Spectral Lagrangian methods (in particular for SW)

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Outline

- Governing equations
- Scheme and motivation
- Numerics
  - Sod
  - Smooth periodic
  - Well-balancing
  - Supercritical smooth
- Conclusions

Section 1

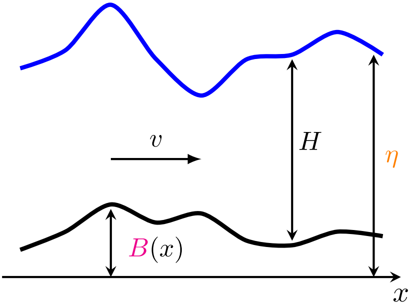
Governing equations

$$\frac{\partial}{\partial t}\boldsymbol{u} + div_{\boldsymbol{x}}\boldsymbol{F}(\boldsymbol{u}) = \boldsymbol{S}(\boldsymbol{x},\boldsymbol{u}), \quad (\boldsymbol{x},t) \in \Omega \times [0,T]$$

$$\boldsymbol{u} := \begin{pmatrix} H \\ H\boldsymbol{v} \end{pmatrix}$$

$$\boldsymbol{F}(\boldsymbol{u}) := \begin{pmatrix} H\boldsymbol{v} \\ H\boldsymbol{v}\otimes\boldsymbol{v} + g\frac{H^2}{2}\mathbb{I} \end{pmatrix}$$

$$\boldsymbol{S}(\boldsymbol{x},\boldsymbol{u}) := -\begin{pmatrix} 0 \\ gH\nabla_{\boldsymbol{x}}B(x) \end{pmatrix}$$



$$\eta := H + B$$

Shallow water equations, simplification of Euler (with gravity)

$$\frac{\partial}{\partial t}\boldsymbol{u} + div_{\boldsymbol{x}}\boldsymbol{F}(\boldsymbol{u}) = \boldsymbol{S}(\boldsymbol{x},\boldsymbol{u}), \quad (\boldsymbol{x},t) \in \Omega \times [0,T]$$

$$\boldsymbol{u} := \begin{pmatrix} H \\ H\boldsymbol{v} \end{pmatrix}$$

$$\boldsymbol{F}(\boldsymbol{u}) := \begin{pmatrix} H\boldsymbol{v} \\ H\boldsymbol{v}\otimes\boldsymbol{v} + g\frac{H^2}{2}\mathbb{I} \end{pmatrix}$$

$$\boldsymbol{S}(\boldsymbol{x},\boldsymbol{u}) := -\begin{pmatrix} 0 \\ gH\nabla_{\boldsymbol{x}}B(x) \end{pmatrix}$$

$$\rho \sim H$$

$$p \sim g\frac{H^2}{2}$$

$$\phi(x) \sim B(x)$$

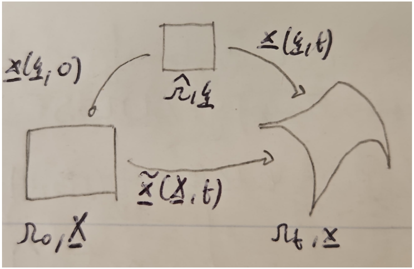
Neglecting the energy equation

Section 2

Scheme and motivation

Shallow water equations, Lagrangian (sorry for low quality)

$$\Omega_0 \ni \boldsymbol{X} \longrightarrow \boldsymbol{x} = \widetilde{\boldsymbol{x}}(\boldsymbol{X}, t) \in \Omega_t$$
$$\widehat{\Omega} \ni \boldsymbol{\xi} \longrightarrow \boldsymbol{x} = \boldsymbol{x}(\boldsymbol{\xi}, t) \in \Omega_t$$
$$\boldsymbol{X} = \boldsymbol{x}(\boldsymbol{\xi}, 0)$$



Shallow water equations, Lagrangian

- Motion

$$\frac{d}{dt}\boldsymbol{x}(\boldsymbol{\xi}, t) = \boldsymbol{v}(\boldsymbol{x}(\boldsymbol{\xi}, t), t)$$

- Water height/density (SMC)

$$H(\boldsymbol{x}(\boldsymbol{\xi}, t), t) = \frac{\widehat{H}(\boldsymbol{\xi})}{det\boldsymbol{J}(\boldsymbol{\xi}, t)}, \quad \boldsymbol{J}(\boldsymbol{\xi}, t) = \frac{\partial \boldsymbol{x}}{\partial \boldsymbol{\xi}}(\boldsymbol{\xi}, t)$$

