



Using a hand-held tool modifies proprioceptive representations of the user's arm and tool

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Introduction

- Descartes (1637) recognized that a blind man can use his walking sticks to perceive object distance¹
- Empirical studies have since demonstrated that extending the body with a tool alters body representation and the perceived surrounding space
- For example, tool extensions have been found to alter:
 - Size and shape of arm and hand representation^{2,3,4}
 - Kinematics^{5,6}
 - Peri-personal space^{4,8}



- However, to the best knowledge of the researcher, whether tool use changes the representation of the tool has not been addressed

Questions addressed in the present study:

- Do humans have proprioceptive representations of the arm and tool?
- Does the represented length of the arm and tool change with tool use?
- Does tool use improve the accuracy of the arm and tool representations? Does one improve more than the other?

Experiment

Proprioceptive Mapping Paradigm

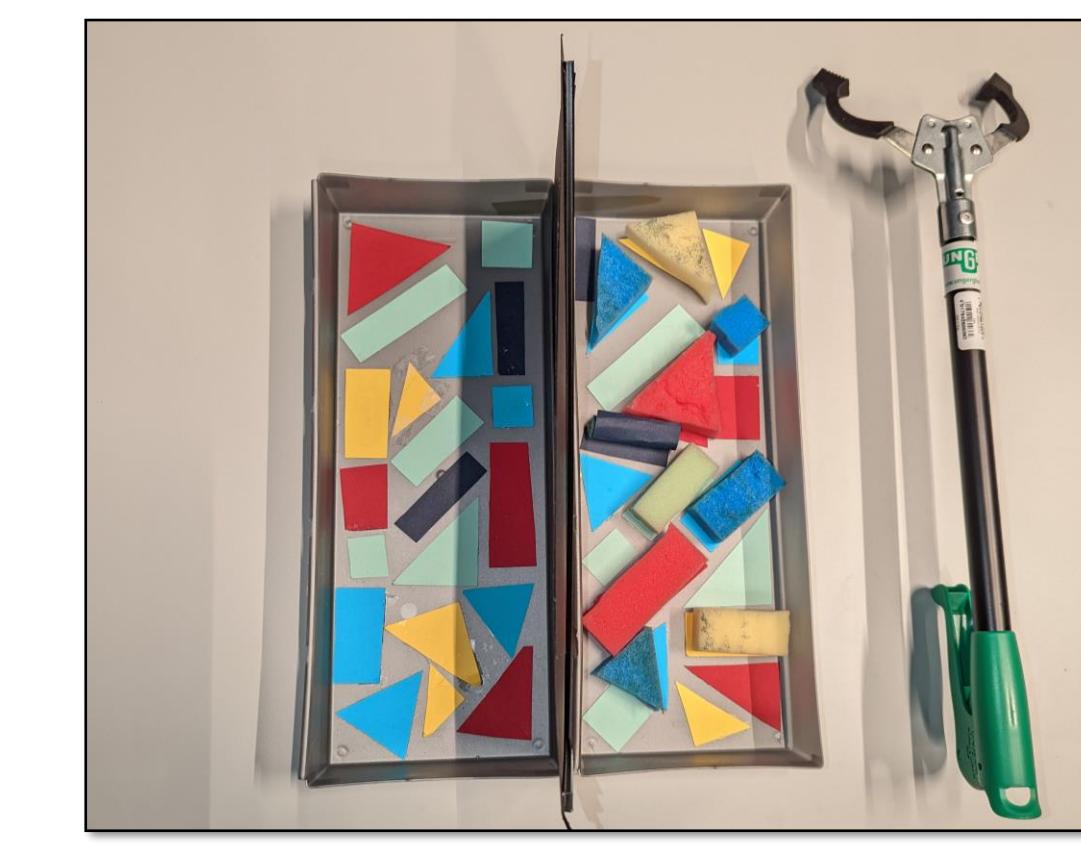
- Participants (n=24) performed a novel proprioceptive mapping paradigm that simultaneously measured proprioceptive maps of the forearm and hand-held tool
- Task:** Point in the space above the arm or tool to indicate the location of a pre-specified landmark
- Twelve landmarks (10 trials each): 6 landmarks for the arm, 6 landmarks for the tool (0 to 100% by steps of 16.67% actual length)
- Before and after tool use

Tool Use Paradigm

- Use mechanical grabber (40 cm) to move foam pieces and align their shapes
- 10-minutes of tool use in total

