

Macrologit: Logit-Space Laplace Approximation for MacroTaylor

We consider an ensemble of N_{ch} independent Markov channels with K microscopic states. The macroscopic occupancy vector is

$$\mathbf{p} = (p_1, \dots, p_K), \quad p_i \geq 0, \quad \sum_{i=1}^K p_i = 1.$$

Over a single interval we observe a scalar current y with MacroTaylor likelihood

$$F_{\text{data}}(\mathbf{p}) = \frac{1}{2} \log V(\mathbf{p}) + \frac{1}{2} \frac{\delta(\mathbf{p})^2}{V(\mathbf{p})},$$

where

$$\mu_y(\mathbf{p}) = N_{\text{ch}} (\mathbf{p} \cdot \boldsymbol{\gamma}), \quad \delta(\mathbf{p}) = y - \mu_y(\mathbf{p}), \quad V(\mathbf{p}) = \epsilon^2 + N_{\text{ch}} (\mathbf{p} \cdot \boldsymbol{\sigma}^2).$$

Here $\boldsymbol{\gamma}$ is the per-state single-channel current and $\boldsymbol{\sigma}^2$ the per-state intrinsic variance (MacroTaylor objects).

A ‘‘Gaussian on the simplex’’ prior is specified by a per-channel covariance $\boldsymbol{\Sigma}$ (rank $K-1$ on the simplex) and a prior mean $\boldsymbol{\mu}$. The corresponding fraction-level prior for \mathbf{p} is

$$F_{\text{prior}}(\mathbf{p}) = \frac{N_{\text{ch}}}{2} (\mathbf{p} - \boldsymbol{\mu}) \boldsymbol{\Sigma}^{-1} (\mathbf{p} - \boldsymbol{\mu})^\top.$$

The exact negative log-posterior in \mathbf{p} is

$$F_{\text{exact}}(\mathbf{p}) = F_{\text{data}}(\mathbf{p}) + F_{\text{prior}}(\mathbf{p}).$$

MacroTaylor provides explicit formulas for the gradient $\mathbf{g}_p(\mathbf{p}) = \nabla_{\mathbf{p}} F_{\text{exact}}(\mathbf{p})$ and Hessian $\mathbf{H}_p(\mathbf{p}) = \nabla_{\mathbf{p}}^2 F_{\text{exact}}(\mathbf{p})$, with a rank-2 data curvature in the directions spanned by $\boldsymbol{\gamma}$ and $\boldsymbol{\sigma}^2$.

1. Softmax parametrisation of the simplex

We introduce unconstrained logits $\boldsymbol{\theta} \in \mathbb{R}^{K-1}$ by choosing state K as reference (gauge). Define the extended logit vector

$$\tilde{\boldsymbol{\theta}} = (\theta_1, \dots, \theta_{K-1}, 0) \in \mathbb{R}^K,$$

and the normalising constant

$$Z(\boldsymbol{\theta}) = \sum_{j=1}^K \exp(\tilde{\theta}_j) = 1 + \sum_{k=1}^{K-1} \exp(\theta_k).$$

Softmax definition. The softmax (reference-state) map $\boldsymbol{\theta} \mapsto \mathbf{p}(\boldsymbol{\theta})$ is

$$p_i(\boldsymbol{\theta}) = \frac{\exp(\tilde{\theta}_i)}{Z(\boldsymbol{\theta})}, \quad i = 1, \dots, K.$$

Explicitly:

$$p_i(\boldsymbol{\theta}) = \frac{\exp(\theta_i)}{Z(\boldsymbol{\theta})}, \quad i = 1, \dots, K-1, \quad p_K(\boldsymbol{\theta}) = \frac{1}{Z(\boldsymbol{\theta})}.$$

By construction

$$p_i(\boldsymbol{\theta}) > 0, \quad \sum_{i=1}^K p_i(\boldsymbol{\theta}) = 1 \quad \text{for all } \boldsymbol{\theta}.$$

Softmax Jacobian. The Jacobian $J(\boldsymbol{\theta}) = \partial \mathbf{p} / \partial \boldsymbol{\theta}$ is a $K \times (K-1)$ matrix with entries

$$J_{ij}(\boldsymbol{\theta}) = \frac{\partial p_i}{\partial \theta_j}, \quad i = 1, \dots, K, \quad j = 1, \dots, K-1.$$

