# Package 'gEcon'

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eral Equilibrium Economic Modelling Language and Solution Framework (gEcon)
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# Description

Package for developing and solving dynamic (stochastic) and static general equilibrium models.

# **Details**

gEcon is a framework for developing and solving large scale dynamic (stochastic) & static general equilibrium models. It consists of model description language and an interface with a set of solvers in R. It was developed at the Department for Strategic Analyses at the Chancellery of the Prime Minister of the Republic of Poland as a part of a project aiming at construction of large scale DSGE & CGE models of the Polish economy.

Publicly available toolboxes used in RBC/DSGE modelling require users to derive the first order conditions (FOCs) and linearisation equations by pen & paper (e.g. Uhlig's tool-kit) or at least require manual derivation of the FOCs (e.g. Dynare). Derivation of FOCs is also required by GAMS and GEMPACK - probably the two most popular frameworks used in CGE modelling. Owing to

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the development of an algorithm for automatic derivation of first order conditions and implementation of a comprehensive symbolic library, gEcon allows users to describe their models in terms of optimisation problems of agents. To authors' best knowledge there is no other publicly available framework for writing and solving DSGE & CGE models in this natural way. Writing models in terms of optimisation problems instead of the FOCs is far more natural to an economist, takes off the burden of tedious differentiation, and reduces the risk of making a mistake. gEcon allows users to focus on economic aspects of the model and makes it possible to design large-scale (100+ variables) models. To this end, gEcon provides template mechanism (similar to those found in CGE modelling packages), which allows to declare similar agents (differentiated by parameters only) in a single block. Additionally, gEcon can automatically produce a draft of LaTeX documentation for a model.

The model description language is simple and intuitive. Given optimisation problems, constraints and identities, computer derives the FOCs, steady-state equations, and linearisation matrices automatically. Numerical solvers can be then employed to determine the steady state and approximate equilibrium laws of motion around it.

#### Author(s)

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```

#### References

Cf. gEcon manual distributed with the package.

```
# copy the example model to current working directory
file.copy(from = file.path(system.file("examples", package = 'gEcon'),
           'rbc.gcn'), to = getwd())
# make and load model
rbc <- make_model('rbc.gcn')</pre>
# solve model
rbc <- steady_state(rbc)</pre>
rbc <- solve_pert(rbc)</pre>
# compute and print correlations
rbc <- set_shock_cov_mat(rbc, shock_matrix = matrix(0.01, 1, 1), shock_order = 'epsilon_Z')</pre>
rbc <- compute_moments(rbc, ref_var = 'Y')</pre>
get_moments(rbc,
            moments = TRUE,
            correlations = TRUE,
            autocorrelations = TRUE,
            var_dec = TRUE)
irf_rbc <- compute_irf(rbc)</pre>
plot_simulation(irf_rbc)
summary(rbc)
```

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check\_bk

Blanchard Kahn conditions and eigenvalues

# **Description**

The check\_bk function checks Blanchard Kahn conditions and prints information about eigenvalues.

# Usage

```
check_bk(model)
```

# **Arguments**

model

an object of the gecon\_model class.

#### **Details**

Eigenvalues are computed when gEcon attempts to solve the perturbation (solver uses the Lapack zgges function to compute eigenvalues). The solve\_pert function must be called before the eigenvalues can be retrieved.

#### Author(s)

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```

## References

Blanchard, O., Kahn C. M. (1980), "The Solution of Linear Difference Models under Rational Expectations", *Econometrica* 

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compute_irf	Compute impulse response functions (IRFs)

# Description

The compute\_irf function computes the impulse response functions for the specified set of variables and shocks and returns an object of the gecon\_simulation class.

# Usage

# **Arguments**

model	an object of the gecon_model class.
shock_list	a list of shocks for which the IRFs are to be computed. If this argument is missing, the IRFs are computed for all the shocks in the model. By default, the impulse response functions are created for all the shocks in the model.
var_list	a list of variables, for which the impact of shocks has to be computed. By default, the impulse response functions are created for the state variables only.
path_length	the number of periods for which the IRFs are to be computed.
cholesky	logical. If this option is set to FALSE, the function computes the IRFs based on uncorrelated shocks, otherwise the variance-covariance matrix is orthogonalized by using the Cholesky decomposition and the IRFs are computed by using this matrix.

# **Details**

Cf. gEcon manual, chapter "Model analysis".

