

This is a function to estimate the distance from a CY with a defining polynomial f , to the discriminant locus.

The method is to find the discrete solutions x_i of $\text{grad } f=0$ in each patch.

Then find the minimal normalized distance between one of these points and the manifold $f=0$, by constrained minimization of $d(x,y)^2$.

The first routine uses the Euclidean distance in the patch,

and the second one uses the distance in P^n , which is $\cos^{-1} |z_1 \cdot \bar{z}_2| / |z_1| |z_2|$.

The second one is better motivated but somewhat slower.

Note that we have to run this once for each independent patch. Often symmetry will relate the results in different patches in which case we need not run it on all the patches.

For the function f , symmetry relates all patches.

For f_2 , symmetry relates (z_1, z_2, z_5) and (z_3, z_4) , so we need two runs.

Should the result depend on patch or not??

In these runs, NMinimize is searching complex values of the coordinates.

Complex parameters might work but they are too slow.

```
In[206]:= Zsubs = {z1 → x1 + I y1, z2 → x2 + I y2, z3 → x3 + I y3, z4 → x4 + I y4, z5 → x5 + I y5}
```

```
Out[206]= {z1 → x1 + I y1, z2 → x2 + I y2, z3 → x3 + I y3, z4 → x4 + I y4, z5 → x5 + I y5}
```

```
In[208]:= XYsubs[vars_] := Variables[Apply[Times, vars] /. Zsubs]
```

```
In[218]:= EstimateDistanceInCPN[f_, patch_, vars_] := Module[{eqs, gradzero},
  eqs = Map[# == 0 &, Grad[f /. patch → 1, vars]];
  gradzero = DeleteDuplicates[Solve[eqs, vars]];
  dmin[sol_] := Norm[Map[(# /. sol) - # &, vars]];
  reim = ReIm[f /. patch → 1];
  MinimalBy[Map[NMinimize[{dmin[#], 0 == reim[[1]], 0 == reim[[2]]} /. Zsubs,
    XYsubs[vars]] &, gradzero], #[[1]] &]
]
```

```
In[227]:= EstimateTrueDistanceInCPN[f_, patch_, vars_] := Module[{eqs, gradzero},
  eqs = Map[# == 0 &, Grad[f /. patch → 1, vars]];
  gradzero = DeleteDuplicates[Solve[eqs, vars]];
  dmin[sol_] := Abs[1 + Total[Map[# Conjugate[# /. sol] &, vars]]]^2 /
    (1 + Norm[vars]^2) / (1 + Norm[Map[(# /. sol) &, vars]]^2);
  reim = ReIm[f /. patch → 1];
  res =
    MaximalBy[Map[NMaximize[{dmin[#], 0 == reim[[1]], 0 == reim[[2]]} /. Zsubs,
      XYsubs[vars]] &, gradzero], #[[1]] &];
  Map[{ArcCos[#[[1]]] / Pi, #[[2]]} &, res]
]
```

The conifold is $\psi=-5$ in these conventions.

```
In[212]:= f = z1^5 + z2^5 + z3^5 + z4^5 + z5^5 + psi z1 z2 z3 z4 z5
```

```
Out[212]= z1^5 + z2^5 + z3^5 + z4^5 + psi z1 z2 z3 z4 z5 + z5^5
```