- Velocity

$$\begin{aligned} H(\boldsymbol{x}, t)\frac{d}{dt}\boldsymbol{v}(\boldsymbol{x}, t) &= -\nabla_{\boldsymbol{x}} p - gH\nabla_{\boldsymbol{x}} B \\ &= -\nabla_{\boldsymbol{x}}\left(\frac{gH^2}{2}\right) - gH\nabla_{\boldsymbol{x}} B \end{aligned}$$

$$\frac{d}{dt}\boldsymbol{v}(\boldsymbol{x}, t) = -g\nabla_{\boldsymbol{x}}(H + B)$$

Shallow water equations, FEM discretization[1]

$\widehat{\varphi}_i \in \mathbb{P}_{M+1}$ continuous
$\widehat{\psi}_i \in \mathbb{P}_M$ discontinuous

$$\varphi_i(\boldsymbol{x}(\boldsymbol{\xi},t),t) = \widehat{\varphi}_i(\boldsymbol{\xi})$$

$$\psi_i(\boldsymbol{x}(\boldsymbol{\xi},t),t) = \widehat{\psi}_i(\boldsymbol{\xi})$$

$$\boldsymbol{x}_h(\boldsymbol{\xi},t) = \sum_i \boldsymbol{x}_i(t)\widehat{\varphi}_i(\boldsymbol{\xi})$$

$$\boldsymbol{v}_h(\boldsymbol{\xi},t) = \sum_i \boldsymbol{v}_i(t)\widehat{\varphi}_i(\boldsymbol{\xi})$$

$$H_h(\boldsymbol{\xi},t) = \sum_i H_i(t)\widehat{\psi}_i(\boldsymbol{\xi})$$

$$\boldsymbol{v}_h(\boldsymbol{x},t) = \sum_i \boldsymbol{v}_i(t)\widehat{\varphi}_i(\boldsymbol{\xi}(\boldsymbol{x},t))$$

$$H_h(\boldsymbol{x},t) = \sum_i H_i(t)\widehat{\psi}_i(\boldsymbol{\xi}(\boldsymbol{x},t))$$

[1] Dobrev, Kolev, Rieben, High-Order Curvilinear Finite Element Methods for Lagrangian Hydrodynamics, 2012

Shallow water equations, discretized equations

- Motion

$$\frac{d}{dt}\boldsymbol{x}_i(t) = \boldsymbol{v}_i(t)$$

- Water height/density (SMC) $\Rightarrow$ PP

$$H_i(t) = \frac{\widehat{H}_i}{det\boldsymbol{J}(\boldsymbol{\xi}_i, t)}, \quad \boldsymbol{J}(\boldsymbol{\xi}, t) = \frac{\partial \boldsymbol{x}}{\partial \boldsymbol{\xi}}(\boldsymbol{\xi}, t)$$

- Velocity

$$\sum_{K \in K_i} \sum_{\boldsymbol{x}_j \in K} \left(\int_K \varphi_i \varphi_j d\boldsymbol{x} \right) \frac{d}{dt}\boldsymbol{v}_j(t)$$
$$= -g \sum_{K \in K_i} \left[\int_K \varphi_i \nabla_{\boldsymbol{x}} (H_h + B_h) d\boldsymbol{x} \right] - \sum_{K \in K_i} \boldsymbol{CT}_i^K - \boldsymbol{ST}_i$$

Shallow water equations, discretized equations

$$\sum_{K\in K_i}\sum_{\boldsymbol{x}_j\in K}\left(\int_K \varphi_i\varphi_j d\boldsymbol{x}\right)\frac{d}{dt}\boldsymbol{v}_j(t)$$
$$= -g\sum_{K\in K_i}\left[\int_K \varphi_i\nabla_{\boldsymbol{x}}(H_h+B_h)d\boldsymbol{x}\right] - \sum_{K\in K_i}\boldsymbol{CT}_i^K - \boldsymbol{ST}_i$$

$$\boldsymbol{CT}_i^K = g\int_{\partial K}\varphi_i(\eta^* - \eta|_K)\boldsymbol{\nu}d\boldsymbol{\sigma}$$

$$\boldsymbol{ST}_i^{CIP} := \sum_f \alpha_f \left[\!\left[\frac{\partial}{\partial x}\varphi_i\right]\!\right]\left[\!\left[\frac{\partial}{\partial x}v\right]\!\right], \quad \boldsymbol{ST}_i^{LxF} := \sum_{K\in K_i}\alpha_K(\boldsymbol{v}_i - \overline{\boldsymbol{v}}_K)$$

