

Learning a Variational Network for Reconstruction of Accelerated MRI Data

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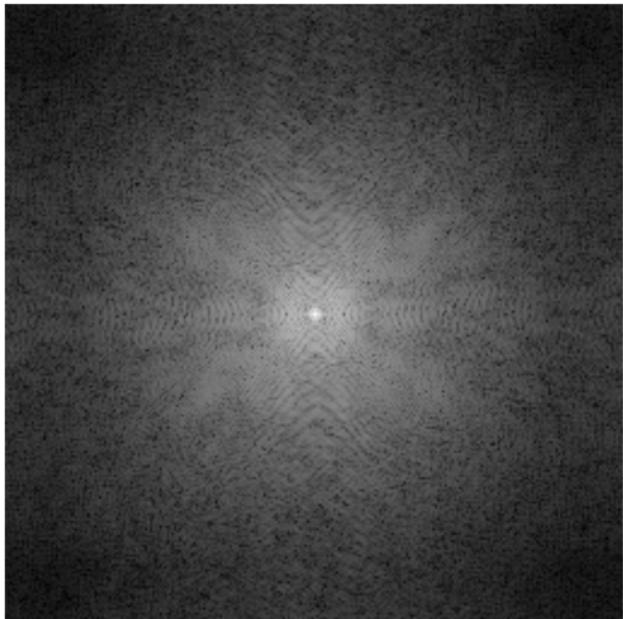
³Center for Advanced Imaging Innovation and Research, NYU School of Medicine

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Deep Reconstruction Workshop 2017

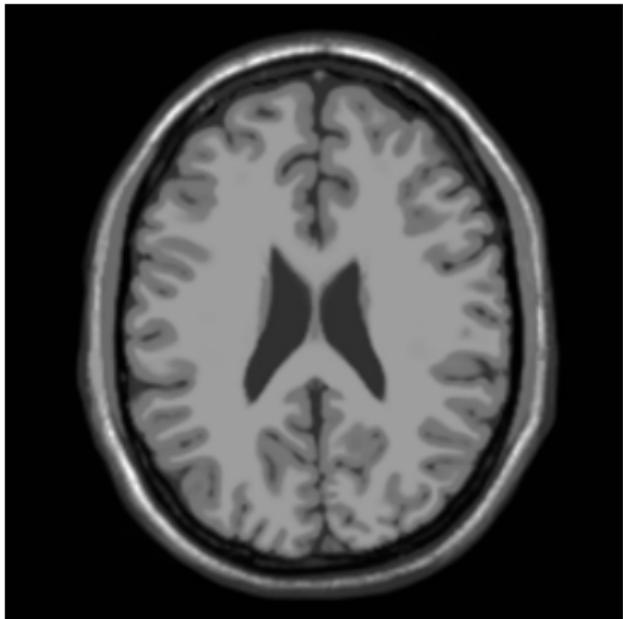


MRI reconstruction in a nutshell

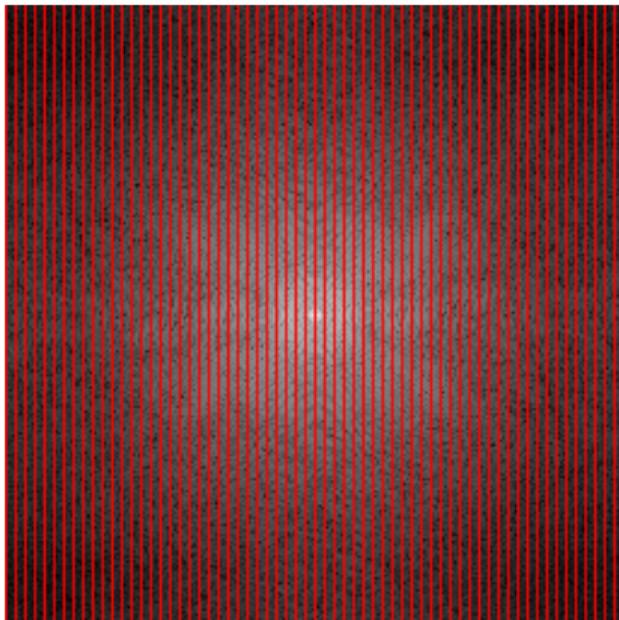


$$\mathcal{FT}^{-1}$$

→

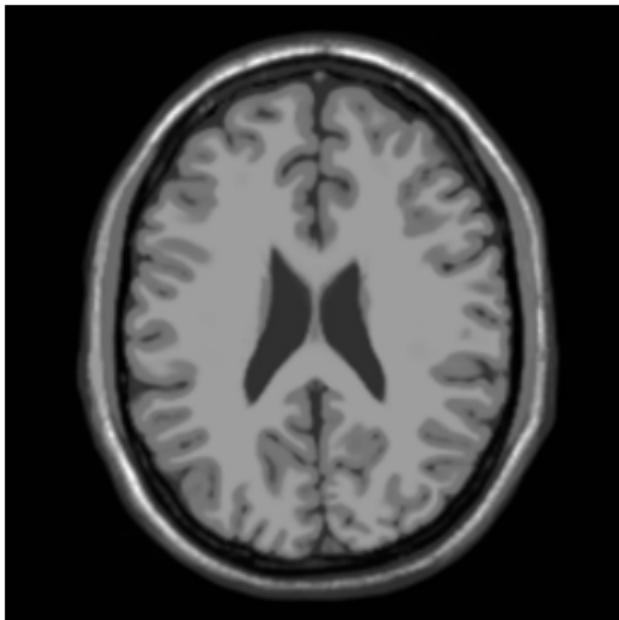


MRI reconstruction in a nutshell



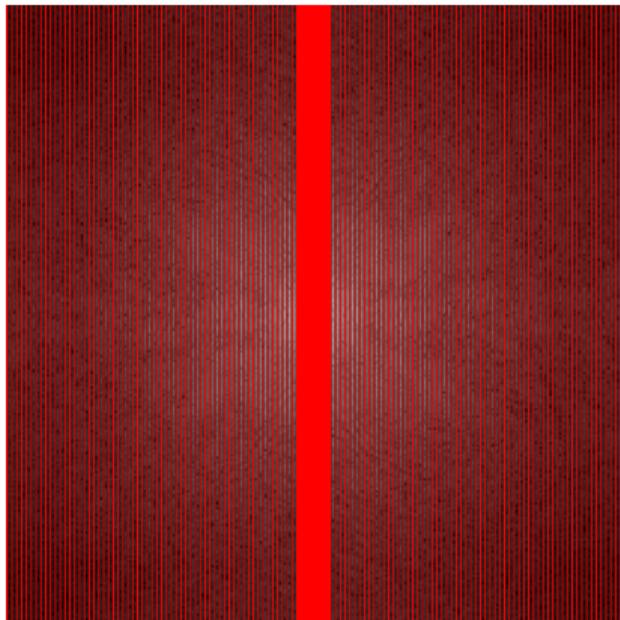
$$\mathcal{FT}^{-1}$$

→



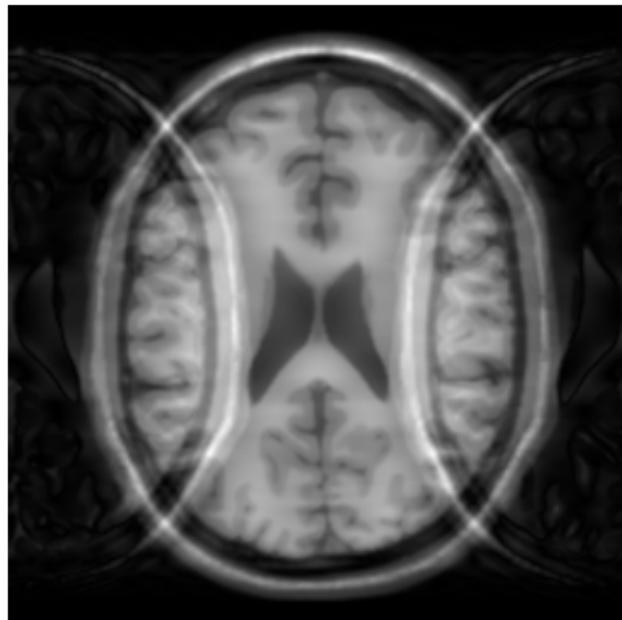
Cartesian undersampling

Accelerated MRI in a nutshell



$$\mathcal{FT}^{-1}$$
$$\longrightarrow$$

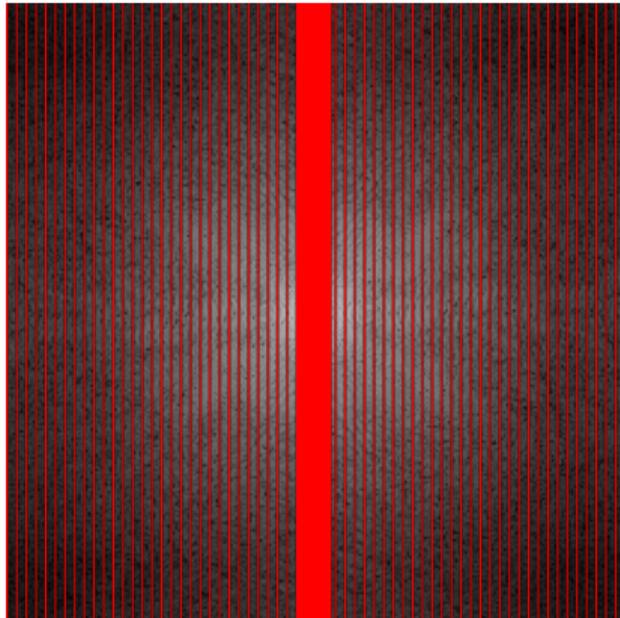
$$R = 2$$



Nyquist-Shannon sampling theorem is violated → backfolding artifacts!

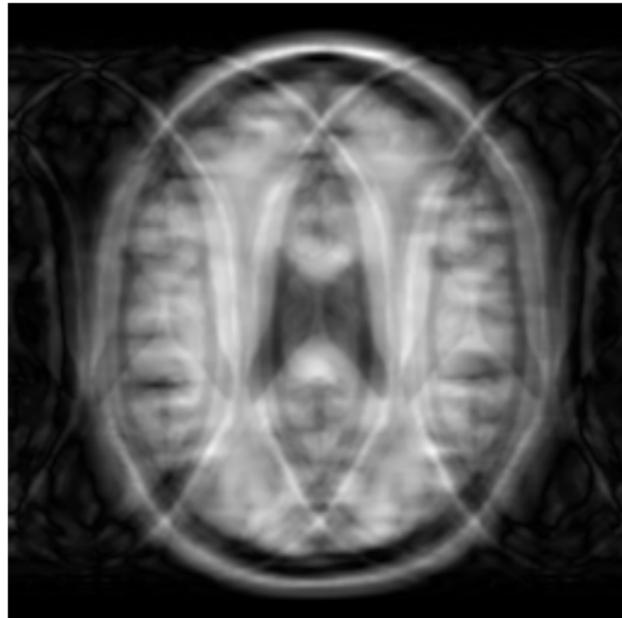
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Accelerated MRI in a nutshell



$$\mathcal{FT}^{-1}$$
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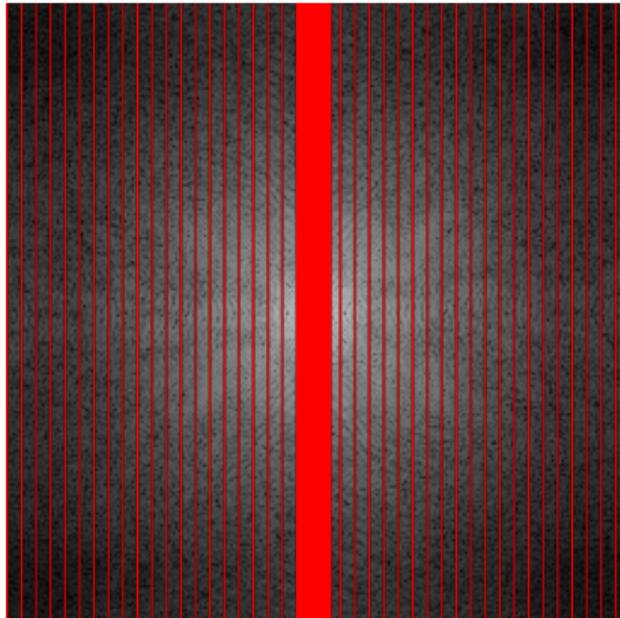
$$R = 4$$



Nyquist-Shannon sampling theorem is violated → backfolding artifacts!

