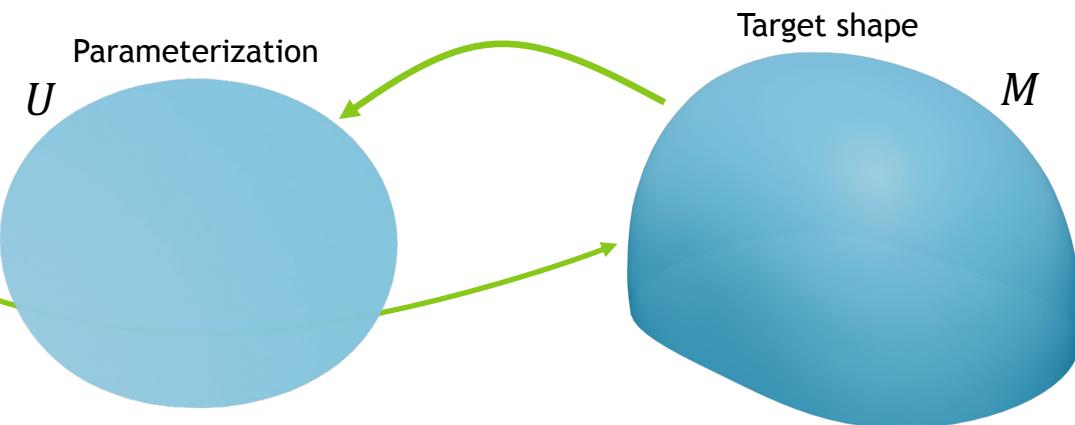
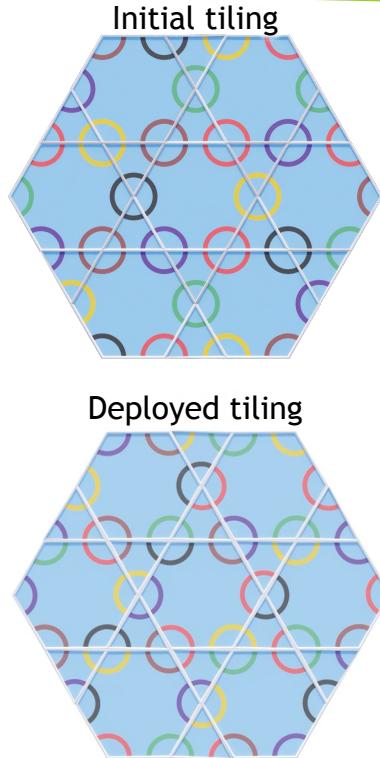
Initial tiling