For $i \leq K-1$ and $j \leq K-1$:

$$\frac{\partial p_i}{\partial \theta_j} = p_i(\delta_{ij} - p_j),$$

and for the reference state K :

$$\frac{\partial p_K}{\partial \theta_j} = -p_K p_j, \quad j = 1, \dots, K-1.$$

Equivalently, in block form, write

$$\mathbf{p}_{1:K-1} = \begin{bmatrix} p_1 \\ \vdots \\ p_{K-1} \end{bmatrix}, \quad \mathbf{p}_{1:K-1} \mathbf{p}_{1:K-1}^\top \in \mathbb{R}^{(K-1) \times (K-1)}.$$

Then

$$J(\boldsymbol{\theta}) = \begin{bmatrix} \text{diag}(\mathbf{p}_{1:K-1}) - \mathbf{p}_{1:K-1} \mathbf{p}_{1:K-1}^\top \\ -p_K \mathbf{p}_{1:K-1}^\top \end{bmatrix}.$$

Because $\sum_i p_i(\boldsymbol{\theta}) \equiv 1$, we have

$$\mathbf{1}^\top J(\boldsymbol{\theta}) = \mathbf{0}^\top, \quad J(\boldsymbol{\theta})^\top \mathbf{1} = \mathbf{0},$$

so the image of J lies in the tangent space of the simplex: all allowed perturbations $\delta \mathbf{p} = J \delta \boldsymbol{\theta}$ satisfy $\mathbf{1}^\top \delta \mathbf{p} = 0$.

2. Prior and posterior in logit space

We place a Gaussian prior on $\boldsymbol{\theta}$:

$$\boldsymbol{\theta} \sim \mathcal{N}(\boldsymbol{m}, \boldsymbol{S}),$$

with mean $\boldsymbol{m} \in \mathbb{R}^{K-1}$ and covariance $\boldsymbol{S} \in \mathbb{R}^{(K-1) \times (K-1)}$. The prior contribution to the energy is

$$F_{\text{prior}}(\boldsymbol{\theta}) = \frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{m})^\top \boldsymbol{S}^{-1}(\boldsymbol{\theta} - \boldsymbol{m}) \quad (+ \text{ constant}).$$

The MacroTaylor data term becomes a function of $\boldsymbol{\theta}$ via $\boldsymbol{p}(\boldsymbol{\theta})$:

$$F_{\text{data}}(\boldsymbol{\theta}) = F_{\text{data}}(\boldsymbol{p}(\boldsymbol{\theta})).$$

The exact negative log-posterior in logit space is therefore

$$F_{\text{exact}}(\boldsymbol{\theta}) = F_{\text{data}}(\boldsymbol{p}(\boldsymbol{\theta})) + \frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{m})^\top \boldsymbol{S}^{-1}(\boldsymbol{\theta} - \boldsymbol{m}).$$

3. Gradient in logit space

Let $\boldsymbol{g}_p(\boldsymbol{p})$ denote the MacroTaylor gradient of F_{exact} with respect to \boldsymbol{p} , treated as a row vector:

$$\boldsymbol{g}_p(\boldsymbol{p}) = \nabla_{\boldsymbol{p}} F_{\text{exact}}(\boldsymbol{p}).$$

By the chain rule,

$$\boldsymbol{g}_\theta(\boldsymbol{\theta}) = \nabla_{\boldsymbol{\theta}} F_{\text{exact}}(\boldsymbol{\theta}) = (\boldsymbol{\theta} - \boldsymbol{m})^\top \boldsymbol{S}^{-1} + J(\boldsymbol{\theta})^\top \boldsymbol{g}_p(\boldsymbol{p}(\boldsymbol{\theta})).$$

This is the gradient used in Newton or quasi-Newton updates in logit space.

4. Hessian and Laplace covariance in logit space

For the data term,

$$F_{\text{data}}(\boldsymbol{\theta}) = F_{\text{data}}(\boldsymbol{p}(\boldsymbol{\theta})),$$

we have

$$\begin{aligned} \nabla_{\boldsymbol{\theta}} F_{\text{data}} &= J(\boldsymbol{\theta})^\top \boldsymbol{g}_p(\boldsymbol{p}), \\ \nabla_{\boldsymbol{\theta}}^2 F_{\text{data}} &= J(\boldsymbol{\theta})^\top \boldsymbol{H}_p(\boldsymbol{p}) J(\boldsymbol{\theta}) + \sum_{i=1}^K g_{p,i}(\boldsymbol{p}) \nabla_{\boldsymbol{\theta}}^2 p_i(\boldsymbol{\theta}), \end{aligned}$$

where $\mathbf{H}_p(\mathbf{p})$ is the MacroTaylor Hessian in \mathbf{p} and $g_{p,i}$ is the i -th component of \mathbf{g}_p .