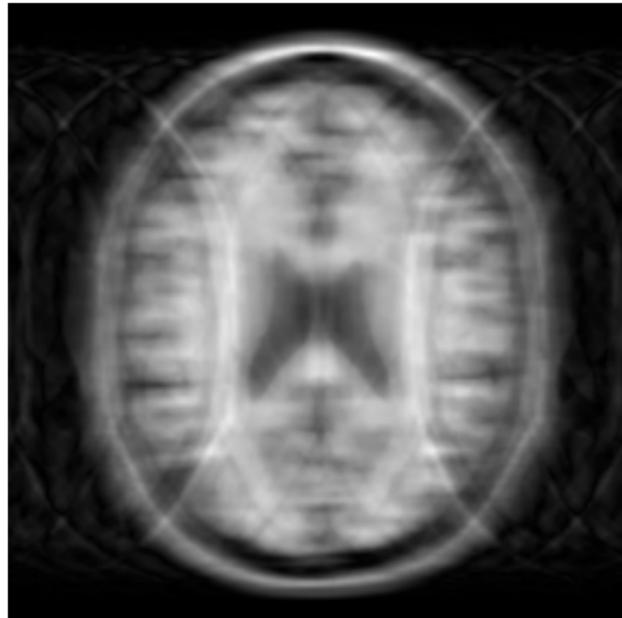
Cartesian undersampling

Accelerated MRI in a nutshell



$$\mathcal{FT}^{-1}$$
$$\longrightarrow$$

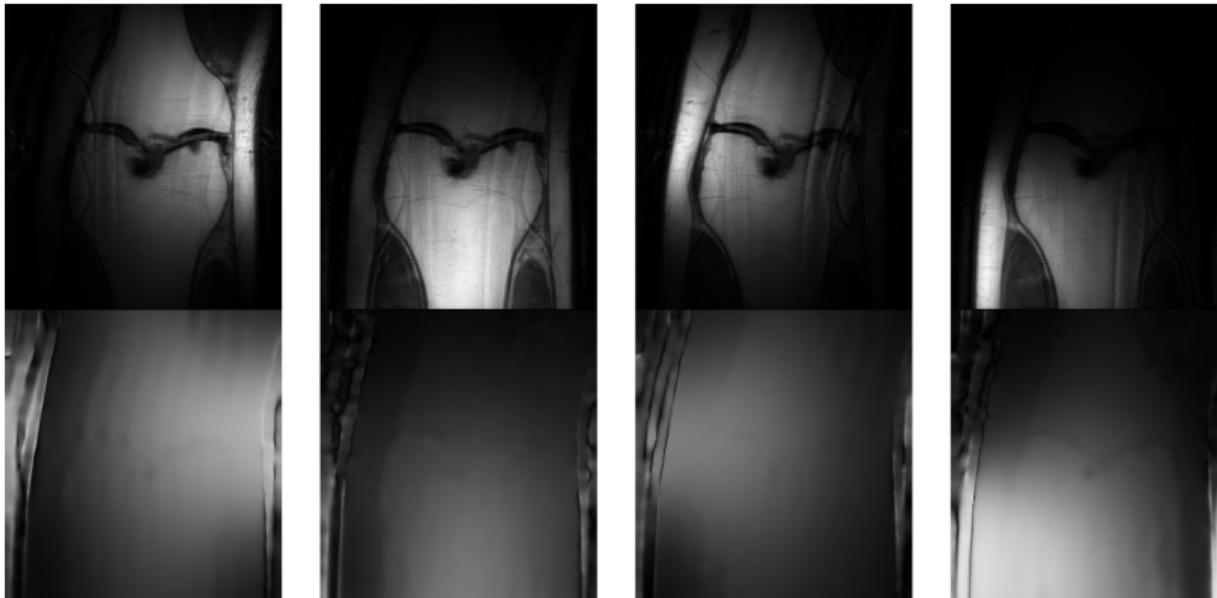
$$R = 6$$



Nyquist-Shannon sampling theorem is violated → backfolding artifacts!

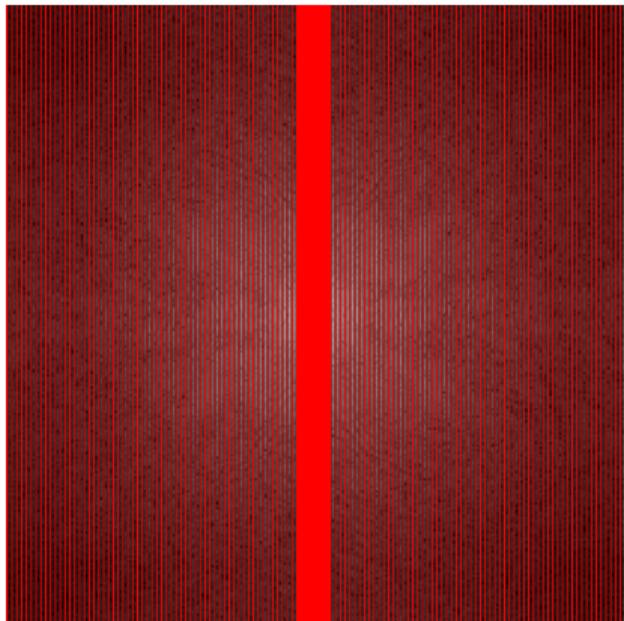
Parallel Imaging (PI) in a nutshell

- Combine data from **multiple** receiver coils
- Each coil is sensitive only in a certain spatial region
- Used for accelerated MRI



Linear reconstruction (SENSE)

[Pruessmann 1999]



SENSE



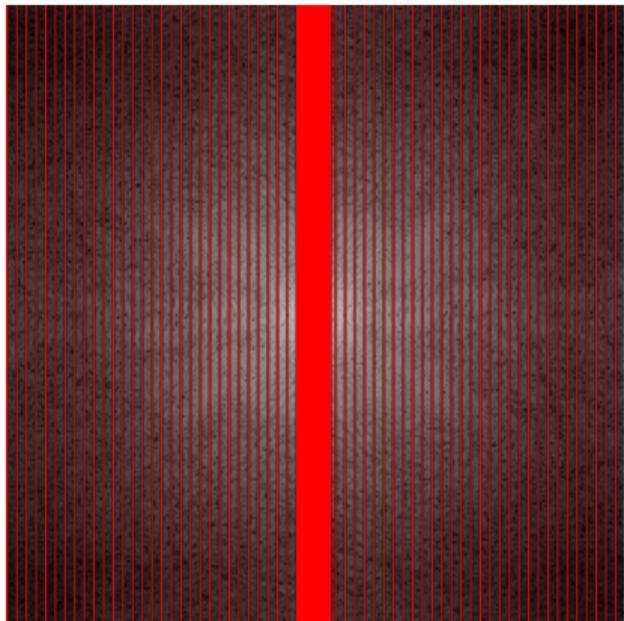
$$R = 2$$



Clinical standard

Linear reconstruction (SENSE)

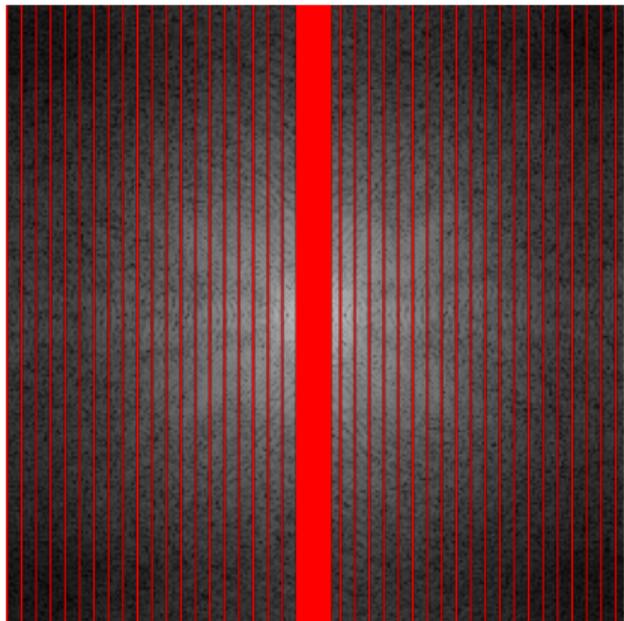
[Pruessmann 1999]



Noise amplification

Linear reconstruction (SENSE)

[Pruessmann 1999]



SENSE

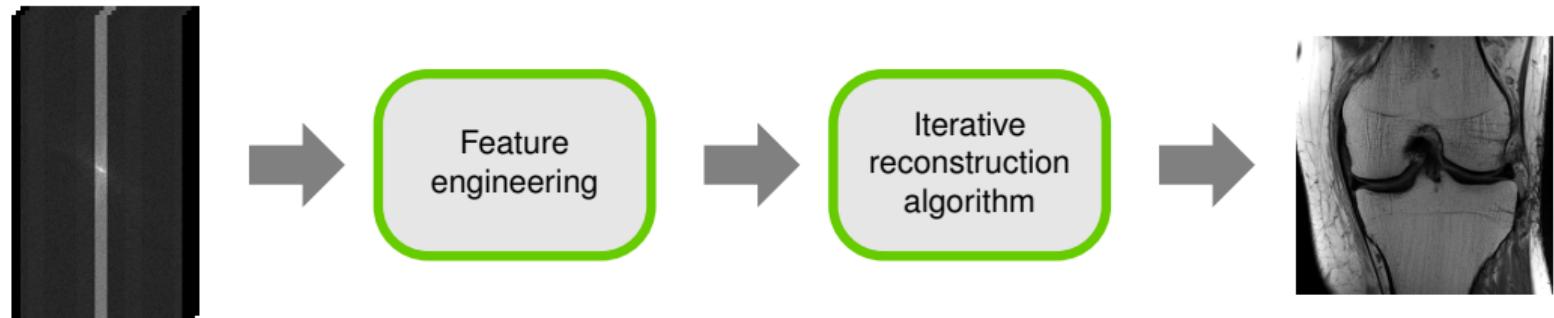


$$R = 6$$



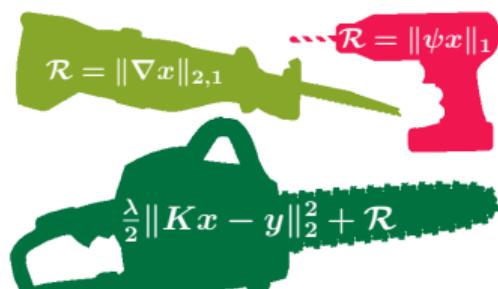
Noise amplification → Add prior knowledge!

