Hyperspherical Variational Auto-Encoder

VAE framework

Observed variable X

Latent variable 2

Distribution to sample
$$p(x) = \int p_{\phi}(x,z)dz = \int p_{\phi}(x\mid z)p(z)dz$$

Likelihood (decoder) $p_{\phi}(x \mid z)$

$$\begin{array}{ll} \text{Posterior (encoder)} & q_{\psi}(z \mid x; \theta) \leftarrow \text{usually } \mathcal{N}(\mu, \Sigma) \\ \\ \text{Prior} & p(z) & \leftarrow \text{usually } \mathcal{N}(0, I) \end{array}$$

ELBO

Motivation: log-likelihood cannot be directly maximized

$$\log \int p_{\phi}(\mathbf{x}, \mathbf{z}) d\mathbf{z}$$
 intractable \Rightarrow variational approach

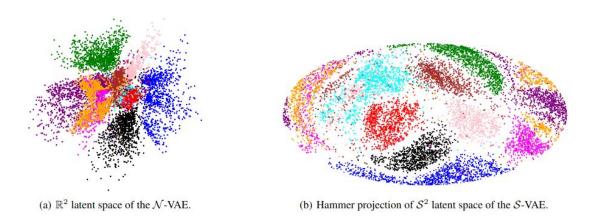
$$\log \int p_{\phi}(\mathbf{x}, \mathbf{z}) d\mathbf{z} \geq \text{ELBO} = \underbrace{\mathbb{E}_{q_{\psi}(z|x;\theta)}[\log p_{\phi}(x \mid z)] - \text{KL}\left(q_{\psi}(z \mid x;\theta) \mid\mid p(z)\right)}_{}$$

To maximize

$$KL_{\mathcal{N}-VAE} = rac{1}{2}\sum_{i=1}^d (1+\logig(\sigma_{\psi,j}^2ig) - \mu_{\psi,j}^2 - \sigma_{\psi,j}^2ig)$$

Motivations

- Limitation of Gaussian prior
 Unsuitable to model latent hyperspherical structure
- Directional data modeling (wind direction, protein structure, etc.)
- Improved clusterability



vMF sampling

Key properties enabling Ulrich-Woods sampling:

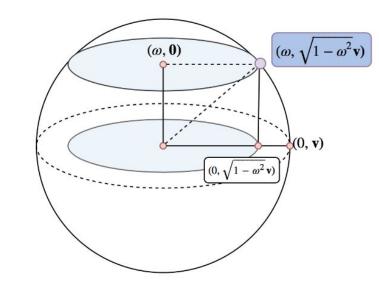
Action of orthogonal transformations :

$$\mathbf{x} \sim \mathrm{VMF}(oldsymbol{\mu}, \kappa) \ \mathbf{y} \sim \mathrm{VMF}(\mathbf{U}oldsymbol{\mu}, \kappa) \ \Rightarrow \mathbf{y} = \mathbf{U}\mathbf{x}$$

Known marginal density :

$$g(\omega|\kappa,m) \propto \exp(\kappa\omega)(1-\omega^2)^{(m-3)/2}$$
 \Rightarrow Rejection Sampling

Uniform on subsphere in hyperplane
 orthogonal to μ



Reparametrization Trick

N-VAE situation:

$$ELBO = \mathbb{E}_{q_{\psi}(z|x;\theta)}[log \, p_{\phi}(x \mid z)] - KL \left(q_{\psi}(z \mid x;\theta) \mid\mid p(z)\right)$$

SGD does not allow gradient to flow

Reparametrization :
$$z = \mu_\phi(x) + \sigma_\phi(x) \odot \epsilon, \quad \epsilon \sim \mathcal{N}(0,I)$$

$$abla_{\phi} ext{ELBO}(\phi, heta) = \mathbb{E}_{\epsilon \sim \mathcal{N}(0, I)} [
abla_{\phi} \log p_{ heta}(x|z) +
abla_{\phi} \log q_{\phi}(z|x) -
abla_{\phi} \log p(z)]$$

For rejection sampling, the number of random variable in the mapping is itself random

Reparametrization Trick

In Naesseth et al. (2017), derivation of a reparametrization trick for rejection sampling schemes based on the accepted sample density:

$$\pi(\varepsilon|\theta) = s(\varepsilon) \frac{g(h(\varepsilon,\theta)|\theta)}{r(h(\varepsilon,\theta)|\theta)}$$

With log-derivative trick, leads to a 2-term gradient :

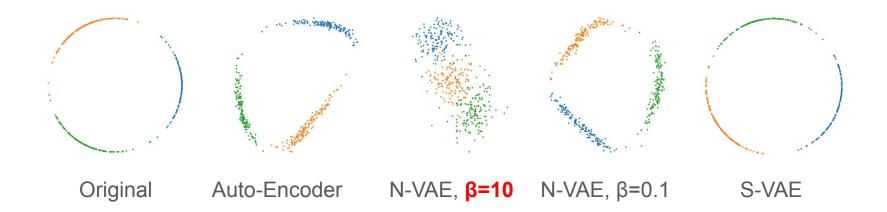
$$\nabla_{\theta} \mathbb{E}_{g(\omega|\theta)}[f(\omega)] = \mathbb{E}_{\pi(\varepsilon|\theta)}[\nabla_{\theta} f(h(\varepsilon,\theta))] + \mathbb{E}_{\pi(\varepsilon|\theta)}\left[f(h(\varepsilon,\theta))\nabla_{\theta} \log \frac{g(h(\varepsilon,\theta)|\theta)}{r(h(\varepsilon,\theta)|\theta)}\right]$$

In this paper, derived in the framework where there are 2 random variables

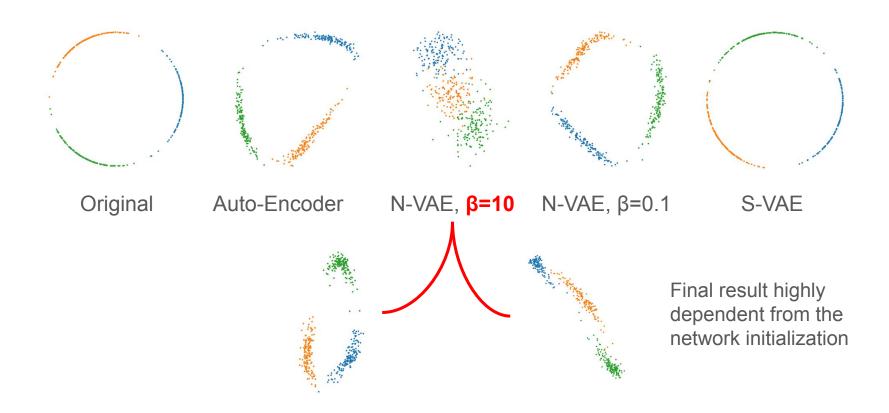


Same 2-term structure for the gradient, no dependance on mu

Experiments



Experiments



Limitations

- Dimensionality
 Vanishing surface
 Similar performance in high dimension (~20)
- High variance term in reparametrization trick for rejection sampling