# Value

The function returns an object of gecon\_simulation class. Generic functions such as print and summary provide information about the impulse response functions. The plot\_simulation function allows to visualize the IRFs.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

# See Also

For details, see gecon\_simulation-class.

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# **Examples**

compute\_moments

Computation of correlations

# **Description**

This function computes the statistics of the model by using spectral and simulation methods.

# Usage

# **Arguments**

model	an object of gecon_model class.
ngrid	density of grid used by the Fourier transform. It has to be a multiplicity of 8.
filter	logical. If TRUE, the statistics are computed for the HP-filtered series, otherwise non-filtered series are used for the statistics computation.
sim	logical. If TRUE, simulation methods are used for correlations computations, otherwise spectral methods are used.
nrun	the number of MC simulation runs.
lambda	the lambda parameter for the HP filter.
ref_var	the name or the number of a variable in relation to which correlations are computed. When not specified, the first variable in variables list is treated as the reference value.
n_leadlags	the number of leads/lags for computing correlation tables.

# **Details**

Cf. gEcon manual, chapter "Model analysis".

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#### Value

An object of gecon\_model class representing a model. Generic functions such as print and summary allow to show model elements. The get\_moments function returns various statistics of the model (both absolute and relative).

#### Note

The grid has to be large enough (at least 64 \* 8) for spectral methods to converge to simulation means.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### References

Hamilton. J.D. (1994), "Time Series Analysis", Princeton University Press

# **Examples**

```
# copy model to current working directory
file.copy(from = file.path(system.file("examples", package = 'gEcon'),
           'rbc.gcn'), to = getwd())
# make and load model
rbc <- make_model('rbc.gcn')</pre>
# solve model
rbc <- steady_state(rbc)</pre>
rbc <- solve_pert(rbc)</pre>
# compute and print correlations
rbc <- set_shock_cov_mat(rbc, shock_matrix = matrix(0.01, 1, 1), shock_order = 'epsilon_Z')</pre>
rbc <- compute_moments(rbc, ref_var = 'Y')</pre>
get_moments(rbc,
            moments = TRUE,
            correlations=TRUE,
             autocorrelations=TRUE,
            var_dec=TRUE)
```

gecon\_model

Constructor of "gecon\_model" class

# **Description**

The gecon\_model function is a constructor of gecon\_model class objects.

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#### **Usage**

#### **Arguments**

model\_info a character vector of length 3, containing information about the model: the input

file name, the input file path and the date of creation.

index\_sets a list containing information about index sets. The names of the list components

correspond to the set names. Each component contains character vector of the

names of the relevant set elements.

variables a character vector of all the variable names.

shocks a character vector of all the shock names.

parameters a character vector of all the parameter names.

parameters\_free

a character vector of all the free parameter names.

parameters\_free\_val

a numeric vector of the values of all the free parameters.

equations a character vector of model equations.

calibr\_equations

a character vector of model calibrating equations.

var\_eq\_map a sparse matrix (a Matrix class object) representing the mapping of variables to

equations.

shock\_eq\_map a sparse matrix (a Matrix class object) representing the mapping of shocks to

equations.

var\_ceq\_map a sparse matrix (a Matrix class object) representing the mapping of variables to

calibrating equations.

cpar\_eq\_map a sparse matrix (a Matrix class object) representing the mapping of calibrated

parameters to equations.

cpar\_ceq\_map a sparse matrix (a Matrix class object) representing the mapping of calibrated

parameters to calibrating equations.

fpar\_eq\_map a sparse matrix (a Matrix class object) representing the mapping of free param-

eters to equations.

fpar\_ceq\_map a sparse matrix (a Matrix class object) representing the mapping of free param-

eters to calibrating equations.

ss\_function a function returning residuals from the steady-state (equilibrium for the static

models) equations.

calibr\_function

a function used for the calibration of parameters.

ss\_calibr\_function\_jac

a function returning a Jacobian of functions returning residuals from the steady-

state (equilibrium for the static models) equations.

pert a function returning a list with the matrices representing canonical form of the

model.

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#### Value

An object of the gecon\_model class.

#### Note

The gecon\_model constructor is used in R files created by gEcon.