Compressed Sensing (CS) accelerated MRI

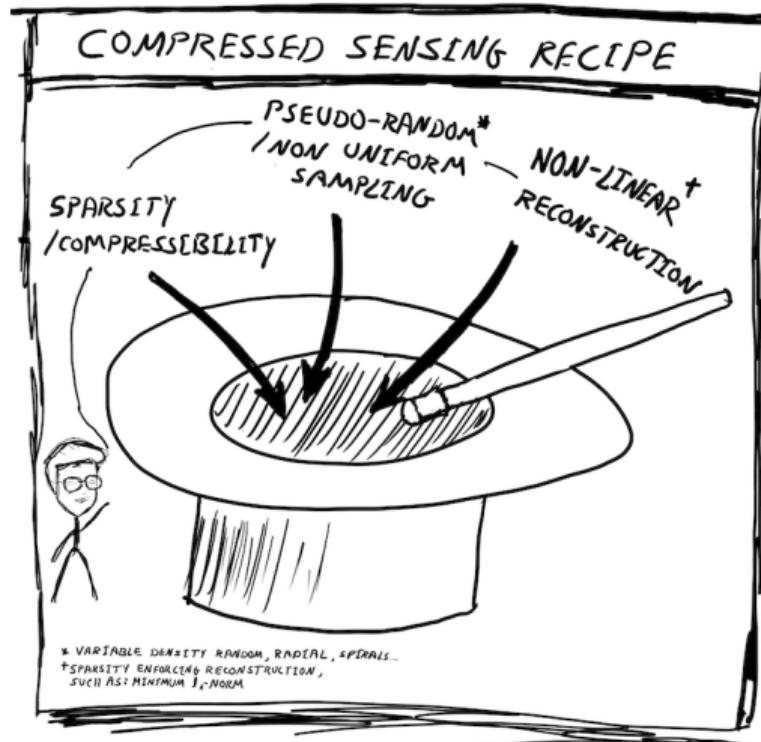


Undersampled
rawdata

Reconstruction

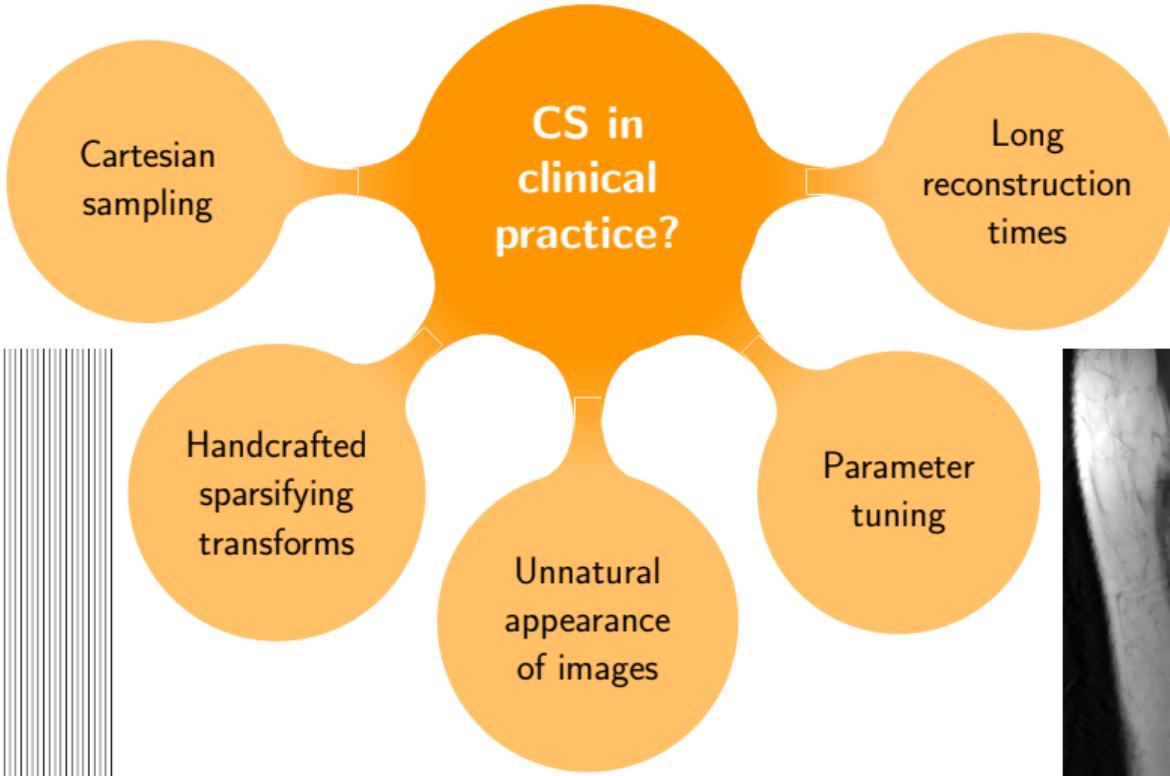


Compressed Sensing (CS) accelerated MRI



© M. Lustig

Application of CS to clinical routine exams?



Challenges in CS

Variational model

$$\min_u E = \min_u \underbrace{\frac{\lambda}{2} \|Au - f\|_2^2}_{\text{data consistency}} + \underbrace{\sum_{i=1}^N \phi_i(K_i u)}_{\text{regularization}}$$

- u ... reconstructed image
- f ... undersampled k-space data
- A ... linear multi-coil sampling operator

Challenges in CS

$$\min_u E = \min_u \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^N \phi_i(K_i u)$$

- How to choose proper regularization term?

Challenges in CS

$$\min_u E = \min_u \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^N \phi_i(K_i u)$$

- How to choose proper regularization term?
 - ϕ_i ... potential function, e.g.: $\|\cdot\|_1$
 - K_i ... sparsifying transform, e.g.: ∇, ψ

Challenges in CS

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Total Variation (TV)

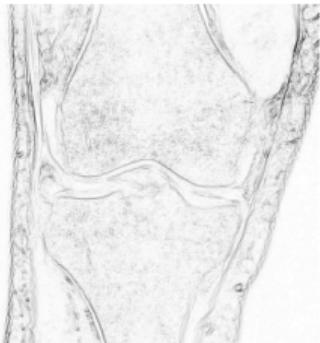
$$\phi(Ku) = \|\nabla u\|_{2,1}$$

sparse edges

[Block 2007]

TGV

[Bredies 2010, Knoll 2011]

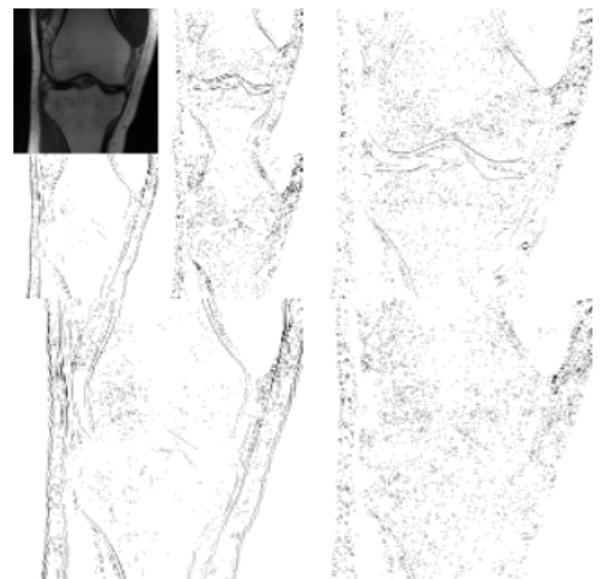


Wavelet transform

$$\phi(Ku) = \|\psi u\|_1$$

sparse coefficients

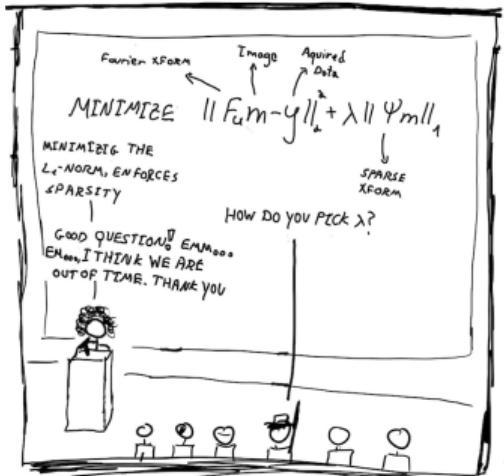
[Lustig 2007]



Challenges in CS

$$\min_u E = \min_u \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^N \phi_i(K_i u)$$

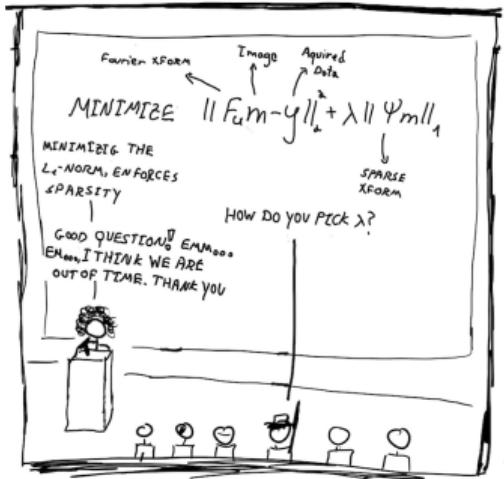
- How to choose proper regularization term?
- How to choose proper regularization parameter λ ?



Challenges in CS

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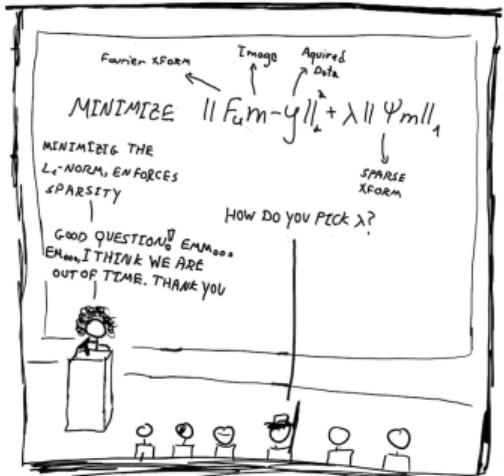
© M. Lustig



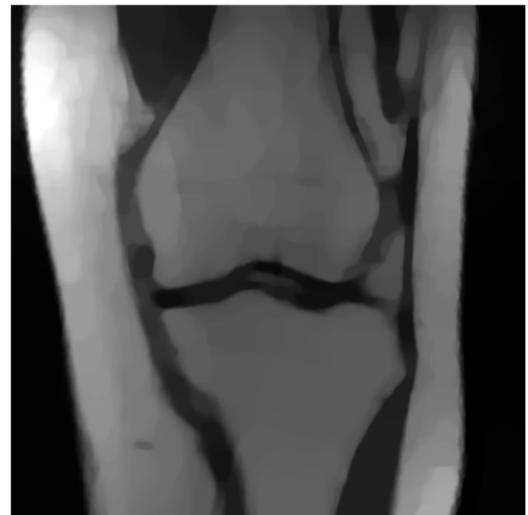
Challenges in CS

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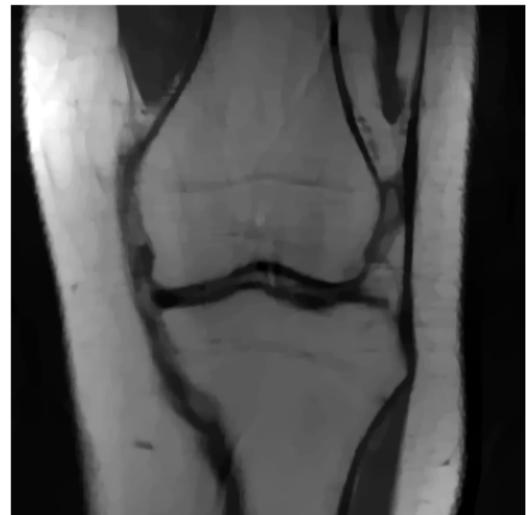
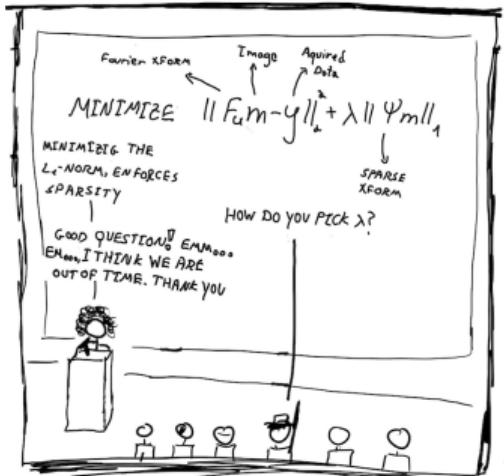
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Challenges in CS

$$\min_u E = \min_u \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^N \phi_i(K_i u)$$

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Challenges in CS

$$\min_u E = \min_u \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^N \phi_i(K_i u)$$

- How to choose proper regularization term?
- How to choose proper regularization parameter λ ?
- Optimization algorithm?
 - non-linear CG, split Bregman, (F)ISTA, primal-dual,...

Challenges in CS

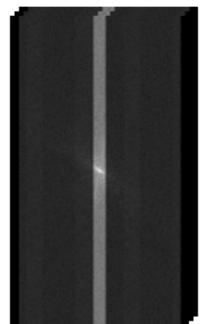
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- Optimization algorithm?

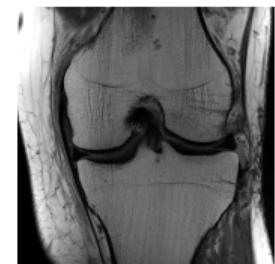
Our approach: CS meets Deep Learning

Learning optimal regularization and reconstruction algorithm
for the reconstruction of undersampled data.

