

Simulation4

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Recap

- N : number of samples one time.
- M : number of bins.
- $H_0: X \perp\!\!\!\perp Y \mid Z, H_1: X \not\perp\!\!\!\perp Y \mid Z$
- Methods:
 - "Cor_kernel" is the method put forward in "Local permutation tests for conditional independence" and I revised it a little bit to make it suitable for continuous X, Y, Z according to page 20 of "Minimax Optimal Conditional Independence Testing"(which is also one of cited paper of the former).
 - "Linear_reg_y": regress Y on X, Z and take the *absolute* coefficient of X as the test statistic.
 - "Linear_reg_x": regress X on Y, Z and take the *absolute* coefficient of Y as the test statistic.
 - "Double_reg": regress Y on Z and regress X on Z separately. Take the *absolute* correlation between residuals from two linear regressions as the test statistic.
 - "double_Cor_kernel": double-binning method (each bin will be divided into *sub* bins).
 - "Linear_reg_y_sub", "Linear_reg_x_sub", "Double_reg_sub": conduct "Linear_reg_y", "Linear_reg_x" and "Double_reg" with permutation in sub-partitions.
- $\alpha = 0.05$
- $X = f_x(Z) + \epsilon, Y = f_y(Z) + \epsilon$
- Noise ϵ :
 - various a
 - H_0
 - normal: $N(Z, a)$
 - uni: $\text{Unif}([-a, +a])$
 - poi: $\text{Poisson}(1/2)$
 - skewed_normal: $N(Z, a)$
 - H_1
 - normal: $N\left([0, 0], \begin{pmatrix} a_1 & 0.8 \cdot \sqrt{a_1 a_2} \\ 0.8 \cdot \sqrt{a_1 a_2} & a_2 \end{pmatrix}\right)$
 - skewed_normal: $N\left([0, 0], \begin{pmatrix} a_1 & 0.8 \cdot \sqrt{a_1 a_2} \\ 0.8 \cdot \sqrt{a_1 a_2} & a_2 \end{pmatrix}\right), \text{skewness} = [5, -5]$
- $N = 100, Z \sim \text{Unif}([0, 10]), M \in \{2, 5, 10, 16, 25, 50\}$.

Smoothness

- is depicted by distance between $X \mid Z$ and $X \mid \tilde{Z}$, where \tilde{Z} is the representative in each bin.
- different distance metrics:
 - Hellinger distance / Rényi Divergence (*Local permutation tests for conditional independence*)
 - TV distance (*Nearest-Neighbor Sampling Based Conditional Independence Testing*)

Questions

1. double binning
2. choice of number of sub-partitions
3. smoothness: yes+no no+no yes+yes
4. choice of xfunc, yfunc