$$z1^5 + z2^5 + z3^5 + z4^5 + psi z1 z2 z3 z4 z5 + z5^5$$

```
In[219]:= EstimateDistanceInCPN[f /. psi -> 0, z1, {z2, z3, z4, z5}]
```

```
Out[219]= {{1. + 0. i,
  {x2 -> -6.69067 x 10^-9, y2 -> -5.34941 x 10^-9, x3 -> -7.2824 x 10^-9, y3 -> -7.80349 x 10^-9,
  x4 -> -5.43845 x 10^-9, y4 -> -2.08305 x 10^-9, x5 -> 0.809017, y5 -> -0.587785}}}}
```

```
In[220]:= EstimateDistanceInCPN[f /. psi -> -1, z1, {z2, z3, z4, z5}]
```

```
Out[220]= {{0.845117, {x2 -> 0.0600428, y2 -> -0.195952, x3 -> 0.80746, y3 -> -0.587842,
  x4 -> 0.066602, y4 -> 0.193821, x5 -> 0.0666019, y5 -> 0.193821}}}}
```

```
In[221]:= EstimateDistanceInCPN[f /. psi -> -2, z1, {z2, z3, z4, z5}]
```

```
Out[221]= {{0.694836, {x2 -> -0.361387, y2 -> -0.23309, x3 -> 0.155358, y3 -> 0.400991,
  x4 -> 0.782842, y4 -> -0.589975, x5 -> -0.333356, y5 -> 0.271667}}}}
```

```
In[222]:= EstimateDistanceInCPN[f /. psi -> -3, z1, {z2, z3, z4, z5}]
```

```
Out[222]= {{0.517283, {x2 -> 0.278849, y2 -> 0.598793, x3 -> 0.792343, y3 -> 0.449458,
  x4 -> -0.577566, y4 -> -0.320533, x5 -> 0.278849, y5 -> 0.598793}}}}
```

```
In[223]:= EstimateDistanceInCPN[f /. psi -> -4, z1, {z2, z3, z4, z5}]
```

```
Out[223]= {{0.316066, {x2 -> 0.848861, y2 -> 0.217256, x3 -> -0.662494, y3 -> 0.481322,
  x4 -> 0.468957, y4 -> 0.740175, x5 -> -0.662494, y5 -> 0.481323}}}}
```

```
In[224]:= EstimateDistanceInCPN[f /. psi -> -4.5, z1, {z2, z3, z4, z5}]
```

```
Out[224]= {{0.210096, {x2 -> -0.830711, y2 -> 0.421781, x3 -> -0.734027, y3 -> -0.534293,
  x4 -> 0.279694, y4 -> -0.863735, x5 -> 0.424037, y5 -> 0.829532}}}}
```

```
In[225]:= EstimateDistanceInCPN[f /. psi -> -4.9, z1, {z2, z3, z4, z5}]
```

```
Out[225]= {{0.0902418 + 0. i, {x2 -> -0.758187, y2 -> 0.629592, x3 -> -0.794325,
  y3 -> 0.576321, x4 -> -0.793576, y4 -> 0.577352, x5 -> 0.364484, y5 -> -0.915634}}}}
```

```
In[226]:= EstimateDistanceInCPN[f /. psi -> -6, z1, {z2, z3, z4, z5}]
```

```
Out[226]= {{0.248543, {x2 -> 0.442569, y2 -> 1.36209, x3 -> -0.929406, y3 -> -0.675255,
  x4 -> 1.1488, y4 -> 1.71445 x 10^-6, x5 -> 0.354997, y5 -> 1.09258}}}}
```

```
In[239]:= EstimateDistanceInCPN[f /. psi -> 0.5, z1, {z2, z3, z4, z5}]
```

```
Out[239]= {{0.900093, {x2 -> -0.0992015, y2 -> 5.83743 x 10^-9, x3 -> -0.030655, y3 -> 0.0943463,
  x4 -> -0.030655, y4 -> 0.0943463, x5 -> 0.809091, y5 -> -0.587839}}}}
```

```

In[240]:= EstimateDistanceInCPN[f /. psi → 4, z1, {z2, z3, z4, z5}]
Out[240]= {{0.388713, {x2 → -0.749087, y2 → 6.45915 × 10-7, x3 → -0.231483,
y3 → -0.712424, x4 → 0.95349, y4 → 0.69275, x5 → -0.231483, y5 → -0.712424}}}}

In[241]:= EstimateDistanceInCPN[f /. psi → 6, z1, {z2, z3, z4, z5}]
Out[241]= {{0.367686, {x2 → -0.350997, y2 → 1.08024, x3 → 1.25437, y3 → -0.911353,
x4 → -0.350996, y4 → -1.08026, x5 → 0.918905, y5 → 0.667625}}}}

In[139]:= EstimateDistanceInCPN[f /. psi → 0.1 I, z1, {z2, z3, z4, z5}]
Out[139]= $Aborted

In[228]:= EstimateTrueDistanceInCPN[f /. psi → 0, z1, {z2, z3, z4, z5}]
Out[228]= {{0.333333, {x2 → 0.809017, y2 → -0.587785, x3 → -1.53187 × 10-8, y3 → -1.42181 × 10-8,
x4 → 1.13199 × 10-9, y4 → 1.83833 × 10-9, x5 → -1.9778 × 10-9, y5 → 1.02064 × 10-8