Our approach: CS meets Deep Learning

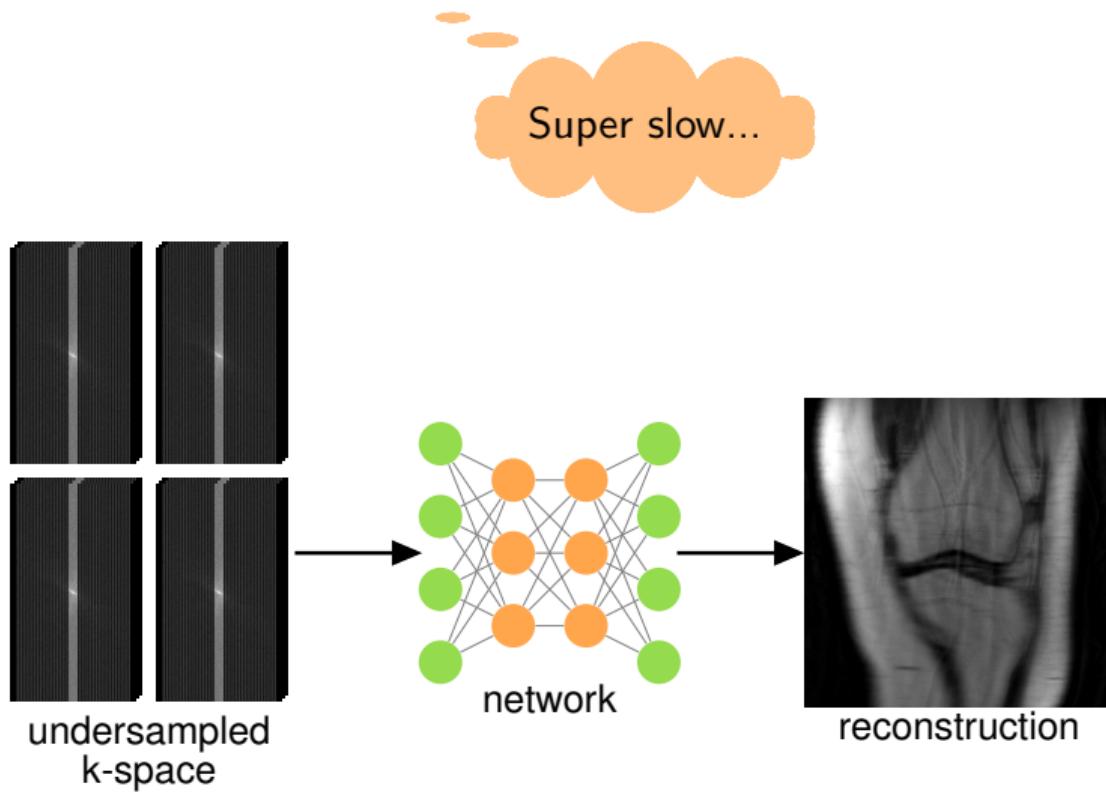


Deep learning
reconstruction
algorithm

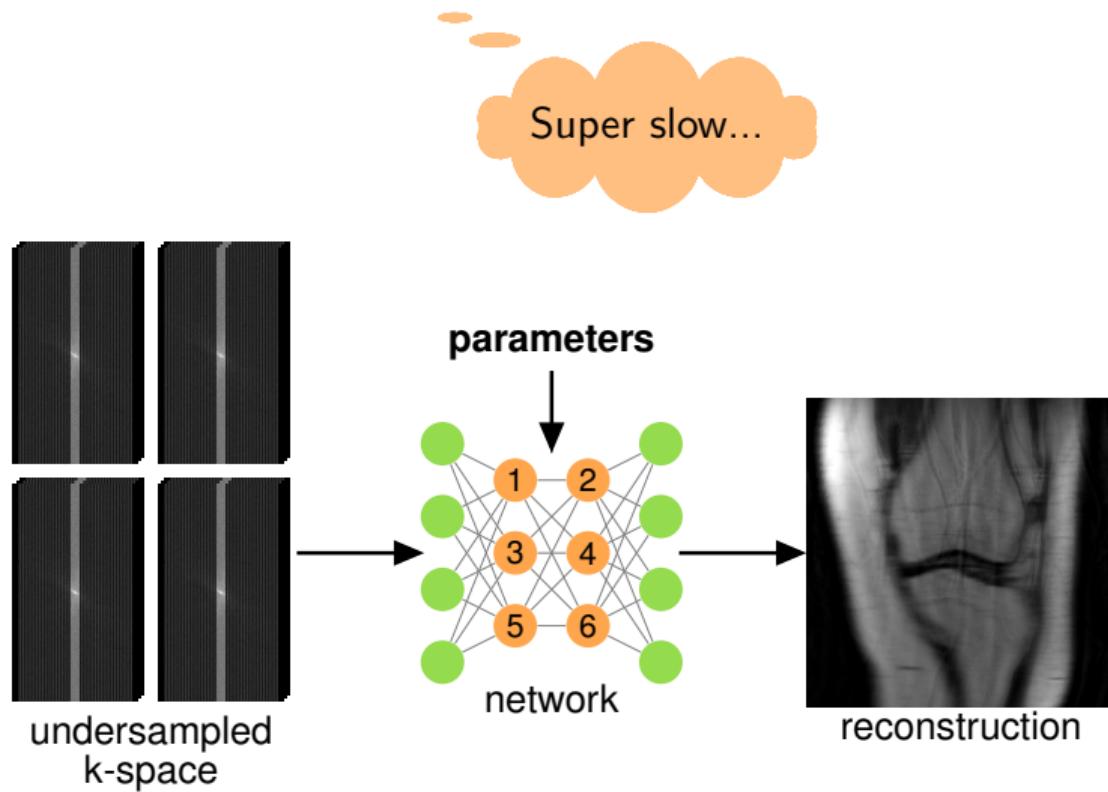


Reconstruction

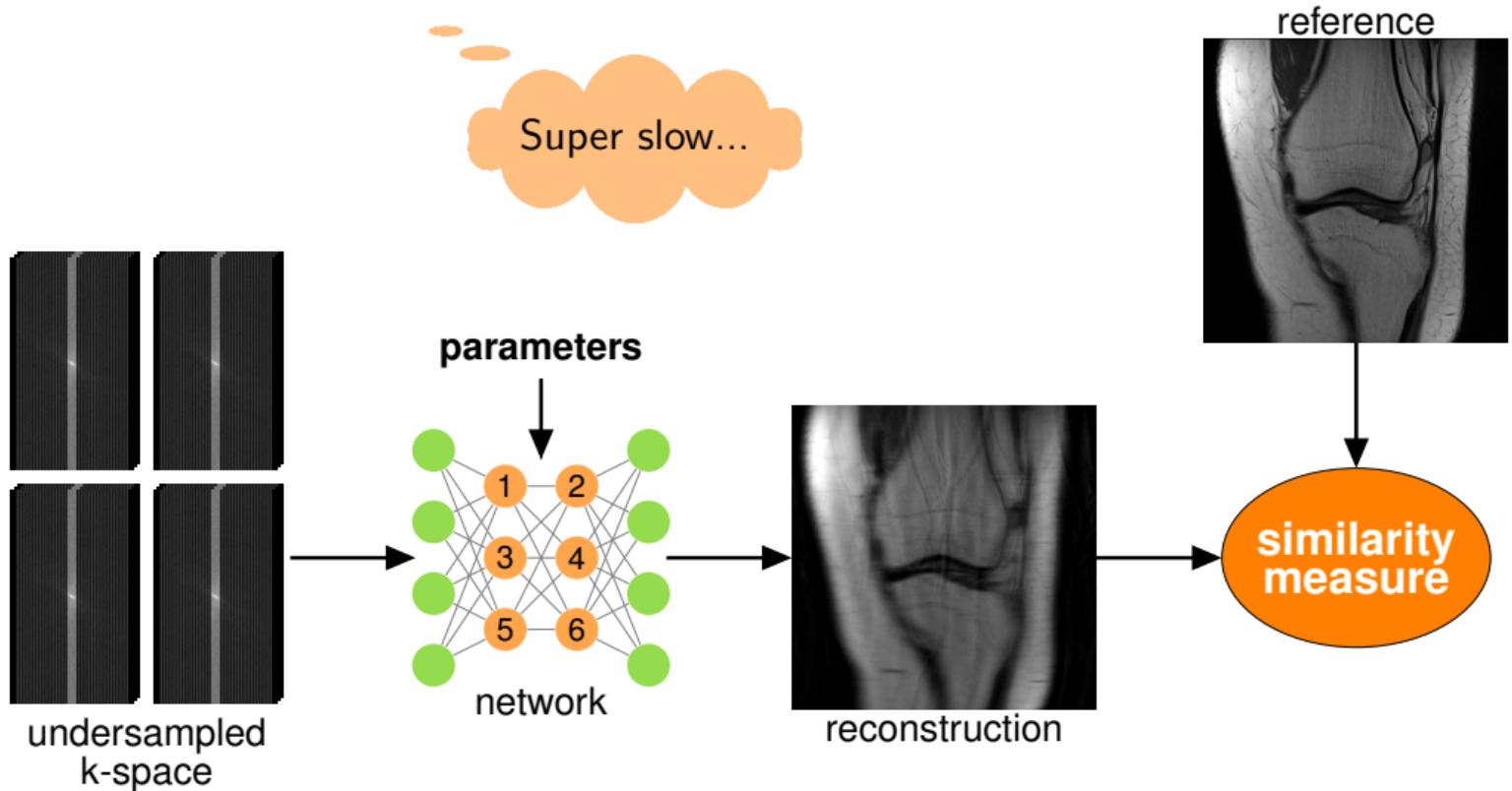
Supervised Learning in a Nutshell



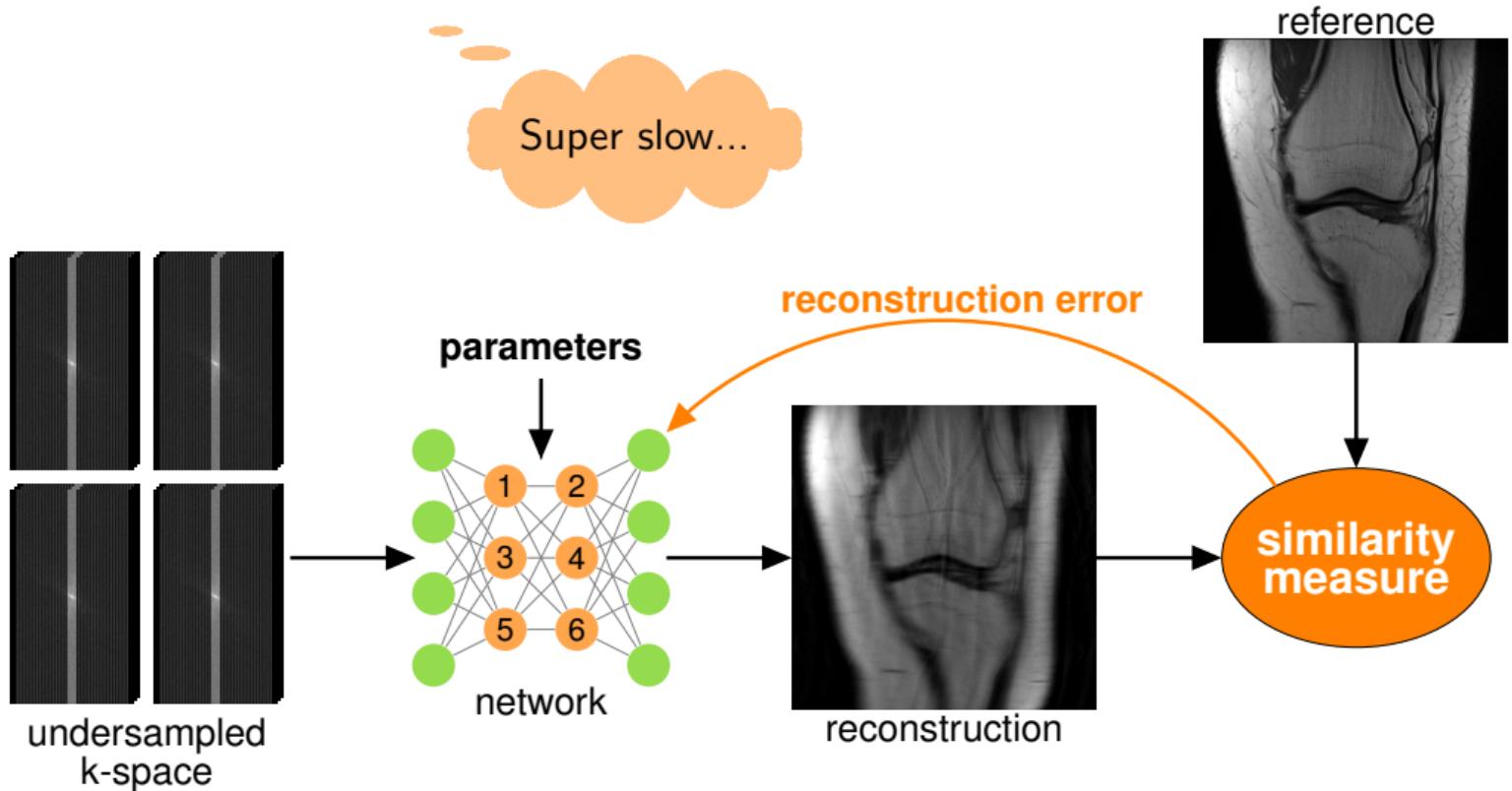