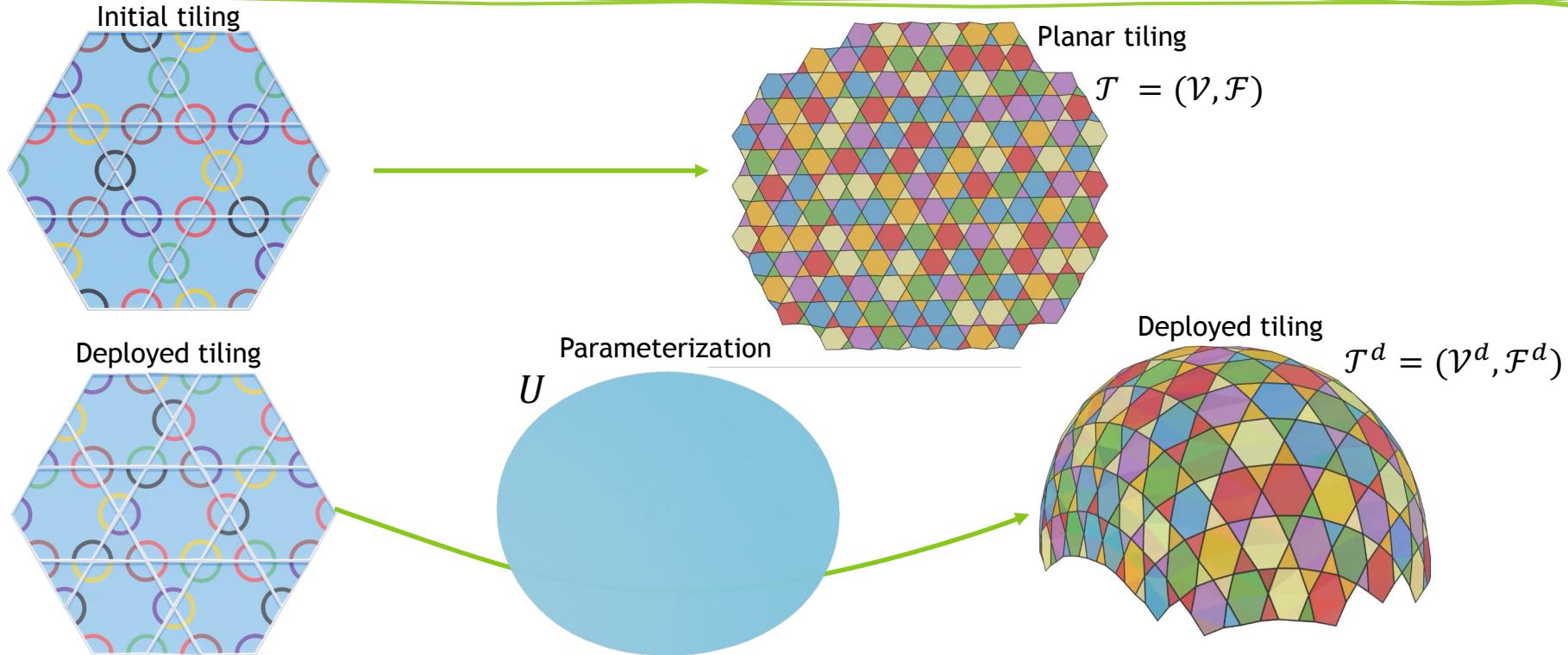
Deployed tiling



# Inverse design

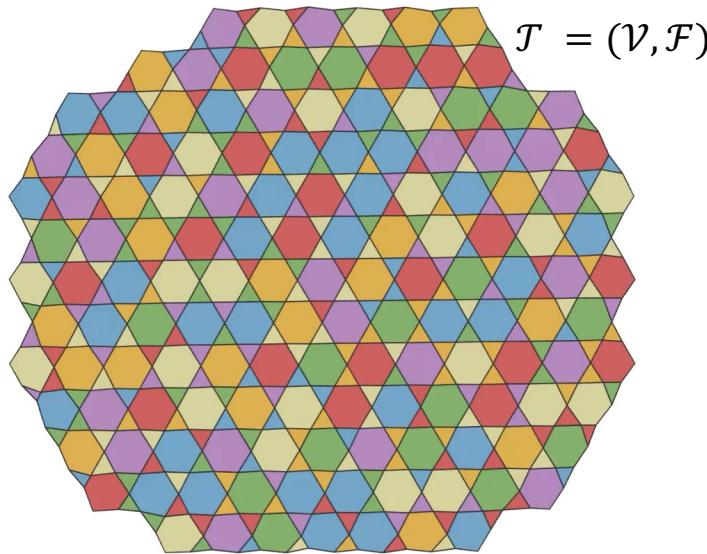


# Inverse design

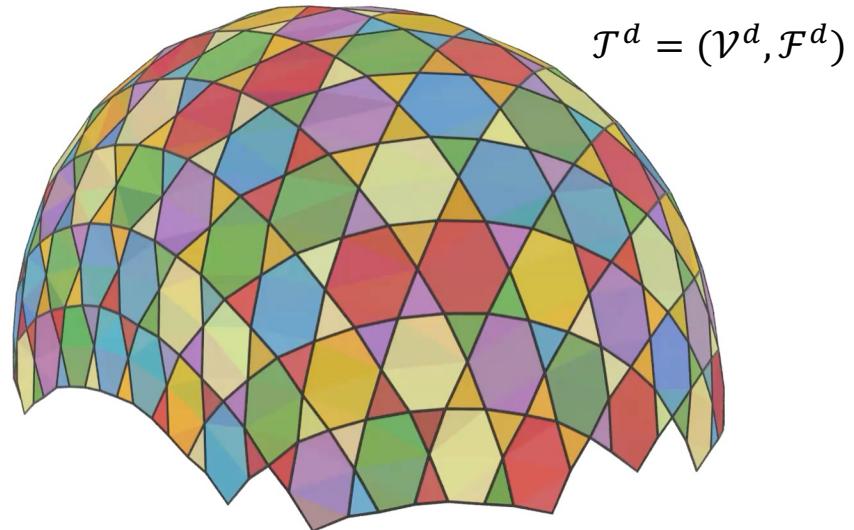


