

# Simulation 4

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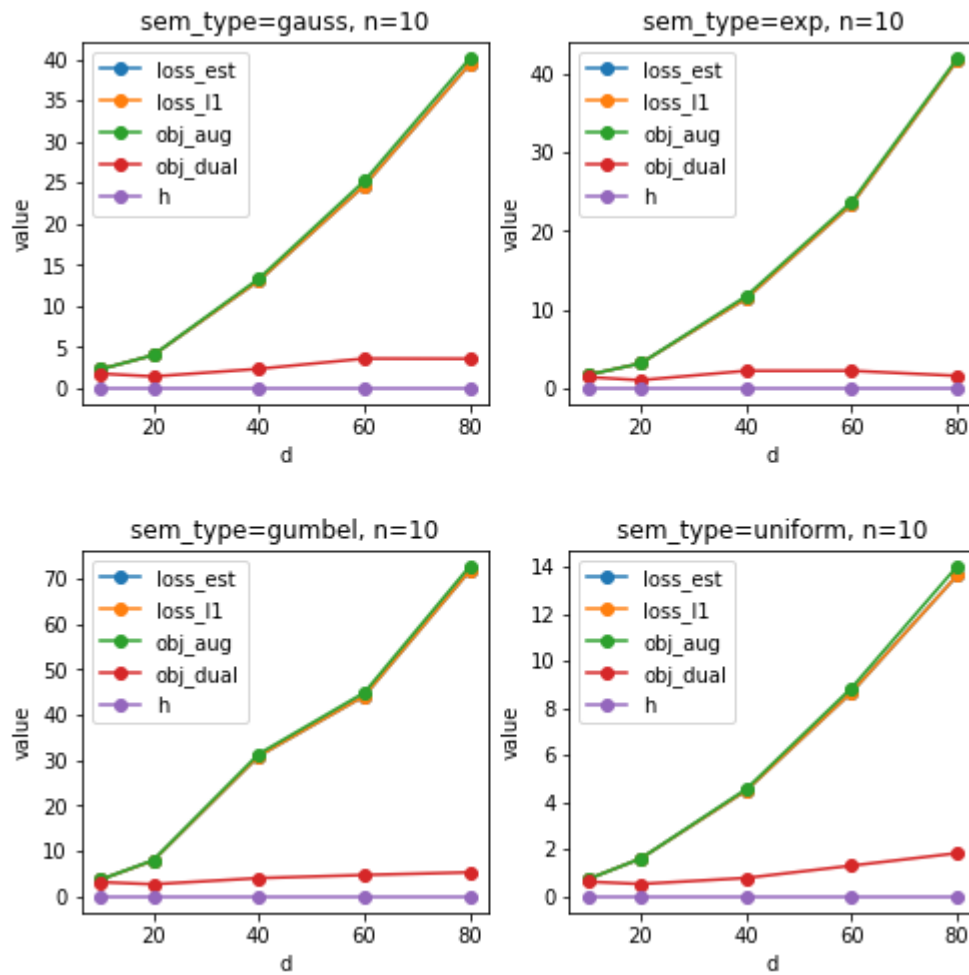
## Setting

- $d$ : number of nodes
- $s_0$ : expected number of edges
- graph\_type: ER
  - ER: Erdős-Rényi Graph randomly choose one from all graphs with  $d$  nodes and  $s_0$  edges + random orientation
- $n$ : number of samples,  $n=\text{inf}$  mimics population risk
- sem\_type: gauss, exp, gumbel, uniform
- loss\_type: l2
- lambda1: penalty for sparsity
- Here I use MCMC to simulate for 20 times or for 6 times.
- losses:
  - $h(W) = 0$ : constraint function
  - loss\_est: loss decided by loss\_type
  - loss\_l1: loss\_est + l1 penalty
  - obj\_new: + quadratic penalty of  $h$
  - obj\_dual: dual function pertaining to obj\_new with Lagrange multiplier  $\alpha$