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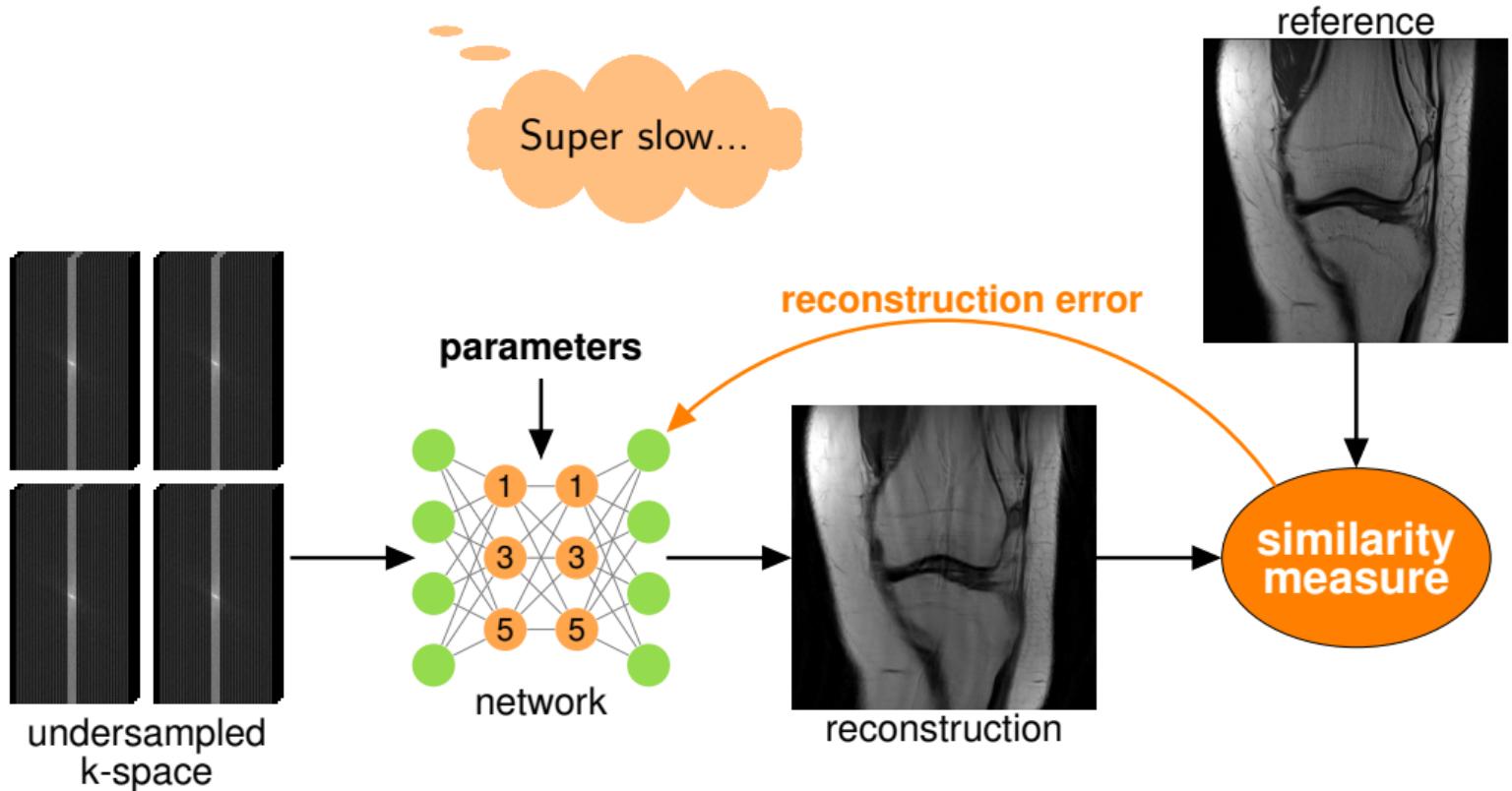
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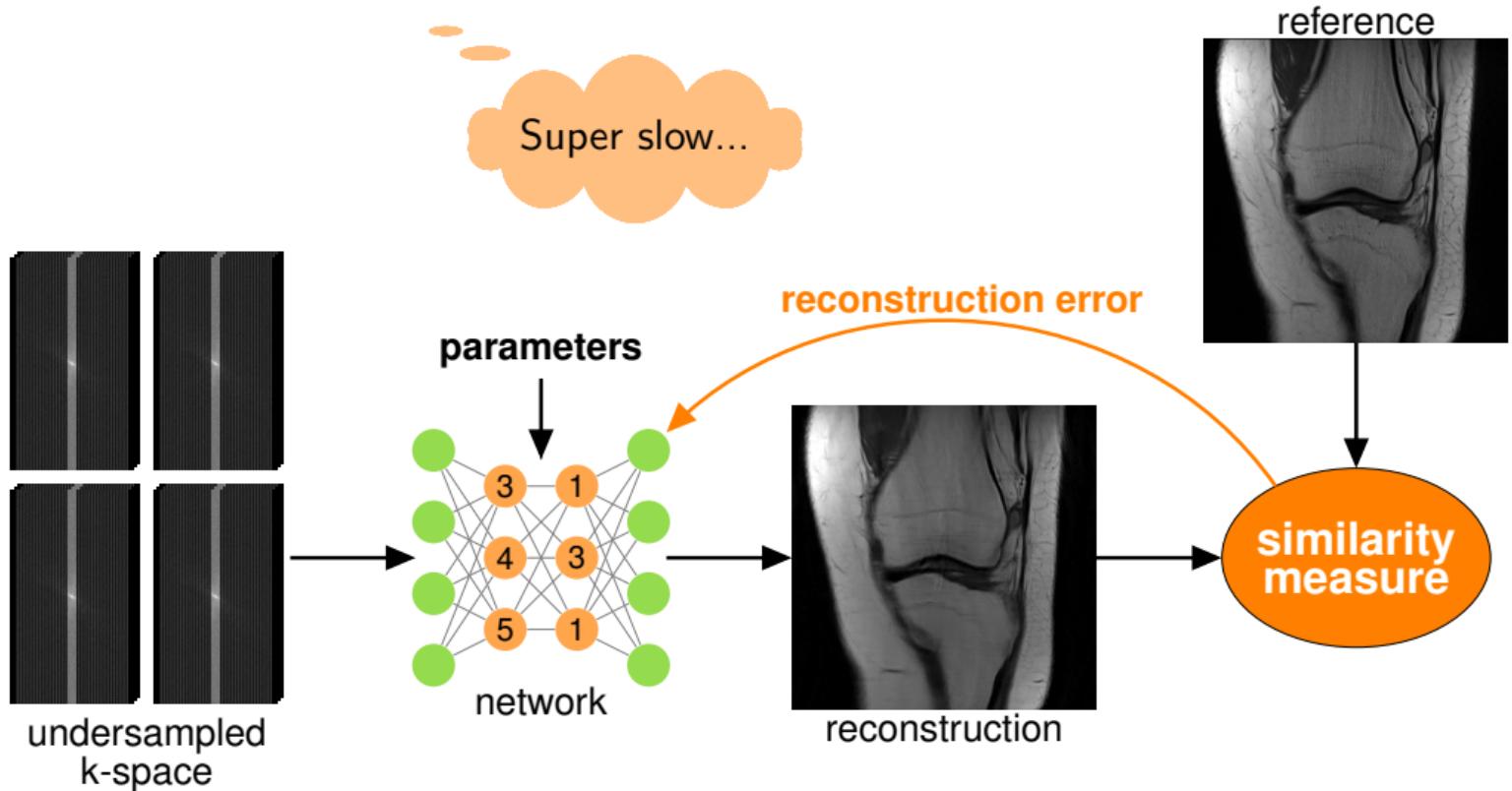
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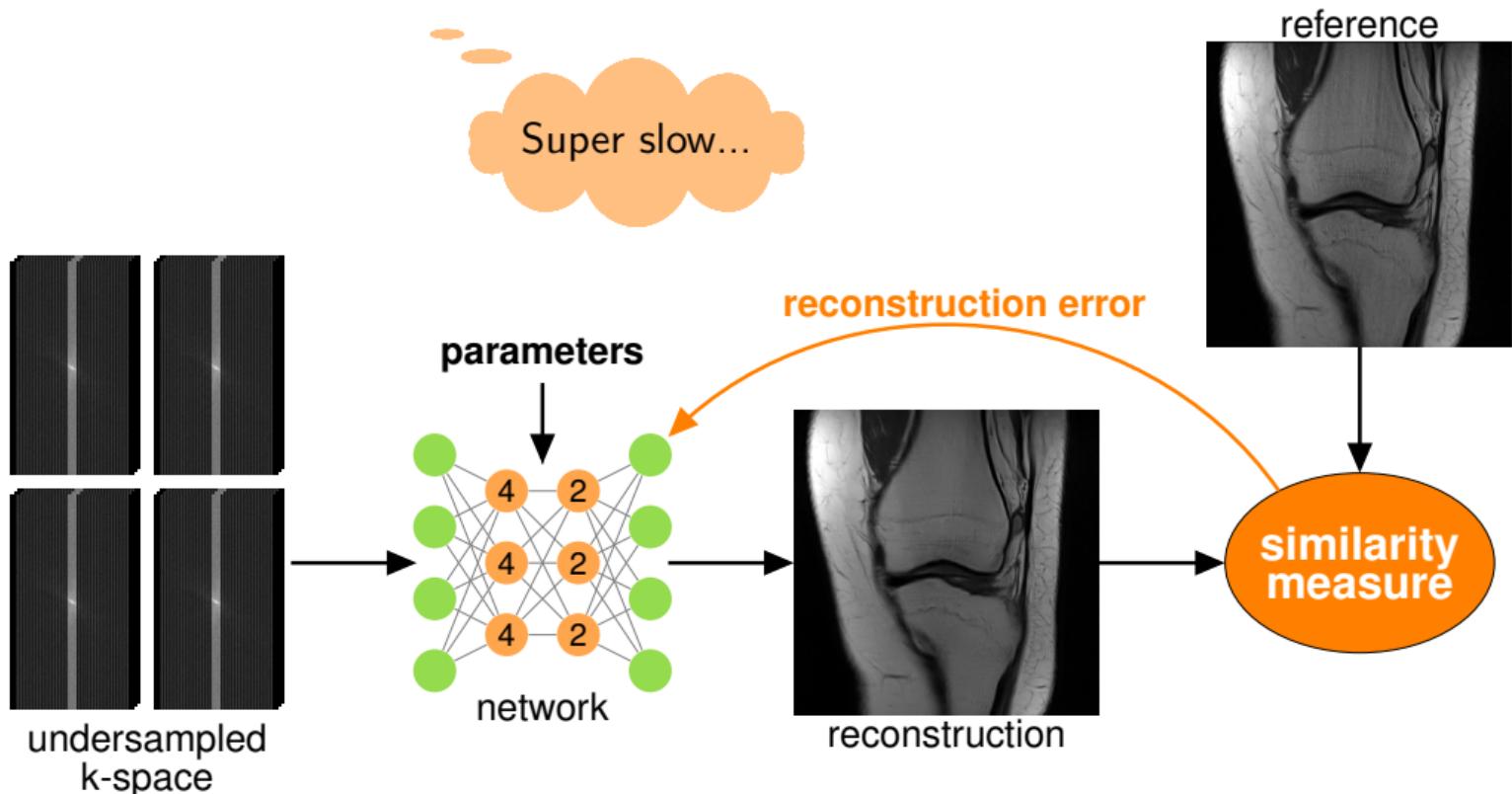
Supervised Learning in a Nutshell