```

```

In[236]:= EstimateTrueDistanceInCPN[f /. psi → -6, z1, {z2, z3, z4, z5}]
Out[236]= {{0.0274821, {x2 → 1.44221, y2 → -3.55397 × 10-6, x3 → 1.44222, y3 → 1.47179 × 10-9,
x4 → 1.44222, y4 → 8.12741 × 10-7, x5 → 1.44221, y5 → 2.73253 × 10-6}}}

In[243]:= EstimateTrueDistanceInCPN[f /. psi → -10, z1, {z2, z3, z4, z5}]
Out[243]= {{0.0211915, {x2 → 2.49353, y2 → 9.30276 × 10-11, x3 → 0.770544,
y3 → 2.37149, x4 → 0.770544, y4 → 2.37149, x5 → -2.01731, y5 → -1.46566}},
{0.0211915, {x2 → 0.770544, y2 → -2.37149, x3 → -2.01731, y3 → -1.46566,
x4 → -2.01731, y4 → 1.46566, x5 → 0.770544, y5 → 2.37149}},
{0.0211915, {x2 → 0.770544, y2 → -2.37149, x3 → -2.01731, y3 → 1.46566,
x4 → -2.01731, y4 → -1.46566, x5 → 0.770544, y5 → 2.37149}},
{0.0211915, {x2 → 0.770544, y2 → -2.37149, x3 → 0.770544, y3 → 2.37149,
x4 → -2.01731, y4 → -1.46566, x5 → -2.01731, y5 → 1.46566}}}

In[237]:= EstimateTrueDistanceInCPN[f /. psi → 4, z1, {z2, z3, z4, z5}]
Out[237]= {{0.0659886, {x2 → -1.08758, y2 → -8.04811 × 10-11, x3 → 0.879872,
y3 → -0.639264, x4 → -0.336081, y4 → 1.03435, x5 → -0.377528, y5 → 1.16191}}}

In[238]:= EstimateTrueDistanceInCPN[f /. psi → 6, z1, {z2, z3, z4, z5}]
Out[238]= {{0.036718, {x2 → -0.477119, y2 → -1.46842, x3 → -1.54399, y3 → -6.91824 × 10-9,
x4 → -1.54399, y4 → 7.40304 × 10-10, x5 → -0.477119, y5 → 1.46842}}}

In[242]:= f2 = f + phi (z3 z4^4 + z3^2 z4^3 + z3^3 z4^2 + z3^4 z4)
Out[242]= z1^5 + z2^5 + z3^5 + z4^5 + phi (z3^4 z4 + z3^3 z4^2 + z3^2 z4^3 + z3 z4^4) + psi z1 z2 z3 z4 z5 + z5^5

In[262]:= Reduce[Append[ Map[# == 0 &, Grad[f2 /. psi → 0.5, {z1, z2, z3, z4, z5} ]],
(f2 == 0 /. psi → 0.5) && z1 == 1], {z1, z2, z3, z4, z5}]
Out[262]= ((phi == -0.5 - 0.00158114 i || phi == -0.5 + 0.00158114 i) && z1 == 1. &&
(z2 == 1. || z2 == -0.809017 - 0.587785 i || z2 == 0.309017 + 0.951057 i ||
z2 == 0.309017 - 0.951057 i || z2 == -0.809017 + 0.587785 i) &&
(z3 == 10. (-1. - 2. phi)^(1/5) || z3 == (-8.09017 - 5.87785 i) (-1. - 2. phi)^(1/5) ||
z3 == (3.09017 + 9.51057 i) (-1. - 2. phi)^(1/5) ||
z3 == (3.09017 - 9.51057 i) (-1. - 2. phi)^(1/5) ||
z3 == (-8.09017 + 5.87785 i) (-1. - 2. phi)^(1/5)) &&
z4 == -7.54119 × 10-56 z3 (1.227 × 1059 + 1.03285 × 1055 phi - 2.45424 × 1059 phi^2 +
3.33776 × 1059 phi^3 - 2.46406 × 1059 phi^4 + 1.15762 × 1059 phi^5 -
3.58123 × 1058 phi^6 + 6.91115 × 1057 phi^7 - 6.28287 × 1056 phi^8 + 3.12992 × 1054 z3^5 -
1.03023 × 1054 phi z3^5 - 8.48053 × 1053 phi^2 z3^5 + 7.98986 × 1053 phi^3 z3^5 -
3.10131 × 1053 phi^4 z3^5 + 2.12426 × 1052 phi^5 z3^5 + 9.42731 × 1051 phi^6 z3^5) &&
z5 == 6.03295 × 10-57 z2^4 z3^3 (7.83746 × 1057 + 4.01461 × 1056 phi - 1.56511 × 1058 phi^2 +
2.05072 × 1058 phi^3 - 1.46762 × 1058 phi^4 + 6.68662 × 1057 phi^5 -
2.00436 × 1057 phi^6 + 3.73471 × 1056 phi^7 - 3.26036 × 1055 phi^8 + 1.15203 × 1053 z3^5 -