The exact posterior Hessian in logit space is

$$\mathbf{H}_\theta(\boldsymbol{\theta}) = \nabla_{\boldsymbol{\theta}}^2 F_{\text{exact}}(\boldsymbol{\theta}) = \mathbf{S}^{-1} + J(\boldsymbol{\theta})^\top \mathbf{H}_p(\mathbf{p}) J(\boldsymbol{\theta}) + \sum_{i=1}^K g_{p,i}(\mathbf{p}) \nabla_{\boldsymbol{\theta}}^2 p_i(\boldsymbol{\theta}).$$

Near the MAP $\boldsymbol{\theta}^*$ the last term (curvature of the softmax mapping itself) is typically small when the posterior is concentrated. A Gauss–Newton approximation drops this term:

$$\mathbf{H}_\theta(\boldsymbol{\theta}^*) \approx \mathbf{S}^{-1} + J(\boldsymbol{\theta}^*)^\top \mathbf{H}_p(\mathbf{p}(\boldsymbol{\theta}^*)) J(\boldsymbol{\theta}^*).$$

The logit-space Laplace covariance is then

$$\boldsymbol{\Sigma}_\theta^{\text{post}} \approx \mathbf{H}_\theta(\boldsymbol{\theta}^*)^{-1}.$$

5. Induced mean and covariance in occupancy space

The posterior over \mathbf{p} induced by the Gaussian posterior in $\boldsymbol{\theta}$ is logistic-normal and skewed. We approximate its first two moments by a Taylor expansion of $\mathbf{p}(\boldsymbol{\theta})$ around $\boldsymbol{\theta}^*$.

Write the i -th component as $p_i(\boldsymbol{\theta})$ and denote its gradient and Hessian with respect to $\boldsymbol{\theta}$ at $\boldsymbol{\theta}^*$ by

$$\mathbf{j}_i := \nabla_{\boldsymbol{\theta}} p_i(\boldsymbol{\theta})|_{\boldsymbol{\theta}^*} \in \mathbb{R}^{K-1}, \quad \mathbf{H}_i := \nabla_{\boldsymbol{\theta}}^2 p_i(\boldsymbol{\theta})|_{\boldsymbol{\theta}^*} \in \mathbb{R}^{(K-1) \times (K-1)}.$$

By definition,

$$\mathbf{j}_i^\top \text{ is the } i\text{-th row of } J(\boldsymbol{\theta}^*).$$

Second-order mean (default). Using a second-order Taylor expansion and taking the Gaussian expectation, the mean of p_i is approximated by

$$\mathbb{E}[p_i] \approx p_i(\boldsymbol{\theta}^*) + \frac{1}{2} \text{tr}(\mathbf{H}_i \boldsymbol{\Sigma}_\theta^{\text{post}}), \quad i = 1, \dots, K.$$

Thus our default Macrologit posterior mean in occupancy space is

$$(\boldsymbol{\mu}_p)_i \approx p_i(\boldsymbol{\theta}^*) + \frac{1}{2} \text{tr}(\mathbf{H}_i \boldsymbol{\Sigma}_\theta^{\text{post}}).$$

The softmax Hessians \mathbf{H}_i can be computed analytically from the definition $p_i(\boldsymbol{\theta}) = \exp(\tilde{\theta}_i)/Z(\boldsymbol{\theta})$. (For implementation: derive $\nabla_{\boldsymbol{\theta}}^2 p_i$ once symbolically and reuse it.)

