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### 1 CONSUMER

### 1.1 Optimization problem

$$\max_{K_t^s, C_t, L_t^s, I_t} U_t = \beta \mathcal{E}_t \left[ U_{t+1} \right] + (1 - \eta)^{-1} \left( (1 - L_t^s)^{1 - \mu} C_t^{\mu} \right)^{1 - \eta}$$
(1.1)

s.t.

$$C_t + I_t = \pi_t + K_{t-1}^s r_t + L_t^s W_t \quad (\lambda_t^{\text{CONSUMER}^1})$$
 (1.2)

$$K_t^s = I_t + K_{t-1}^s (1 - \delta) \quad (\lambda_t^{\text{CONSUMER}^2})$$
 (1.3)

#### 1.2 First order conditions

$$-\lambda_t^{\text{CONSUMER}^2} + \beta \left( (1 - \delta) \operatorname{E}_t \left[ \lambda_{t+1}^{\text{CONSUMER}^2} \right] + \operatorname{E}_t \left[ \lambda_{t+1}^{\text{CONSUMER}^1} r_{t+1} \right] \right) = 0 \quad (K_t^s)$$
(1.4)

$$-\lambda_t^{\text{CONSUMER}^1} + \mu C_t^{-1+\mu} (1 - L_t^s)^{1-\mu} \left( (1 - L_t^s)^{1-\mu} C_t^{\mu} \right)^{-\eta} = 0 \quad (C_t)$$
 (1.5)

$$\lambda_t^{\text{CONSUMER}^1} W_t + (-1 + \mu) (1 - L_t^s)^{-\mu} \Big( (1 - L_t^s)^{1-\mu} C_t^{\mu} \Big)^{-\eta} C_t^{\mu} = 0 \quad (L_t^s)$$
(1.6)

$$\lambda_t^{\text{CONSUMER}^2} - \lambda_t^{\text{CONSUMER}^1} = 0 \quad (I_t)$$
 (1.7)

### 2 FIRM

#### 2.1 Optimization problem

$$\max_{K_t^d, L_t^d, Y_t} \pi_t = Y_t - L_t^d W_t - r_t K_t^d$$
(2.1)

s.t.

$$Y_t = Z_t K_t^{d^{\alpha}} L_t^{d^{1-\alpha}} \quad (\lambda_t^{\text{FIRM}^1})$$
(2.2)

#### 2.2 First order conditions

$$-r_t + \alpha \lambda_t^{\text{FIRM}^1} Z_t K_t^{d-1+\alpha} L_t^{d^{1-\alpha}} = 0 \quad (K_t^d)$$

$$\tag{2.3}$$

$$-W_t + \lambda_t^{\text{FIRM}^1} Z_t (1 - \alpha) K_t^{d^{\alpha}} L_t^{d^{-\alpha}} = 0 \quad (L_t^d)$$

$$(2.4)$$

$$1 - \lambda_t^{\text{FIRM}^1} = 0 \quad (Y_t) \tag{2.5}$$

### 2.3 First order conditions after reduction

$$-r_t + \alpha Z_t K_t^{d-1+\alpha} L_t^{d^{1-\alpha}} = 0 \quad (K_t^d)$$
 (2.6)

$$-W_t + Z_t (1 - \alpha) K_t^{d^{\alpha}} L_t^{d^{-\alpha}} = 0 \quad (L_t^d)$$
(2.7)