```

$$\begin{aligned}
& 1.45129 \times 10^{53} \text{phi} z^3^5 + 1.09538 \times 10^{53} \text{phi}^2 z^3^5 - 5.31283 \times 10^{52} \text{phi}^3 z^3^5 + \\
& 1.70647 \times 10^{52} \text{phi}^4 z^3^5 - 3.44875 \times 10^{51} \text{phi}^5 z^3^5 + 3.2733 \times 10^{50} \text{phi}^6 z^3^5) \mid \mid \\
& \left((\text{phi} = 2.54367 \mid \mid \text{phi} = 0.995883 - 1.99903 \text{ i} \mid \mid \text{phi} = 0.995883 + 1.99903 \text{ i} \mid \mid \right. \\
& \quad \text{phi} = 1.00412 - 2.00098 \text{ i} \mid \mid \text{phi} = 1.00412 + 2.00098 \text{ i} \mid \mid \\
& \quad \text{phi} = 2.47816 - 0.038147 \text{ i} \mid \mid \text{phi} = 2.47816 + 0.038147 \text{ i}) \&\& z1 = 1. \&\& \\
& \quad (z2 = 1. \mid \mid z2 = -0.809017 - 0.587785 \text{ i} \mid \mid z2 = 0.309017 + 0.951057 \text{ i} \mid \mid \\
& \quad z2 = 0.309017 - 0.951057 \text{ i} \mid \mid z2 = -0.809017 + 0.587785 \text{ i}) \&\& \\
& \quad \left. z3 = \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - 15055.3 \text{ phi}^3 + 5844.32 \text{ phi}^4 - \right. \right. \\
& \quad \quad 399.965 \text{ phi}^5 - 177.782 \text{ phi}^6 - 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - \right. \right.} \\
& \quad \quad \quad 1.41476 \times 10^{17} \text{ phi} - 1.16207 \times 10^{17} \text{ phi}^2 + 1.09538 \times 10^{17} \text{ phi}^3 - \\
& \quad \quad \quad 4.25218 \times 10^{16} \text{ phi}^4 + 2.91005 \times 10^{15} \text{ phi}^5 + 1.2935 \times 10^{15} \text{ phi}^6)^2} \Big)^{1/5} \mid \mid \\
& \quad z3 = (-0.809017 - 0.587785 \text{ i}) \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - \right. \\
& \quad \quad 15055.3 \text{ phi}^3 + 5844.32 \text{ phi}^4 - 399.965 \text{ phi}^5 - 177.782 \text{ phi}^6 - 1.37443 \times 10^{-13} \\
& \quad \quad \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \text{ phi} - 1.16207 \times 10^{17} \text{ phi}^2 + \right. \right.} \\
& \quad \quad \quad 1.09538 \times 10^{17} \text{ phi}^3 - 4.25218 \times 10^{16} \text{ phi}^4 + 2.91005 \times 10^{15} \text{ phi}^5 + \\
& \quad \quad \quad 1.2935 \times 10^{15} \text{ phi}^6)^2} \Big)^{1/5} \mid \mid z3 = (0.309017 + 0.951057 \text{ i}) \\
& \quad \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - 15055.3 \text{ phi}^3 + 5844.32 \text{ phi}^4 - \right. \\