Analysis

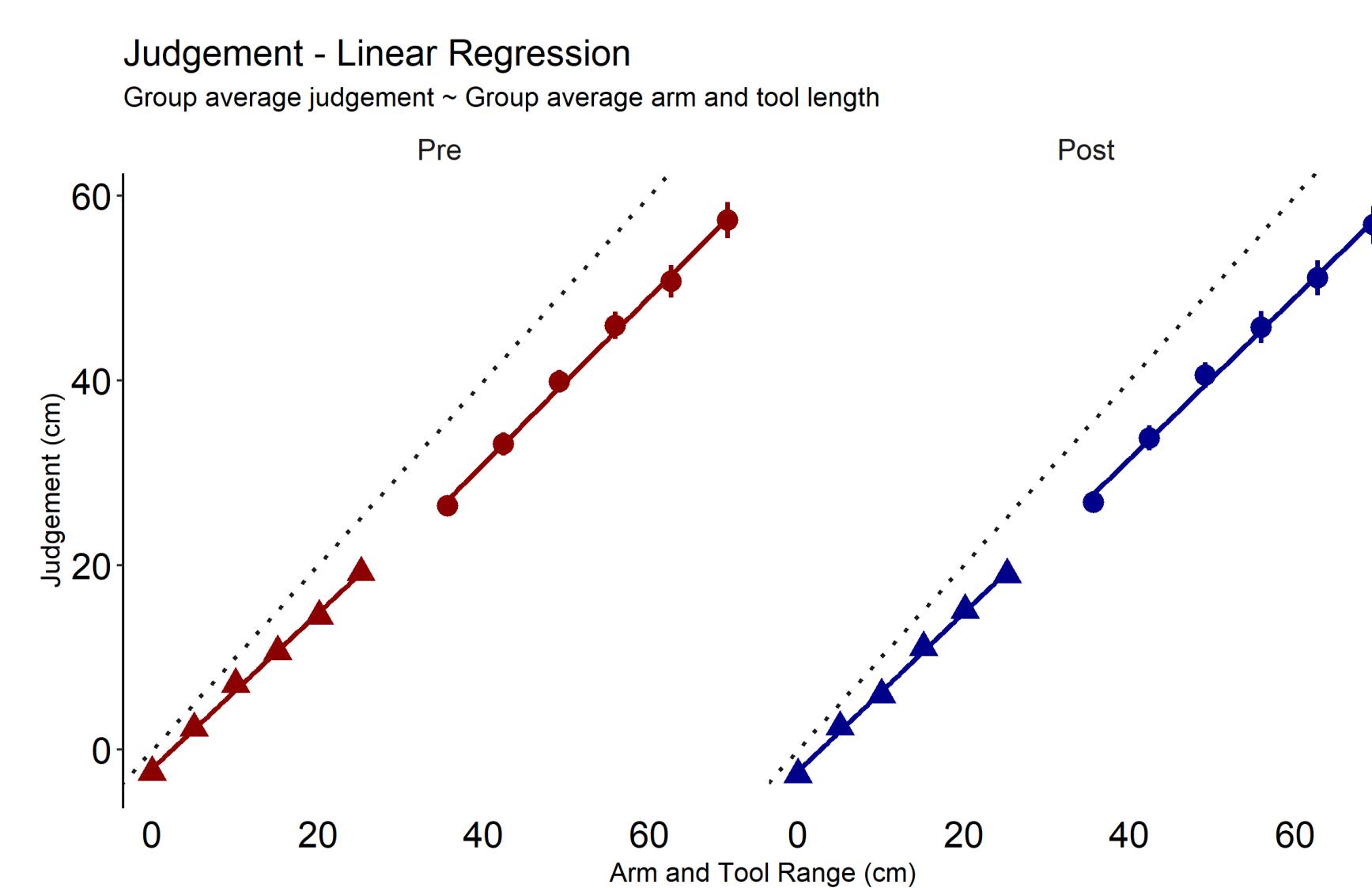
- Fitting linear regression to judgements of participants
- Comparing slope and intercept from linear regression models for arm/tool and pre/post
- Comparing constant and variable error for arm/tool and pre/post
- Calculating Euclidean distance between pre and post to compare the change of pattern between tool and arm



Results

QUESTION 1 - Do humans have a proprioceptive representation of the tool and arm?