Last but not least an ODE integrator

Problem: mass matrix

$$\sum_{K \in K_i} \sum_{\boldsymbol{x}_j \in K} \left(\int_K \varphi_i \varphi_j d\boldsymbol{x} \right) \frac{d}{dt} \boldsymbol{v}_j(t)$$

$$= -g \sum_{K \in K_i} \left[\int_K \varphi_i \nabla_{\boldsymbol{x}} (H_h + B_h) d\boldsymbol{x} \right] - \sum_{K \in K_i} \boldsymbol{CT}_i^K - \boldsymbol{ST}_i$$

$$\mathcal{M} \frac{d}{dt} \boldsymbol{v} = \boldsymbol{r}$$

Solutions

- LO mass lumping
- DeC Remi[2] (problems for order 4 on)
- Spectral methods $\varphi_i \sim \boldsymbol{x}_i$ (1D GLB, 2D tensor product or Cubature)

[2] Abgrall, High order schemes for hyperbolic problems using globally continuous approximation and avoiding mass matrices, 2017

Price to pay: time-dependent mass matrix

$$\int_{K(t)} \varphi_i(\boldsymbol{x},t)\varphi_j(\boldsymbol{x},t)d\boldsymbol{x} = \int_{\widehat{K}} \widehat{\varphi}_i(\boldsymbol{\xi})\widehat{\varphi}_j(\boldsymbol{\xi}) det\boldsymbol{J}(\boldsymbol{\xi},t)d\boldsymbol{\xi}$$
$$\approx \delta_{i,j}\widehat{\omega}_i det\boldsymbol{J}(\boldsymbol{\xi}_i,t)$$

$$\int_{K(t)} H_h(\boldsymbol{x},t)\varphi_i(\boldsymbol{x},t)\varphi_j(\boldsymbol{x},t)d\boldsymbol{x} = \int_{\widehat{K}} H_h(\boldsymbol{\xi},t)\widehat{\varphi}_i(\boldsymbol{\xi})\widehat{\varphi}_j(\boldsymbol{\xi}) det\boldsymbol{J}(\boldsymbol{\xi},t)d\boldsymbol{\xi}$$
$$\approx \delta_{i,j}\widehat{\omega}_i H_h(\boldsymbol{\xi}_i,t) det\boldsymbol{J}(\boldsymbol{\xi}_i,t)$$

However, only a point evaluation

Advantages

$$\frac{d}{dt}\boldsymbol{x} = \boldsymbol{v}, \quad \frac{d}{dt}\boldsymbol{v} = \boldsymbol{r}, \quad \text{SMC}$$

- Truly arbitrary high order (no problems as for Bernstein and β-limiting)
- Extendible to Euler
- Extendible to multi-D (quads, PGL, tensor products, Cubature)
- Whatever time integration method.

Section 3

Numerics

Sod

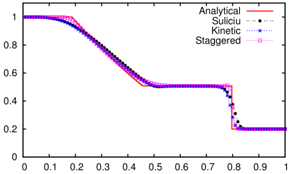
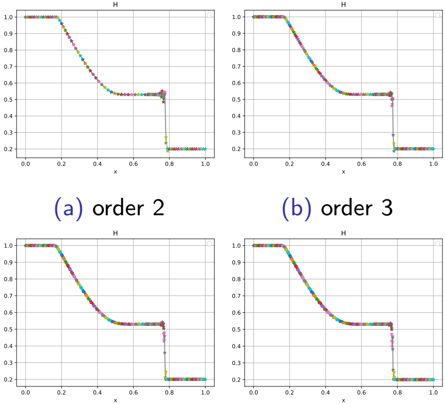


Figure: Reference



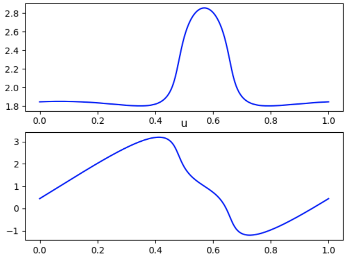
(a) order 2

(b) order 3

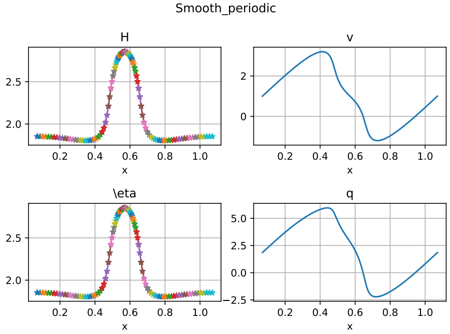
(c) order 4

(d) order 5

$$
\begin{cases}
H = 2 + cos(2\pi x) \\
v = 1
\end{cases}
$$



(a) Eulerian



(b) Lagrangian

Numerics, Convergence[3] ($2p$)