New gains

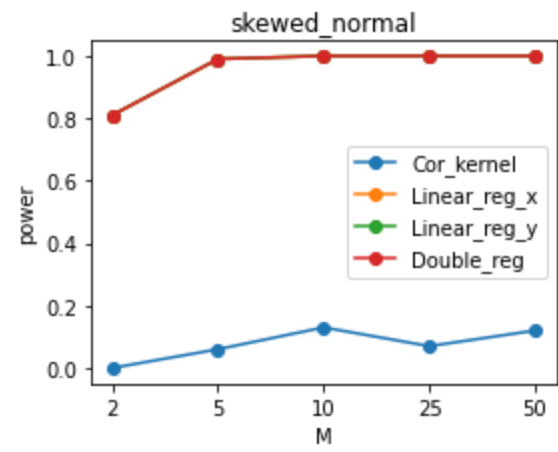
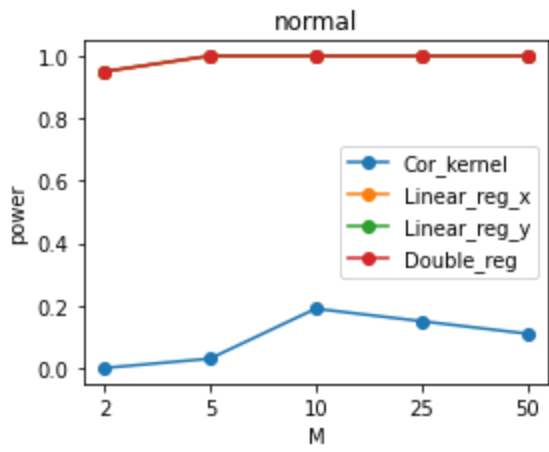
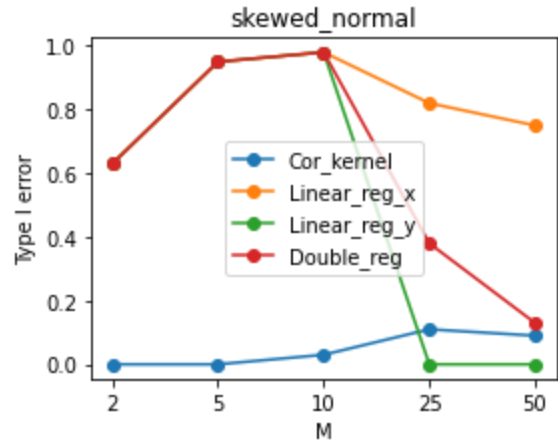
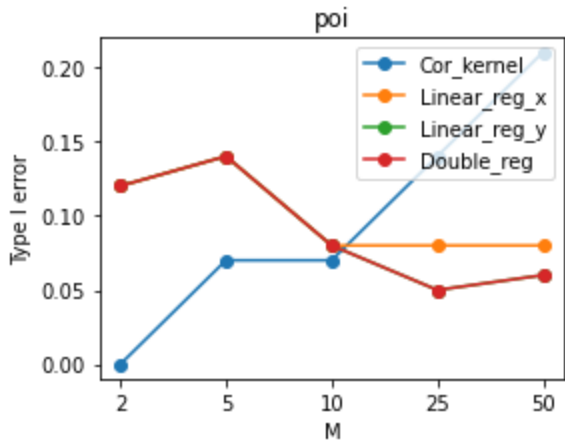
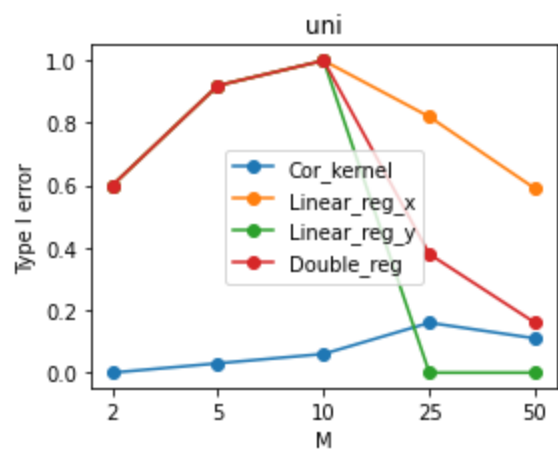
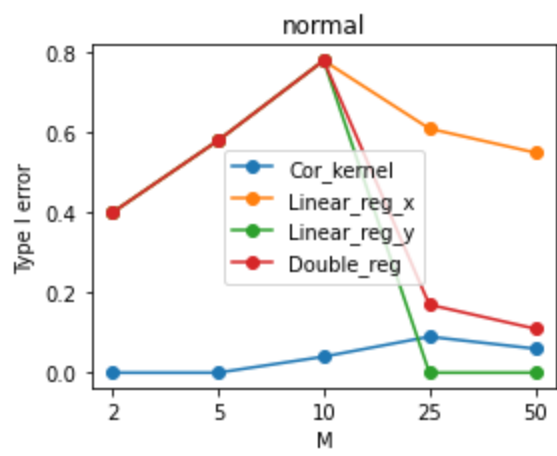
- The number of sub-partitions in each interval will effect the power and type-1 control of "cor_kernel_sub" method.
- High type-I error without double binning.
 - sensitive to different distributions.
 - "Linear_reg_x" is the worst
 - experiment 5's last figure : special failure
- Weak advantage of power.
 - distributions matter.
 - varying degrees of smoothness matter. (experiment 5)
- "Linear_reg_y_sub", "Linear_reg_x_sub" and "Double_reg_sub" have almost the same performance. (have checked the code)
- Failure in part II: $X \mid Z$ is smooth and $Y \mid Z$ is the more non-smooth due to polynomial f_y .

