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In [1]: import numpy as np
```

```
class NeuralNetwork(object):
    def __init__(self, input_nodes, hidden_nodes, output_nodes, learning_rate):
        # Set number of nodes in input, hidden and output layers.
        self.input_nodes = input_nodes
        self.hidden_nodes = hidden_nodes
        self.output_nodes = output_nodes

        # Initialize weights
        self.weights_input_to_hidden = np.random.normal(0.0, self.input_nodes, (self.input_nodes, self.hidden_nodes))

        self.weights_hidden_to_output = np.random.normal(0.0, self.hidden_nodes, (self.hidden_nodes, self.output_nodes))
        self.lr = learning_rate

        ##### TODO: Set self.activation_function to your implemented sigmoid function.
        #
        # Note: in Python, you can define a function with a lambda expression,
        # as shown below.
        self.activation_function = lambda x : 1.0 / (1.0 + np.exp(-1.0*x))

        ### If the lambda code above is not something you're familiar with,
        # You can uncomment out the following three lines and put your
        # implementation there instead.
        #
        #def sigmoid(x):
        #    return 0 # Replace 0 with your sigmoid calculation here
        #self.activation_function = sigmoid

    def train(self, features, targets):
        ''' Train the network on batch of features and targets.

        Arguments
        -----

        features: 2D array, each row is one data record, each column is a feature
        targets: 1D array of target values

        '''
        n_records = features.shape[0]
        delta_weights_i_h = np.zeros(self.weights_input_to_hidden.shape)
        delta_weights_h_o = np.zeros(self.weights_hidden_to_output.shape)
        for X, y in zip(features, targets):

            final_outputs, hidden_outputs = self.forward_pass_train(X) # Implement the forward pass function below
            # Implement the backpropagation function below
            delta_weights_i_h, delta_weights_h_o = self.backpropagation(final_outputs, hidden_outputs, y)

        self.update_weights(delta_weights_i_h, delta_weights_h_o, n_records)

    def forward_pass_train(self, X):
        ''' Implement forward pass here

        Arguments
        -----
        X: features batch

        '''
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        final_inputs = np.dot(hidden_outputs, self.weights_hidden_to_output)
        final_outputs = final_inputs # signals from final output layer

    return final_outputs, hidden_outputs

def backpropagation(self, final_outputs, hidden_outputs, X, y, delta_weights_i_h, delta_weights_h_o):
    ''' Implement backpropagation

    Arguments
    -----
    final_outputs: output from forward pass
    y: target (i.e. label) batch
    delta_weights_i_h: change in weights from input to hidden layer
    delta_weights_h_o: change in weights from hidden to output layer

    '''
    ##### Implement the backward pass here #####
    ### Backward pass ###

    ##NOTA: en el excel unit_tests_model.xlsx mostramos el cálculo de
    # del error respecto a cada uno de los parámetros, justificando la

    # TODO: Output error - Replace this value with your calculations.
    # Output layer error is the difference between desired target and
    error = np.transpose(y - final_outputs)

    # TODO: Calculate the hidden layer's contribution to the error
    hidden_error = np.outer(X, (hidden_outputs*(1-hidden_outputs)))

    # TODO: Backpropagated error terms - Replace these values with your
    output_error_term = -1.0*error*hidden_outputs # Para que esto sea
    # ser  $E(y_{\hat{}}) = (1/2)*(y-y_{\hat{}})^2$ , de modo que la derivada respec
    # una función diferente, este término cambiaría

    hidden_error_term = -1.0*error*hidden_error*np.transpose(self.weights_hidden_to_output)

    # Weight step (input to hidden)
    delta_weights_i_h += hidden_error_term*-1.0
    # Weight step (hidden to output)
    delta_weights_h_o += np.expand_dims(output_error_term*-1.0, axis=1)
    return delta_weights_i_h, delta_weights_h_o

def update_weights(self, delta_weights_i_h, delta_weights_h_o, n_records):
    ''' Update weights on gradient descent step

    Arguments
    -----
    delta_weights_i_h: change in weights from input to hidden layer
    delta_weights_h_o: change in weights from hidden to output layer
    n_records: number of records

    '''
    self.weights_hidden_to_output += (1 / n_records) * self.lr * delta_weights_h_o
    self.weights_input_to_hidden += (1 / n_records) * self.lr * delta_weights_i_h

def run(self, features):
    ''' Run a forward pass through the network with input features

```

```
return final_outputs
```

```
#####  
# Set your hyperparameters here  
#####  
iterations = 100  
learning_rate = 0.1  
hidden_nodes = 2  
output_nodes = 1
```