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Studying the logging capability of Windows Telemetry component using Reverse Engineering

Tesis de Licenciatura en Ciencias de la Computación

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ABSTRACT (ENGLISH VERSION)

Windows, one of the most popular OS, has a component called Telemetry. It collects information from the system with the goal of analyzing and fixing software & hardware problems, improving the user experience, among others. The kind of information that can be obtained by this component is partially configurable in four different levels: security, basic, enhanced and full, being "security" the level where less information is gathered and "full" the opposite case.

How Telemetry stores/process/administrates the information extracted? It employs a widely used framework called Event Tracer for Windows (ETW) [4]. Embedded not only in userland application but also in the kernel modules, the ETW framework has the goal of providing a common interface to log events and therefore help to debug and log system operations, by instrumenting it.

In this work, we are going to analyze a part of the Windows kernel to better understand how Telemetry works from an internal perspective. This work will make windows analysts, IT admins or even windows users, more aware about the functionality of the Telemetry component helping to deal with privacy issues, bug fixing, knowledge of collected data, etc. Our analysis implies performing reverse engineering [5],[6] on the Telemetry component, which involves challenging processes such as kernel debugging, dealing with undocumented kernel internal structures, reversing of bigger frameworks (i.e. ETW), binary libraries which lack symbols, etc. As part of the analysis we will also develop an in depth comparison between the differences among each level of Telemetry, stressing the contrast in the amount of events written, verbosity of information, etc. Finally, we will study how the communication between the Windows instance and the Microsoft backend servers is carried out.

ABSTRACT (SPANISH VERSION)

ACKNOWLEDGMENTS

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1. MOTIVATION

The following analysis was performed against the Telemetry component of the Windows OS, with looking forward to achieve the following goals:

- \bullet Understand how the process of generating logs was carried out.
- $\bullet\,$ How, where and what logs were stored.
- Which applications are involved in gathering Telemetry information

2. INTRODUCTION

The analysis presented, was carried out in a particular version of the Windows OS. Specifically, Windows 10 64 bits Enterprise, 1607. Windows delivers a new version, usually, each .. Some words about ERNW and the project with the FBI

There are several reasons why this version was chosen:

- It was one of the mainstream version of Windows at the moment of starting the project.
- It was a long support version (EOS: April 2019).
- It was used by the German Police Office

2.1 Basic concepts

This section will describe basic concepts needed to fully understand the carried out process to perform the analysis.

2.1.1 Reverse Engineering

Software engineering can be defined as the process of designing, building and testing computer software. The processor of a computer, works with 1's and 0's, therefore developing any kind of sofware will mean

Key concepts about what RE means, from a general perspective, how it should tackled which tools are usually there. 64 bits, calling convention ..

2.1.2 Debugging

Explaniation of the concept of debugging, what is the different with doing static RE. Some words specifically for KERNEL debugging.

2.2 Tools

2.2.1 IDA pro

Introduction to IDA pro. Explaniation of what it is and how it works.talk about hxrays

2.2.2 WinDBG

Introduction to WINDBG. Explaniation of what it is and how it works.

2.2.3 YARA

2.2.4 XPERF?

2.3 Windows components

$2.3.0.1 \quad \text{Event Tracing for Windows}$

Complete explainiation of how it works due to its importance for the rest of the analysis. Different components: session, providers, consumers ,etc . Talk about the guid of the providers

2.3.0.2 Telemetry

Full description of the different features / characteristic which are involved in this analysis. Explaniation of how the worflow of the data is followed. talk about the name of the session, the levels of configuration, when it can be configured.. etc.

3. PREVIOUS WORK

Some lines about previous works in this topic. Most of them focused on just analysis from traffic / documentation.

4. ANALYSIS

Several files (dynamic libraries, executables, drivers) were analyzed and reversed in order to achieve the aforementioned goals. However, the main analysis was performed in the **ntoskrnl.exe** file, which is the one holding the actual implementation of the Windows Kernel.