# Inverse design

Planar tiling

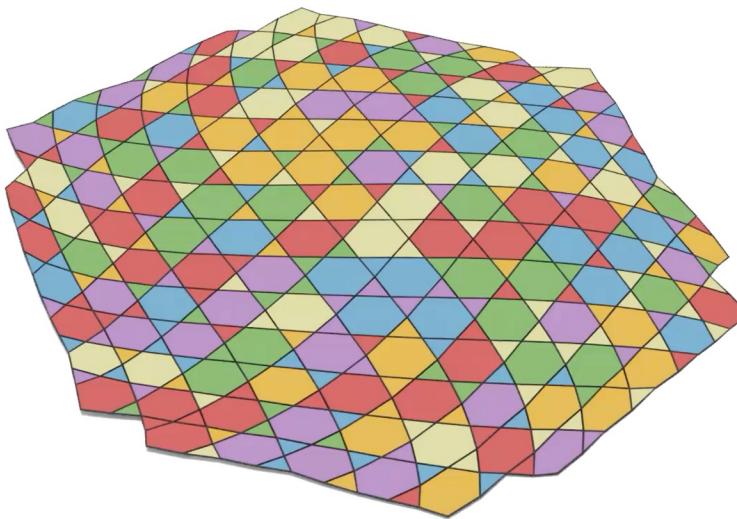


Deployed tiling

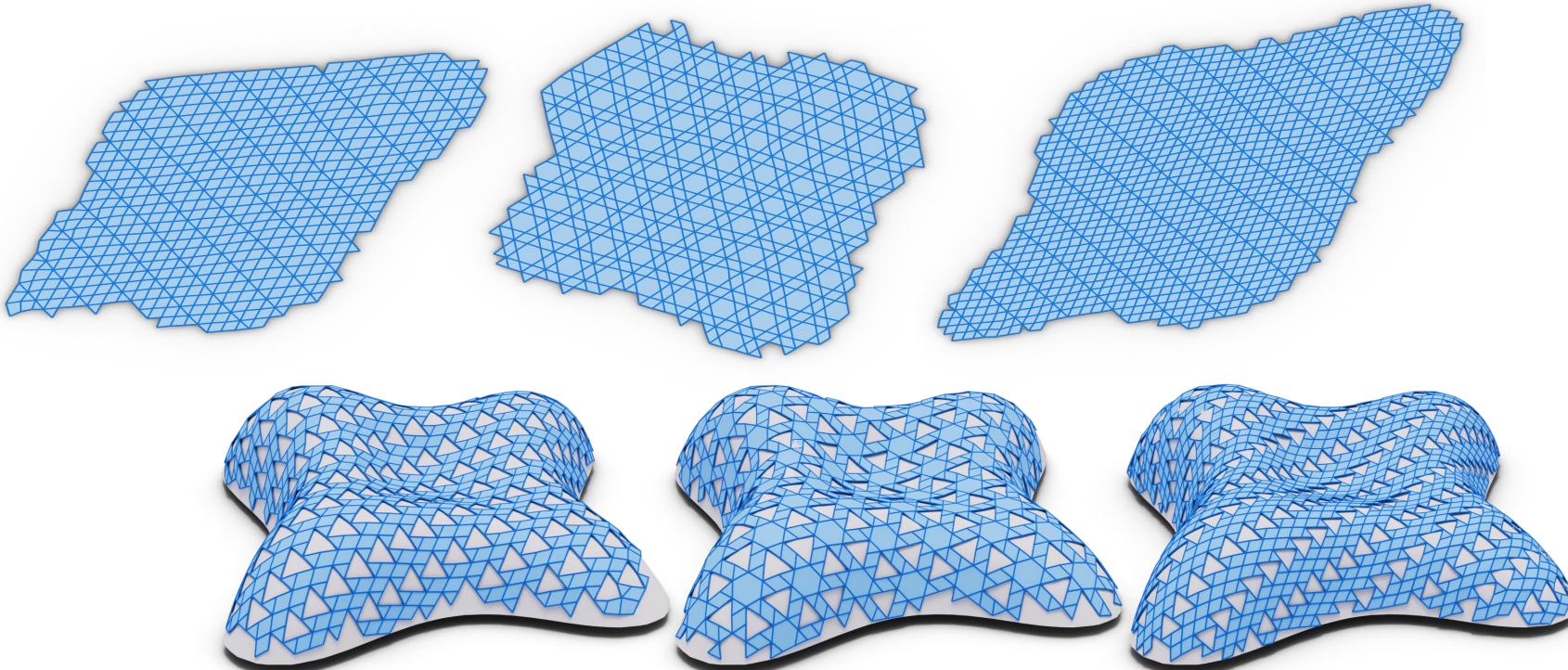


$$\min_{V, V^d} \omega_1 \mathbb{E}_{rigid}(V, V^d) + \omega_2 \mathbb{E}_{planar}(V^d) + \omega_3 \mathbb{E}_{shape}(V^d | \mathcal{M}) + \omega_4 \mathbb{E}_{fairness}(V^d)$$