Part I: Linear f_x & f_y in Z

Smooth $X \mid Z$ and non-smooth $Y \mid Z$

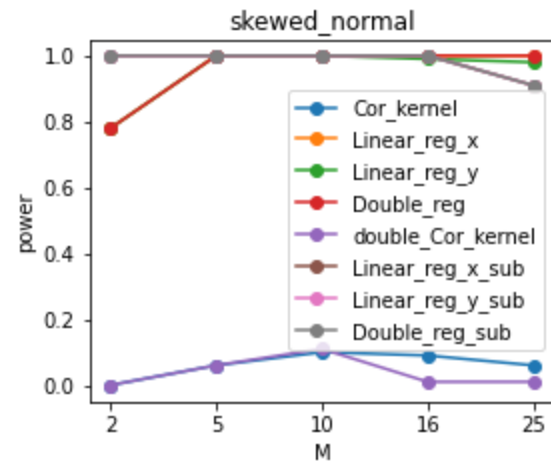
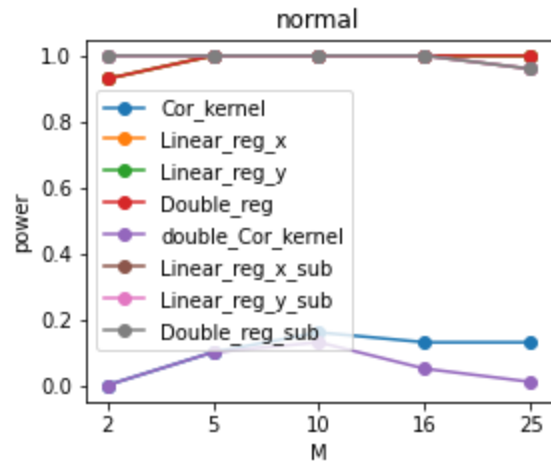
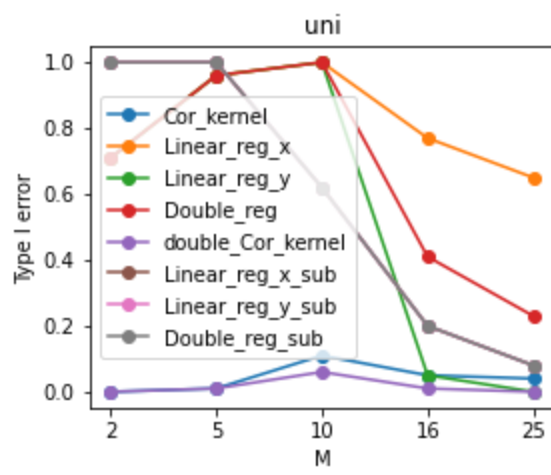
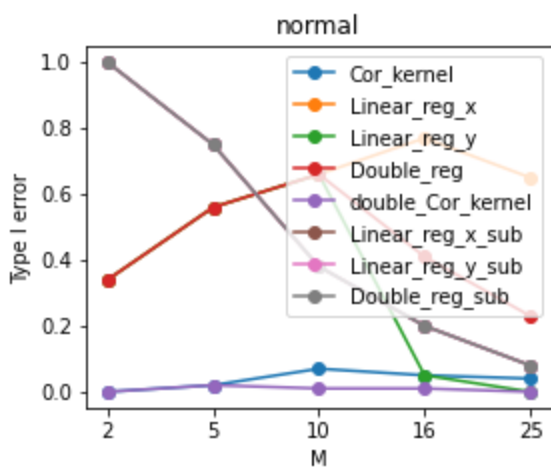
experiment 1

$f_x(Z) = Z, f_y(Z) = Z, \text{sub} = 4, \epsilon_x \sim N(\cdot, 1), \epsilon_y \sim N(\cdot, 0.1).$