It's important to stress that most of the general analysis was carried out using the Basic level of Telemetry.

Further sections will depict different challenges and achievements faced during the analysis.

4.1 Understanding how Telemetry makes use of ETW

Where, who and what were some of the questions that needed to be answered in order to be able to get information about the providers that were registered against the DiagTrack session. It's possible to obtain the whole list of providers registered to a particular session, by executing the following powershell command:

```
Get-EtwTraceProvider | where {$\( \). SessionName -match "<SESSION_NAME>"}
```

Fig. 4.1: Powershell comand to list ETW providers registered against a particular session.

One way to answer all the aforementioned questions, was to intercept the moment when some provider was going to write a message. If a breakpoint was set at that exact moment, it would be possible to gather information such as:

- 1. The piece of code that triggered the write (by inspecting the call stack of the function).
- 2. The actual content of the log being written.

However, the function being used for executing writes (**EtwWrite**) was not just used by the providers attached to the DiagTrack session but also by all the providers using the ETW framework. It was necessary to find a way to filter them and only intercept the ones important for the analysis.

Using ??, it was possible to extract a GUID's list of the providers that were attached to the DiagTrack session. With this information, it would be possible to make the breakpoint to be triggered only when the provider's GUID that was trying to write was in the list.

Nevertheless, this strategy had one minor issue. The function (**EtwWrite**) had five parameters and none of them would show directly the GUID:

```
NTSTATUS EtwWrite(

REGHANDLE RegHandle,
PCEVENT_DESCRIPTOR EventDescriptor,
LPCGUID ActivityId,
ULONG UserDataCount,
PEVENT_DATA_DESCRIPTOR UserData
);
```

Fig. 4.2: Documentation for EtwWrite function ¹.

The first parameter is the registration handler. This object is returned once the provider executed the registration (**EtwRegister**) successfully. On the other hand, the **EtwRegister** receives the GUID as parameter:

```
C++

NTSTATUS EtwRegister(
LPCGUID ProviderId,
PETWENABLECALLBACK EnableCallback,
PV0ID CallbackContext,
PREGHANDLE RegHandle
);
```

Fig. 4.3: Documentation for EtwRegister function ².

Therefore, in order to perform the cross-check it was not enough with information from the **EtwWrite** function, but also information from the **EtwRegister** was needed. To summarize, to understand if the write was being done by a provider registered against the DiagTrack session it was necessary to:

- 1. Extract the whole list of providers registered attached to the DiagTrack session.
- 2. Intercept all the **EtwRegister** executions and check if the GUID being used was inside the list.
- 3. If it was, save the handler.
- 4. Intercept all the **EtwWrite** executions and check if the handler being used is one of the stored handlers.
- 5. If it was, the provider that is writing, is attached to the DiagTrack session.

Even though the strategy seemed to be theoretically promising, it was necessary to understand how to actually carry out these actions. Further sections will depict that process.

4.1.1 Reversing registration process

As mentioned in section 2.3.0.1, whenever a provider wants to register itself against a particular session, it has to call the function **EtwWrite**. Because of this, the first step was to analyze the behavior of this function, using **IDA**(2.2.1). As we can see in ??, the only action being performed by **EtwRegister**, was a call to another function named **EtwpRegisterProvider**.

```
sub
        rsp, 48h
        r10, rcx
mov
        PsGetCurrentServerSiloGlobals
call
        [rsp+48h+a7], r9; a7
mov
        r9, rdx
mov
        rdx, r10
                         ; ptr_guid
mov
        rcx, [rax+350h]; a1
mov
        rax, [rsp+48h]
mov
        [rsp+48h*ptr_to_handler], rax ; __int64
mov
mov
        [rsp+48h+a5], r8; a5
        r8d, 3
mov
call
        EtwpRegisterProvider ;
```

