std::enable shared from this < Player > + sophia::monte carlo ::tic tac toe::models ::Player # m player symbol + Player() + ~Player() + symbol() + NextMove() + Value()

sophia::monte_carlo ::tic_tac_toe::observer ::Observer + Update()

sophia::monte_carlo ::tic_tac_toe::models::Bot

- node
- iterations_
- + Bot()
- + NextMove()
- + Update()

sophia::monte_carlo ::tic_tac_toe::models ::Human

- + Human()
- + NextMove()
- + Update()