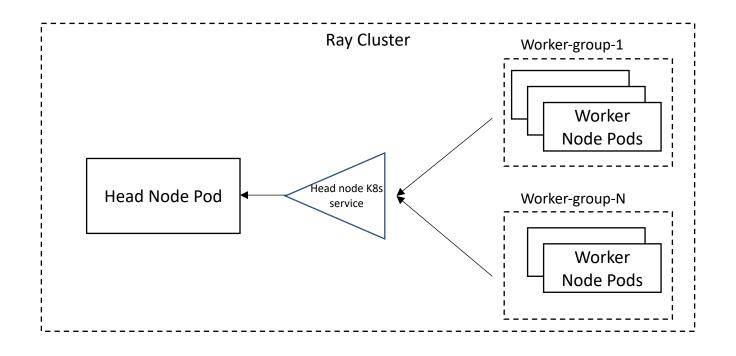


Ray AutoScaling Alternatives

Ali Kanso *, Edi Palencia*, Edward Oakes*, Eric Liang*, Yiran Wang*





Autoscaling list of tasks:

The component(s) that is <u>managing</u> the lifecycle **and** <u>auto-scaling</u> a Ray cluster, must be capable of performing the following tasks:

Life-Cycle Management

- 1. Create a Ray cluster
- 2. Delete a Ray cluster and cleanup all the relevant resources
- 3. Failure recovery (e.g. if a physical machine fails, create the Ray nodes on another machine(s))
- 4. Creating additional nodes and deleting idle nodes.
- 5. Metrics collection: determine the CPU, Mem, GPU, TPU utilization in the cluster (currently there is only one threshold supported). And determine the idle nodes.
- 6. Making a scaling up/down decision based on the metrics collected

Auto-scaling

Discussed Options

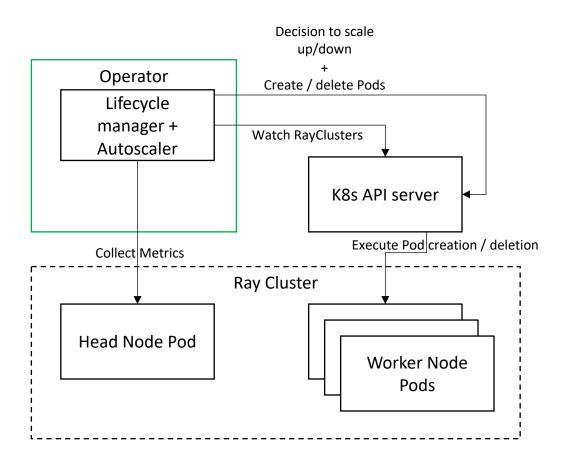
Auto-scaler + Limited **Auto-scaler Monolith** Operator **RAY** Only Operator with Auto-Auto-scaler + Operator (Separation on Concerns) scaling functionality

Auto-scaler monolith:

Currently, the auto-scaler in Ray, can carry out all the above tasks (1 \rightarrow 6).

| Pros | Cons |
|---|--|
| Has access to internal Ray-nodes information | Mixes concerns for the auto-scaler (metrics collection, decision making, autoscaling by creating/deleting nodes) |
| Can select which idle nodes to remove | Has excessive permissions on the Ray cluster and the K8s cluster (no RBAC in place today) |
| Is not limited to K8s, supports AWS, GCP, Azure, etc. | More complicated to maintain and modify |
| | If a k8s Pod fails, the auto-scaler might not be fast as an operator to recover the failed pod. |

Only Operator with autoscaling functionality



Auto-scaler + Limited Operator:

Let the limited-Operator only take care of creating and managing the head node of the ray cluster, and delegate the task of <u>managing the worker nodes to the auto-scaler</u>.

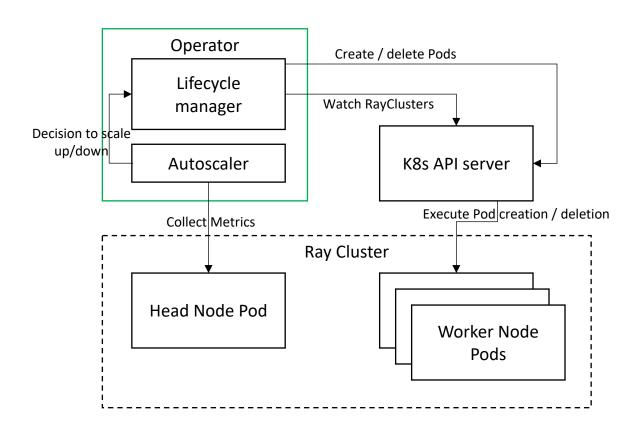
| Pros | Cons |
|--|---|
| Ray head node availability is improved | Mixes concerns for the auto-scaler (metrics collection, decision making, autoscaling by creating/deleting worker nodes) |
| | Added complexity for adding the Operator for a trivial task of managing the head node of the ray cluster |
| | In addition to the concerns about excessive permissions, etc. mentioned before |