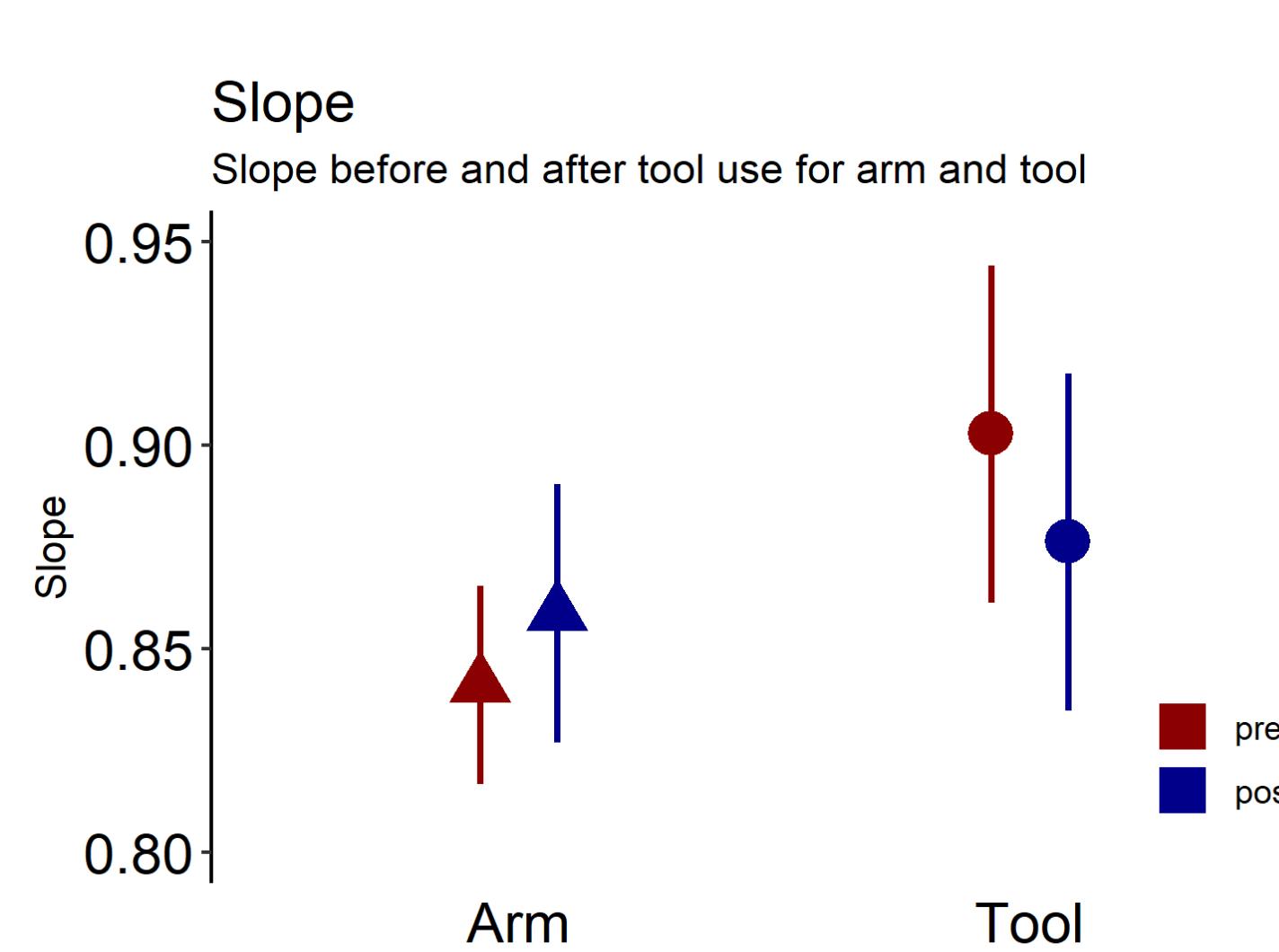
- Arm representation:**
Intercept: -2.04 (pre), -2.33 (post) Slope: 0.84 (pre), 0.86 (post)
- Tool Representation:**
Intercept: -5.01 (pre), -3.57 (post) Slope: 0.90 (pre), 0.88 (post)
- Conclusion:** Humans have a proprioceptive representation of arm and tool with similar fits to proprioceptive judgements



QUESTION 2 – Does the length of the arm and tool change with tool use?

