NAHYEON KIM

1 EDUCATION

University of California, Los Angeles (UCLA)

CA, US

M.S. in Mechanical Engineering

2023 - 2024

Thesis Advisor: Prof. Dr. Khalid Jawed, Structures-Computer Interaction Lab

Seoul National University

South Korea

B.S. in Mechanical Engineering and B.B.A. in Entrepreneurship

2018 - 2023

2 RESEARCH EXPERIENCE

Diffusion Model for Medical Research

South Korea

Research Engineer (Full time), CONNECTEVE.Inc

2024

Advisor: Dr. Prof. Duhyun Ro, Seoul National University

- ♦ Developed a novel diffusion image synthesis framework that de-noise by synthesizing images using two diffusion models.
- ♦ Proposed 4-channel training, the diffusion model generates a mask for more natural synthesis.
- ♦ This approach successfully generates anomaly detection and object detection datasets, combining each diffusion model trained on objects and backgrounds.

Self-Supervised Viewpoint Selector for Neural Radiance Fields (NeRF)

CA, US

M.S. student, Structures-Computer Interaction Lab

2023 - 2024

Advisor: Prof. Dr. Khalid Jawed), UCLA

- ♦ Maximized the training efficiency of NeRF models by introducing Self-supervised NeRF Image Selection (SNIS), an unprecedented image selection strategy that identifies optimal camera poses.
- ♦ Proposed a novel pseudo-label, analogous to a reinforcement learning reward function, enabling the application of a self-supervised learning framework into NeRF model training
- Integrated NeRF training with Unity environment-operated cameras, introducing an innovative research methodology to advance NeRF studies.

Visual Positioning System (VPS) with Machine Learning

South Korea

Research Engineer (Full time), VR Crew Inc.

2023

- ♦ Implemented a VPS algorithm for a VR game, estimating user location via mobile device.
- VPS system includes LiDAR, point cloud analysis, computer vision feature analysis with deep learning, epipolar geometry, homography adaptation.
- ♦ Led research focused on Keypoint Extractor, PnP, PnL, Point Matching, and Global Descriptor.

Knowledge Distillation with Network Inversion, Domain Adaptation

South Korea

Research Internship, Korea Institute of Science and Technology (KIST)

2021 - 2022

Advisor: Dr. Prof. Suhyun Kim, KIST Data Science Team

- ♦ Proposed a novel performance restoration method for pruned networks via optimized knowledge distillation loss with synthetic dataset generated by network inversion.
- Discovered an upper performance limit during training of the pruned network using synthetic data, indicating the current one-hot label format of the network inversion dataset is incorrect, and proposed an alternative vector-form label.
- ♦ Observed domain shrinkage increases performance during pruning and studied domain adaptation to obtain optimal sub-network focusing on the Batch-Normalization layer.

Optical Character Recognition (OCR)

South Korea

Research Internship, Saige Research Inc.

2021

Advisor: Dr. Prof. Frank Park, Seoul National University

- ♦ Investigated and customized OCR models to automate manufacturing process.
- ♦ The research investigates bilingual models for Korean and English, encompassing document understanding, custom dataset generation, character detection, and recognition.

3 DEVELOPMENT EXPERIENCE

Junior Software Developer, Datacrunch Global Inc.

2023

- Developed Business Decision Solution (BDS), a B2B web service that manages and analyzes large amounts of data in logistics centers, tracking inventory flows in warehouses and evaluating marketing methods based on actual user purchases.
- Mainly worked on API management using Python, Django, React, and MySQL, as a freelance engagement on a project basis.

Software Development Internship, PSX Inc.

2020 - 2021

- ♦ Developed web backend for stock trading platform using Python and Django.
- ♦ Developed the frontend and backend for a prototype of a hybrid application service using React-Native.
- ♦ Established recommendation algorithm for OTT media service that provides content suggestions for users.

4 SELECTED PROJECTS

Comparison Study: Traditional Computer Vision and Deep Learning [Code]

2021

- Conducted comparative study examining the performance of deep neural networks when augmented with traditional computer vision algorithms: Warping, SIFT, Edge Detection, and Gabor Filters.
- Creatively utilized the algorithms to enable the first layer of deep neural networks to comprehend the information.
- ♦ Discovered that computer vision algorithms tend to aid deep neural networks more effectively when operating with higher resolutions compared to lower resolutions.

3D Mouse: Spatial Information Inputs

Seoul National University Creative Design Fair

2021

- ♦ Won 3rd prize at the 10th Creative Engineering Design Fair.
- ♦ Created a 3D mouse equipped with gyro sensors and ultrasonic sensors, provides spatial input to the computer.
- ♦ Implemented and presented a prototype of interactive spatial mouse control service in 3D visualization of the skeletal structure captured through CT imaging.

Spline Visualization and Scene Rendering [Code]

2020 - 2021

- \diamond Designed 3D polygonal objects with B-Spline and Cat mull-Rom spline.
- Created dynamic interaction window via mouse and keyboard controls, showcasing implicit surfaces and objects.
- ♦ Depicted the details of objects using various light sources and Phong illumination, and represented them through ray-tracing.

5 PUBLICATIONS & PATENT

[Submitted] Nahyeon Kim and Suhyun Kim. "Data-Free Retraining of Pruned Networks." IEEE Access, 2024.

[Issued] Kim, Nahyeon, 2023, Apparatus and method for performing visual localization effectively, Korean Patent 1020230054544, filed April 26, 2023, and issued December 18, 2023.

6 SKILLS

Programming: Python, C++, MATLAB, React, React-Native, Javascript, Node JS

Scientific Libraries: Pytorch, SciPy, OpenCV, Scikit-Learn, Tensorflow, ROS

Software & Tools: Docker, Singularity, Git, MySQL, Linux OS, LATEX, HTML & CSS, Blender Domain Knowledge: Neural Radiance Fields (NeRF), Reinforcement Learning, Computer Vision Feature

Analysis with ML, Knowledge Distillation, Network Pruning, LLM