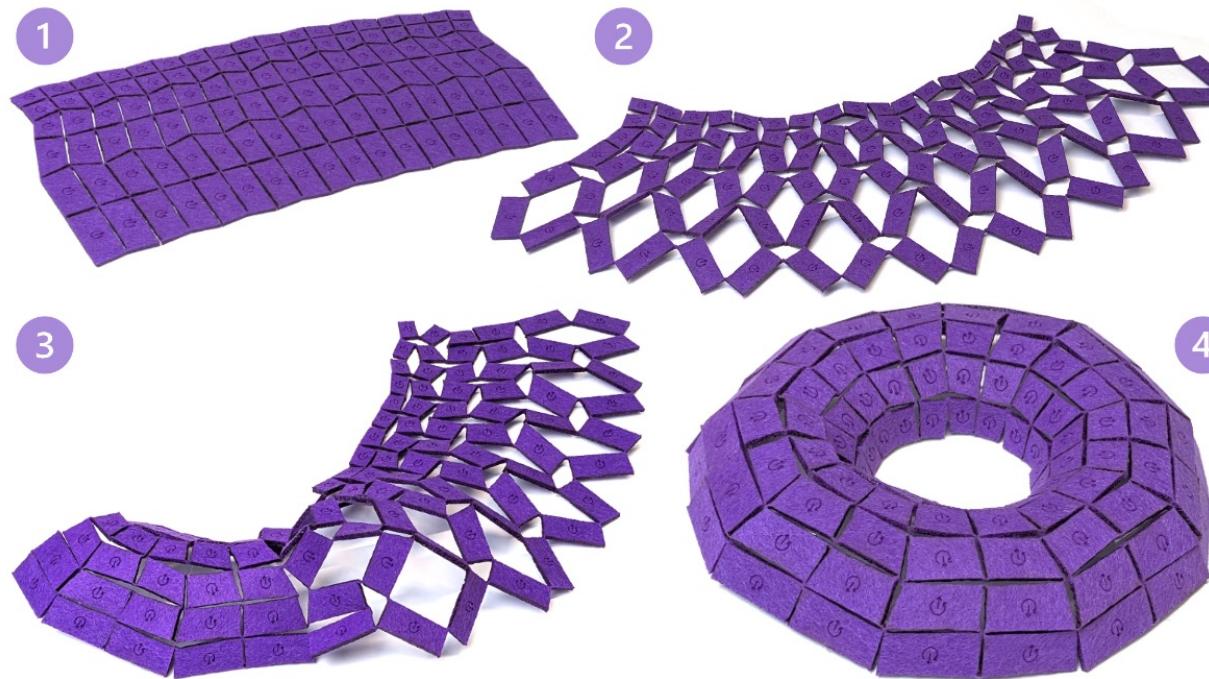
# Deployment



# Results: different patterns



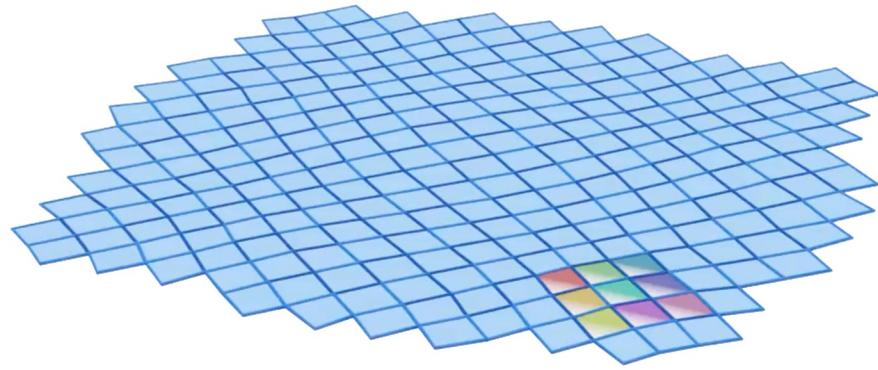
# Results: fabrications



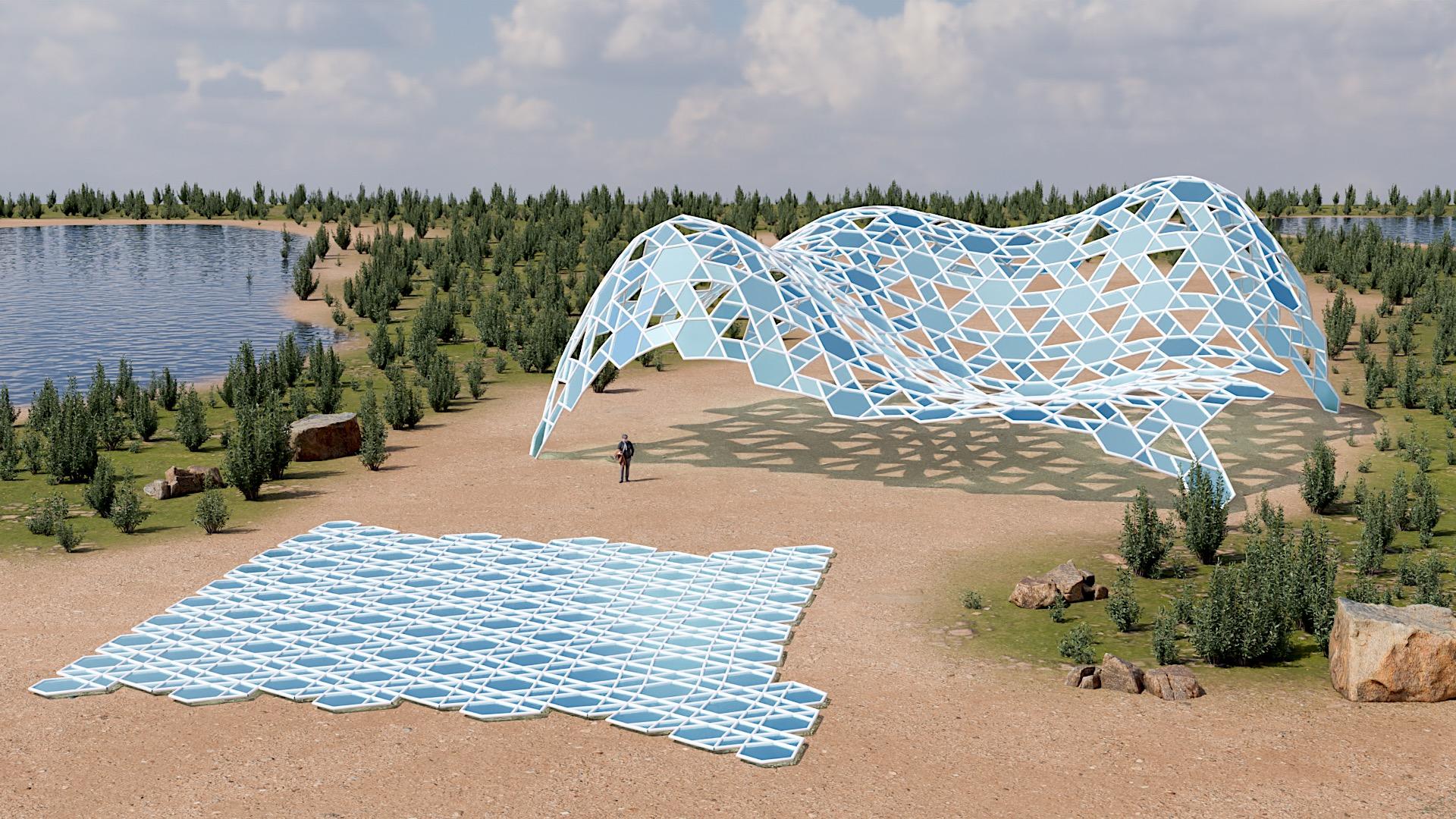
# Fabrications

(paper & felt, fixed with tapes)









# Limitations

Fabrication is not easy

- Cylinder hinges -> no rigid motion