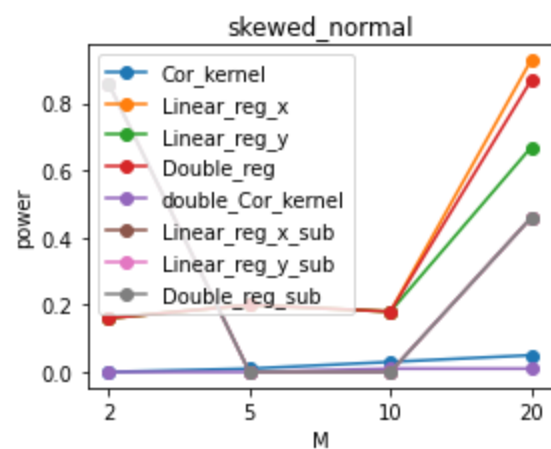
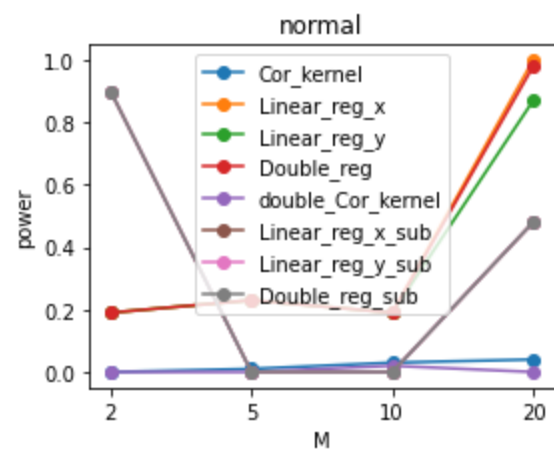
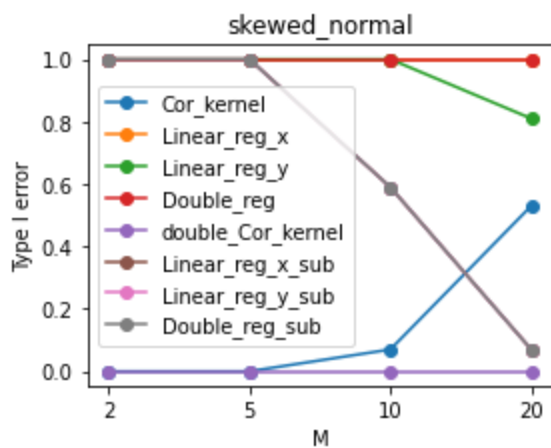
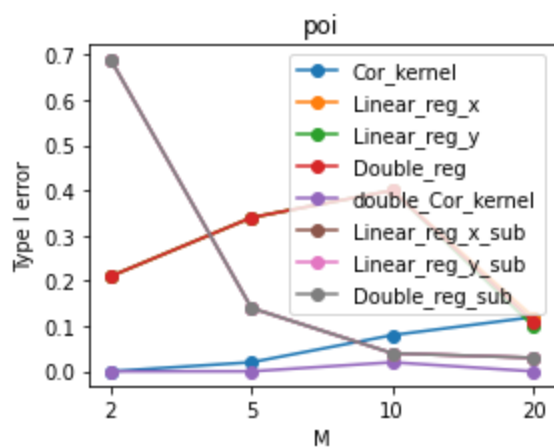
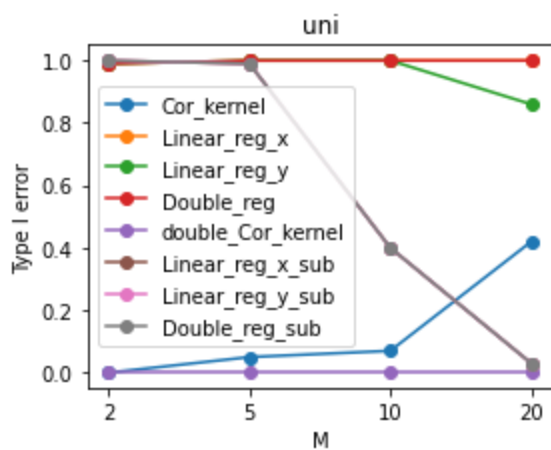
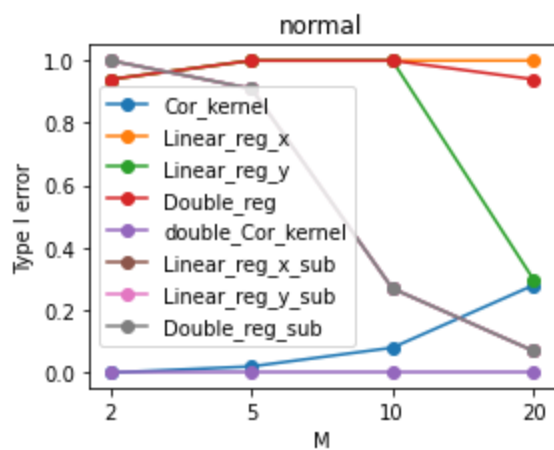
experiment 2

$f_x(Z) = Z, f_x(Z) = Z, \text{sub} = 2, \epsilon_x \sim N(\cdot, 1), \epsilon_y \sim N(\cdot, 0.1).$



