

Then $W_2^T W_2 = I$, so

Then $P^{(2)} = I - 2W_2 W_2^T$ is a Householder matrix
and

$$P^{(2)} A = \begin{pmatrix} s_1 & x & x & \dots & x \\ 0 & s_2 & x & & \\ \vdots & 0 & x & & \\ \vdots & \vdots & \vdots & & \\ 0 & 0 & x & \dots & x \end{pmatrix}$$

↳ the action of $P^{(2)}$ is to leave the first line unchanged, to set \tilde{a}_{22} to s_2 and zero out all coefficients in the second column below \tilde{a}_{22} .

③ → If we do this repetitively then

$$P^{(n-1)} \dots P^{(2)} P^{(1)} A = R \quad \leftarrow \text{the successive operations turn } A \text{ into an upper triangular matrix.}$$

But since $P^{(i)}$ is an orthogonal matrix,

$\prod_i P^{(i)}$ is also orthogonal

$$\rightarrow \text{let } Q^T = Q^{-1} = \prod_i P^{(i)} \text{ then}$$

$$A = QR \text{ as desired.}$$

④ Use of QR for least-square methods

In standard least-square solution, the over-determined $n \times m$ problem

$$AX = B \quad (n > m)$$

is reduced to

$$A^T A X = A^T B \rightarrow \text{an } (m \times m) \text{ problem.}$$

A common problem arises if the entries of A span several orders of magnitude \Rightarrow truncation errors accumulate in the calculation of $A^T A$

which lead to even bigger errors in the calculation of the solution x .

→ The idea is to avoid constructing $A^T A$ but instead to work with A only

QR method for Least-Square problems

if $Ax = b$ then

$$QRx = b \Rightarrow Rx = Q^T b$$

\nwarrow
 $n \times m$

\downarrow
 m

\downarrow
 $n \times n$

Now R is upper triangular, and can be re-written as

$$R = \begin{pmatrix} \triangle & \\ & 0 \end{pmatrix} = \begin{pmatrix} \tilde{R} \\ 0 \end{pmatrix} \left\{ \begin{array}{l} \text{an } m \times m \text{ matrix} \\ \text{an } (n-m) \times m \text{ 0 matrix} \end{array} \right.$$

$$\Rightarrow Rx = \begin{pmatrix} \tilde{R}x \\ 0 \end{pmatrix} \left\{ \begin{array}{l} m \text{ elements} \\ n-m \text{ elements, all zero} \end{array} \right.$$

So if we write $Q^T = \begin{pmatrix} \tilde{Q}_1^T \\ \tilde{Q}_2^T \end{pmatrix} \leftarrow \begin{matrix} (m \times n) \\ (n-m \times n) \end{matrix}$

then the system becomes (exactly)

$$\begin{pmatrix} \tilde{R}x \\ 0 \end{pmatrix} = \begin{pmatrix} \tilde{Q}_1^T b \\ \tilde{Q}_2^T b \end{pmatrix} \Rightarrow \begin{cases} \tilde{R}x = \tilde{Q}_1^T b \\ 0 = \tilde{Q}_2^T b \end{cases}$$

Claim : The solution of this system which minimizes the approximate error is the solution of the reduced system $\tilde{R}x = \tilde{Q}_1^T b$ exact

Proof:

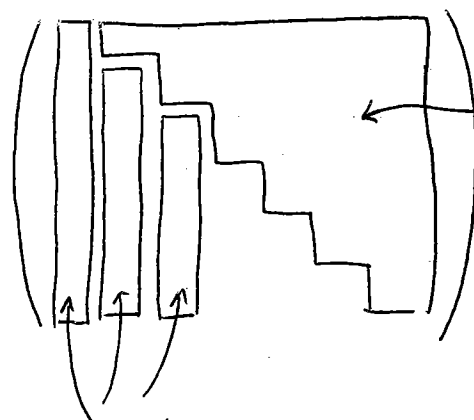
The error is measured with the Euclidean norm
as

$$\begin{aligned}
 \|Ax - b\| &= \|QRx - b\| \\
 &= \|Q^T QRx - Q^T b\| && \text{since } \|AB\| = \|A\|\|B\| \\
 & && \text{and } \|Q\| = \|Q^T\| = 1 \\
 &= \|Rx - Q^T b\| && \text{since } Q^T Q = I \\
 &= \sqrt{\|\tilde{R}x - \tilde{Q}_1^T b\|^2 + \|\tilde{Q}_2^T b\|^2}
 \end{aligned}$$

→ to minimize this number, find x such that
 $\tilde{R}x = \tilde{Q}_1^T b$.

