std::enable shared sophia::examples::tic from this < Player > tac toe::observer::Observer Update() + sophia::examples::tic tac toe::models::Player # m player symbol + Player() + ~Player() + symbol() + NextMove() + Value() sophia::examples::tic sophia::examples::tic tac toe::models::Bot tac toe::models::Human node iterations Human() Bot() + NextMove() + NextMove() + Update() + Update() +