Only Operator with autoscaling functionality

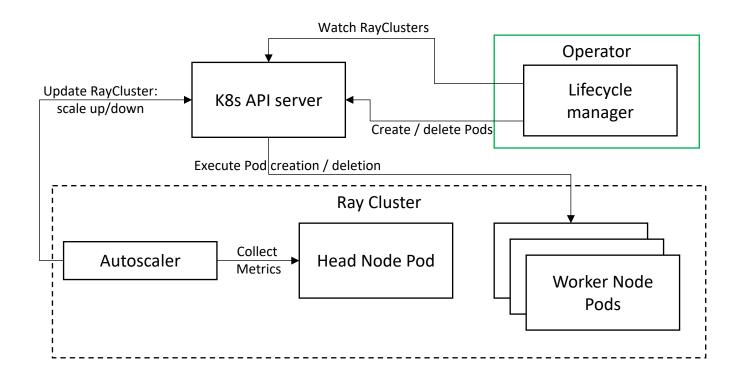
The Operator will be **responsible for tasks 1 to 6 described** above. Basically, replacing the auto-scaler logic we have today.

| Pros | Cons |
|---|--|
| Ray nodes availability is improved | Requires the existence of a K8s API server. i.e. |
| | it is tied down to K8s* |
| Better user experience. The user only deals with K8s Yaml manifest | Mixes concerns for the Operator (metrics |
| for the cluster configuration as K8s Custom resource | collection, decision making, autoscaling by |
| | creating/deleting worker nodes) |
| Added security by managing through RBAC who has permissions to | Requires a re-write of the current auto-scaler |
| create/modify/delete Ray clusters on the K8s cluster | and a re-write of the current Ray Operator |
| Ability to enforce admission control on the Ray cluster | |
| configuration. E.g. reject configuration that are not semantically | |
| valid. | |
| Using the OpenAPI V3 validation mechanisms we can also enforce | |
| syntactical validation with minimum effort. | |
| Ability to enforce resource quota in the namespace of the Ray | |
| cluster. | |
| Leverages the ubiquitous availability of K8s as a service offering of | |
| cloud vendors . | |

Only Operator with autoscaling functionality



Auto-scaler + Operator

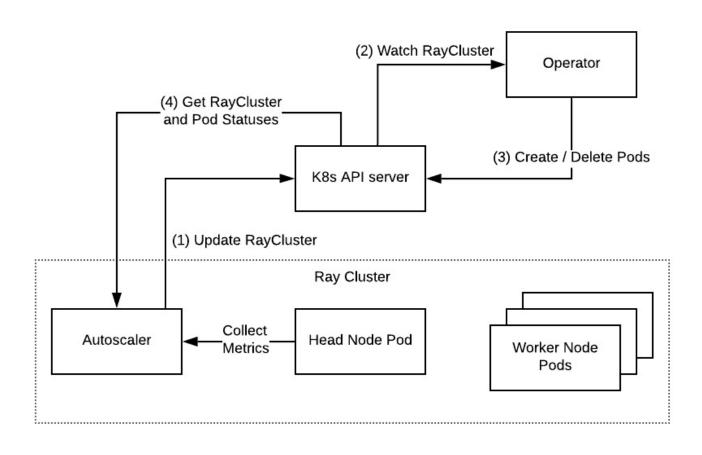


Auto-scaler + Operator

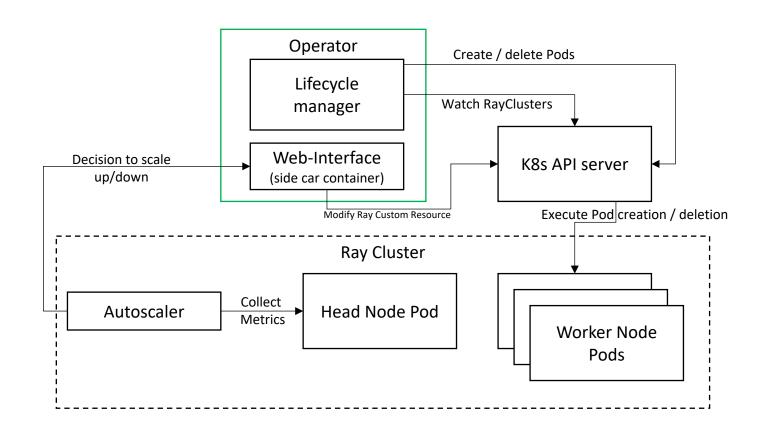
The auto-scaler makes the auto-scaling decisions (tasks 5 and 6) and the Operator takes care of the life-cycle management of the Ray cluster nodes (tasks 1, 2, 3, 4).