Fig. 4.4: Dissasembly of ETWRegister function

A quick analysis of the latter function showed that, apparently, this was the function holding the actual implementation of the registration process. However, due to the lack of documentation regarding this function, it was necessary to understand in a more in-depth way what was actually happening. Following chapters will present a detailed description of reversing (partially, only the interesting parts for this research) **EtwpRegisterProvider**. To make it easier, it will be divided in different parts:

- Understanding the layout of the function
- Check if a GUID for this provider already exists.
- If not found, create a new one.
- Create new entry and get the handler

4.1.1.1 Understanding the layout of the function

EtwpRegisterProvider received seven parameters:

```
signed __int64 __fastcall EtwpRegisterProvider(__int64 a1, _QWORD *a2,
    int a3, void (__fastcall *a4)(ULONG_PTR, __int64, __int128 *,
    __int64), __int64 a5, __int64 a6, __int64 *a7)
```

Usually when performing reverse engineering, it is not necessary to understand every tiny detail, but only the key points that are important to meet the proposed goals. This wasn't the exception.

The main focus here was not to understand how the registration process fully worked but just to get an idea of it plus get to know the relation between GUID and registration handler.

After understanding a little bit more about this function, it was possible to conclude that:

1. **a1**: Is the pointer to a structure.

- 2. **a2**: Is the pointer to the GUID structure.
- 3. **a7**: Is the address where the pointer to the registration handler will be placed (can be think as "function output").

What is this **a1** structure? The figure 4.4 shows that before calling **EtwpRegister-Provider**, the function **PsGetCurrentServerSiloGlobals** is invoked. This latter one returns a pointer to a structure S of type **ESERVERSILO_GLOBALS**.

```
kd> dt nt!_ESERVERSILO_GLOBALS
   +0x000 ObSiloState
                                   OBP SILODRIVERSTATE
                                  _SEP_SILOSTATE
   +0x2e0 SeSiloState
                                   SEP_RM_LSA_CONNECTION_STATE
tr64 _ETW_SILODRIVERSTATE
   +0x300 SeRmSiloState
                                  Ptr64
   +0x350 EtwSiloState
   +0x358 MiSessionLeaderProcess : Ptr64 EPROCESS
   +0x360 ExpDefaultErrorPortProcess
                                             Ptr64 _EPROCESS
   +0x368 ExpDefaultErrorPort
                                   : Ptr64 Void
   +0x370 HardErrorState
                                  Uint4B
   +0x378 WnfSiloState
                                   WNF_SILODRIVERSTATE
                                  \overline{P}tr6\overline{4} Void
   +0x3b0 ApiSetSection
   +0x3b8 ApiSetSchema
                                  Ptr64
   +0x3c0 OneCoreForwardersEnabled
                                 ame : _UNICODE_STRING
Ptr64 PSP CTORY
                                           UChar
   +0x3c8 SiloRootDirectoryName :
   +0x3d8
           Storage
                                   SERVERSILO_STATE
           State
   +0x3e0
   +0x3e4 ExitStatus
                                  Int4B
                                          KEVENT
   +0x3e8 DeleteEvent
                                  Ptr64
   +0x3f0 UserSharedData : _SILO_USER_SHARED_DATA
+0x410 TerminateWorkItem : _WORK_QUEUE_ITEM
```

Fig. 4.5: $_$ ESERVERSILO $_$ GLOBALS structure layout (S).

However, the first parameter provided to **EtwpRegisterProvider** is not the pointer to S but is the pointer to another structure S_2 of type **_ETW_SILODRIVERSTATE**. which is part S, more precisely, it is situated at the offset 0x350.

Fig. 4.6: $_$ ETW $_$ SILODRIVERSTATE structure layout (S_2) .

With all this information, was possible to conclude that **a1** will point to a global structure holding configurations, settings and information in general directly related with the **ETW** framework. In the other hand, **a2** and **a7** will hold pointers to a GUID and to a place were a registration handler will be placed afterwards, respectively. With the knowledge of the purpose of just these three parameters, was possible to move forward.