#### Author(s)

```
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Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

gecon\_model-class

Class "gecon\_model"

# **Description**

The class for storing models.

## **Objects from the Class**

Objects can be created by calling new("gecon\_model", ...) or preferably using gecon\_model constructor.

#### **Slots**

model\_info: a character vector of length 3, containing information about the model: the input file name, the input file path, and the date of creation.

index\_sets: a list containing information about index sets. The names of the list components correspond to the set names. Each component contains character vector of the names of the relevant set elements.

parameters: a character vector of all parameter names.

parameters\_free: a character vector of free parameter names.

map\_free\_into\_params: the mapping of free parameters to parameters indices.

parameters\_free\_mod\_flag: a logical vector of flags denoting if particular free parameter has been modified with respect to the .gcn file calibration

parameters\_calibr: a character vector of the names of calibrated parameters.

parameters\_calibr\_mod\_flag: a logical vector of the flags denoting if any non-default value has been given for the calibrated parameter.

map\_calibr\_into\_params: a numeric vector of the mapping of free parameters to parameters
indices.

variables: a character vector of the names of variables.

shocks: a character vector of the names of shocks.

equations: a character vector of the names of equations.

calibr\_equations: a character vector of the names of calibrating equations.

var\_eq\_map: a sparse matrix (a Matrix class object) representing the mapping of variables to equations.

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shock\_eq\_map: a sparse matrix (a Matrix class object) representing the mapping of shocks to equations.

- var\_ceq\_map: a sparse matrix (a Matrix class object) representing the mapping of variables to calibrating equations.
- cpar\_eq\_map: a sparse matrix (a Matrix class object) representing the mapping of calibrated parameters to equations.
- cpar\_ceq\_map: a sparse matrix (a Matrix class object) representing the mapping of calibrated parameters to calibrating equations.
- fpar\_eq\_map: a sparse matrix (a Matrix class object) representing the mapping of free parameters
  to equations.
- fpar\_ceq\_map: a sparse matrix (a Matrix class object) representing the mapping of free parameters to calibrating equations.
- init\_calib\_pars\_supplied: logical. It informs if calibrated parameters values have been supplied.
- init\_vals\_supplied: logical. It informs if values of variables have been supplied.
- loglin: logical. It informs if the model has to be log-linearised. The default value is TRUE.
- loglin\_var: logical. Flags are set to TRUE for log-linearised variables.
- re\_solved: logical. It is set to TRUE if the model has been solved. The default value is FALSE.
- corr\_computed: logical. If TRUE, indicates that the correlations and other statistics of variables have been computed. The default value is FALSE.
- is\_stochastic: logical. If TRUE, the model has stochastic shocks.
- is\_dynamic: logical. If TRUE, the model has any lead or lagged variables.
- is\_calibrated: logical. If TRUE, the model takes into account calibrating equations when solving for the steady state for a dynamic model (equilibrium in case of static model).
- parameters\_free\_init\_val: a vector of free parameters values which have been declared in .gcn file.
- parameters\_free\_val: a vector of current free parameter values.
- parameters\_calibr\_val: a vector of current values of calibrated parameters.
- params: a vector of the model parameters.
- steady: a vector of the steady-state values of variables for dynamic models or equilibrium for static models.
- ss\_function: a function returning the steady state (equilibrium for static models) equations resid-
- ss\_function\_jac: a function computing the Jacobian of steady-state function (equilibrium for static models).
- ss\_calibr\_function\_jac: a function computing the Jacobian of both steady-state (equilibrium) and calibrating functions.
- calibr\_function: calibrating functions
- init\_residual\_vector: a numeric vector of residuals of the steady-state (equilibrium) function computed for intial values and calibrating parameters.
- residual\_vector: a numeric vector of residuals of the steady-state (equilibrium) function computed for the values of variables and calibrating parameters after the nonlinear solver has exited.
- solver\_status: a character string describing the steady-state (equilibrium) solver status.

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ss\_solved: logical. If TRUE, steady state (equilibrium for static models) has been found.

pert: functions returning the perturbation of first order (returning a list of matrices).

eig\_vals: a matrix of system eigenvalues.

solution: a list with elements P, Q, R, S storing solution of the model.

state\_var\_indices: a numeric vector containing the indices of state variables.

solver\_exit\_info: a character string containing information about perturbation solver exit information.

solution\_resid: residuals of checking equations, verifying if the model has been solved.

active\_shocks: a logical vector of the length equal to the number of shocks. If entry is set to FALSE, the shock is not taken into account while performing stochastic simulations of the model.

shock\_mat: a variance-covariance matrix of model shocks.

shock\_mat\_flag: logical. Set to TRUE when the user specifies non-default entries in variance-covariance matrix for shocks.

corr\_mat: a matrix of the model variables correlations.

autocorr\_mat: a matrix of the model variables autocorrelations.

corr\_variable\_mat: a matrix of correlations of variables with the reference variable lead and lagged values.

var\_position: a numeric value indicating position of reference variable for the computation of statistics.

var\_dec: a matrix of variance decomposition of shocks.

sdev: a vector of standard deviations of variables.

# Methods