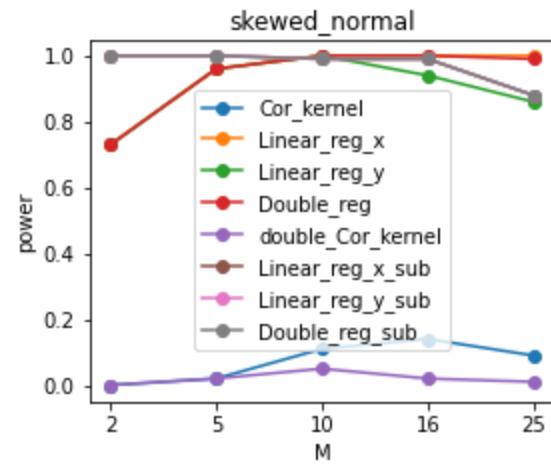
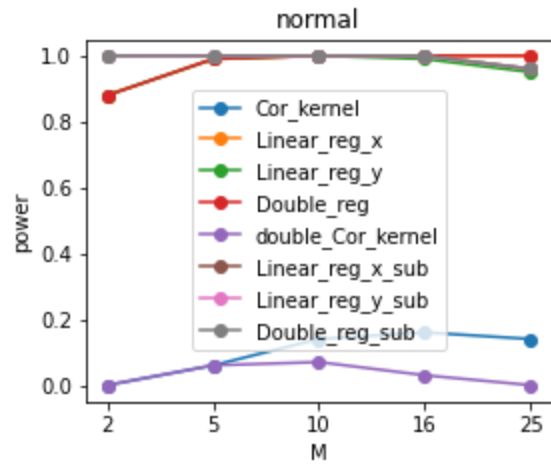
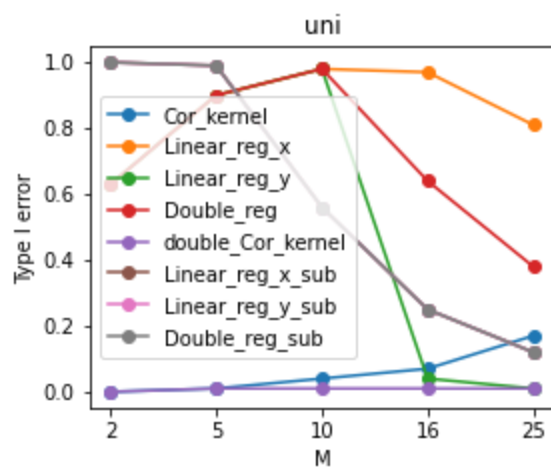
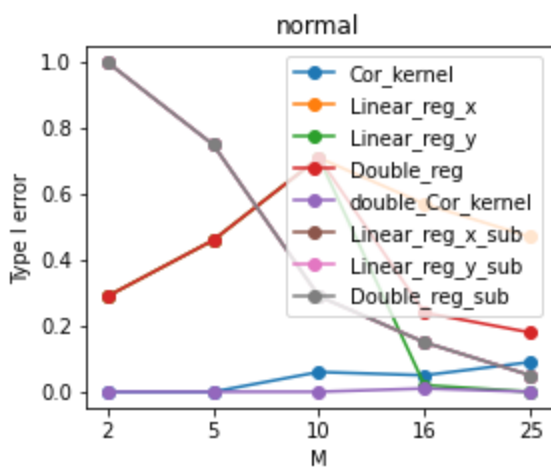
experiment 3

$f_x(Z) = Z, f_x(Z) = -Z, \text{sub} = 4, \epsilon_x \sim N(\cdot, 1), \epsilon_y \sim N(\cdot, 0.1).$