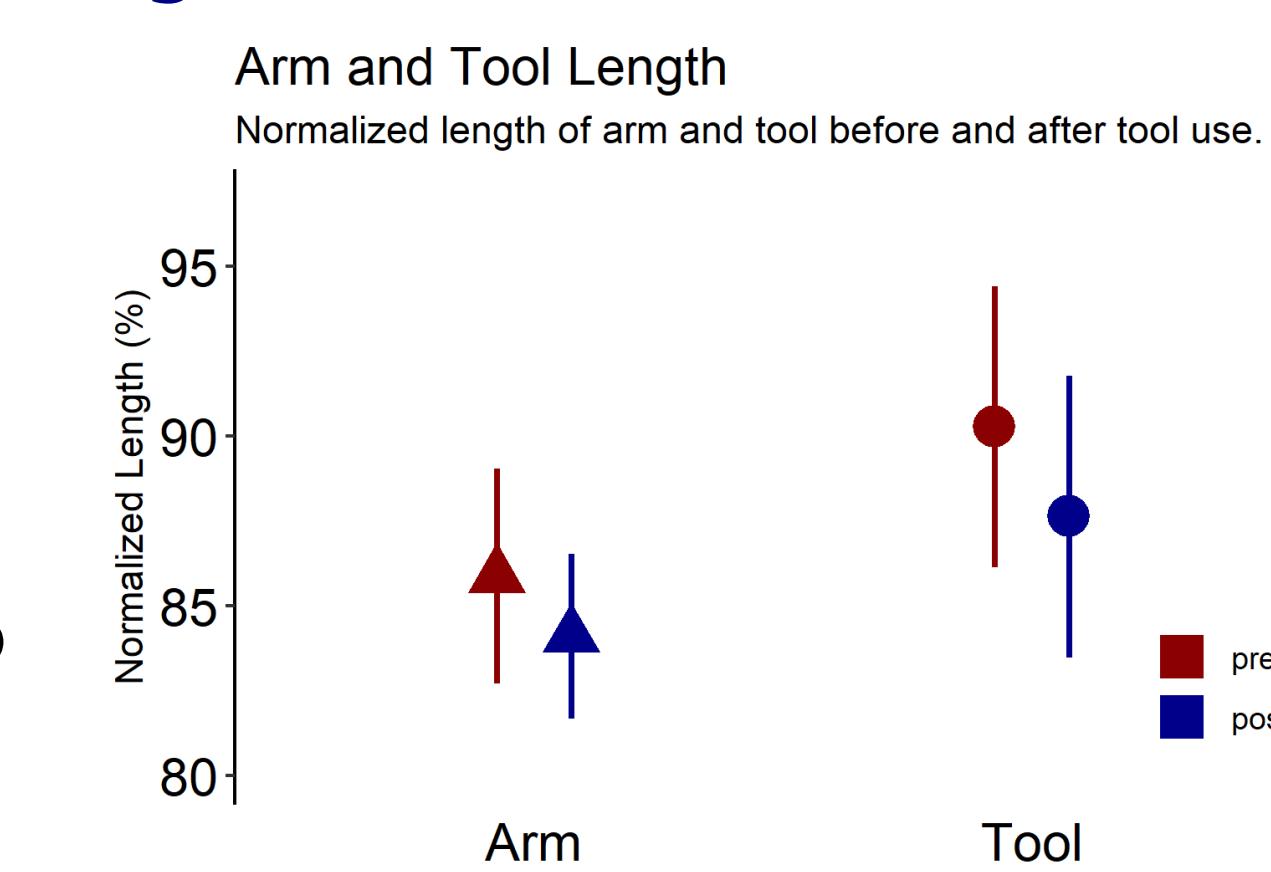
Comparison slope and intercept before and after tool use

- Repeated measures ANOVA:**
- Slope:**
Main effect of surface: $F=0.74$, $p=.4$; Main effect of time: $F=0.06$, $p=.81$ Interaction: $F=2.17$, $p=.15$
- Intercept:**
Main effect of surface: $F=2.27$, $p=.15$; Main effect of time: $F=1.04$, $p=.32$ Interaction: $F=2.64$, $p=.12$
- Conclusion:** this study did not find a main effect of surface, time or interaction for slope and intercept



Comparison of regression derived length elbow/wrist and base/tip before and after tool Use