& \quad \quad 399.965 \text{ phi}^5 - 177.782 \text{ phi}^6 - 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - \right. \right.} \\
& \quad \quad \quad 1.41476 \times 10^{17} \text{ phi} - 1.16207 \times 10^{17} \text{ phi}^2 + 1.09538 \times 10^{17} \text{ phi}^3 - \\
& \quad \quad \quad 4.25218 \times 10^{16} \text{ phi}^4 + 2.91005 \times 10^{15} \text{ phi}^5 + 1.2935 \times 10^{15} \text{ phi}^6)^2} \Big)^{1/5} \mid \mid \\
& \quad z3 = (0.309017 - 0.951057 \text{ i}) \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - \right. \\
& \quad \quad 15055.3 \text{ phi}^3 + 5844.32 \text{ phi}^4 - 399.965 \text{ phi}^5 - 177.782 \text{ phi}^6 - \\
& \quad \quad 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \text{ phi} - \right. \right.} \\
& \quad \quad \quad 1.16207 \times 10^{17} \text{ phi}^2 + 1.09538 \times 10^{17} \text{ phi}^3 - 4.25218 \times 10^{16} \text{ phi}^4 + \\
& \quad \quad \quad 2.91005 \times 10^{15} \text{ phi}^5 + 1.2935 \times 10^{15} \text{ phi}^6)^2} \Big)^{1/5} \mid \mid \\
& \quad z3 = (-0.809017 + 0.587785 \text{ i}) \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - \right. \\
& \quad \quad 15055.3 \text{ phi}^3 + 5844.32 \text{ phi}^4 - 399.965 \text{ phi}^5 - 177.782 \text{ phi}^6 - \\
& \quad \quad 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \text{ phi} - \right. \right.} \\
& \quad \quad \quad 1.16207 \times 10^{17} \text{ phi}^2 + 1.09538 \times 10^{17} \text{ phi}^3 - 4.25218 \times 10^{16} \text{ phi}^4 + \\
& \quad \quad \quad 2.91005 \times 10^{15} \text{ phi}^5 + 1.2935 \times 10^{15} \text{ phi}^6)^2} \Big)^{1/5} \mid \mid \\
& \quad z3 = \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - 15055.3 \text{ phi}^3 + 5844.32 \text{ phi}^4 - \right. \\
& \quad \quad 399.965 \text{ phi}^5 - 177.782 \text{ phi}^6 + 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - \right. \right.} \\
& \quad \quad \quad 1.41476 \times 10^{17} \text{ phi} - 1.16207 \times 10^{17} \text{ phi}^2 + 1.09538 \times 10^{17} \text{ phi}^3 - \\
& \quad \quad \quad 4.25218 \times 10^{16} \text{ phi}^4 + 2.91005 \times 10^{15} \text{ phi}^5 + 1.2935 \times 10^{15} \text{ phi}^6)^2} \Big)^{1/5} \mid \mid \\
& \quad \left. z3 = (-0.809017 - 0.587785 \text{ i}) \left(-59027.2 + 19444.9 \text{ phi} + 15971.8 \text{ phi}^2 - \right. \right.
\end{aligned}$$