  - Elastic energy stored in hinges/panels
  - Only the final configuration is rigid
- Spherical joints -> too much freedom
  - Requires gluing

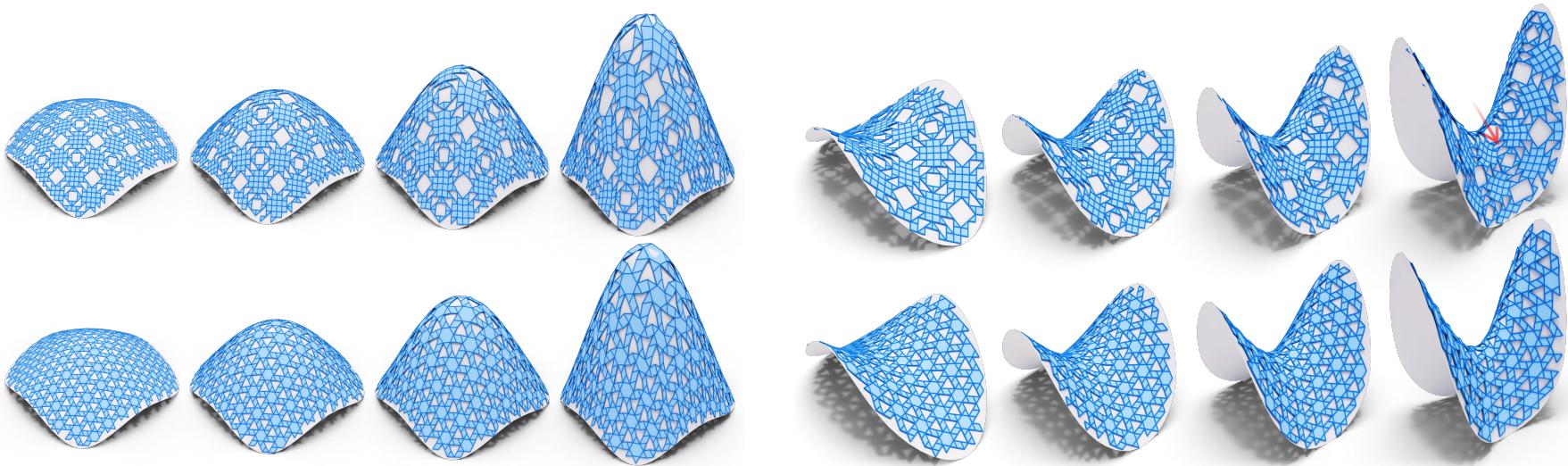
# Limitations

Fabrication is not easy

- Spherical joints with constrained axis trajectory
  - Hard to fabricate
  - Allows for a full rigid motion