Supervised Learning in a Nutshell

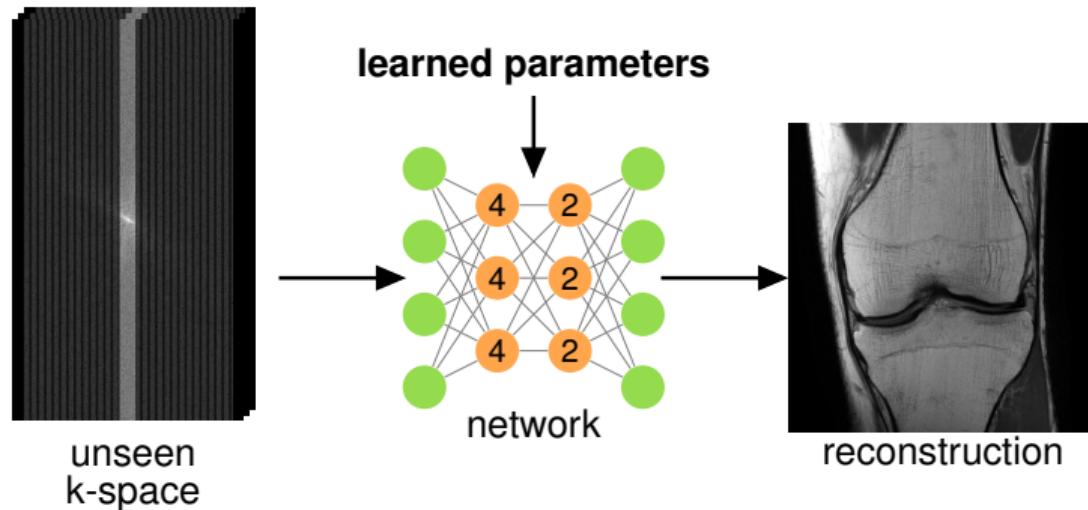


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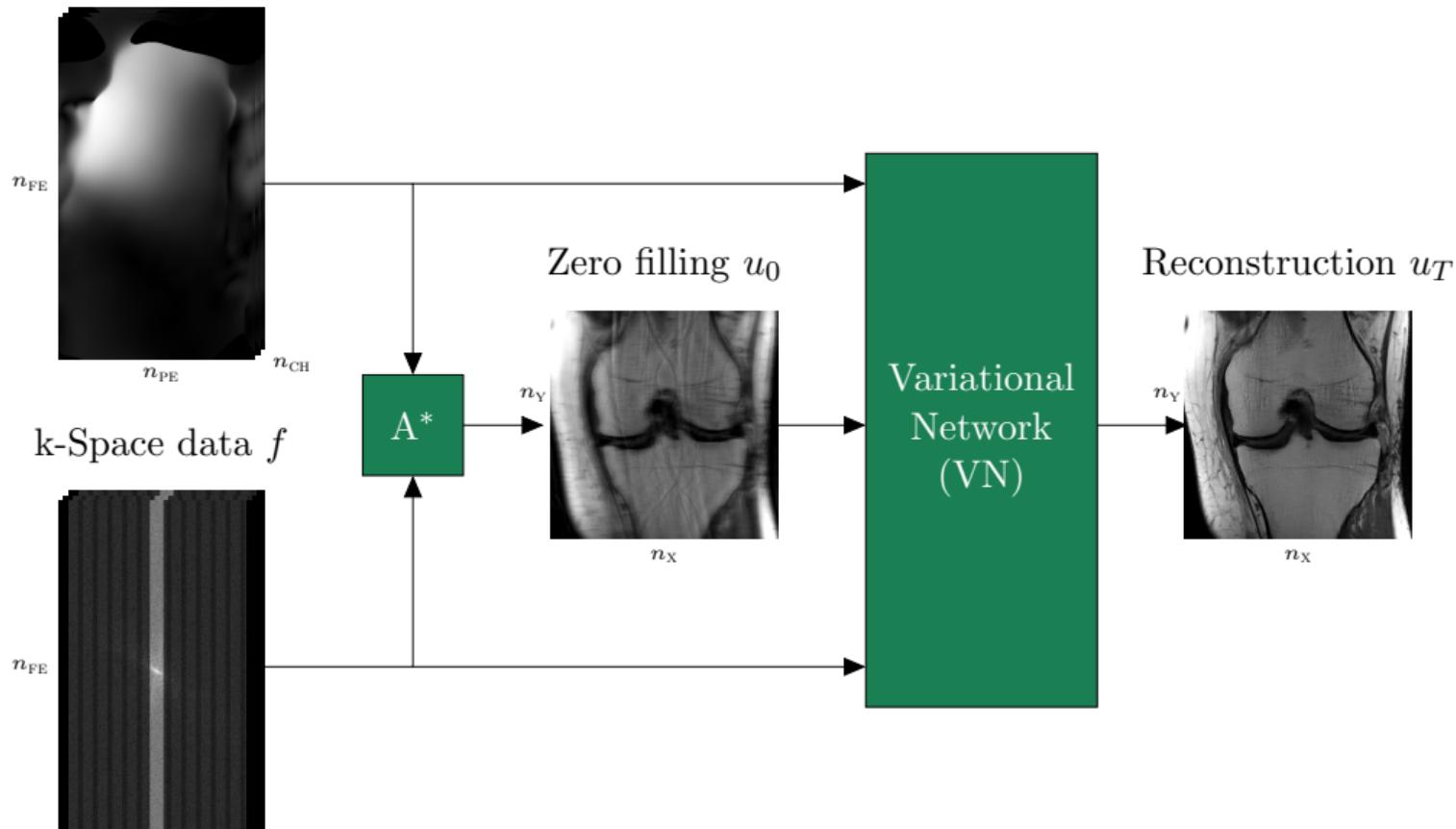


Inference / Testing on new unseen data

Super fast!



Sensitivity maps



Variational Network

Unrolled Gradient Descent Scheme

Learn T gradient descent (GD) steps

$$u^{t+1} = u^t - \frac{\partial}{\partial u} E(u^t)$$

$$E(u) = \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^{N_k} \phi_i(K_i u)$$

Variational Network

Unrolled Gradient Descent Scheme

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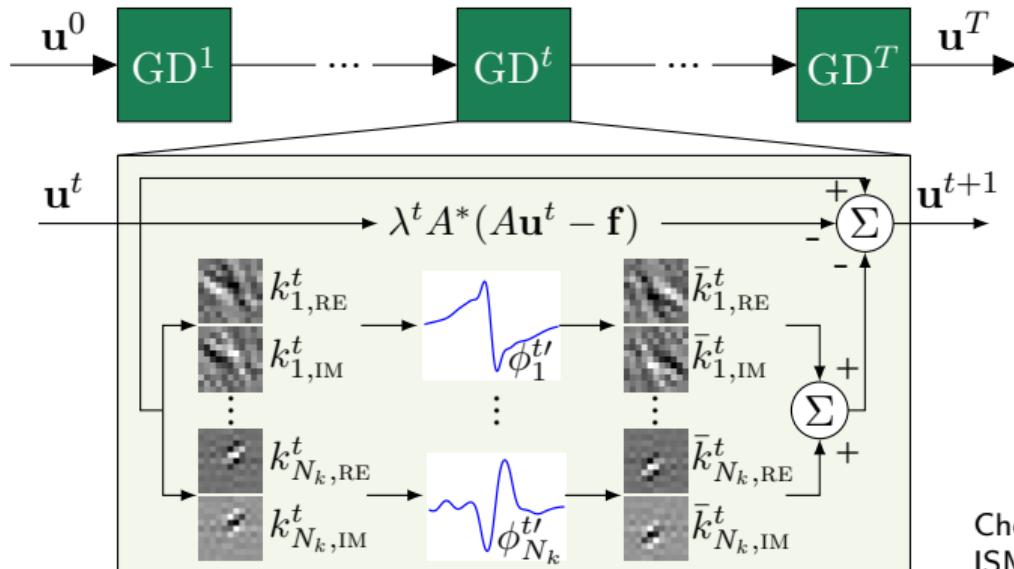
$$E(u) = \frac{\lambda}{2} \|Au - f\|_2^2 + \sum_{i=1}^{N_k} \phi_i(K_i u)$$

Relation to Compressed Sensing

$$N_k = 1, \quad \phi_1 = \|\cdot\|_1, \quad K_1 = \nabla$$

Variational Network

Unrolled Gradient Descent Scheme



$$\mathbf{u}^{t+1} = \mathbf{u}^t - \sum_{i=1}^{N_k} (\mathbf{K}_i^t)^\top \phi_i^{t'} (\mathbf{K}_i^t \mathbf{u}^t)$$

Chen et al. CVPR 2015
ISMRM 2016 (1088)
ISMRM 2017 (644, 645, 687)
Kobler et al. GCPR 2017
Hammernik et al. MRM 2017

Network Parameters

Network Parameters

- **Filter kernels k_i^t :**

$$\|k_i^t\|_2 \leq 1, \mu(k_i^t) = 0$$

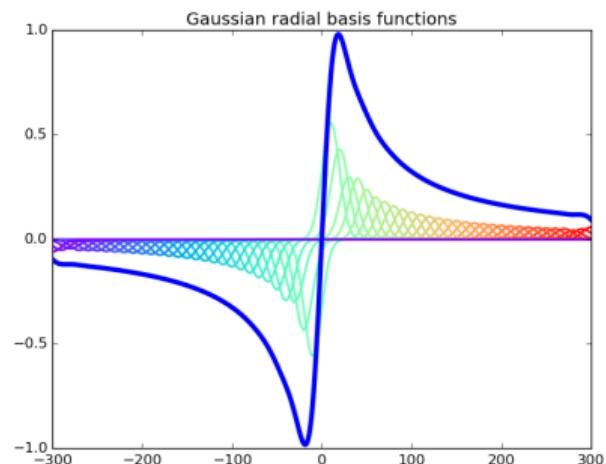
Network Parameters

- **Filter kernels** k_i^t :

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- **Activation functions** $\phi_i^{t'}(z)$:
Gaussian radial basis functions

$$\phi_i^{t'}(z) = \sum_{j=1}^M w_{ij}^t \exp\left(-\frac{(z - \mu_j)^2}{2\gamma^2}\right)$$



Network Parameters

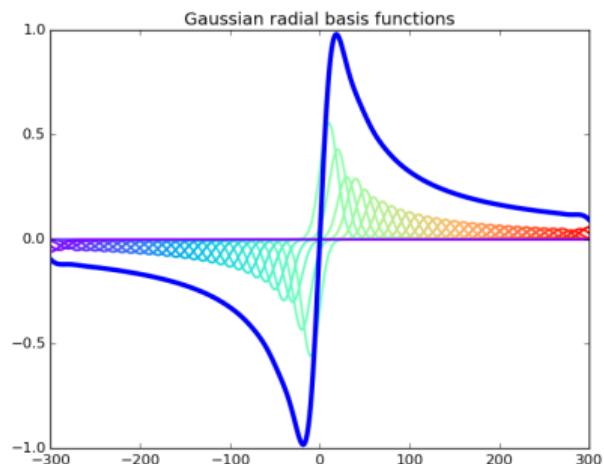
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- **Regularization parameter** λ