$$\begin{aligned}
& 15\,055.3 \, \text{phi}^3 + 5844.32 \, \text{phi}^4 - 399.965 \, \text{phi}^5 - 177.782 \, \text{phi}^6 + \\
& 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \, \text{phi} - \right. \right. \\
& \quad \left. \left. 1.16207 \times 10^{17} \, \text{phi}^2 + 1.09538 \times 10^{17} \, \text{phi}^3 - 4.25218 \times 10^{16} \, \text{phi}^4 + \right. \right. \\
& \quad \left. \left. 2.91005 \times 10^{15} \, \text{phi}^5 + 1.2935 \times 10^{15} \, \text{phi}^6\right)^2\right)}^{1/5} \mid \mid \\
z3 = & (0.309017 + 0.951057 \, \text{i}) \left(-59\,027.2 + 19\,444.9 \, \text{phi} + 15\,971.8 \, \text{phi}^2 - \right. \\
& 15\,055.3 \, \text{phi}^3 + 5844.32 \, \text{phi}^4 - 399.965 \, \text{phi}^5 - 177.782 \, \text{phi}^6 + \\
& 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \, \text{phi} - \right. \right. \\
& \quad \left. \left. 1.16207 \times 10^{17} \, \text{phi}^2 + 1.09538 \times 10^{17} \, \text{phi}^3 - 4.25218 \times 10^{16} \, \text{phi}^4 + \right. \right. \\
& \quad \left. \left. 2.91005 \times 10^{15} \, \text{phi}^5 + 1.2935 \times 10^{15} \, \text{phi}^6\right)^2\right)}^{1/5} \mid \mid \\
z3 = & (0.309017 - 0.951057 \, \text{i}) \left(-59\,027.2 + 19\,444.9 \, \text{phi} + 15\,971.8 \, \text{phi}^2 - \right. \\
& 15\,055.3 \, \text{phi}^3 + 5844.32 \, \text{phi}^4 - 399.965 \, \text{phi}^5 - 177.782 \, \text{phi}^6 + \\
& 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \, \text{phi} - \right. \right. \\
& \quad \left. \left. 1.16207 \times 10^{17} \, \text{phi}^2 + 1.09538 \times 10^{17} \, \text{phi}^3 - 4.25218 \times 10^{16} \, \text{phi}^4 + \right. \right. \\
& \quad \left. \left. 2.91005 \times 10^{15} \, \text{phi}^5 + 1.2935 \times 10^{15} \, \text{phi}^6\right)^2\right)}^{1/5} \mid \mid \\
z3 = & (-0.809017 + 0.587785 \, \text{i}) \left(-59\,027.2 + 19\,444.9 \, \text{phi} + 15\,971.8 \, \text{phi}^2 - \right. \\
& 15\,055.3 \, \text{phi}^3 + 5844.32 \, \text{phi}^4 - 399.965 \, \text{phi}^5 - 177.782 \, \text{phi}^6 + \\
& 1.37443 \times 10^{-13} \sqrt{\left(5.29365 \times 10^{30} + \left(4.29467 \times 10^{17} - 1.41476 \times 10^{17} \, \text{phi} - \right. \right. \\
& \quad \left. \left. 1.16207 \times 10^{17} \, \text{phi}^2 + 1.09538 \times 10^{17} \, \text{phi}^3 - 4.25218 \times 10^{16} \, \text{phi}^4 + \right. \right. \\
& \quad \left. \left. 2.91005 \times 10^{15} \, \text{phi}^5 + 1.2935 \times 10^{15} \, \text{phi}^6\right)^2\right)}^{1/5} \Big) \&\& \\
z4 = & -5.49755 \times 10^{-29} z3 \left(-2.24833 \times 10^{28} + 1.59651 \times 10^{28} \, \text{phi} + 1.16331 \times 10^{27} \, \text{phi}^2 - \right. \\
& 1.096 \times 10^{27} \, \text{phi}^3 + 4.25418 \times 10^{26} \, \text{phi}^4 - 2.91392 \times 10^{25} \, \text{phi}^5 - \\
& 1.29318 \times 10^{25} \, \text{phi}^6 + 4.29343 \times 10^{27} z3^5 - \\
& 1.41321 \times 10^{27} \, \text{phi} z3^5 - 1.16331 \times 10^{27} \, \text{phi}^2 z3^5 + \\
& 1.096 \times 10^{27} \, \text{phi}^3 z3^5 - 4.25418 \times 10^{26} \, \text{phi}^4 z3^5 + \\
& 2.91392 \times 10^{25} \, \text{phi}^5 z3^5 + 1.29318 \times 10^{25} \, \text{phi}^6 z3^5 \Big) \&\& \\
z5 = & 4.39804 \times 10^{-30} z2^4 z3^3 \left(9.96308 \times 10^{30} - 1.53441 \times 10^{31} \, \text{phi} + \right. \\
& 1.18957 \times 10^{31} \, \text{phi}^2 - 5.8015 \times 10^{30} \, \text{phi}^3 + \\
& 1.79503 \times 10^{30} \, \text{phi}^4 - 3.44687 \times 10^{29} \, \text{phi}^5 + \\
& 3.37513 \times 10^{28} \, \text{phi}^6 + 1.58028 \times 10^{26} z3^5 - \\
& 1.99079 \times 10^{26} \, \text{phi} z3^5 + 1.50258 \times 10^{26} \, \text{phi}^2 z3^5 - \\
& 7.2878 \times 10^{25} \, \text{phi}^3 z3^5 + 2.34082 \times 10^{25} \, \text{phi}^4 z3^5 - \\
& 4.73077 \times 10^{24} \, \text{phi}^5 z3^5 + 4.4901 \times 10^{23} \, \text{phi}^6 z3^5 \Big)
\end{aligned}$$