## Results

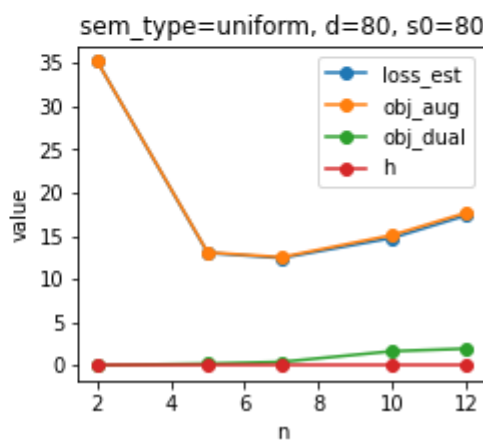
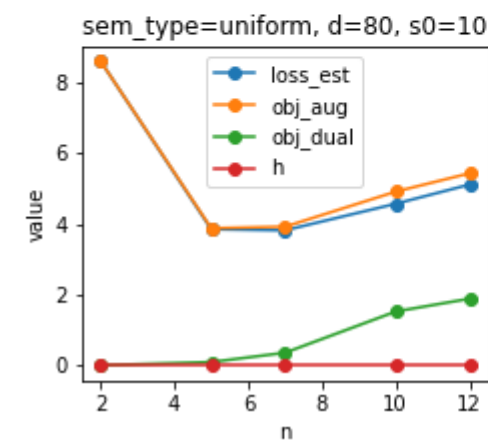
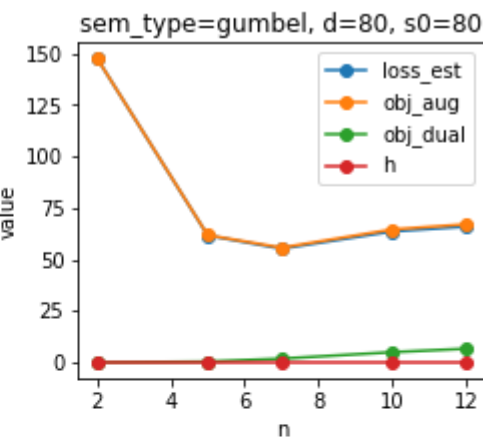
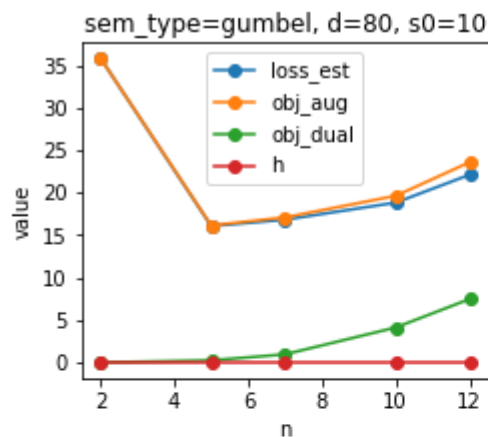
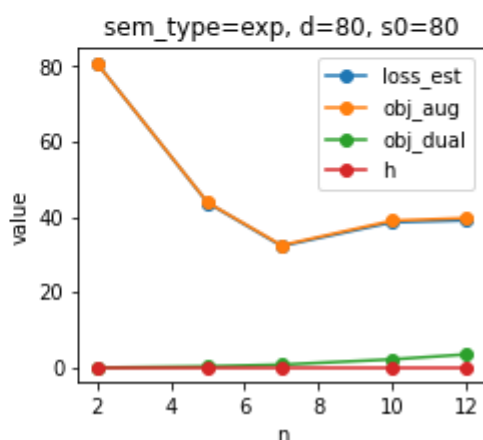
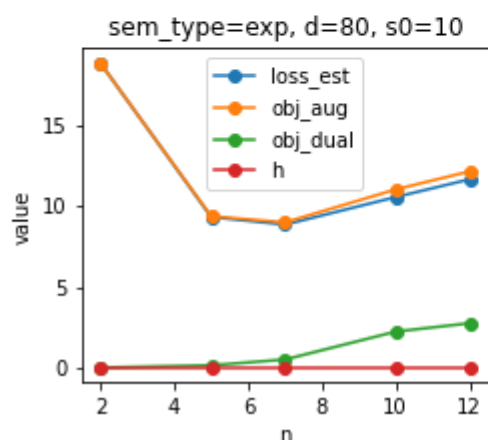
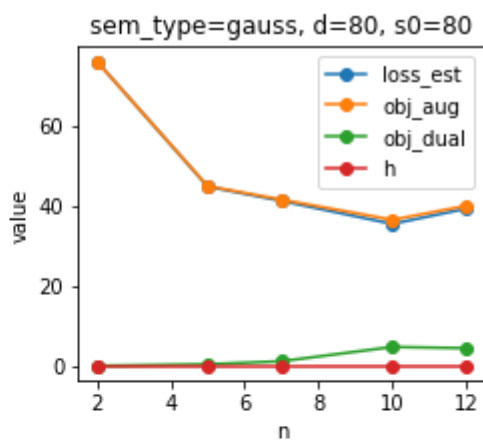
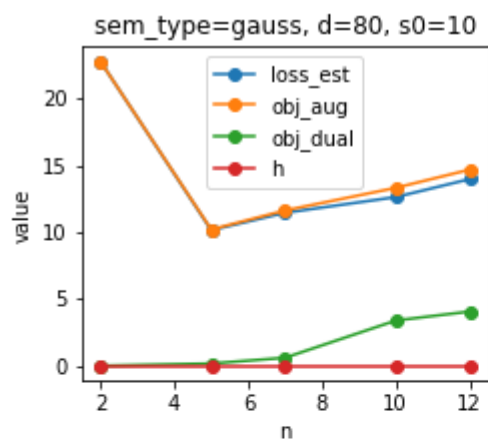
### Experiment 1

Here I set  $\text{lambda1} = 0$ ,  $d \in \{10, 20, 40, 60, 80\}$ ,  $n = 10$  and  $s_0 = d$ .