```
print signature(x = "gecon_model"): prints information about the model solution status.
```

show signature(object = "gecon\_model"): prints short information about the model solution
status

summary signature(object = "gecon\_model"): prints detailed results of the model.

#### Author(s)

```
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Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

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```
gecon_par_info-class Class "gecon_par_info"
```

## **Description**

The class storing information about parameters chosen by the user.

# **Objects from the Class**

Objects of this class are created when calling the par\_info function.

#### **Slots**

model\_info: a character vector of length 3, containing information about the model: the input file name, the input file path, and the date of creation.

model\_variable\_name: a character string denoting the name of a variable storing the model for which the information about parameters has been created.

par\_names: a character vector of parameter names.

gcn\_values: a numeric vector of the values of free parameters specified in the .gcn file.

current\_values: a numeric vector of the most recent values of the parameters.

calibr\_flag: a logical vector of the length equal to the number of the parameters. The TRUE entries denote that a corresponding parameter is a calibrated parameter.

incid\_mat: a Matrix object representing the mapping of parameters to equations and calibrating equations.

## Methods

print signature(x = "gecon\_par\_info"): Prints all the available information (short listing, values, type, incidence) about the parameters retrieved from the model when creating a gecon\_par\_info-class object.

**show** signature(object = "gecon\_par\_info"): Prints information about parameters' types, values, and the incidence matrix.

**summary** signature(object = "gecon\_par\_info"): Prints all the available information (short listing, values, type, incidence) about the parameters, retrieved from the model when creating a gecon\_par\_info-class object.

## Author(s)

```
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```

## See Also

par\_info to create a gecon\_par\_info object. The analogous classes storing the information about shocks and variables are gecon\_shock\_info-class and gecon\_var\_info-class.

gecon\_shock\_info-class

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#### **Examples**

```
# copy model to current working directory
 file.copy(from = file.path(system.file("examples", package = 'gEcon'),
            'rbc.gcn'), to = getwd())
 # make and load model
 rbc <- make_model('rbc.gcn')</pre>
 # compute steady state and calibrate alpha
 rbc <- steady_state(rbc)</pre>
 rbc <- solve_pert(rbc)</pre>
 rbc <- set_shock_cov_mat(rbc, shock_matrix = matrix(0.01, 1, 1), shock_order = 'epsilon_Z')</pre>
 rbc <- compute_moments(rbc, ref_var = 'Y')</pre>
 rbc_par_info <- par_info(rbc, all_parameters = TRUE)</pre>
 print(rbc_par_info)
 summary(rbc_par_info)
 show(rbc_par_info)
gecon_shock_info-class
                           Class "gecon_shock_info"
```

## **Description**

The class storing information about shocks chosen by the user.

# **Objects from the Class**

Objects of this class are created when calling the shock\_info function.

#### **Slots**

model\_info: a character vector of length 3, containing information about the model: the input file name, the input file path, and the date of creation.

model\_variable\_name: a character string denoting the name of a variable storing the model for which simulations have been performed.

shock\_names: a character vector of the shock names.

shock\_matrix: a matrix object containing columns of the variance-covariance matrix corresponding to given shocks.

shock\_matrix\_flag: logical. Set to TRUE when the user specifies non-default entries in a variance-covariance matrix of shocks.

incid\_mat: a Matrix object representing the mapping of shocks to equations.

#### Methods

**print** signature(x = "gecon\_shock\_info"): Prints all the available information (the incidence matrix, the variance-covariance matrix) about the shocks.

**show** signature(object = "gecon\_shock\_info"): Prints the incidence matrix and the variance-covariance matrix of shocks specified when creating a gecon\_shock\_info object.

**summary** signature(object = "gecon\_shock\_info"): Prints all the available information (the incidence matrix, the variance-covariance matrix) about the shocks.