⑤ Practical implementation of QR factorization

- A standard QR algorithm will return the QR factorization in the original matrix A as



truncated matrix R
(diagonal missing)

Note: the diagonal, which contains the coefficients (s_1, \dots, s_n) is returned as a separate vector.

vectors \underline{u}_i defined

$$\text{as } \underline{u}_i = \sqrt{2s_i(s_i - a_{ii})} \underline{w}_i$$

- Note how the algorithm does not return Q nor the matrices $P_i \Rightarrow$ only the vectors " \underline{w}_i " are returned, which can be used to reconstruct $P_i^{(i)}$ and Q easily
- It turns out that the vectors \underline{u}_i are easier to store than the \underline{w}_i , as they naturally arise as the algorithm unfolds.

(a) Algorithm for QR reduction (for a square matrix A)

do $k = 1, n-1$ $\leftarrow n-1$ steps of QR

- calculate $s_k = \pm \sqrt{\sum_{i=k}^n a_{ik}^2}$
 - store $c_k = s_k(s_k - a_{kk})$ in vector s
 - "Apply $P^{(k)}$ to A" which involves
 - ① $\left\{ \begin{array}{l} \text{lines } 1 \rightarrow k-1 \text{ of matrix are unchanged} \\ \text{do nothing} \end{array} \right.$ $\left\{ \begin{array}{l} \text{columns } 1 \rightarrow k-1 \text{ of matrix are unchanged} \end{array} \right.$
 - ② $\left\{ \begin{array}{l} a_{kk} = a_{kk} - s_k \leftarrow \text{diagonal element is now } a_{kk} - s_k \\ \text{rest of column } k \text{ is unchanged} \end{array} \right.$

this stores vector u_k in column k
 - ③ Calculate the effect of P^k on A on the submatrix $i = k \rightarrow n, j = k+1 \rightarrow n$

do $j = k+1, n$

do $i = k, n$

$a_{ij} := (P^{(k)} A)_{ij} \quad (*)$

enddo

enddo
- enddo

The step (*) involves calculating ~~for~~

$$\sum_{m=1}^n \left(I_{im} - 2w_i^{(k)} w_m^{(k)} \right) a_{mj} = \sum_{m=1}^n \delta_{im} a_{mj} - \frac{u_i^{(k)} u_m^{(k)}}{c_k} a_{mj}$$

$$= a_{ij} - \sum_{m=k}^n \frac{1}{c_k} u_i^{(k)} u_m^{(k)} a_{mj}$$

but the $u_i^{(k)}$ and $u_m^{(k)}$ components are stored already in a_{ik} and a_{mk} so

$$a_{ij} := a_{ij} - \sum_{m=k}^n \frac{a_{ik} a_{mk} a_{mj}}{c_k}$$

$$= a_{ij} - \frac{a_{ik}}{c_k} \sum_{m=k}^n a_{mk} a_{mj}$$

⑥ Solution of $QRX=b$ (for a square system)

\Rightarrow This algorithm returns the matrix A as shown, as well as the vectors \underline{s} (containing the s_k coefficients) and \underline{c} (containing $s_k(s_k - a_{kk})$).

Now we simply have to use the given algorithm output to find solutions to $QRX=b$. (\Rightarrow) $RX = Q^T b$.

To do this, we must evaluate $Q^T b$, then simply perform a back-substitution. To evaluate $Q^T b$, note that

$$Q^T b = (P^{(n-1)} P^{(n-2)} \dots P^{(2)} P^{(1)}) b$$

\rightarrow we must first calculate $P^{(1)} b$, then $P^{(2)} P^{(1)} b$, etc... Remember that

$$P^{(i)} b = (I - 2\underline{w}_i \underline{w}_i^T) \underline{b}$$

$$= \left(I - \frac{1}{c_i} \underline{u}_i \underline{u}_i^T \right) \underline{b}$$

but the vector \underline{u}_i is now stored in the i -th lower-column of A so the following algorithm will return $Q^T b$:

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do k = 1, n-1
  |
  | do i = 1, n
  |   |
  |   |  $b_i = b_i - \frac{a_{ik}}{c_k} \sum_{m=k}^n a_{mk} b_m$ 
  |   |
  |   | enddo
  | enddo
enddo

```

Finally, backsubstitute with the stored R , remembering that the diagonal of R is stored in \underline{s} .