experiment 4

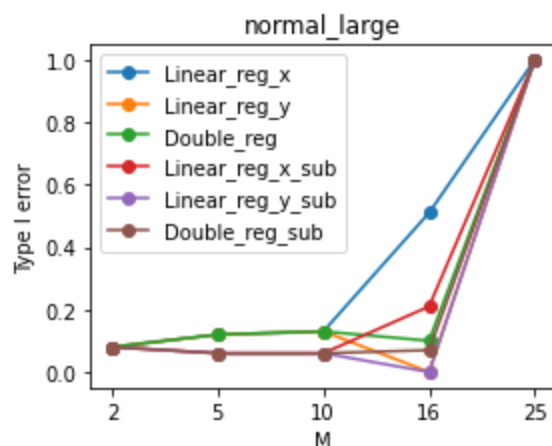
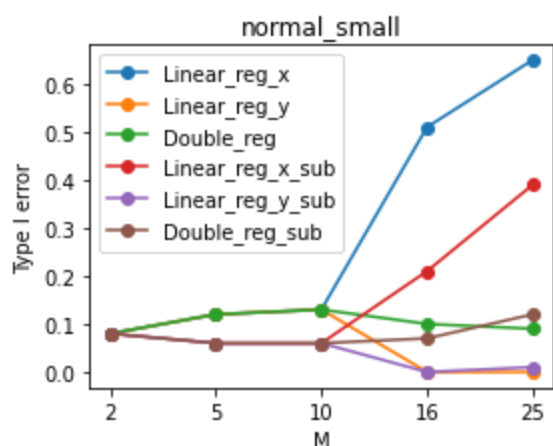
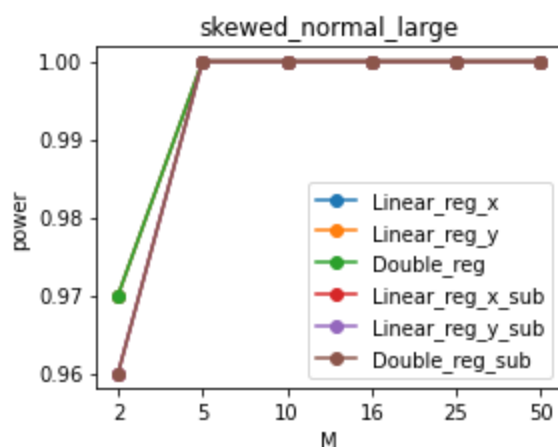
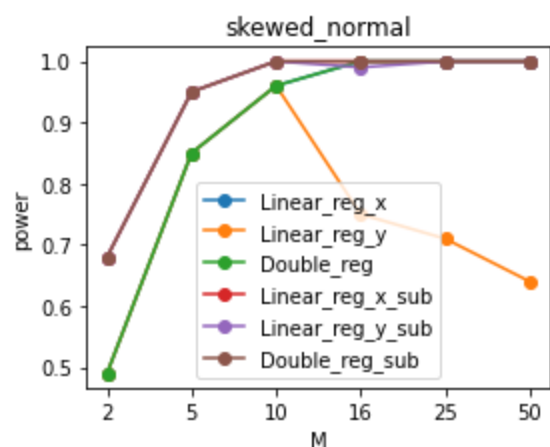
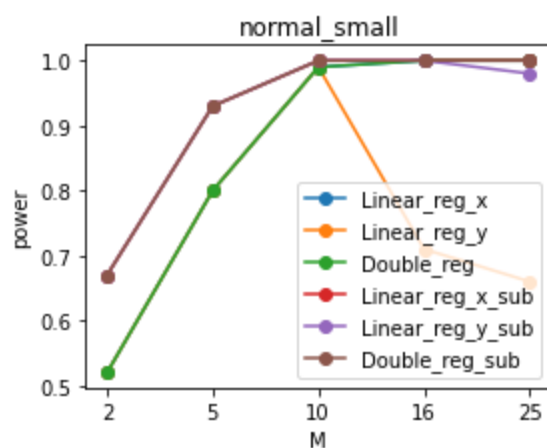
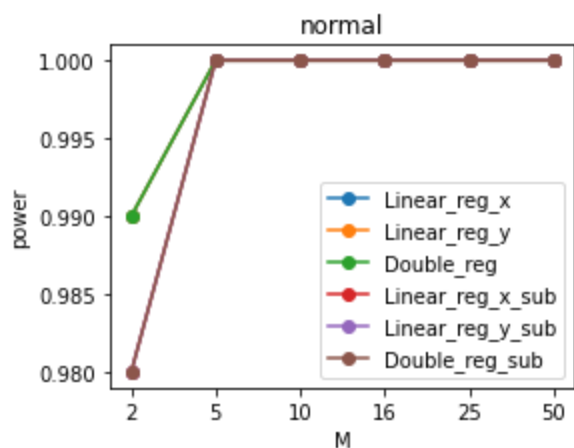
$f_x(Z) = Z, f_x(Z) = 5Z, \text{sub} = 2, \epsilon_x \sim N(\cdot, 1), \epsilon_y \sim N(\cdot, 1).$