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#### Author(s)

```
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```

#### See Also

shock\_info to create a gecon\_shock\_info object. The analogous classes storing the information about variables and parameters are gecon\_var\_info-class and gecon\_par\_info-class.

## **Examples**

gecon\_simulation

Constructor for "gecon\_simulation" class object

#### **Description**

This function creates an object of gecon\_simulation class.

## Usage

```
gecon_simulation(sim, shock_list, var_list, sim_type, time_n, model_info, model_variable_name)
```

# Arguments

sim	the array of simulation results (three dimensional when the impulse response functions have been computed for more than one shock).
shock_list	a list of shocks for which the simulations have been computed.
var_list	a list of variables used.
sim_type	a type of simulation.
time_n	the number of periods for which the simulation has been performed.
model_info	a character vector of length 3, containing information about the model: the input file name, the input file path, and the date of creation.

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```
model_variable_name
```

a character string denoting the name of the model for which the simulation has been performed.

# Value

An object of the gecon\_simulation class.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### See Also

Generic functions such as print and summary can provide information about the simulations. The plot\_simulation function allows to visualize the impact on variables.

```
gecon_simulation-class
```

Class "gecon\_simulation"

# **Description**

The class storing simulation results.

# **Objects from the Class**

Objects can be created by calling the new("gecon\_simulation", ...) form or (preferably) using gecon\_simulation constructor.

# **Slots**

sim: a three-dimensional array with impulse response functions (the dimensions are variables, time, shocks) or two-dimensional array when storing the results of user-specified path of shocks or random path of shocks.

shock\_list: a vector of shocks for which simulations have been computed.

var\_list: a vector of names of simulated variables.

sim\_type: a type of simulation.

time\_n: the number of simulation periods.

model\_info: a character vector of length 3, containing information about the model: the input file name, the input file path and the date of creation.

model\_variable\_name: a character string denoting the name of a variable storing the model for which the simulations have been performed.

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#### Methods

```
print signature(x = "gecon_simulation"): prints diagnostic information about the simulation
    performed.
```

show signature(object = "gecon\_simulation"): prints short information about the simulation.

summary signature(object = "gecon\_simulation"): prints and returns the simulation results
in the form of list.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

## See Also

get\_simulation\_results to retrieve the simulated series from sim slot.

#### **Examples**

```
gecon_var_info-class Class "gecon_var_info"
```

# Description

The class storing information about variables chosen by the user.

# **Objects from the Class**

Objects of this class are created when calling the var\_info function.

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#### Slots

model\_info: a character vector of length 3, containing information about the model: the input file name, the input file path, and the date of creation.

- model\_variable\_name: a character string, the name of a variable storing the model for which the simulations have been performed.
- var\_names: a character vector of the variable names.
- is\_stochastic: logical. If TRUE, the model, based on which the info was generated, has stochastic shocks.
- is\_dynamic: logical. If TRUE, the model, based on which the info was generated, has any lead or lagged variables.
- ss\_solved: logical. If TRUE, the steady state (equilibrium for static models) for the model has been found.
- re\_solved: logical. It is set to TRUE if the model, based on which the info was generated, has been solved. The default value is FALSE.
- corr\_computed: logical. If TRUE, it indicates that the correlations and other statistics of variables have been computed. The default value is FALSE.
- ss\_val: a vector of the steady-state values of variables (dynamic models) or equilibrium (static models). If the steady state has not been computed, this slot contains initial values of variables.
- state: a logical vector of the length equal to the number of the variables. The TRUE entries denote that a corresponding variable is a state variable.
- state\_var\_impact: the rows of the matrices P and R of state space representation corresponding to the chosen variables.
- shock\_impact: the rows of the matrices Q and S of state space representation corresponding to the chosen variables.
- std\_dev\_val: a numeric vector of standard deviations of chosen variables.
- loglin\_flag: a logical vector of the length equal to the number of the variables. The TRUE entries denote that a corresponding variable has been loglinearised before solving the model.
- cr: a matrix containing the correlations of the chosen variables with all the model variables.
- incid\_mat: a Matrix object representing the mapping of variables to equations and calibrating equations.

#### Methods

- **print** signature(x = "gecon\_var\_info"): Prints all the available information (short listing, values, statistics, incidence) about the variables, retrieved from the model when creating a gecon\_var\_info-class object.
- **show** signature(object = "gecon\_var\_info"): Prints information about the variables incidence and the results already obtained for the variables.
- **summary** signature(object = "gecon\_var\_info"): Prints all the available information (short listing, values, statistics, incidence) about the variables, retrieved from the model when creating a gecon\_var\_info-class object.

# Author(s)

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#### See Also

var\_info to create a gecon\_var\_info object. The analogous classes storing the information about shocks and parameters are gecon\_shock\_info-class and gecon\_par\_info-class.

# **Examples**

get\_index\_sets

List of index sets

# Description

The get\_index\_sets function retrieves a list with all the index sets specified in the .gcn file.