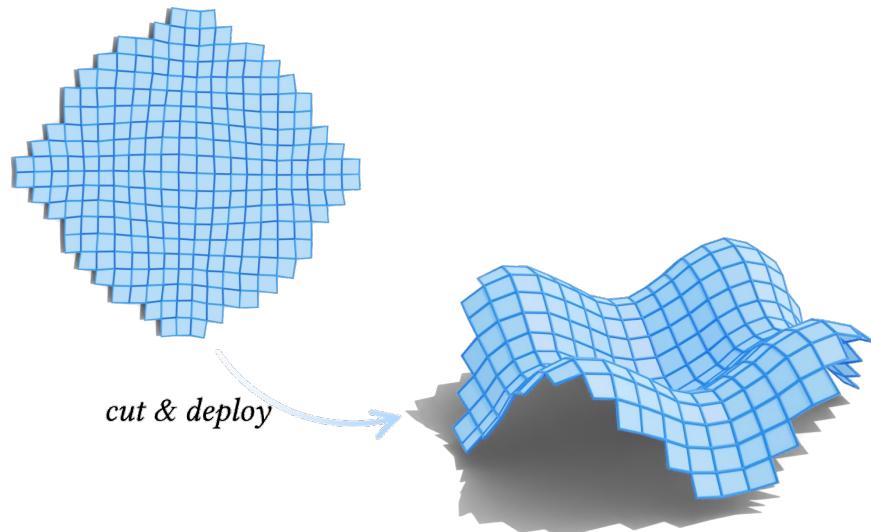
# Limitations

Shape space?

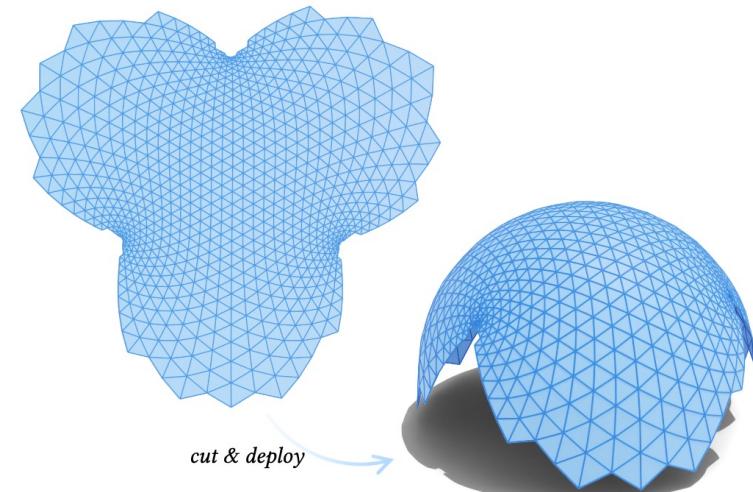


# Limitations

Shape space?



Conjugate net?

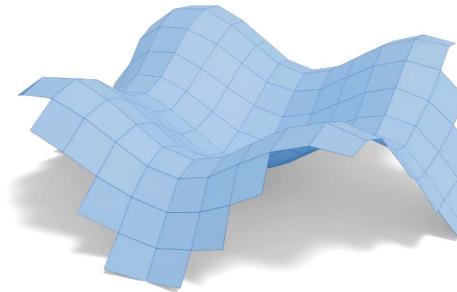


Semi-conformal map?

# Limitations

## Stability analysis of deployed shapes

- Is it possible to achieve bi-stability?
- Analyze equilibrium points assuming non-negligible masses



# Thank You