| Pros | Cons |
|---|--|
| Ray nodes availability is improved | Requires the existence of a K8s API server. i.e. it is |
| | tied down to K8s* |
| Separation of concerns for the auto-scaler (metrics collection, decision | Requires the auto-scaler to convey the decisions |
| making,) and the Operator manages the lifecycle of the ray nodes) | to the Operator. E.g. by creating an auto-scaling |
| | request in K8s, or modifying the Custom |
| | Resource |
| Better user experience. The user only deals with K8s Yaml manifest for the | |
| cluster configuration as K8s Custom resource | |
| Added security by managing through RBAC who has permissions to | |
| create/modify/delete Ray clusters on the K8s cluster | |
| Ability to enforce admission control on the Ray cluster configuration. E.g. | |
| reject configuration that are not semantically valid. | |
| Using the OpenAPI V3 validation mechanisms we can also enforce | |
| syntactical validation with minimum effort. | |
| Ability to enforce resource quota in the namespace of the Ray cluster. | |
| Leverages the ubiquitous availability of K8s as a service offering of cloud | |
| vendors. | |

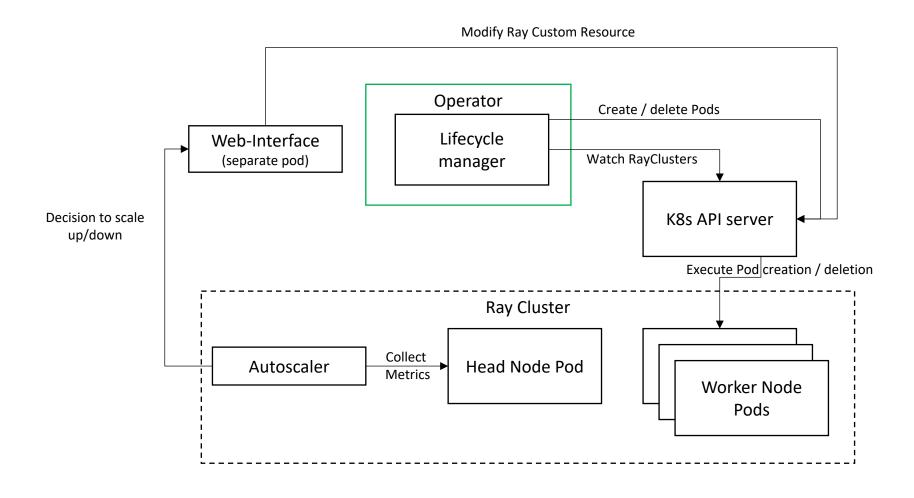
Auto-scaler + Operator: Option 1



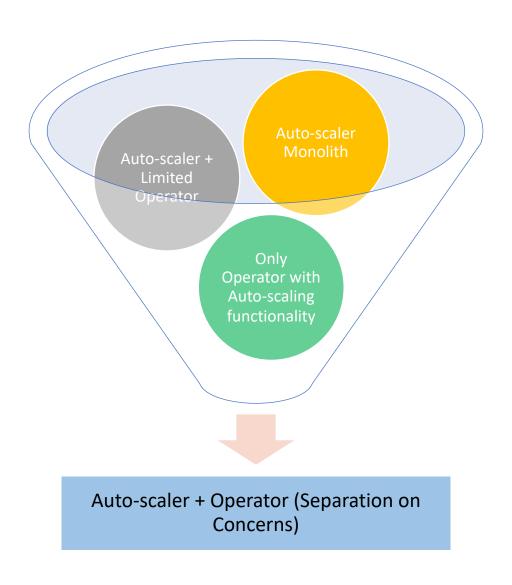
Auto-scaler + Operator + WebServer: Option 2



Auto-scaler + Operator + WebServer : Option 3



Conclusion: Auto-scaler + Operator (Separation on Concerns)



(Ray users not running on K8s clusters, can substitute the Operator with Ray Cluster-Launcher)