CMSI 2130 - Classwork 2

OPTIONAL SUPPLEMENT

Instructions:

This worksheet gives you some important practice with the basics of uninformed search:

- Provide answers to each of the following questions and write your responses in the blanks. If you are expected to show your work in arriving at a particular solution, space will be provided for you.
- Place the names of your group members below:

Group Members:

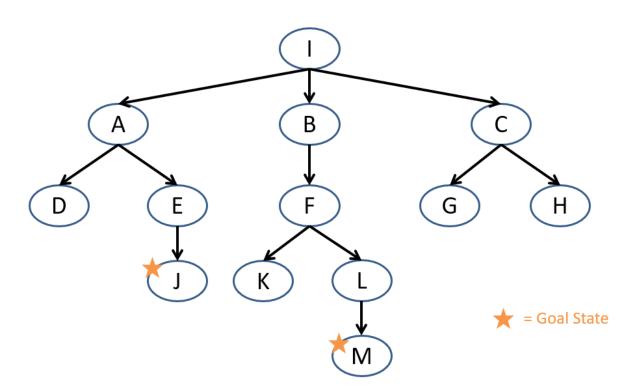
1.	 	
2.		
3.		

[!] NOTE: If completing digitally, since several exercises have you draw on an existing graphic, I suggest using editing tools on the PDF version (e.g., Adobe Acrobat or Mac's Preview). It is also acceptable to print this skeleton, write your solutions on the paper, and then scan your final copy so long as the resulting document is a single, multi-page PDF document that is legible (i.e., DO NOT submit like 10 blurry .jpgs you took with your 1998 Nokia).

Problem 1 – Uninformed Searches

Let's get some practice with the procedure of uninformed search strategies—the best way: doing a couple of examples by hand! Time to pretend you're a computer for a moment. Use the following search tree skeleton to answer the questions that follow—some notes:

- We'll provide some simple names to each node's state as capital letters A, B, C, etc. but this is assumed to be some arbitrary, abstract search problem.
- Goal states will be indicated with a star. Remember: with breadth-first and depth-first searches, the goal-test terminating condition is performed upon node *generation*.
- Although the full search tree is displayed for this worksheet, the following exercise traces
 how that tree is constructed, so recall that the full tree does not exist at the start (nor
 necessarily the end) of search, but is instead grown iteratively from the initial state / root.
 For example, node A doesn't exist until it is generated from having expanded its parent:
 node I.
- Node I, unimaginatively, represents the initial state from which all search strategies will begin.
- Assume that this is a uniform-cost problem in which each edge represents an action with the same cost as any other edge.



- **1.1.** Using *Breadth-first Tree Search*, on the search tree from the previous page, complete the following questions.
- **1.1.1.** Trace the execution of BFS by showing the state of the frontier and the next node expanded at each iteration of search in the table below. Some caveats:
 - Remember that search terminates when the goal test finds a goal state, so you may not use the whole table below, but you also won't need more than its number of columns.
 - In the event that multiple children are generated from an expanded parent, add them to the frontier in ascending alphabetic order. For example, when we expand the initial state, its children {A, B, C} are added to the frontier in order of A first (earliest alphabetically), then B, and finally C.
 - The first two columns / iterations are done for you. Complete the remaining columns until the search would terminate.

Queue Back						
Back						
		С				
Queue Front		В				
	I	Α				

1.1.2. In what order were nodes expanded during the search operation in 1.1.1.? (you may not use every cell below and should not include the found goal).								
1 1 2 Dot	ormino (1) v	which goal	ctato was f	ound by the	s coarch on	oration in 1	1 1 1 and /	2) whathar

1.1.3. Determine (1) which goal state was found by the search operation in 1.1.1. and (2) whether or not that goal is optimal and why.

- **1.2.** Now using *Depth-limited Tree Search* with a generation depth limit m=4 and the same search tree from the previous problem, answer the following questions:
- **1.2.1.** Repeat exercise 1.1.1. in the table below, but for DLFS with a depth limit m=4. Again, the first two columns / iterations are done for you, but note the change in the frontier's data structure!

Stack Top						
Тор						
		С				
Stack Bottom		В				
Bottom	Ī	А				

1.2.2. In what order we	ere nodes expanded	during the search	operation in 1.2	.1.? (you r	nay no
use every cell below ar	nd should not include	the found goal).			

1.2.3. Determine (1) which goal state was found by the search operation in 1.2.1. and (2) whethe
or not that goal is optimal and why.

or not t	of flot that goal is optimal and why.						