Experimental setup

Acquisition

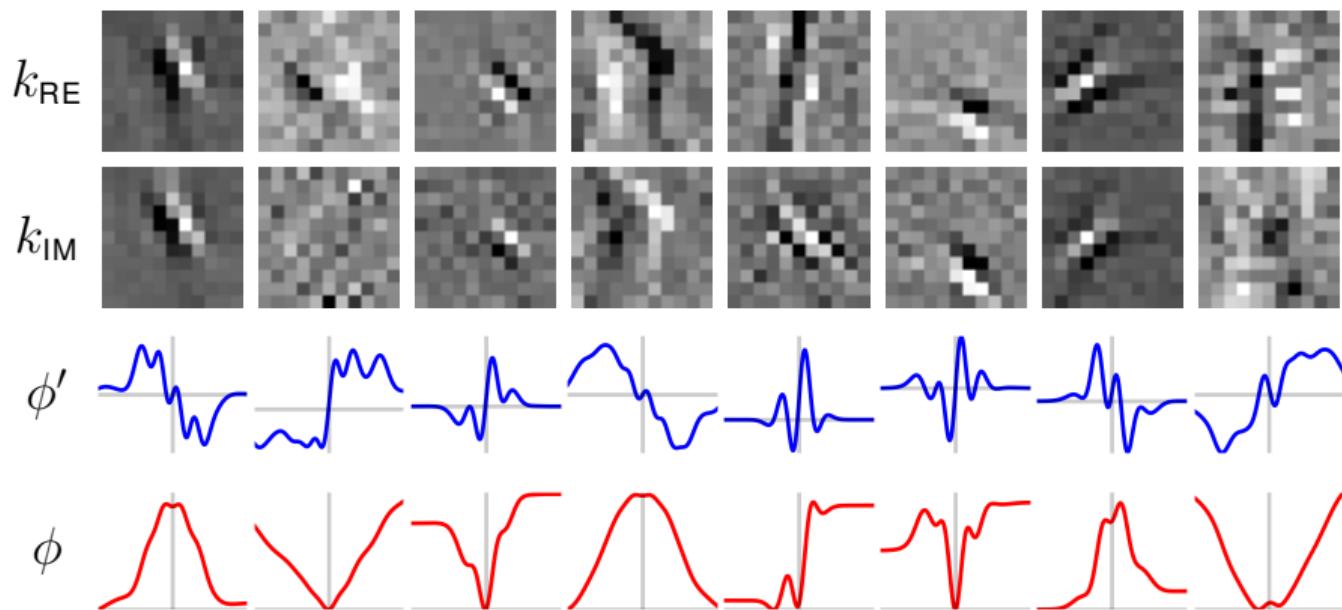
- 20 patients
- 3T clinical scanner (Siemens Magnetom Skyra), 15-channel knee coil
- Regular clinical 2D TSE sequence with turbo factor 4
- 24 calibration lines
- Full clinical protocol with 5 sequences:
 - Coronal PD
 - Coronal fat-saturated PD
 - Axial fat-saturated T_2
 - Sagittal PD
 - Sagittal T_2

Experimental setup

Variational network

- 10 patients for training (200 slices)
- 10 patients for testing
- Similarity measure: Mean-squared error (MSE)
- Optimizer: Inertial Incremental Proximal Gradient Algorithm (IIPG)
- Stages / gradient steps: 10
- Filter kernels: 48
- Filter kernels size: 11×11
- Total network parameters: 131,050

Learned Network Parameters



Results

Coronal PD R=4

Zero filling



RMSE=0.16
SSIM=0.78

Results

Coronal PD R=4

CG SENSE



RMSE=0.10
SSIM=0.85

Results

Coronal PD R=4

PI-CS: Total Generalized Variation



RMSE=0.06
SSIM=0.88

Knoll et al. MRM 2011

Results

Coronal PD R=4

Dictionary Learning



RMSE=0.07
SSIM=0.88

Ravishankar et al. TMI 2011

Results

Coronal PD R=4

Variational Network



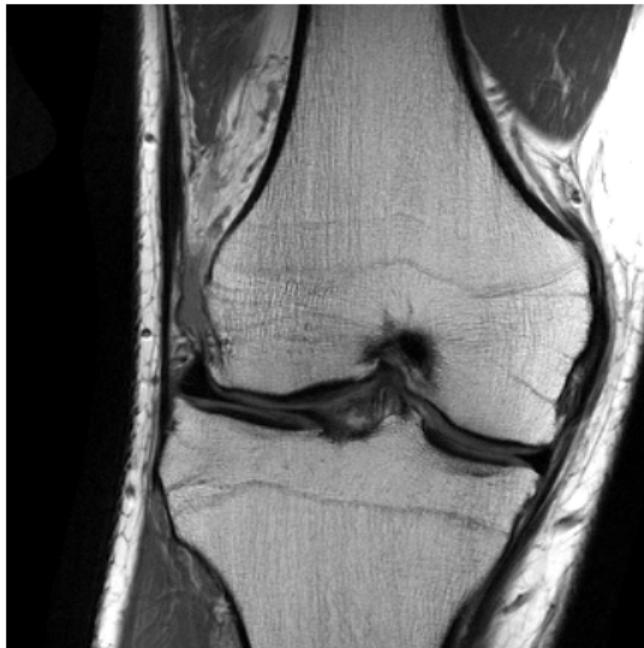
RMSE=0.06

SSIM=0.92

Results

Coronal PD R=4

Reference



Results

Coronal fat-sat. PD R=4

Zero filling



RMSE=0.17
SSIM=0.85

Results

Coronal fat-sat. PD R=4

CG SENSE



RMSE=0.16
SSIM=0.86

Results

Coronal fat-sat. PD R=4

PI-CS: Total Generalized Variation



RMSE=0.12

SSIM=0.89

Results

Coronal fat-sat. PD R=4

Dictionary Learning



RMSE=0.12
SSIM=0.90

Results

Coronal fat-sat. PD R=4

Variational Network



RMSE=0.11
SSIM=0.91

Results

Coronal fat-sat. PD R=4

Reference



Results for prospectively undersampled data

Axial fat-sat. T_2 R=4

PI-CS: Total Generalized Variation



Results for prospectively undersampled data

Axial fat-sat. T_2 R=4

Dictionary Learning



Results for prospectively undersampled data

Axial fat-sat. T_2 R=4

Variational Network



Going beyond accelerated MRI reconstruction

Low-Dose 3D Computed Tomography

X-ray tube current reduction

Reference



SAFIRE (Siemens)



Variational Network



4× dose reduction

Low-Dose 3D Computed Tomography

X-ray beam interruption

Reference



Total Variation



Variational Network

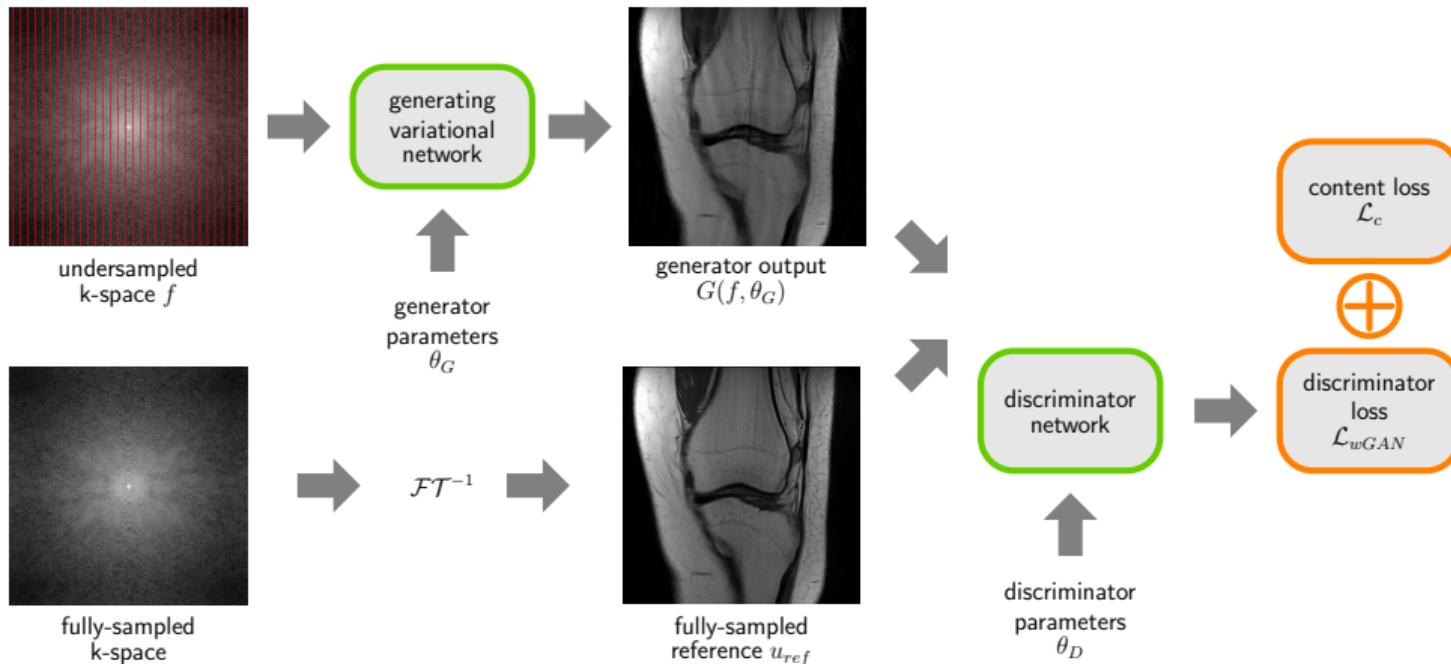


4× dose reduction

Outlook: How can we improve the image quality of low SNR images?



Outlook: Adversarial Training



Outlook: Discriminator Training

Training iteration: 1000

Generator output
of variational network
 $G(f, \theta_G)$



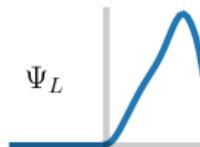
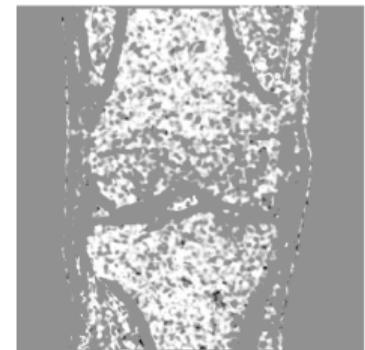
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



Outlook: Discriminator Training

Training iteration: 5000

Generator output
of variational network
 $G(f, \theta_G)$



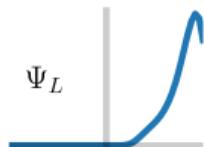
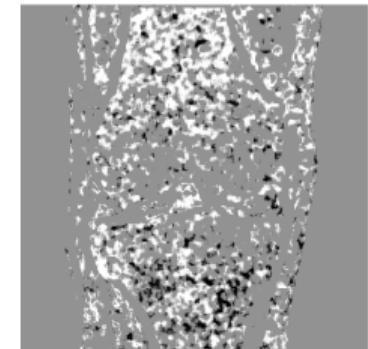
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



Outlook: Discriminator Training

Training iteration: 10000

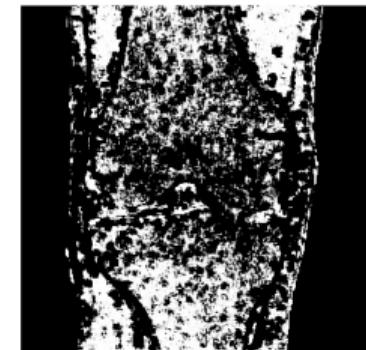
Generator output
of variational network
 $G(f, \theta_G)$



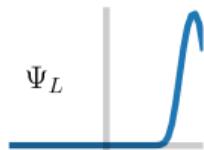
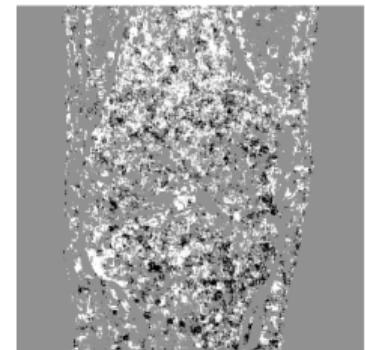
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



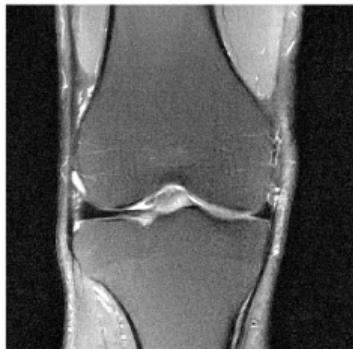
Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