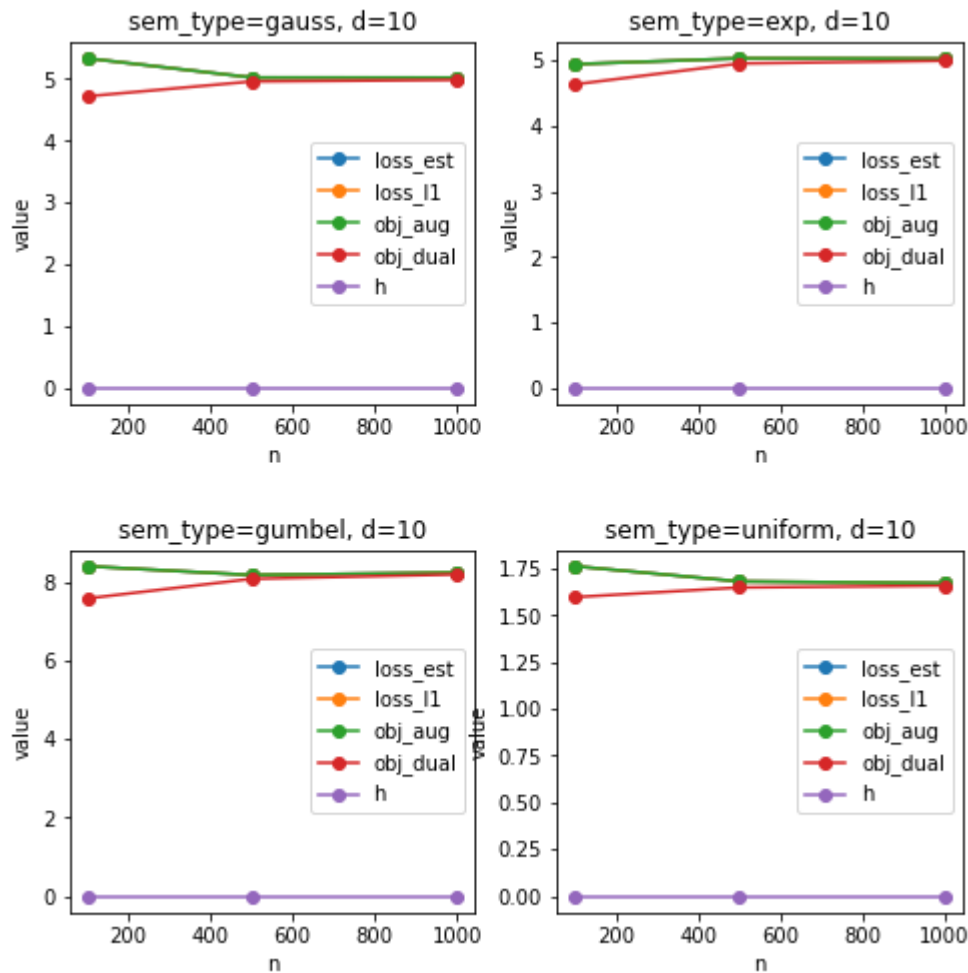
## Experiment 2

Here I set  $\lambda_1 = 0$ ,  $n \in \{2, 5, 7, 10, 12\}$ ,  $d = 80$  and  $s_0 \in \{10, 80\}$ .



## Experiment 3

Here I set  $\lambda_1 = 0$ ,  $n \in \{100, 500, 1000\}$ ,  $d = 10$  and  $s_0 = d$ .



## Gains and reflection

- When  $n$  is fixed, as the  $d$  gets bigger, the  $\text{loss\_est}$  gets bigger, where  $\text{obj\_dual}$  remains basically the same. ( $n \leq d$ )
- When  $d$  is fixed, as the  $n$  gets bigger, the  $\text{loss\_est}$  gets smaller first and then go bigger, where  $\text{obj\_dual}$  increases very slowly. ( $n \leq d$ )
- When  $d$  is fixed, as the  $n$  gets extremely bigger, the  $\text{loss\_est}$  and  $\text{obj\_dual}$  keep constant and the difference  $\text{loss\_est} - \text{obj\_dual}$  seems to become smaller than in second experiment. ( $n \gg d$ )

**Question: Why doesn't  $\text{loss\_est}$  approach zero?**

Technically,

- $W\_est[\text{np.abs}(W\_est) < w\_threshold] = 0$  -> arbitrary threshold -> how about delete this code line? -> "2"

- `scale_vec = np.zeros(d)` -> this noise level may be too large to introduce more messy data ->  
`scale_vec = np.zeros(d) * noise_scale`
- if `loss_type == 'l2'`: `X = X - np.mean(X, axis=0, keepdims=True)`

Theoretically,

- Considering the large gap between `loss_est/obj_new` and `obj_dual`, it may be that the systematic error of optimizing this problem is relatively large, rather than specific optimization steps.