4.1.1.2 Check if GUID for this provider already exists

Once inside the EtwpRegisterProvider function, after performing some sanity checks, it tries to get the guid entry related with the GUID. If it doesn't exist, it will create one.

Fig. 4.7: First lines of EtwpRegisterProvider

In this section, the focus will be on understanding how the process of recovering the already existing "GUID entry" works.

The action of recovering is performed by a particular function called **EtwpFind-GuidEntryByGuid**:

```
ptr_guid_entry = (char *)EtwpFindGuidEntryByGuid(etw_silo, ptr_guid, 0);
```

As can be inferred from the previous line, two important parameters are provided: the **ETWSILODRIVERSTATE**(a1) structure S and the pointer to the GUID ptr_guid .

EtwpFindGuidEntryByGuid proc near

```
arg_8= qword ptr 10h
arg_10= qword ptr 18h
        [rsp+arg_8], rbx
mov
        [rsp+arg_10], rbp
mov
push
        rsi
push
        rdi
push
        r12
        r14
push
        r15
push
        rsp, 20h
sub
        eax, [rdx+8]
mov
        rcx, 590h
add
        eax, [rdx+0Ch]
xor
        r12d, r12d
xor
        eax, [rdx+4]
xor
        rdi, rdx
mov
        eax, [rdx]
xor
        r14d, r12d
mov
        eax, 3Fh
and
        rsi, r8d
movsxd
        rax, 38h
imul
        rsi, 4
shl
        rcx, rax
add
mov
        rax, gs:188h
add
        rsi, rcx
        word ptr [rax+1E4h]
dec
lea
        rbp, [rcx+30h]
        r8d, r8d
xor
```

Fig. 4.8: First basic block of EtwpFindEntryByGuid.

Figure 4.6 depicts how the function gets the guid entry related to the provider (if it exists). rcx holds the pointer to S and rdx holds ptr_guid .

The first highlight is the add function, which stores in rcx the pointer to the structure stored at the offset 0x590 of S. Going back to the structure layout of S (figure 4.6), it can be appreciated that at the offset 0x590, the structure EtwpGuidHashTable of type $_ETW_HASH_BUCKET$ [64] is present. Figure 4.10 depicts its layout.

Just before the add function, eax is filled with the content of the address rdx + 8. rdx held the ptr_guid , meaning that eax will have the third group of 4 bytes inside of the guid structure. Why the third? Because the offset was 8. Why 4 bytes? Because the register eax (32 bits) was used.

In the following lines, the value of eax is being constantly modified by xoring it, successively with the different group of 4 bytes that compose the guid structure³. After performing this successive xor operations, an and function is applied against eax using a mask of 0x3f and lastly multiplies the result of it against 0x38 (size of ETW_HASH_BUCKET structure). Finally, the value of rax(eax) is added to rcx which had the pointer to the EtwpGuidHashTable structure.

Writing the aforementioned function in a pseudo-code style (ptr is a short version of "pointer"):

```
xor_guid_parts = ptr_guid[0] ^ ptr_guid[1] ^ ptr_guid[2] ^ ptr_guid[3]
ptr_hash_table = ptr_S + 0x590
ptr_bucket = ptr_hash_table + 0x38 * ((xor_guid_parts) & 0x3F)
```

Therefore, ptr_bucket is basically a pointer to a particular bucket inside the EtwpGuidHashTable, calculated based on the GUID of the provider. Once this value is determined, a "look up" inside the structure is carried out in the following way:

```
iterator = *ptr_bucket;
if ( *ptr_bucket != ptr_bucket )
{
    while ( 1 )
    {
        v12 = *ptr_guid_cpy - iterator[3];
        if ( *ptr_guid_cpy == iterator[3] )
            v12 = ptr_guid_cpy[1] - iterator[4];
        if ( !v12 && EtwpReferenceGuidEntry((ULONG_PTR)iterator) )
            break;
        iterator = (_QWORD *)*iterator;
        if ( iterator == ptr_bucket )
            goto LABEL_13;
    }
    v4 = iterator;
}
```

Fig. 4.9: Part of EtwpFindEntryByGuid function extracted using IDA Hex-Rays plugin.