ORDER 2 P1P2

N	error x	Order x	Error v	Order v
50	2.850e-04	0.000	1.305e-02	0.000
100	7.166e-05	1.992	3.021e-03	2.111
200	1.798e-05	1.995	7.579e-04	1.995
400	4.504e-06	1.997	1.901e-04	1.996
800	1.127e-06	1.998	4.756e-05	1.999

ORDER 3 P2P3

N	error x	Order x	Error v	Order v
50	1.197e-06	0.000	9.768e-04	0.000
100	1.497e-07	2.999	4.086e-05	4.579
200	9.487e-09	3.980	4.666e-06	3.131
400	6.040e-10	3.973	3.973e-07	3.554
800	3.811e-11	3.986	2.878e-08	3.787

ORDER 4 P3P4 (final plateau probably due to the fact that H hit machine precision)

N	error x	Order x	Error v	Order v
50	2.696e-07	0.000	8.121e-05	0.000
100	7.205e-09	5.226	4.995e-06	4.023
200	7.689e-11	6.550	6.990e-08	6.159
400	1.060e-12	6.181	1.087e-09	6.007
800	1.739e-14	5.930	1.606e-10	2.758

ORDER 5 P4P5

N	error x	Order x	Error v	Order v
50	2.973e-08	0.000	3.642e-05	0.000
100	2.038e-10	7.188	2.641e-07	7.108
200	9.721e-13	7.712	1.196e-09	7.786

[3] Mantri, Oeffner, Ricchiuto, Fully well balanced entropy controlled DGSEM, 2022

Numerics, well-balancing

In particular (in Eulerian) $\frac{\partial}{\partial t}\boldsymbol{u} \equiv 0 \;\Leftrightarrow\; \frac{\partial}{\partial x}\boldsymbol{F}(\boldsymbol{u}) = \boldsymbol{S}(x, \boldsymbol{u})$

- Refine a lot the mesh $\Rightarrow$ Longer computational time
- Well-balancing

$$\boldsymbol{u}_{eq} := \begin{pmatrix} \eta - B \\ 0 \end{pmatrix}$$

$$\eta = H + B \equiv const$$

Figure: Lake of Zürich at rest

Lake at rest is exactly preserved

$$\frac{d}{dt}\boldsymbol{x} = \boldsymbol{v}, \quad \frac{d}{dt}\boldsymbol{v} = \boldsymbol{r}, \quad \text{SMC}$$

$$H(\boldsymbol{x}(\boldsymbol{\xi},t),t) = \frac{\widehat{H}(\boldsymbol{\xi})}{det\boldsymbol{J}(\boldsymbol{\xi},t)}, \quad \boldsymbol{J}(\boldsymbol{\xi},t) = \frac{\partial \boldsymbol{x}}{\partial \boldsymbol{\xi}}(\boldsymbol{\xi},t)$$

$$\sum_{K\in K_i}\sum_{\boldsymbol{x}_j\in K}\left(\int_K \varphi_i\varphi_j d\boldsymbol{x}\right)\frac{d}{dt}\boldsymbol{v}_j(t)$$
$$= -g\sum_{K\in K_i}\left[\int_K \varphi_i \nabla_{\boldsymbol{x}}(H_h + B_h)d\boldsymbol{x}\right] - \sum_{K\in K_i}\boldsymbol{CT}_i^K - \boldsymbol{ST}_i$$

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Non-smooth bathymetry, only C^0

$$\eta(x) = \begin{cases} \eta_{eq} + A \exp\left(1 - \frac{1}{1-\left(\frac{x-6}{0.5}\right)^2}\right) & 5.5 < x < 6.5 \\ \eta_{eq} & otherwise \end{cases}$$

with $A = 5 \cdot 10^{-5}$.