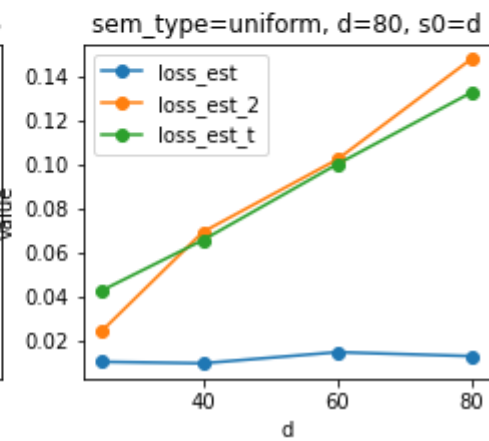
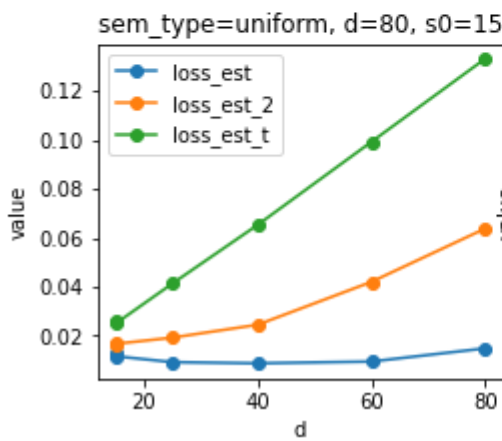
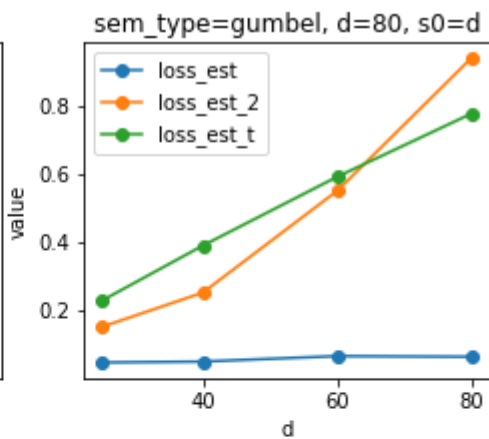
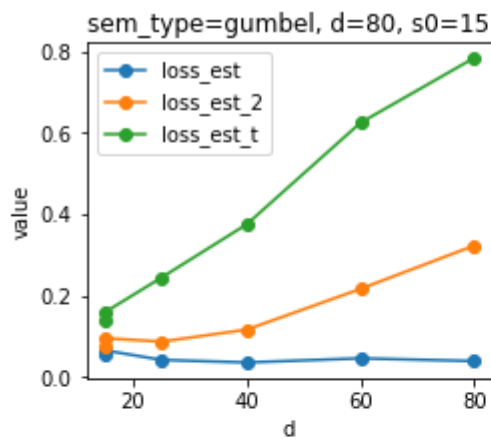
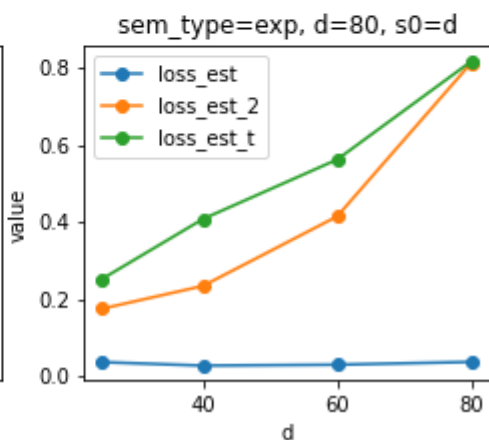
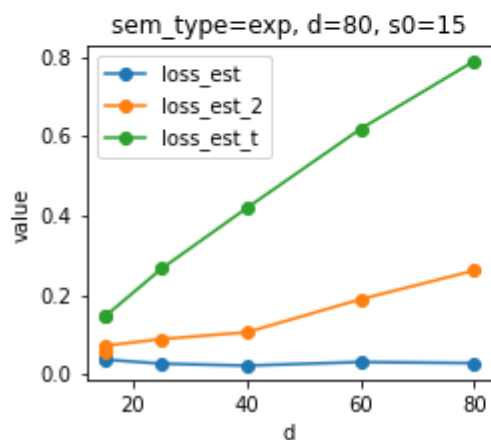
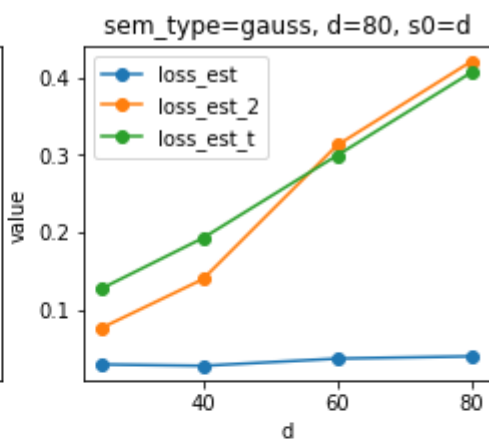
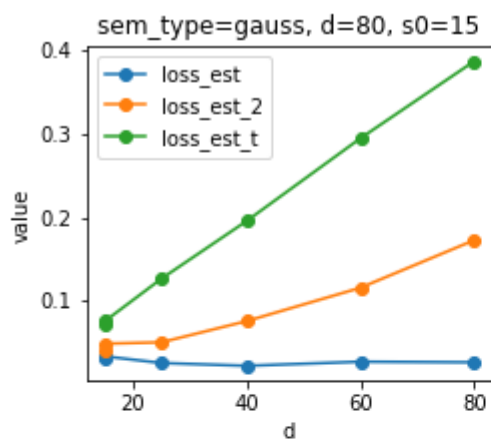
#### **Ideas for the next experiment:**