First-order covariance (delta method). For the covariance we keep the first-order (delta method) approximation: to first order in $(\boldsymbol{\theta} - \boldsymbol{\theta}^*)$,

$$\mathbf{p}(\boldsymbol{\theta}) \approx \mathbf{p}(\boldsymbol{\theta}^*) + J(\boldsymbol{\theta}^*)(\boldsymbol{\theta} - \boldsymbol{\theta}^*),$$

so

$$\boldsymbol{\Sigma}_p \approx J(\boldsymbol{\theta}^*) \boldsymbol{\Sigma}_\theta^{\text{post}} J(\boldsymbol{\theta}^*)^\top.$$

Because $J(\boldsymbol{\theta}^*)$ satisfies $\mathbf{1}^\top J(\boldsymbol{\theta}^*) = \mathbf{0}^\top$, the induced covariance obeys

$$\boldsymbol{\Sigma}_p \mathbf{1} = \mathbf{0}, \quad \mathbf{1}^\top \boldsymbol{\Sigma}_p = \mathbf{0}^\top,$$

so all fluctuations lie in the tangent space of the simplex and the sum of probabilities is preserved.

If desired, a purely first-order mean approximation is obtained by dropping the Hessian terms:

$$(\boldsymbol{\mu}_p)_i \approx p_i(\boldsymbol{\theta}^*).$$

In Macrologit we use the second-order expression above as the default.

6. Macrologit interval update algorithm (summary)

For one interval and observation y :

1. **Prior in logit space.** Start from a prior $\boldsymbol{\theta} \sim \mathcal{N}(\mathbf{m}, \mathbf{S})$, or map a prior in \mathbf{p} to logits via $\boldsymbol{\theta}_0 = \text{logit}(\mathbf{p}_0)$ (reference-state gauge).
2. **Newton iterations in $\boldsymbol{\theta}$.** At a current iterate $\boldsymbol{\theta}_k$:
 - (a) Compute $\mathbf{p}_k = \mathbf{p}(\boldsymbol{\theta}_k)$ via the softmax definition.
 - (b) Evaluate the MacroTaylor gradient $\mathbf{g}_p(\mathbf{p}_k)$ and Hessian $\mathbf{H}_p(\mathbf{p}_k)$ in \mathbf{p} .
 - (c) Compute the softmax Jacobian $J_k = J(\boldsymbol{\theta}_k)$.
 - (d) Form

$$\mathbf{g}_\theta(\boldsymbol{\theta}_k) = (\boldsymbol{\theta}_k - \mathbf{m})^\top \mathbf{S}^{-1} + J_k^\top \mathbf{g}_p(\mathbf{p}_k),$$

$$\mathbf{H}_\theta(\boldsymbol{\theta}_k) \approx \mathbf{S}^{-1} + J_k^\top \mathbf{H}_p(\mathbf{p}_k) J_k$$

(Gauss–Newton approximation).

- (e) Take a Newton step

$$\Delta \boldsymbol{\theta}_k = -\mathbf{g}_\theta(\boldsymbol{\theta}_k) \mathbf{H}_\theta(\boldsymbol{\theta}_k)^{-1}, \quad \boldsymbol{\theta}_{k+1} = \boldsymbol{\theta}_k + \Delta \boldsymbol{\theta}_k.$$

3. **MAP and logit covariance.** Iterate until convergence to the MAP $\boldsymbol{\theta}^*$. Approximate the logit posterior as

$$\boldsymbol{\theta} \mid y \approx \mathcal{N}(\boldsymbol{\theta}^*, \boldsymbol{\Sigma}_\theta^{\text{post}}), \quad \boldsymbol{\Sigma}_\theta^{\text{post}} \approx \mathbf{H}_\theta(\boldsymbol{\theta}^*)^{-1}.$$

4. **Posterior in occupancy space.** Compute the Macrologit posterior summary in \mathbf{p} :

$$(\boldsymbol{\mu}_p)_i \approx p_i(\boldsymbol{\theta}^*) + \frac{1}{2} \text{tr}(\mathbf{H}_i \boldsymbol{\Sigma}_\theta^{\text{post}}), \quad \boldsymbol{\Sigma}_p \approx \mathbf{J}(\boldsymbol{\theta}^*) \boldsymbol{\Sigma}_\theta^{\text{post}} \mathbf{J}(\boldsymbol{\theta}^*)^\top.$$

This respects $p_i > 0$ and $\sum_i p_i = 1$ by construction, and fluctuations remain in the tangent space of the simplex.

Away from the boundaries of the simplex, the resulting MAP and covariance in \mathbf{p} agree, to Laplace order, with the linear MacroTaylor approximation performed directly in \mathbf{p} -space. Near the boundaries, the logit parametrisation prevents illegal probabilities while preserving the MacroTaylor interval likelihood structure.