### 3 EQUILIBRIUM

### 3.1 Identities

$$K_t^d = K_{t-1}^s (3.1)$$

$$L_t^d = L_t^s \tag{3.2}$$

### 4 EXOG

#### 4.1 Identities

$$Z_t = e^{\epsilon_t^Z + \phi \log Z_{t-1}} \tag{4.1}$$

### 5 Equilibrium relationships

$$-r_t + \alpha Z_t K_{t-1}^s {}^{-1+\alpha} L_t^{s1-\alpha} = 0 (5.1)$$

$$-W_t + Z_t (1 - \alpha) K_{t-1}^s {}^{\alpha} L_t^{s-\alpha} = 0$$
 (5.2)

$$-Y_t + Z_t K_{t-1}^s {}^{\alpha} L_t^{s1-\alpha} = 0 (5.3)$$

$$Z_t - e^{\epsilon_t^Z + \phi \log Z_{t-1}} = 0 \tag{5.4}$$

$$\beta \left(\mu \mathcal{E}_{t} \left[r_{t+1} C_{t+1}^{-1+\mu} \left(1 - L_{t+1}^{s}\right)^{1-\mu} \left(C_{t+1}^{\mu} \left(1 - L_{t+1}^{s}\right)^{1-\mu}\right)^{-\eta}\right] + \mu \left(1 - \delta\right) \mathcal{E}_{t} \left[C_{t+1}^{-1+\mu} \left(1 - L_{t+1}^{s}\right)^{1-\mu} \left(C_{t+1}^{\mu} \left(1 - L_{t+1}^{s}\right)^{1-\mu}\right)^{-\eta}\right]$$

$$(5.5)$$

$$(-1+\mu)\left(1-L_{t}^{s}\right)^{-\mu}\left(\left(1-L_{t}^{s}\right)^{1-\mu}C_{t}^{\mu}\right)^{-\eta}C_{t}^{\mu}+\mu W_{t}C_{t}^{-1+\mu}\left(1-L_{t}^{s}\right)^{1-\mu}\left(\left(1-L_{t}^{s}\right)^{1-\mu}C_{t}^{\mu}\right)^{-\eta}=0$$
(5.6)

$$-C_t - I_t + Y_t = 0 (5.7)$$

$$I_t - K_t^s + K_{t-1}^s (1 - \delta) = 0 (5.8)$$

$$U_t - \beta E_t [U_{t+1}] - (1 - \eta)^{-1} \left( (1 - L_t^s)^{1 - \mu} C_t^{\mu} \right)^{1 - \eta} = 0$$
 (5.9)

# 6 Steady state relationships

$$-r_{\rm ss} + \alpha Z_{\rm ss} K_{\rm ss}^{s-1+\alpha} L_{\rm ss}^{s-1-\alpha} = 0 \tag{6.1}$$

$$-W_{\rm ss} + Z_{\rm ss} (1 - \alpha) K_{\rm ss}^{s \alpha} L_{\rm ss}^{s - \alpha} = 0$$
(6.2)

$$-Y_{\rm ss} + Z_{\rm ss} K_{\rm ss}^{s \alpha} L_{\rm ss}^{s 1-\alpha} = 0 \tag{6.3}$$

$$Z_{\rm ss} - e^{\phi \log Z_{\rm ss}} = 0 \tag{6.4}$$

$$\beta \left(\mu r_{\rm ss} (1 - L_{\rm ss}^s)^{1-\mu} \left(C_{\rm ss}^{\ \mu} (1 - L_{\rm ss}^s)^{1-\mu}\right)^{-\eta} C_{\rm ss}^{-1+\mu} + \mu (1 - \delta) C_{\rm ss}^{-1+\mu} (1 - L_{\rm ss}^s)^{1-\mu} \left(C_{\rm ss}^{\ \mu} (1 - L_{\rm ss}^s)^{1-\mu}\right)^{-\eta} - \mu C_{\rm ss}^{-1+\mu} (1 - L_{\rm ss}^s)^{1-\mu} \left(C_{\rm ss}^{\ \mu} (1 - L_{\rm ss}^s)^{1-\mu}\right)^{-\eta} \right)$$

$$(6.5)$$

$$(-1+\mu)C_{\rm ss}^{\mu}(1-L_{\rm ss}^{s})^{-\mu}\left(C_{\rm ss}^{\mu}(1-L_{\rm ss}^{s})^{1-\mu}\right)^{-\eta} + \mu W_{\rm ss}C_{\rm ss}^{-1+\mu}(1-L_{\rm ss}^{s})^{1-\mu}\left(C_{\rm ss}^{\mu}(1-L_{\rm ss}^{s})^{1-\mu}\right)^{-\eta} = 0$$
 (6.6)