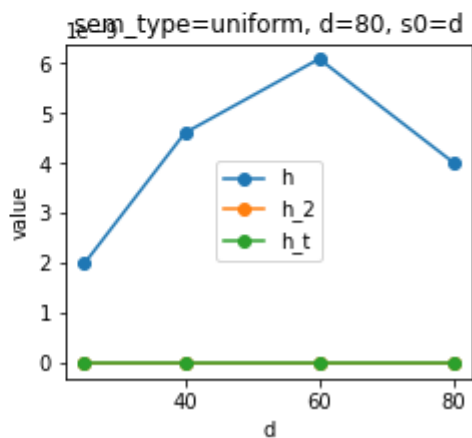
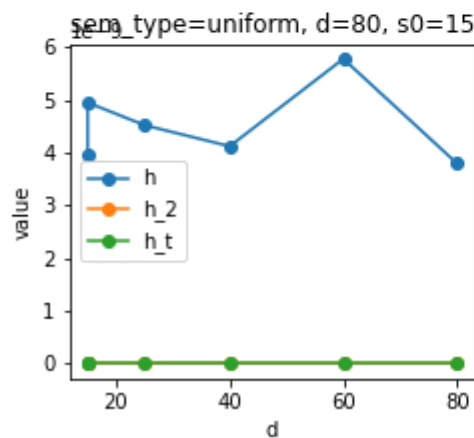
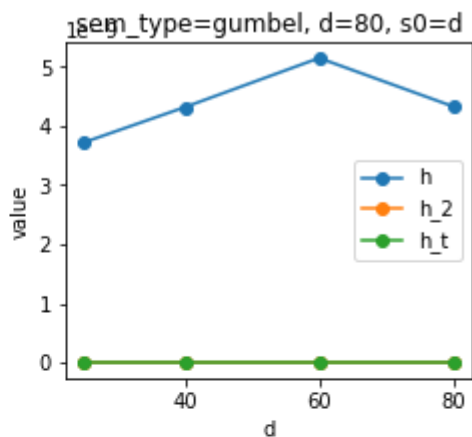
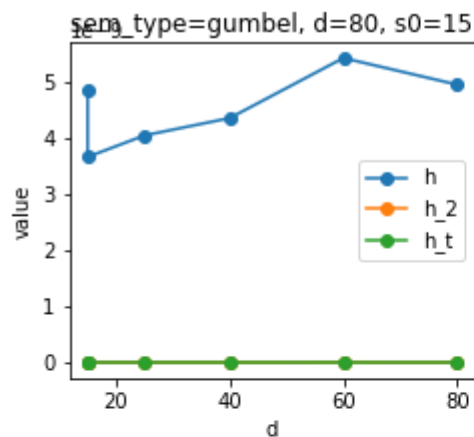
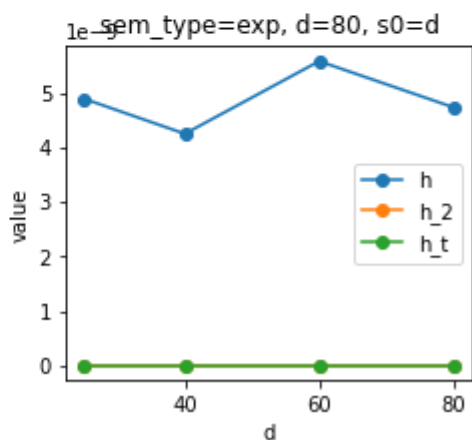
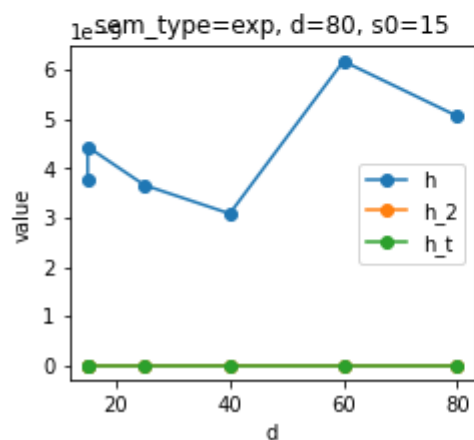
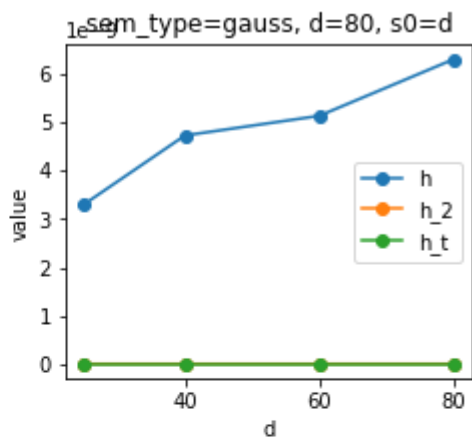
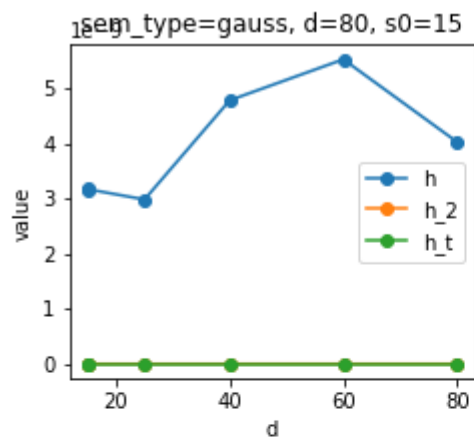
- Explore whether arbitrary threshold for `W_est` will effect the losses.
- Will losses be zero if we set `noise_scale` to be smaller?
- If losses cannot achieve zero, how do they compared to losses with regard to the global true `W`?