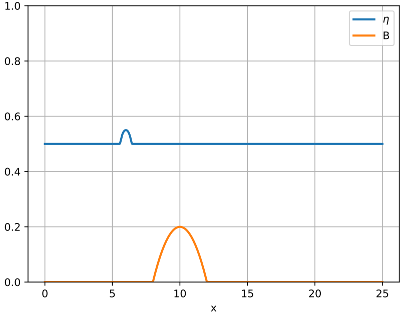
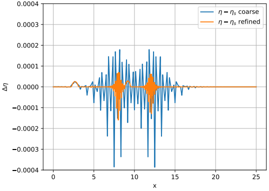
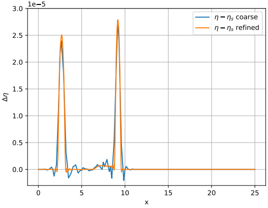


Figure: Perturbation amplified by 1000

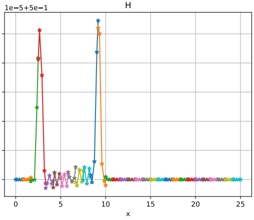
Order 5, 30 elements



(a) Eulerian, non WB

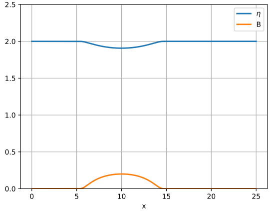


(b) Eulerian, WB

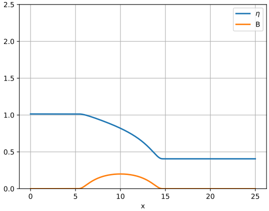


(c) Lagrangian

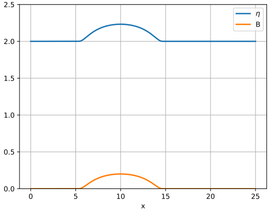
Numerics, smooth steady states



(a) Sub, $Hv \equiv 4.42$



(b) Trans, $Hv \equiv 1.53$



(c) Super, $Hv \equiv 24$

$$\boldsymbol{F}_x(\boldsymbol{u}) = \boldsymbol{S}(\boldsymbol{x}, \boldsymbol{u})$$

Numerics, supercritical (problem with order 3)

P1P2 -> order 2

N	L^1(v)	Order v	L^1(H)	Order H	L^1(q)	Order q	||v||_2	Order v	||H||_2	Order H
25	4.281e-02	0.000	1.837e-02	0.000	1.875e-01	0.000	3.024e-03	0.000	1.113e-03	0.000
50	1.021e-02	2.068	5.229e-03	1.813	4.787e-02	1.970	8.202e-04	1.882	3.348e-04	1.733
100	2.431e-03	2.070	9.872e-04	2.405	1.045e-02	2.196	1.884e-04	2.122	6.528e-05	2.359
200	4.775e-04	2.348	1.446e-04	2.771	1.928e-03	2.438	3.731e-05	2.336	1.091e-05	2.581
400	1.125e-04	2.086	2.981e-05	2.278	4.510e-04	2.096	8.973e-06	2.056	2.450e-06	2.155
800	2.793e-05	2.010	7.313e-06	2.027	1.126e-04	2.002	2.243e-06	2.000	6.048e-07	2.018

P2P3 -> order 3 (instead I get 2)

N	L^1(v)	Order v	L^1(H)	Order H	L^1(q)	Order q	||v||_2	Order v	||H||_2	Order H
25	9.342e-03	0.000	3.326e-03	0.000	3.702e-02	0.000	9.183e-04	0.000	3.003e-04	0.000
50	1.945e-03	2.264	7.998e-04	2.056	1.033e-02	1.841	1.574e-04	2.545	7.969e-05	1.914
100	4.239e-04	2.198	1.947e-04	2.038	2.180e-03	2.244	3.369e-05	2.224	1.590e-05	2.325
200	8.308e-05	2.351	3.091e-05	2.655	3.042e-04	2.841	6.592e-06	2.354	2.444e-06	2.702
400	1.833e-05	2.180	5.953e-06	2.376	4.774e-05	2.672	1.523e-06	2.114	4.756e-07	2.361
800	4.502e-06	2.026	1.455e-06	2.033	1.120e-05	2.092	3.758e-07	2.019	1.150e-07	2.048

P3P4 -> order 4

N	L^1(v)	Order v	L^1(H)	Order H	L^1(q)	Order q	||v||_2	Order v	||H||_2	Order H
25	3.877e-03	0.000	1.475e-03	0.000	1.573e-02	0.000	5.056e-04	0.000	2.086e-04	0.000
50	7.459e-04	2.378	3.024e-04	2.286	3.726e-03	2.078	6.793e-05	2.896	3.157e-05	2.724
100	9.525e-05	2.969	5.184e-05	2.544	6.887e-04	2.436	7.144e-06	3.249	4.526e-06	2.802
200	9.417e-06	3.338	4.700e-06	3.463	6.982e-05	3.302	6.768e-07	3.400	3.857e-07	3.553
400	3.955e-07	4.574	1.974e-07	4.573	2.982e-06	4.549	2.757e-08	4.618	1.556e-08	4.632