EstimateDistanceInCPN[f2 /. {psi -> 0.5, phi -> 1}, z1, {z2, z3, z4, z5}]

Out[178]= { {0.901534 + 0. i, {z2 -> -0.999766, z3 -> 0.149416, z4 -> -0.125699, z5 -> 0.131492}},
{0.901534 + 0. i, {z2 -> -0.999766, z3 -> 0.149416, z4 -> -0.125699, z5 -> 0.131492}} }

EstimateDistanceInCPN[f2 /. {psi → 0.5, phi → 1}, z4, {z1, z2, z3, z5}]

Out[181]= $\left\{ \left\{ 0.584779 + 0. i, \left\{ z1 \rightarrow -6.43016 \times 10^{-9}, \right. \right. \right.$
 $\left. \left. z2 \rightarrow -6.61161 \times 10^{-9}, z3 \rightarrow -1., z5 \rightarrow -9.1173 \times 10^{-9} \right\} \right\}, \left\{ 0.584779 + 0. i, \right.$
 $\left. \left\{ z1 \rightarrow -6.43016 \times 10^{-9}, z2 \rightarrow -6.61161 \times 10^{-9}, z3 \rightarrow -1., z5 \rightarrow -9.1173 \times 10^{-9} \right\} \right\}$

In[179]:= **EstimateDistanceInCPN[f2 /. {psi → 0.5, phi → 2}, z1, {z2, z3, z4, z5}]**

Out[179]= $\left\{ \left\{ 0.835949 + 0. i, \left\{ z2 \rightarrow -0.99723, z3 \rightarrow 0.369146, z4 \rightarrow -0.335788, z5 \rightarrow 0.245961 \right\} \right\}, \right.$
 $\left. \left\{ 0.835949 + 0. i, \left\{ z2 \rightarrow -0.99723, z3 \rightarrow 0.369146, z4 \rightarrow -0.335788, z5 \rightarrow 0.245961 \right\} \right\} \right\}$

In[182]:= **EstimateDistanceInCPN[f2 /. {psi → 0.5, phi → 2}, z4, {z1, z2, z3, z5}]**

Out[182]= $\left\{ \left\{ 0.357282 + 0. i, \left\{ z1 \rightarrow -7.27525 \times 10^{-9}, \right. \right. \right.$
 $\left. \left. z2 \rightarrow -7.18925 \times 10^{-9}, z3 \rightarrow -1., z5 \rightarrow -7.02754 \times 10^{-9} \right\} \right\}, \left\{ 0.357282 + 0. i, \right.$
 $\left. \left\{ z1 \rightarrow -7.27525 \times 10^{-9}, z2 \rightarrow -7.18925 \times 10^{-9}, z3 \rightarrow -1., z5 \rightarrow -7.02754 \times 10^{-9} \right\} \right\}$

In[244]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 0}, z1, {z2, z3, z4, z5}]**

Out[244]= $\left\{ \left\{ 0.291029, \left\{ x2 \rightarrow 0.145636, y2 \rightarrow 0.105811, x3 \rightarrow -0.0556279, y3 \rightarrow 0.171205, \right. \right. \right.$
 $\left. \left. x4 \rightarrow -0.0556279, y4 \rightarrow -0.171205, x5 \rightarrow 0.809397, y5 \rightarrow -0.588061 \right\} \right\}$

In[245]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 0}, z4, {z1, z2, z3, z5}]**

Out[245]= $\left\{ \left\{ 0.291029, \left\{ x1 \rightarrow 0.145636, y1 \rightarrow 0.105811, x2 \rightarrow -0.0556279, y2 \rightarrow 0.171205, \right. \right. \right.$
 $\left. \left. x3 \rightarrow -0.0556279, y3 \rightarrow -0.171205, x5 \rightarrow 0.809397, y5 \rightarrow -0.588061 \right\} \right\}$

In[246]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 1}, z1, {z2, z3, z4, z5}]**

Out[246]= $\left\{ \left\{ 0.274846, \left\{ x2 \rightarrow -0.0685271, y2 \rightarrow -0.217561, x3 \rightarrow 0.00945118, y3 \rightarrow -0.14496, \right. \right. \right.$
 $\left. \left. x4 \rightarrow 0.809252, y4 \rightarrow 0.615961, x5 \rightarrow -0.22809, y5 \rightarrow -0.00205777 \right\} \right\}$

In[247]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 1}, z4, {z1, z2, z3, z5}]**

Out[247]= $\left\{ \left\{ 0.100177, \left\{ x1 \rightarrow 0.291374, y1 \rightarrow -0.119705, x2 \rightarrow 0.291374, \right. \right. \right.$
 $\left. \left. y2 \rightarrow -0.119705, x3 \rightarrow 0.500529, y3 \rightarrow 0.866945, x5 \rightarrow 0.203886, y5 \rightarrow 0.240122 \right\} \right\}$