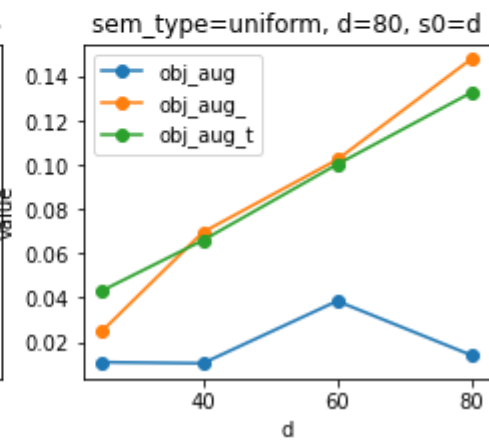
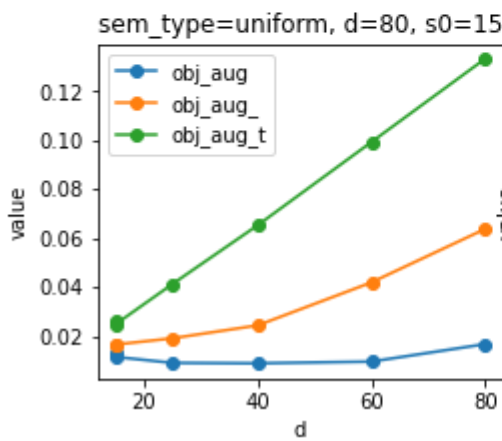
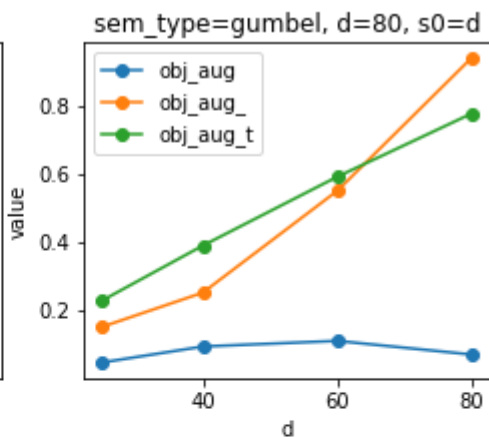
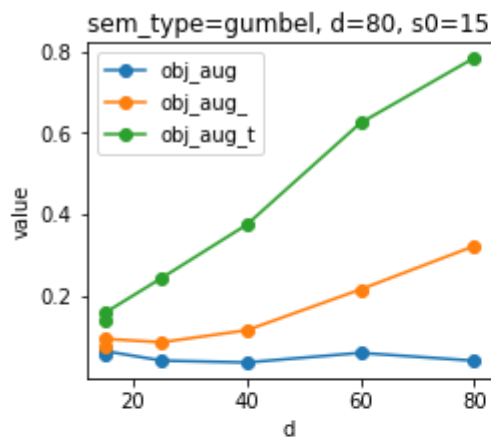
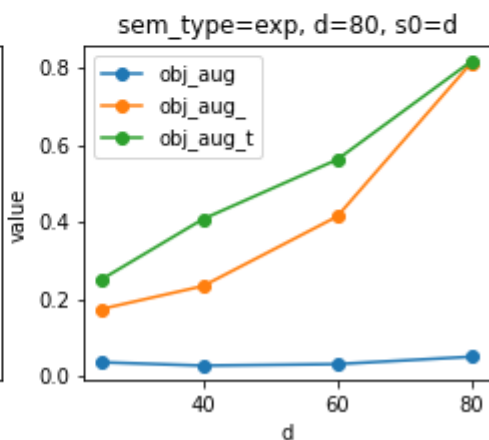
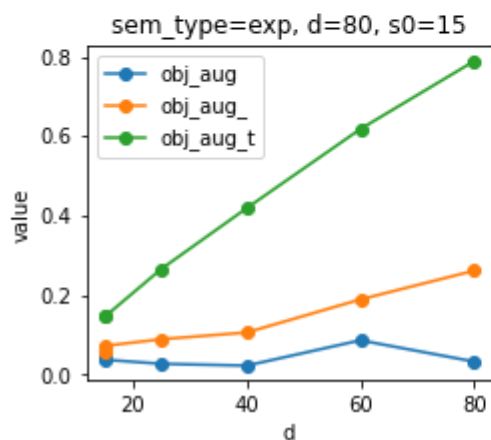
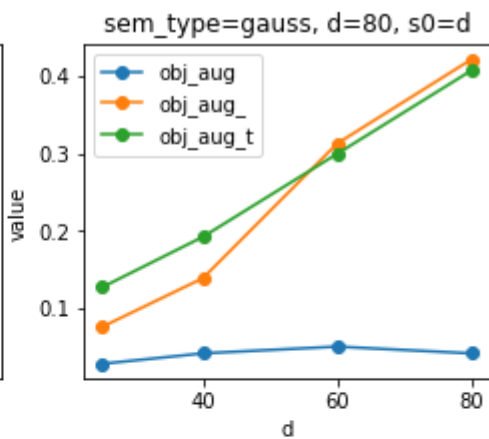
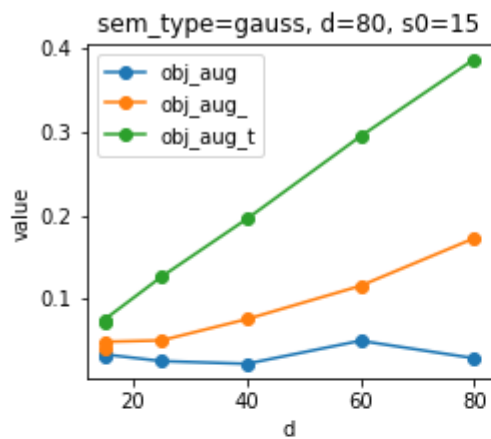
## Experiment 4