# Usage

```
get_index_sets(model)
```

# Arguments

model

an object of gecon\_model class.

# **Details**

Cf. gEcon manual, chapter "Templates".

## Value

The function returns a list of index sets. Each component of the list corresponds to one set and contains all the set elements' names as a character vector.

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#### **Examples**

get\_moments

Statistics of the model

# Description

The get\_moments function prints and returns the statistics of the model (absolute and relative to the reference variable).

## Usage

## **Arguments**

model an object of the gecon\_model class.
var\_names the names of the variables of interest.

relative\_to logical. The default value is FALSE. If TRUE, the function returns moments

relative to one of the variables in accordance with relevant options chosen in the compute\_moments (then only 'moments' and 'correalations' are active options).

moments logical. If TRUE, the moments of variables: steady state values, standard de-

viations and variances are returned with the information about which variables have been log-linearised. If 'relative\_to' is set to TRUE then the moments and

steady-state values relative to the reference variable are returned.

correlations logical. The default value is TRUE. If TRUE, a correlation matrix is returned.

If relative\_to is set to TRUE, then the corraletions of variables with lagged and

leading values of a chosen variable are returned.

autocorrelations

logical. The default value is TRUE. If TRUE then the autocorrelations of variables are returned. If the relative\_to is set to TRUE, this option is inactive.

var\_dec logical. The default value is TRUE. If TRUE then the variance decomposition

(of shocks) is returned. If the relative\_to is set to TRUE, the option is inac-

tive.

to\_tex logical. The default value is FALSE. If TRUE, the output is written to a .tex file.

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#### Value

The function returns a list of absolute or relative moments of variables depending on the value of the relative\_to argument.

When the relative\_to is set to FALSE, the list may consist of the following elements:

- moments means, standard deviations, and variances of variables,
- correlation\_matrix a matrix of correlation of variables,
- autocorrelations a matrix of correlation of variables with their own lagged values (autocorrelations),
- variance\_decomposition the variance decomposition, describing the amount of variable variability that can be ascribed to each of shocks.

When the relative\_to is set to TRUE, the list may consist of two elements:

- relative\_moments means, standard deviations, and variance of variables with respect to reference variable specified in the compute\_moments function,
- correlations\_variable a matrix of correlation of variables with lead and lagged values of a reference variable (usually GDP).

## Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### See Also

the compute\_moments function to see how the statistics are computed.

get\_par\_names 21

get	par	names	

Accessing parameter names used by gecon\_model class objects

# **Description**

The get\_par\_names function allows to retrieve the names of parameters from gecon\_model class objects.

# Usage

```
get_par_names(model, free_par = TRUE, calibr_par = TRUE)
```

#### **Arguments**

model an object of gecon\_model class.

free\_par logical. If TRUE (default), free parameters are added to the vector of parameter

names.

calibr\_par logical. If TRUE (default), calibrated parameters are added to the vector of

parameter names.

# Value

The function returns a character vector of parameter names, stored by the chosen object of gecon\_model class.

#### See Also

For details, see gecon\_model-class.

```
get_par_names_by_index
```

Parameters corresponding to given indices

# Description

The get\_par\_names\_by\_index function retrieves the names of parameters with given indices.

#### Usage

```
get_par_names_by_index(model, index_names)
```

# Arguments

```
model an object of gecon_model class.

index_names a character vector of the chosen indices.
```

# **Details**

Cf. gEcon manual, chapter "Templates".

#### Value

The function returns a character vector of relevant parameter names.

```
# copy model to current working directory
file.copy(from = file.path(system.file("examples", package = 'gEcon'),
          'pure_exchange_t.gcn'), to = getwd())
# make and load model
pure_exchange_t <- make_model('pure_exchange_t.gcn')</pre>
# model calibration
pure_exchange_t <- set_free_par(pure_exchange_t, free_par= c("alpha__A__1" = 0.3, "alpha__A__2" = 0.4,</pre>
                                                 "alpha_A_3" = 0.3, "alpha_B_1" = 0.3,
                                                 "alpha_B_2" = 0.4, "alpha_B_3" = 0.3,
                                               "e_calibr__A__1" = 3, "e_calibr__B__1" = 1,
                                               "e_calibr__A__2" = 2, "e_calibr__B__2" = 1,
                                               "e_calibr__A__3" = 1, "e_calibr__B__3" = 3))
# get all parameters associated with the agent A
par_names_A <- get_par_names_by_index(pure_exchange_t, index_names = "A")</pre>
par_info(pure_exchange_t, par_names_A)
# get all parameters associated with the agent B
par_names_B <- get_par_names_by_index(pure_exchange_t, index_names = "B")</pre>
par_info(pure_exchange_t, par_names_B)
```

get\_par\_values 23

		-	
get	par	val	lues

Parameters of the model

# Description

The get\_par\_values function prints and returns the values of parameters.