experiment 5

$$f_x(Z) = Z, f_x(Z) = Z, \text{sub} = 2.$$

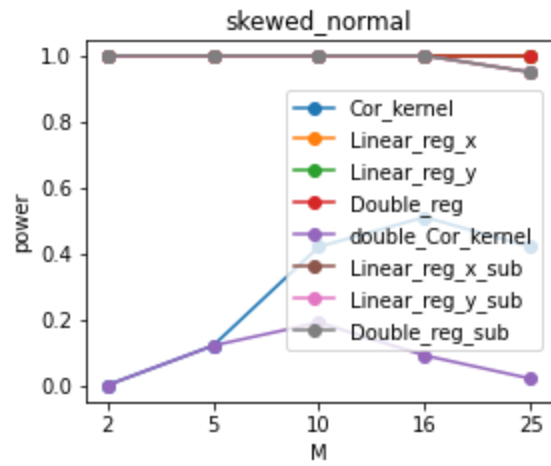
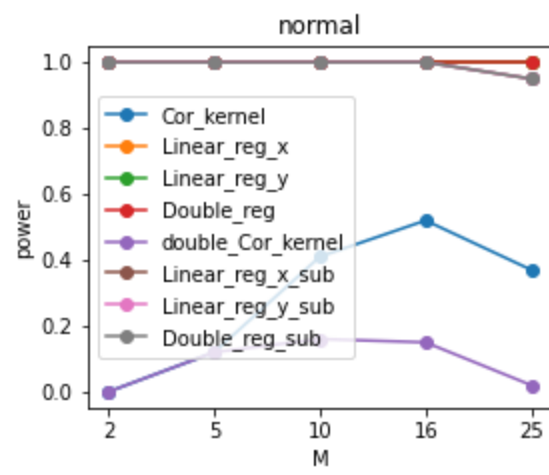
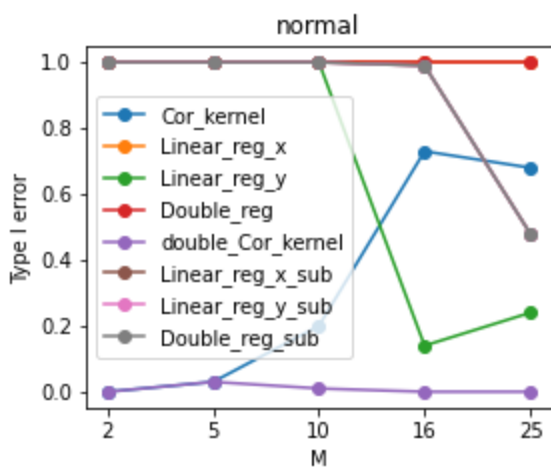
| Distribution | $\text{Var}(\epsilon_x)$ | $\text{Var}(\epsilon_y)$ |
|------------------------------------|--------------------------|--------------------------|
| normal / skewed_normal | 1 | 0.1 |
| normal_small | 5 | 0.01 |
| normal_large / skewed_normal_large | 5 | 0.5 |



Non-smooth $X|Z$ and non-smooth $Y|Z$

experiment 6

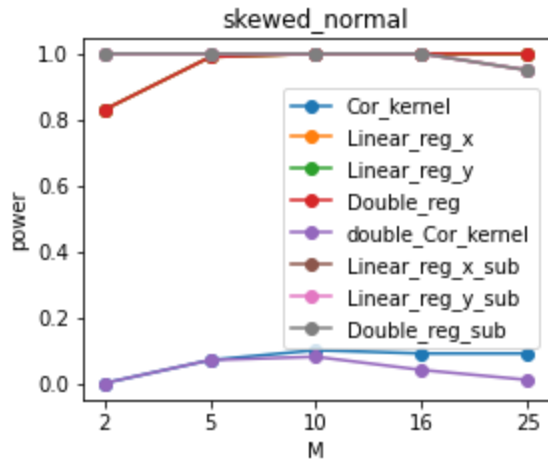
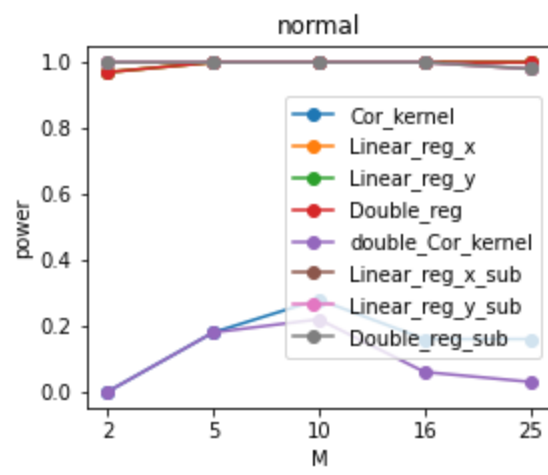
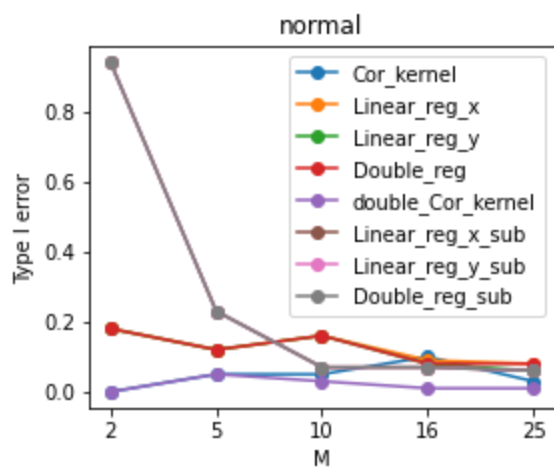
$f_x(Z) = Z, f_y(Z) = Z, \text{sub} = 2, \epsilon_x \sim N(\cdot, 0.1), \epsilon_y \sim N(\cdot, 0.1).$