Here I set  $\lambda_1 = 0$ ,  $d \in \{15, 25, 40, 60, 80\}$ ,  $n = 15$  and  $s_0 = \{15, d\}$ .

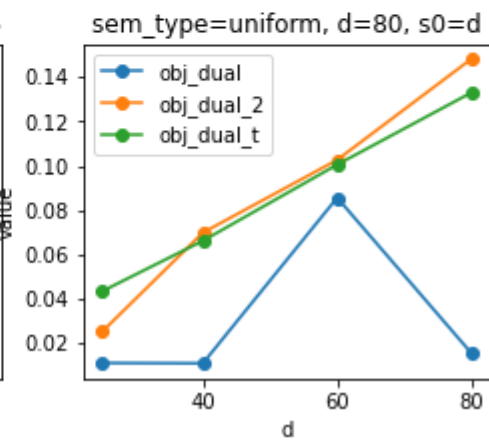
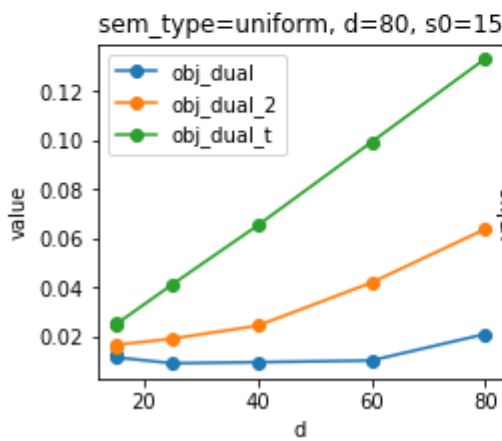
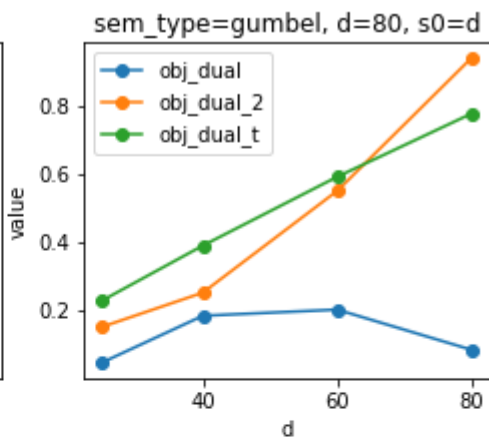
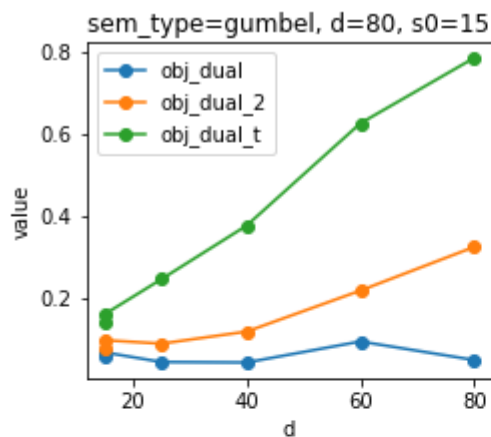
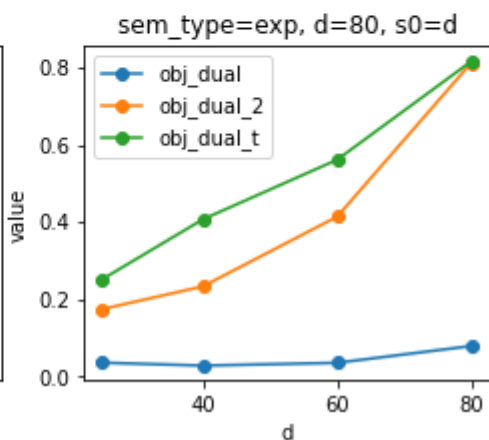
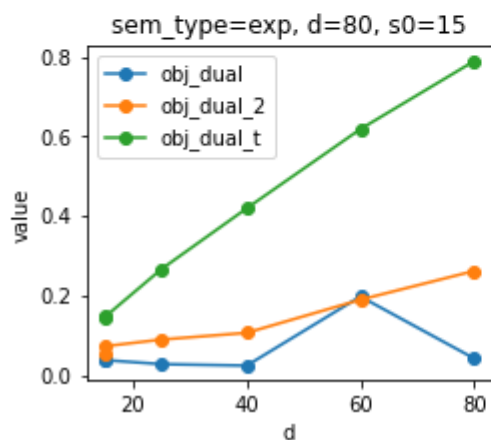
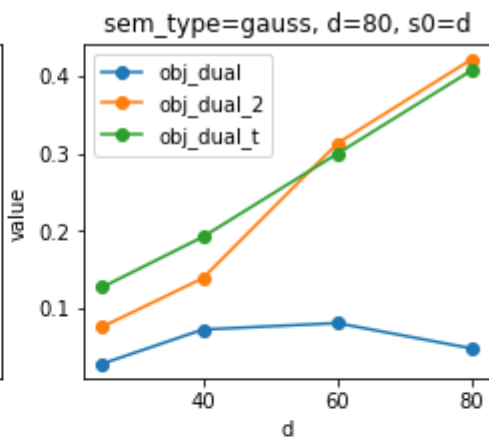
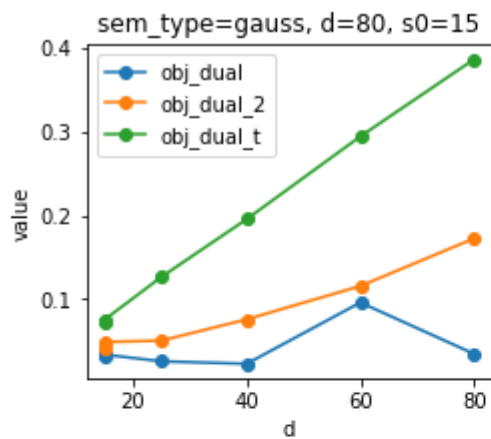
- Blue lines stand for original `W_est` and its losses.
- Orange lines stand for `W_est2` with "`W_est[np.abs(W_est) < w_threshold] = 0`" and its losses.
- Green lines stand for true `W` and its losses.











## New gains

- Surprisingly, green lines and orange lines are more close, which means sparsely estimated  $W_{\text{est}}$  may behave more like true  $W$ .
- Unfortunately, losses associated with estimated matrix are smaller. This may indicate some systematic problem in optimization problem or overfitting.
- The constraint function computed by originally estimated  $W_{\text{est}}$  and  $W_{\text{est2}}$  is not strictly 0 in some cases. The severity of the problem is uncertain.
- Smaller  $\text{noise\_scale}$  will lead to smaller losses and shorter running time.