In[248]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 2}, z1, {z2, z3, z4, z5}]**

Out[248]= $\left\{ \left\{ 0.202251, \left\{ x2 \rightarrow 0.297598, y2 \rightarrow -0.223127, x3 \rightarrow 0.340795, y3 \rightarrow 0.190015, \right. \right. \right.$
 $\left. \left. x4 \rightarrow -0.441519, y4 \rightarrow -1.02765, x5 \rightarrow -0.109612, y5 \rightarrow 0.355438 \right\} \right\}$

In[249]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 2}, z4, {z1, z2, z3, z5}]**

Out[249]= $\left\{ \left\{ 0.0608233, \left\{ x1 \rightarrow -0.302668, y1 \rightarrow -0.100814, x2 \rightarrow 0.30412, y2 \rightarrow -0.0963429, \right. \right. \right.$
 $\left. \left. x3 \rightarrow -0.812156, y3 \rightarrow 0.590101, x5 \rightarrow -0.18941, y5 \rightarrow 0.256701 \right\} \right\}$

In[250]:= **EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 3}, z1, {z2, z3, z4, z5}]**

Out[250]= $\left\{ \left\{ 0.194815, \left\{ x2 \rightarrow 0.101076, y2 \rightarrow -0.311079, x3 \rightarrow -0.330873, y3 \rightarrow 1.01832, \right. \right. \right.$
 $\left. \left. x4 \rightarrow 0.0352418, y4 \rightarrow -0.108466, x5 \rightarrow -0.26462, y5 \rightarrow -0.192257 \right\} \right\}$

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In[251]:= EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 3}, z4, {z1, z2, z3, z5}]
Out[251]= {{0.0538794, {x1 → 0.252789, y1 → 0.183662, x2 → -0.0965568, y2 → 0.297171,
x3 → -0.993698, y3 → -8.05418 × 10-8, x5 → 0.252789, y5 → 0.183662}}}}

In[263]:= EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 2.5}, z1, {z2, z3, z4, z5}]
Out[263]= {{0.00234036, {x2 → -0.0540671, y2 → -0.066603, x3 → 0.427804, y3 → 16.4797,
x4 → -0.427804, y4 → -16.4797, x5 → 0.0574509, y5 → -0.0637082}}}}

In[264]:= EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 2.5}, z4, {z1, z2, z3, z5}]
Out[264]= {{0. + 6.70788 × 10-9 i,
{x1 → -2.50986 × 10-9, y1 → 5.76312 × 10-10, x2 → 8.82588 × 10-9, y2 → 7.42003 × 10-10,
x3 → -1., y3 → -4.78238 × 10-9, x5 → -1.34373 × 10-9, y5 → -8.57799 × 10-9}}}

In[276]:= Reduce[Append[ Map[# == 0 &, Grad[f2 /. psi → 0.5, {z1, z2, z3, z4, z5} ]],
(f2 == 0 /. psi → 0.5) && z1 == 0 && z3 == 1], {z1, z2, z3, z4, z5}]
Out[276]= (phi == -0.5 && z1 == 0 && z2 == 0 && z3 == 1. && z4 == 1. && z5 == 0) ||
((phi == 1. - 2. i || phi == 1. + 2. i || phi == 2.5) && z1 == 0 && z2 == 0 && z3 == 1. &&
(z4 == 0.05 (-5. - 1. phi - 2. phi2 - 1.  $\sqrt{-400. + (5. + phi + 2. phi^2)^2}$ ) ||
z4 == 0.05 (-5. - 1. phi - 2. phi2 +  $\sqrt{-400. + (5. + phi + 2. phi^2)^2}$ )) && z5 == 0)

In[277]:= EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 2.4}, z4, {z1, z2, z3, z5}]
Out[277]= {{0.025252, {x1 → 0.140666, y1 → -0.286745, x2 → -0.229243, y2 → -0.222391,
x3 → -0.975724, y3 → -0.284747, x5 → -0.229243, y5 → -0.222391}}}}

In[278]:= EstimateTrueDistanceInCPN[f2 /. {psi → 0.5, phi → 2.6}, z4, {z1, z2, z3, z5}]
Out[278]= {{0.0177361, {x1 → -0.295191, y1 → -0.214469, x2 → 0.364876, y2 → 1.82726 × 10-11,
x3 → -1.30517, y3 → -2.5996 × 10-10, x5 → -0.295191, y5 → 0.214469}}}}

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