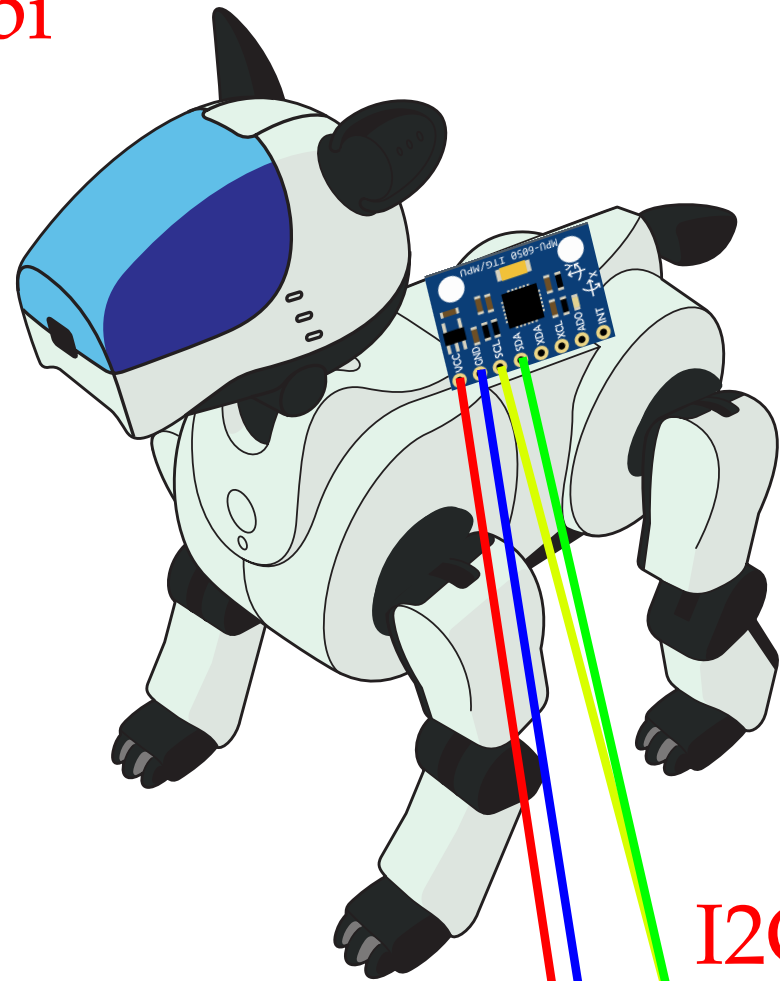
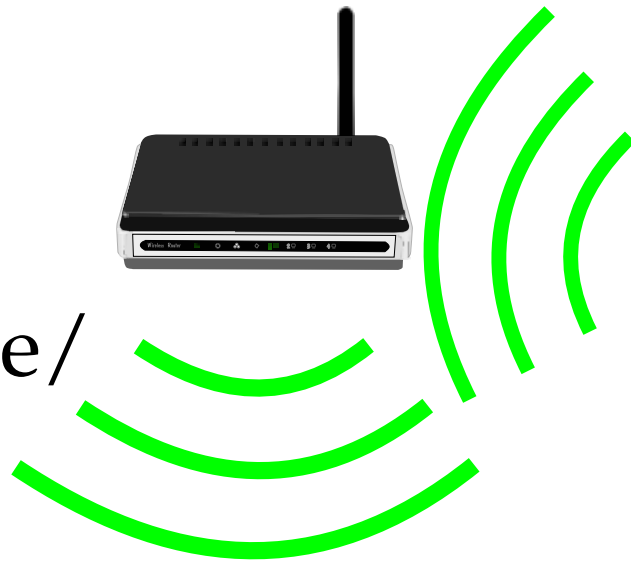


LibUrbi

ROS

topic:  
"/aibo\_execute/  
aibo/..."



I2C

ROS

topic: "/pos"