# Usage

```
get_par_values(model, par_names, to_tex)
```

# Arguments

model an object of the gecon\_model class.

par\_names a list of requested parameters names.

to\_tex logical. The default value is FALSE. If TRUE, the output is written to a .tex file.

#### Value

This function returns both free and calibrated parameter values.

# Author(s)

```
Karol Podemski <a range colong c
```

#### See Also

For details, see gecon\_model-class.

24 get\_pert\_solution

get\_pert\_solution

Recursive laws of motion for the model variables

#### **Description**

The get\_pert\_solution function prints and returns the recursive laws of motion for the model's variables.

# Usage

```
# getting recursive laws of motion
get_pert_solution(model, to_tex = FALSE)
```

## **Arguments**

model an object of the gecon\_model class.

to\_tex logical. The default value is FALSE. If TRUE, the output is written to a .tex file.

#### Value

A list with P, Q, R, S elements. P and Q matrices denote the impact of lagged state variables and current values of shocks variables on current values of state variables. R and S matrices denote the impact of lagged state variables and current values of shocks variables on current values of non-state variables.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### See Also

solve\_pert for the description of solution procedure and description of output.

get\_residuals 25

get\_residuals

Retriving residuals

## **Description**

The get\_residuals function allows to check the residuals of the steady-state equations (equations characterising equilibrium in case of static models) and identify equations with the highest errors. This information may help to assign better initial values to variables when the solver cannot find the steady state (equilibrium).

#### Usage

```
get_residuals(model, highest = 5)
```

# **Arguments**

model an object of the gecon\_model class.

highest the number of equations with the highest error to be printed.

#### Value

This function returns a list with the initial and final elements. The initial residuals are residuals computed using the initial values. The final residuals are residuals computed after the solver has exited. The function prints the indices of equations with the highest initial and final errors. The equations can be investigated by using the list\_eq function.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

```
# copy model to current working directory
file.copy(from = file.path(system.file("examples", package = 'gEcon'),
                             'home_prod_templ.gcn'), to = getwd())
# make and load model
home_prod_templ <- make_model('home_prod_templ.gcn')</pre>
# For the example purpose, we set the initial values extremely far from the solution
home_prod_templ <- initval_var(home_prod_templ, c(N = 0.02,</pre>
                                                                 N_{-}H = 0.01,
                                                                 N_{M} = 0.01)
home_prod_templ <- steady_state(home_prod_templ)</pre>
get_residuals(home_prod_templ)
# Initial residuals for the equations 2, 18, and 4 are very high
# therefore initial values are set to more reasonable values and the steady state will be found
home_prod_templ <- initval_var(home_prod_templ, c(N = 0.5,</pre>
                                                                 N_{-}H = 0.25,
                                                                 N_{M} = 0.25)
```

```
home_prod_templ <- steady_state(home_prod_templ)
get_residuals(home_prod_templ)</pre>
```

get\_shock\_names

Accessing shock names used by gecon\_model class objects

# **Description**

The get\_shock\_names function allows to retrieve the names of shocks from gecon\_model class objects.

## Usage

```
get_shock_names(model)
```

# **Arguments**

model

an object of gecon\_model class.

#### Value

The function returns a character vector of shock names, stored by the chosen object of gecon\_model class.

#### See Also

For details, see gecon\_model-class.

# **Examples**

```
get_shock_names_by_index
```

Shocks corresponding to given indices

# Description

The get\_shock\_names\_by\_index function retrieves the names of shocks with given indices.

# Usage

```
get_shock_names_by_index(model, index_names)
```

get\_simulation\_results 27

#### **Arguments**

```
model an object of gecon_model class.
index_names a character vector of the chosen indices.
```

#### **Details**

```
Cf. gEcon manual, chapter "Templates".
```

#### Value

The function returns a character vector of relevant shock names.

# **Examples**

```
get_simulation_results
```

Retrieve series of simulated variables

# **Description**

The get\_simulation\_results function retrieves the series of simulated variables from an object of the gecon\_simulation class.