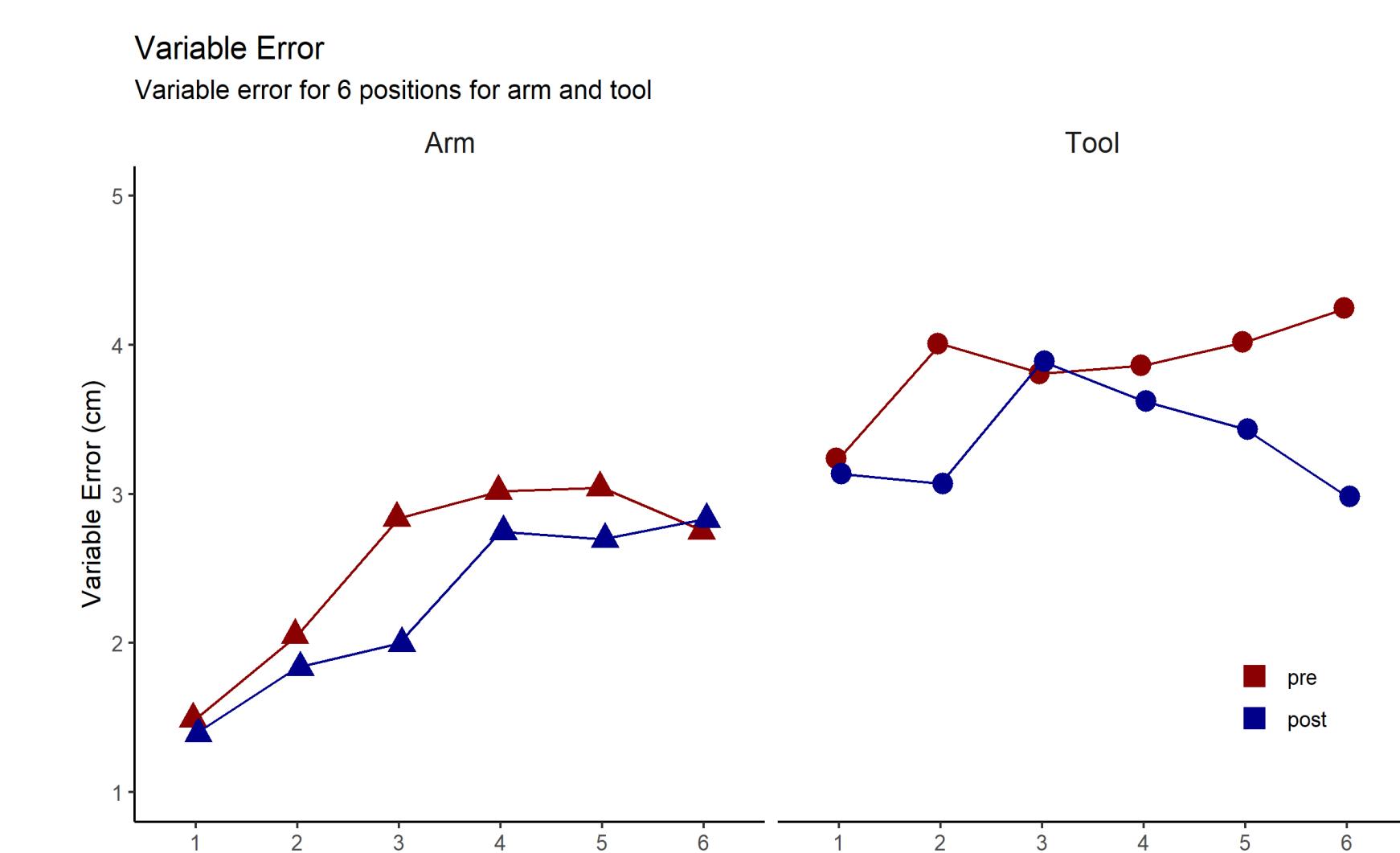
- Arm representation length (% of total):** pre = 85.9 %, and post = 84.1 %
- Tool representation length (% of total):** pre = 90.3 %, and post = 87.6 %
- 2x2 repeated measures ANOVA found no main effect for surface, time or interactions (all $p > .05$)



QUESTION 3 – Does tool use improve the accuracy of the arm and tool representation? Does one improve better than the other?