Smooth $X|Z$ and smooth $Y|Z$

experiment 7

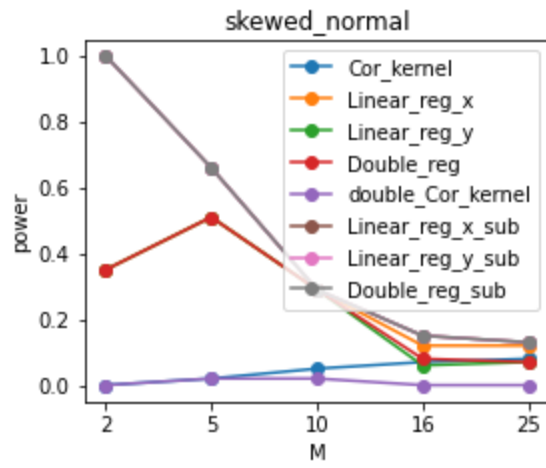
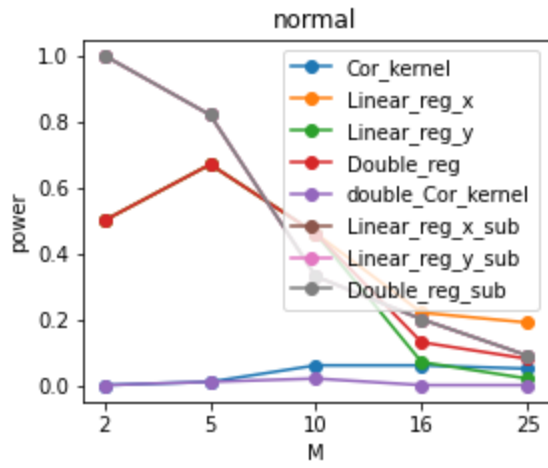
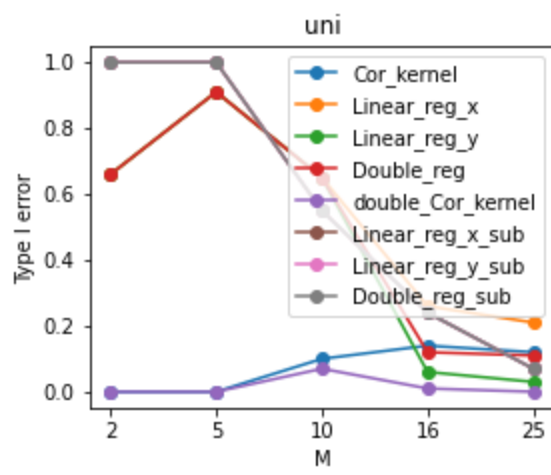
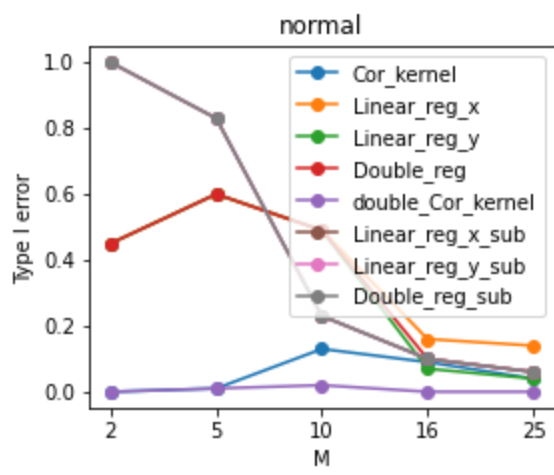
$f_x(Z) = Z, f_x(Z) = Z, \text{sub} = 2, \epsilon_x \sim N(\cdot, 1), \epsilon_y \sim N(\cdot, 1).$



Part II: Linear f_x & non-linear f_y in Z

experiment 8

$f_x(Z) = Z$, $f_y(Z) = Z + 3Z^2 + 2$, sub = 2, $\epsilon_x \sim N(\cdot, 1)$, $\epsilon_y \sim N(\cdot, 0.1)$.



experiment 9

$f_x(Z) = Z$, $f_y(Z) = Z + 3Z^2 + 2$, $\text{sub} = 4$, $\epsilon_x \sim N(\cdot, 1)$, $\epsilon_y \sim N(\cdot, 0.1)$.

