

PDE : $\mathcal{N}(\mathcal{U}, s(x, t); \theta) = g$ Operator Learning $\mathcal{G}_\theta: \mathcal{U} \rightarrow \mathcal{S}$ $\zeta = \{x, y, t, \alpha\}$ $\theta \in \Theta$, $x_i \in \mathcal{U}$

