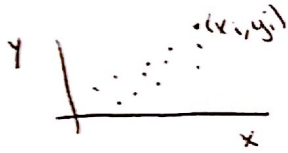


Why do the eigenvectors of the covariance matrix capture the direction along which the data varies the most?

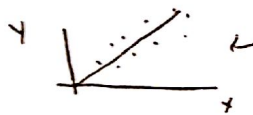
⇒ To answer this, let's consider a simple case - like 2-D data.



Here's the accompanying data matrix:

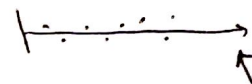
$$X = \begin{bmatrix} x_1 & \dots & x_n \\ y_1 & \dots & y_n \end{bmatrix}$$

Let's just think about what happens when we project this data onto 1-dimension. To capture the most structure in the data, we want this line to be in the direction with the most variance:



like this

when projected:



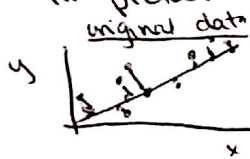
The accompanying equation for this transformation (from 2D to 1D) is:

$$\begin{matrix} \text{data along} \\ \text{u-axis} \end{matrix} \quad [u_1 \dots u_n] = \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} \begin{bmatrix} x_1 & \dots & x_n \\ y_1 & \dots & y_n \end{bmatrix}$$

$\underbrace{\begin{bmatrix} p_1 \\ p_2 \end{bmatrix}}_{\text{line that we project data onto}} \quad \underbrace{\begin{bmatrix} x_1 & \dots & x_n \\ y_1 & \dots & y_n \end{bmatrix}}_{\text{original data}}$

After I can shrink data slightly off the u-axis so you can see it, but really these points lie directly on the line.

* a quick note on what projection means in picture form:



We find the shortest distance from each data point to the line, and take that location on the line as the "projected" data point.

Okay, so we have: $[u_1 \dots u_n] = \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} \begin{bmatrix} x_1 & \dots & x_n \\ y_1 & \dots & y_n \end{bmatrix}$. We want the new data points $[u_1 \dots u_n]$ to have maximum variance (think about this).

That means, we want to maximize the variance of $\begin{bmatrix} p_1 \\ p_2 \end{bmatrix} \begin{bmatrix} x_1 & \dots & x_n \\ y_1 & \dots & y_n \end{bmatrix}$, or $p^T X$. From class, recall that the variance of a vector \vec{a} is $\text{var} = \frac{1}{n} \sum a_i^2 = \frac{1}{n} \vec{a}^T \vec{a}$, if \vec{a} is a column vector, or $\frac{1}{n} \vec{a} \vec{a}^T$ if \vec{a} is a row vector.

So, the variance of pX (also a vector) is $\frac{1}{n}(pX)(pX)^T$.

$\Rightarrow \frac{1}{n}(pX)(pX)^T = \frac{1}{n} pXX^T p^T = pC_X p^T$, where C_X is the covariance matrix of X .

Now, what we want to do is maximize $pC_X p^T$. (Remember - that this is just a number). Recall that because C_X is symmetric, we can decompose this into: $C_X = EDE^T$. Then,

$pC_X p^T = pEDE^T p^T$. Let $E = [e_1, e_2]$ and $D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$. Then, (where $\lambda_1 \geq \lambda_2$)

$$pEDE^T p^T = p[e_1, e_2] \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} e_1^T \\ e_2^T \end{bmatrix} p^T$$

$$= p[e_1, e_2] \begin{bmatrix} \lambda_1 e_1^T \\ \lambda_2 e_2^T \end{bmatrix} p^T$$

$$= p(\lambda_1 e_1 e_1^T + \lambda_2 e_2 e_2^T) p^T \leq p(\lambda_1 e_1 e_1^T + \lambda_2 e_2 e_2^T) p^T$$

This is still $pC_X p^T$, the thing we want to maximize

Because $\lambda_1 \geq \lambda_2$, this expression (where $\lambda_2 = \lambda_1$) represents the ~~maximum~~ ^{maximum} of this function

So: $\lambda_1 p(e_1 e_1^T + e_2 e_2^T) p^T$ is the maximum value of $pC_X p^T$. But this isn't super clear, so let's keep simplifying.

$$\begin{aligned} \Rightarrow \lambda_1 p(e_1 e_1^T + e_2 e_2^T) p^T &= \lambda_1 p([e_1, e_2] \begin{bmatrix} e_1^T \\ e_2^T \end{bmatrix}) p^T \\ &= \lambda_1 p(EE^T) p^T \\ &= \lambda_1 p p^T \end{aligned}$$

Let's assume $p p^T = 1$ (that p is normalized such that its length is 1).

Now, λ_1 is the maximum value of $pC_X p^T$, i.e. the variance of our projected data. So, now the question is, for what value of p does $pC_X p^T = \lambda_1$?

Let's return to the expression $p(\lambda_1 e_1 e_1^T + \lambda_2 e_2 e_2^T) p^T$. Bunting this

$$\Rightarrow \lambda_1 p e_1 e_1^T p^T + \lambda_2 p e_2 e_2^T p^T. \text{ If } p = e_1^T, \text{ then:}$$

$$\Rightarrow \lambda_1 e_1^T e_1 e_1^T e_1 + \lambda_2 e_1^T e_2 e_2^T e_1. \text{ Because } e_1^T e_1 = 1 \text{ and } e_1^T e_2 = 0, \text{ this equals } \lambda_1.$$

So: $p = e_1^T$ maximizes the variance of our projected data, and e_1^T is the eigenvector with the largest eigenvalue of the covariance matrix of our data!