P4P5 -> order 5

N	L^1(v)	Order v	L^1(H)	Order H	L^1(q)	Order q	||v||_2	Order v	||H||_2	Order H
25	2.130e-03	0.000	8.068e-04	0.000	7.579e-03	0.000	2.959e-04	0.000	1.281e-04	0.000
50	3.021e-04	2.818	1.253e-04	2.687	1.390e-03	2.447	2.776e-05	3.414	2.241e-05	2.515
100	2.822e-05	3.420	1.237e-05	3.340	1.310e-04	3.407	2.418e-06	3.521	2.042e-06	3.456
200	1.202e-06	4.553	5.293e-07	4.547	6.777e-06	4.273	9.730e-08	4.635	7.038e-08	4.859

Numerics, debugging in progress

- Burman (no changes)
- SSPRK4 (no changes)
- one time-step (correct order)
- Exact v (OK)
- Exact H (Not OK, so the problem must be in the update of v)
- Checking the code

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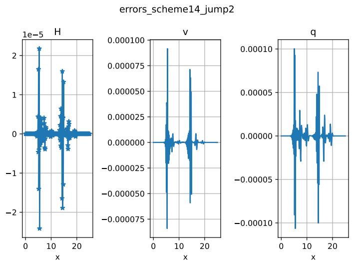
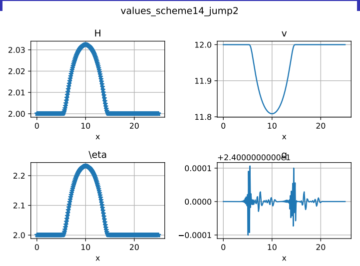
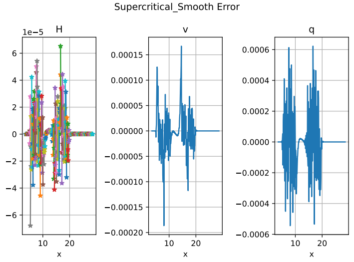
Numerics, shape of the error



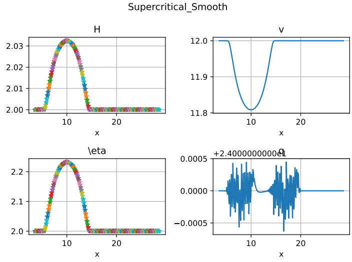
(a) Error Eulerian



(b) Values Eulerian

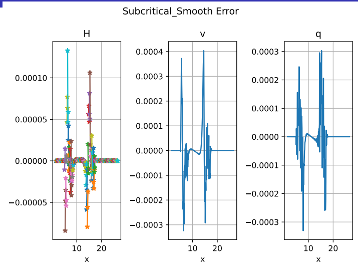


(c) Error Lagrangian

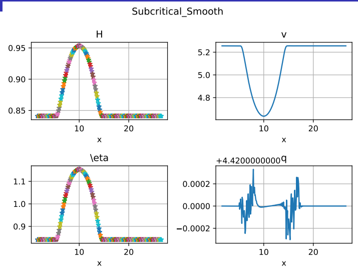


(d) Values Lagrangian

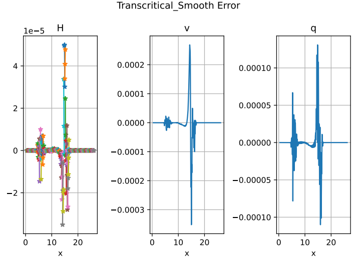
Numerics, shape of the error



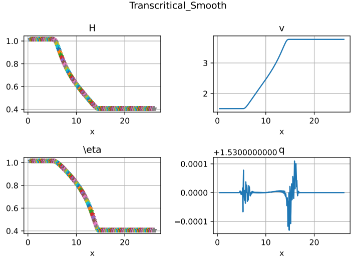
(a) Error Subcritical



(b) Values Subcritical



(c) Error Transcritical



(d) Values Transcritical

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Section 4

Conclusions

Conclusions

- Spectral approach and advantages
- Some results
- Some problems that hopefully are due to a bug

Thanks


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