³ Sometimes the structures weren't documented at all. Sometimes they were, but was not possible to find it until some kind of clue pointing to it was found. So far the layout of the structure pointed by *ptr_guid* was unknown, however from this function it was possible to conclude that the structure had a size of 16 bytes.

```
kd> dt nt!_ETW_HASH_BUCKET
+0x000 ListHead : [3] _LIST_ENTRY
+0x030 BucketLock : EX PUSH LOCK
```

Fig. 4.10: _ETW_HASH_BUCKET structure layout.

At first an iterator is built. This iterator will point initially to the Flink of the first list entry⁴ of the bucket (figure 4.10). The right-after if will capture the special case were the list is empty. In that particular case, the whole cycle will be skipped and the **LABEL_13** (routine to exit, which isn't displayed in the figure) will be executed. The only important thing of this routine is that it executes a return statement with the value of the variable v4 (which is initially defined as 0).

If the list is not empty, the first operation which is carried out is a subtraction between the first quadword of the GUID and a value of iterator[3]. Due to the variable iterator is defined as a 8-bytes pointer, iterator[3] will point to the offset 0x18 of the structure stored inside the Flink. In the case that both values are equal, the second comparison (between the second quadword of the GUID and the iteartor[4]) is carried out.

At this point some things can be concluded:

- The cycle is iterating a double-linked-list which holds a particular structure T.
- T has the GUID of the provider stored at offset 0x18
- Again, seems that the GUID is 16 bytes long.
- From the function name, it can concluded that T is structure that represents the GUID entry.

Continuing with the code analysis, if some of the comparisons failed, the iterator changes its values to the next one in the list. Before continuing, it ensures that the cycle is not finished by checking if the actual value of the iterator is the same one used as the starting point. If they are equal, the exit routine is executed meaning that the return value will be 0.

If both comparisons are equal (the GUID of the provider and the one stored in T are the same), a function called EtwpReferenceGuidEntry with the current value of the iterator as parameter, is called. After this execution, the cycle is finished by the break statement. However, before executing the exit routine, the value of v4 is filled up with the value of the iterator, meaning that the return value will be pointer to the guid entry related to the GUID of the provider. The EtwpReferenceGuidEntry function just made some security checks not relevant for this task.

Therefore, as a summary, it is possible to say that:

The function EtwpFindGuidEntryByGuid looks for a particular structure (most probably called guid entry), which is stored inside a double-linked-list of a bucket inside the EtwpGuidHashTable of the ETWSILODRIVERSTATE, based on doing some mathematical operations with the GUID of the provider.

After finishing with this anlaysis,

⁴ https://docs.microsoft.com/en-us/windows/desktop/api/ntdef/ns-ntdef_list_entry

4.1.1.3 If not found, create a new one

In the previous section, it was explained how the

4.1.1.4 Create new entry and get the handler

- 1. We couldn't ensure that the data was being written was actually going to the DiagTrack session
- 4.2 When and how providers are registered
- 4.3 How writes are carried out
- 4.4 Relation between ETW session and ETW providers
- 4.5 Identifying the buffers
- 4.6 Provider GUID vs Group Provider GUID
- 4.7 Checking correctness of logged events
- 4.8 Automatization of event logging
- 4.9 Service isolation
- 4.10 Triggers
- 4.11 searching for new triggers

YARA

- 4.12 Difference among configuration levels of telemtry
- 4.13 Analysis of sent data over the channel to Microsfot backend services

5. RESULTS

6. CONCLUSIONS

GDPR?

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