$$-C_{\rm ss} - I_{\rm ss} + Y_{\rm ss} = 0 ag{6.7}$$

$$I_{ss} - K_{ss}^s + K_{ss}^s (1 - \delta) = 0 ag{6.8}$$

$$U_{\rm ss} - \beta U_{\rm ss} - (1 - \eta)^{-1} \left( C_{\rm ss}^{\ \mu} (1 - L_{\rm ss}^s)^{1 - \mu} \right)^{1 - \eta} = 0 \tag{6.9}$$

# 7 Calibrating equations

$$-0.36Y_{\rm ss} + r_{\rm ss}K_{\rm ss}^s = 0 (7.1)$$

# 8 Parameter settings

$$\beta = 0.99 \tag{8.1}$$

$$\delta = 0.025 \tag{8.2}$$

$$\eta = 2 \tag{8.3}$$

$$\mu = 0.3 \tag{8.4}$$

$$\phi = 0.95 \tag{8.5}$$

## 9 Steady state values

	Steady state values
r	0.0351
C	0.7422
I	0.2559
$K^s$	10.2368
$L^s$	0.2695
U	-136.2372
W	2.3706
Y	0.9981
Z	1

# 10 The solution of the perturbation

### 10.1 P

$$\begin{array}{ccc} K_{t-1}^s & Z_{t-1} \\ K^s & 0.9631 & 0.0962 \\ Z & 0 & 0.95 \end{array} \right)$$

### 10.2 Q

$$\begin{array}{c} \epsilon^Z \\ K^s & \left( \begin{array}{c} 0.1012 \\ 1 \end{array} \right) \end{array}$$

### 10.3 R

$$\begin{array}{cccc} K_{t-1}^s & Z_{t-1} \\ r \\ C \\ C \\ I \\ I \\ -0.4745 & 3.8461 \\ L^s \\ -0.181 & 0.6282 \\ U \\ -0.0418 & -0.0644 \\ W \\ 0.4252 & 0.7238 \\ Y \\ \end{array}$$

### 10.4 S

$$\begin{array}{c} \epsilon^Z \\ r \\ C \\ I \\ I \\ 4.0485 \\ L^s \\ 0.6613 \\ U \\ -0.0678 \\ W \\ 0.7619 \\ Y \\ \end{array}$$

# 11 Statistics of the model

## 11.1 Moments

	Steady state value	Std. dev.	Variance	Loglinear
r	0.0351	0.1893	0.0358	Y
C	0.7422	0.0711	0.0051	Y
I	0.2559	0.5284	0.2792	Y
$K^s$	10.2368	0.0469	0.0022	Y
$L^s$	0.2695	0.0867	0.0075	Y
U	-136.2372	0.009	0.0001	Y
W	2.3706	0.1011	0.0102	Y
Y	0.9981	0.1857	0.0345	Y
Z	1	0.1303	0.017	Y

# 11.2 Correlation matrix

	r	C	I	$K^s$	$L^s$	U	W	Y	Z
r	1	0.8683	0.9893	0.0841	0.9959	-0.9182	0.926	0.9689	0.9823
C	0.8683	1	0.9313	0.5674	0.9095	-0.9938	0.9913	0.964	0.9458
I	0.9893	0.9313	1	0.2285	0.9984	-0.9661	0.9711	0.9946	0.9991
$K^s$	0.0841	0.5674	0.2285	1	0.1737	-0.472	0.4541	0.3282	0.2693
$L^s$	0.9959	0.9095	0.9984	0.1737	1	-0.9502	0.9563	0.9873	0.9952
U	-0.9182	-0.9938	-0.9661	-0.472	-0.9502	1	-0.9998	-0.9877	-0.9761
W	0.926	0.9913	0.9711	0.4541	0.9563	-0.9998	1	0.9906	0.9803
Y	0.9689	0.964	0.9946	0.3282	0.9873	-0.9877	0.9906	1	0.9981
$\overline{Z}$	0.9823	0.9458	0.9991	0.2693	0.9952	-0.9761	0.9803	0.9981	1