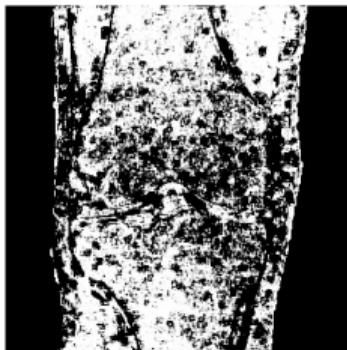
Outlook: Discriminator Training

Training iteration: 15000

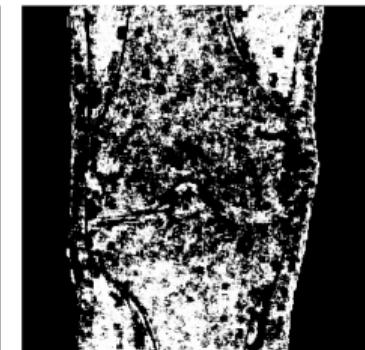
Generator output
of variational network
 $G(f, \theta_G)$



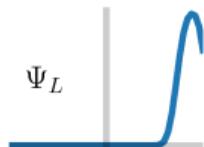
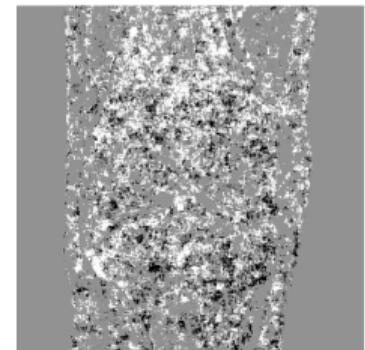
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



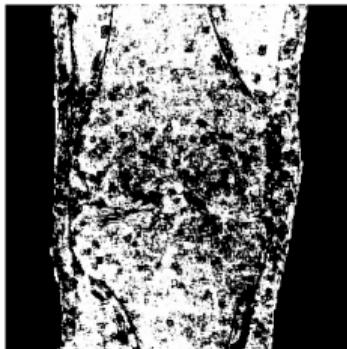
Outlook: Discriminator Training

Training iteration: 20000

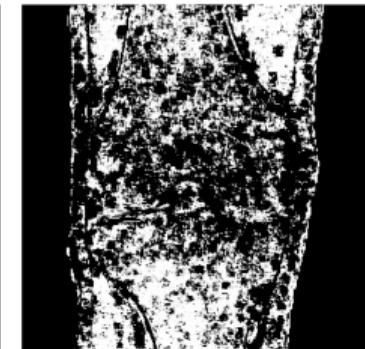
Generator output
of variational network
 $G(f, \theta_G)$



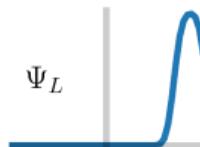
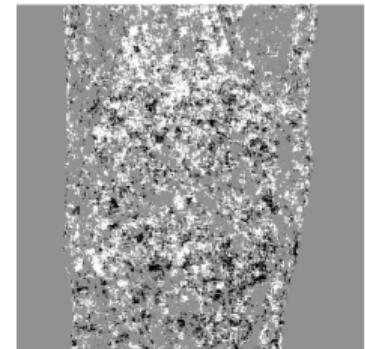
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



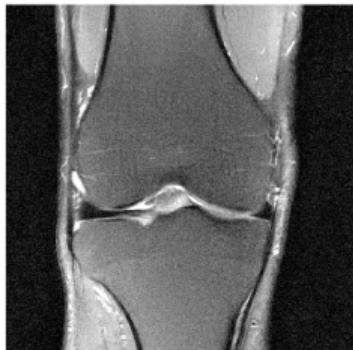
Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



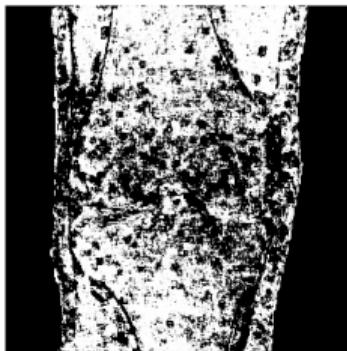
Outlook: Discriminator Training

Training iteration: 25000

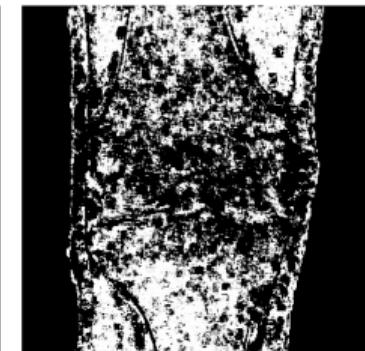
Generator output
of variational network
 $G(f, \theta_G)$



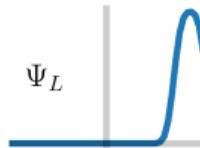
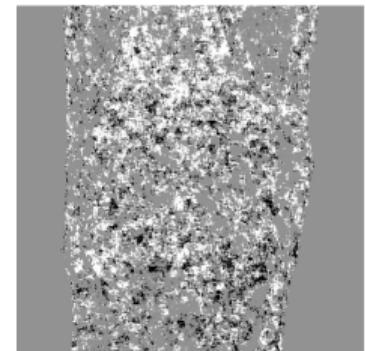
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



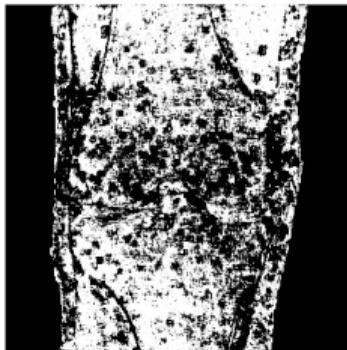
Outlook: Discriminator Training

Training iteration: 30000

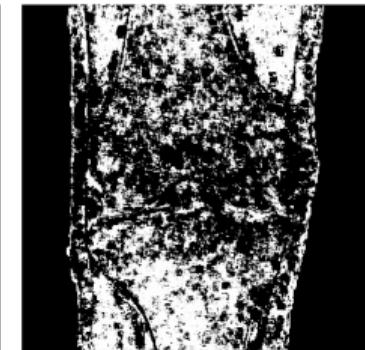
Generator output
of variational network
 $G(f, \theta_G)$



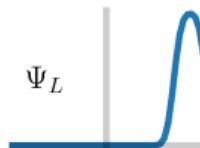
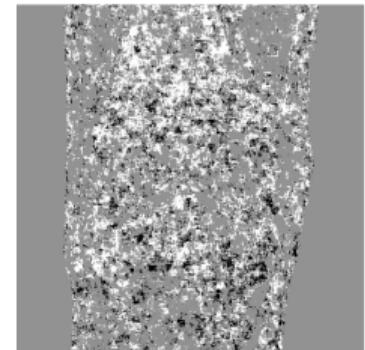
Discriminator output
for generated image
 $D(G(f, \theta_G), \theta_D)$



Discriminator output
for reference
 $D(u_{ref}, \theta_D)$



Difference of
discriminator outputs
 $D(G(f, \theta_G), \theta_D) - D(u_{ref}, \theta_D)$



Preliminary Results

Coronal fat-sat. PD R=4

Reference



Variational Network



Preliminary Results

Coronal fat-sat. PD R=4

Reference



Variational Network

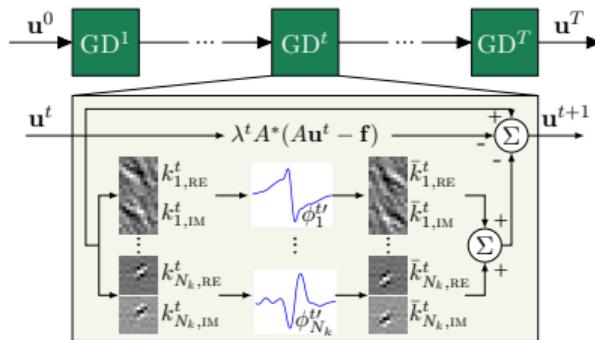


Variational Adversarial Network



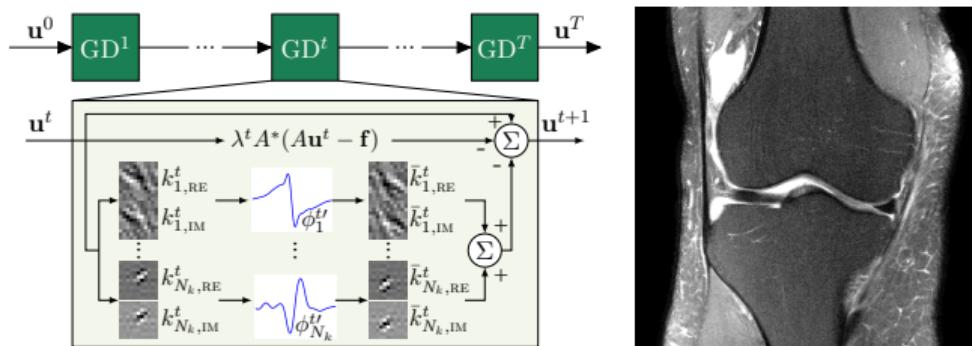
Conclusion

- Variational networks: Connecting variational models and deep learning



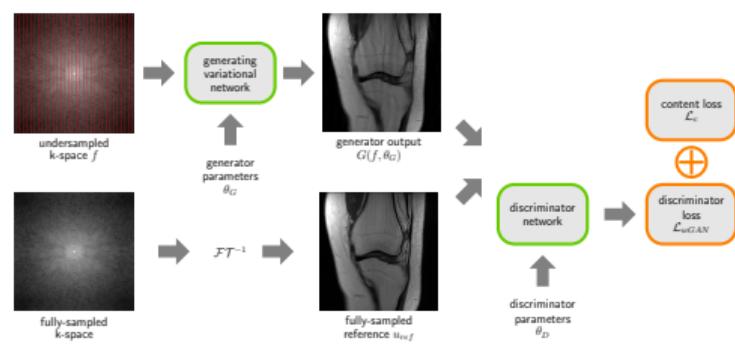
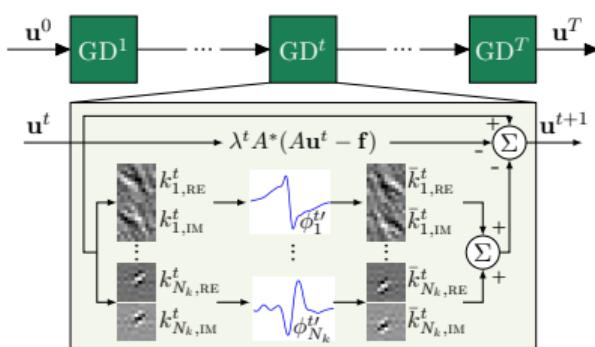
Conclusion

- Variational networks: Connecting variational models and deep learning
- Training environment with real multi-coil patient data



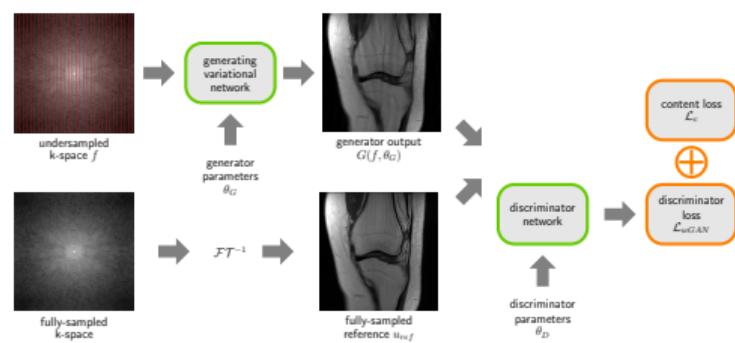
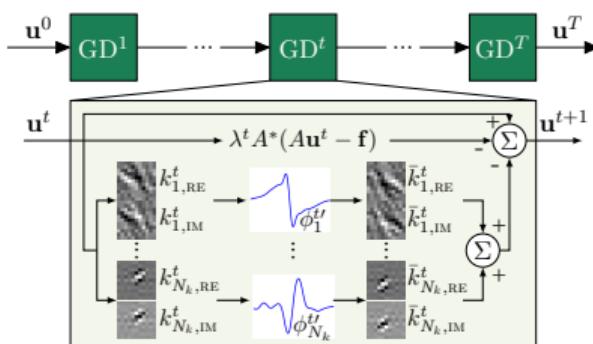
Conclusion

- Variational networks: Connecting variational models and deep learning
- Training environment with real multi-coil patient data
- Outlook: Variational Adversarial Networks - Inspired by adversarial training



Conclusion

- Variational networks: Connecting variational models and deep learning
- Training environment with real multi-coil patient data
- Outlook: Variational Adversarial Networks - Inspired by adversarial training
- Coming soon: Tensorflow source code



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