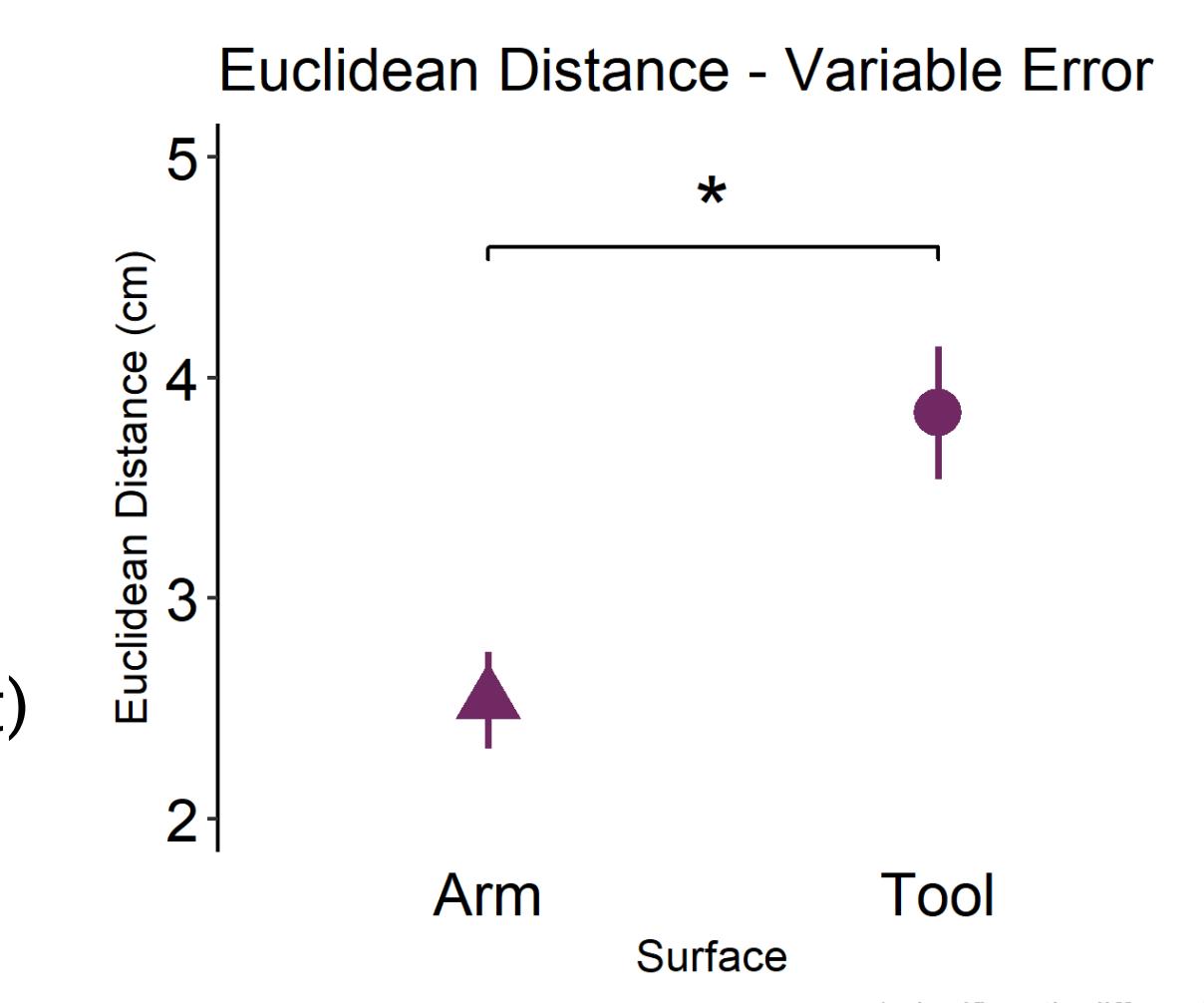
Variable error

- Arm representation:**
Main effect of time: $F=6.21$, $p=0.02$; Main effect of position: $F=20.58$, $p<.001$; Interaction: $F=2.33$, $p<.05$
- Tool representation:**
Main effect of time: $F=8.23$, $p=.01$; Main effect of position: $F=1.92$, $p=0.1$; Interaction: $F=3.24$, $p=.01$



Variable error – Euclidean distance

- Pattern of change (pre-post):**
Arm = 2.537 (cm)
Tool = 3.840 (cm)
Wilcoxon signed ranked test ($p < .001$)
- Conclusion:** this study found a significant difference in the pattern of change (pre-post) for arm and tool with the tool becoming more accurate than the arm



Discussion

- We designed a novel task for mapping the arm and tool at a fine-grained level
- We found that humans have proprioceptive representations of the arm and tool⁷
- The proprioceptive representation of the tool has a similar underestimation of length as the arm representation⁸
- It is unlikely to be an effect of visual-spatial memory⁹
- In contrast with previous findings, we found no change of arm representation length through tool extension and active tool use^{1,2,3,4,5}

- However, we found a tool-use induced change of the variable error for arm and tool
- The magnitude of change in variable error before and after tool use was significantly bigger for the tool than for the arm, which suggests tool-use builds a more precise representation of the tool instead of practice effect
- In total, we found that the proprioceptive representations for arm and tool are malleable and can change following tool use

References

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