# 11.3 Autocorrelations

	t-1	t-2	t-3	t-4
r	0.7098	0.4657	0.2647	0.1034
C	0.7596	0.5446	0.3568	0.1964
I	0.7109	0.4674	0.2668	0.1055
$K^s$	0.9597	0.8621	0.7271	0.5709
$L^s$	0.7092	0.4647	0.2636	0.1023
U	0.7389	0.5118	0.3185	0.1578
W	0.7356	0.5066	0.3125	0.1517
Y	0.7183	0.4791	0.2803	0.1192
Z	0.7133	0.4711	0.2711	0.1098

# 12 Statistics of the model

## 12.1 Moments relative to moments of the reference variable

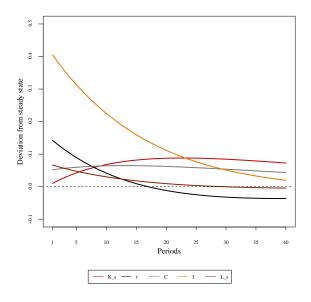
	Steady state value relative to $Y$	Std. dev. relative to $Y$	Variance relative to $Y$	Loglinear
r	0.0352	1.0193	1.0389	Y
C	0.7436	0.3827	0.1465	Y
I	0.2564	2.8453	8.0959	Y
$K^s$	10.2561	0.2526	0.0638	Y
$L^s$	0.27	0.4669	0.218	Y
U	-136.4937	0.0486	0.0024	Y
W	2.3751	0.5441	0.2961	Y
Y	1	1	1	Y
$\overline{Z}$	1.0019	0.7018	0.4926	Y

### 12.2 Correlations with the reference variable

	$Y_{t-4}$	$Y_{t-3}$	$Y_{t-2}$	$Y_{t-1}$	$Y_t$	$Y_{t+1}$	$Y_{t+2}$	$Y_{t+3}$	$Y_{t+4}$
r	0.2344	0.3779	0.5477	0.7447	0.9689	0.6234	0.343	0.1215	-0.0479
C	-0.0128	0.1562	0.3722	0.64	0.964	0.7703	0.5919	0.4314	0.2902
I	0.1684	0.3233	0.5115	0.7348	0.9946	0.684	0.4257	0.2159	0.0501
$K^s$	-0.4149	-0.3135	-0.1616	0.0493	0.3282	0.5125	0.6196	0.6649	0.6624
$L^s$	0.1941	0.3451	0.5267	0.7405	0.9873	0.6625	0.3951	0.1802	0.0127
U	-0.0425	-0.2097	-0.4203	-0.6785	-0.9877	-0.7553	-0.5498	-0.3718	-0.221
W	0.0524	0.2191	0.4285	0.6846	0.9906	0.7516	0.5414	0.3605	0.2082
Y	0.1192	0.2803	0.4791	0.7183	1	0.7183	0.4791	0.2803	0.1192
Z	0.1486	0.3063	0.499	0.7291	0.9981	0.6988	0.448	0.2424	0.0783

# 13 Impulse response functions

# 13.1 Shock $\epsilon^Z$



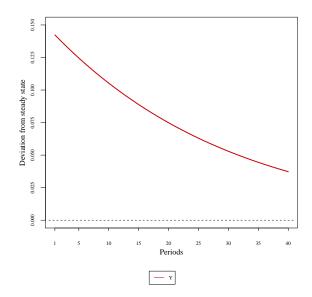


Figure 1: Impulse response function for  $\epsilon^Z$  shock

Figure 2: Impulse response function for  $\epsilon^Z$  shock