# Usage

```
get_simulation_results(sim_obj)
```

#### **Arguments**

sim\_obj An object of the gecon\_simulation-class class.

# Value

The results are returned as one element list when the simulation has been invoked by the random\_path or simulate\_model functions or a list of more elements corresponding to the number of shocks when the simulation has been performed with the compute\_irf function.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

28 get\_ss\_values

#### See Also

For details, see gecon\_simulation-class.

# **Examples**

get\_ss\_values

Return the steady-state (equilibrium) values

# Description

The get\_ss\_values function returns (and prints) the steady state of the model for dynamic models (equilibrium for static models).

# Usage

```
get_ss_values(model, var_names, to_tex = FALSE)
```

# **Arguments**

model an object of the gecon\_model class.

var\_names the names or the indices of the variables, whose steady-state values (equilibrium

values) are to be returned. The default option is a vector containing all the

variable names.

to\_tex logical. The default value is FALSE. If TRUE, the output is written to a .tex file.

#### Value

A numeric vector of the steady-state (equilibrium for static models) values.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

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## **Examples**

get\_var\_names

Accessing variable names used by gecon\_model class objects

# **Description**

The get\_var\_names function allows to retrieve the names of variables from gecon\_model class objects.

#### Usage

```
get_var_names(model)
```

# **Arguments**

model

an object of gecon\_model class.

## Value

The function returns a character vector of variable names, stored by the chosen object of gecon\_model class.

# See Also

For details, see gecon\_model-class.

```
get_var_names_by_index
```

Variables corresponding to given indices

#### **Description**

The get\_var\_names\_by\_index function retrieves the names of variables with given indices.

## Usage

```
get_var_names_by_index(model, index_names)
```

# **Arguments**

```
model an object of gecon_model class.
index_names a character vector of the chosen indices.
```

#### **Details**

Cf. gEcon manual, chapter "Templates".

#### Value

The function returns a character vector of relevant variable names.

```
# copy model to current working directory
file.copy(from = file.path(system.file("examples", package = 'gEcon'),
                                     'pure_exchange_t.gcn'), to = getwd())
# make and load model
pure_exchange_t <- make_model('pure_exchange_t.gcn')</pre>
# model calibration
pure\_exchange\_t <- set\_free\_par(pure\_exchange\_t, free\_par= c("alpha\_A\_1" = 0.3, "alpha\_A\_2" = 0.4, free\_par= c("alpha\_A_1" = 0.3, "alpha_A_2" = 0.4, free\_par= c("alpha_A_1" = 0.3, "alpha_A_1" = 0.4, free\_par= c("alpha_A_1" = 0.4, free\_par= c(
                                                                                                                                                                          "alpha_A_3" = 0.3, "alpha_B_1" = 0.3,
                                                                                                                                                                    "alpha_B_2" = 0.4, "alpha_B_3" = 0.3, 
"e_calibr_A_1" = 3, "e_calibr_B_1" = 1,
                                                                                                                                                                    "e_calibr__A_2" = 2, "e_calibr__B_2" = 1,
"e_calibr__A_3" = 1, "e_calibr__B_3" = 3))
# compute equilibrium
pure_exchange_t <- steady_state(pure_exchange_t)</pre>
# get all variable names associated with the agent A
var_names_A <- get_var_names_by_index(pure_exchange_t, index_names = "A")</pre>
# get all variable names associated with the agent B
var_names_B <- get_var_names_by_index(pure_exchange_t, index_names = "B")</pre>
# compare equilibrium allocations
```

initval\_calibr\_par 31

```
get_ss_values(pure_exchange_t, var_names_A)
get_ss_values(pure_exchange_t, var_names_B)
```

initval\_calibr\_par

Setting initial values of calibrated parameters

#### **Description**

The initval\_calibr\_par function enables setting the initial values of calibrated parameters for the nonlinear solver searching for the steady state of dynamic models (equilibrium for static models) and the values of calibrated parameters. If not set by this function, the default values of parameters are assumed to be 0.5.

# Usage

```
initval_calibr_par(model, calibr_par)
```

#### **Arguments**

```
model an object of the gecon_model class.
calibr_par a named list or a vector of parameters.
```

#### Details

The values of parameters passed to the gecon\_model are treated as initial values for the steady-state solver when the user specifies calibrating equations in a .gcn file and requests that steady\_state function shall use it. If the calibration is omitted, the initial values of calibrated parameters are treated as their final values, so one has to specify the right set of calibrated parameters values when decides to omit the calibrating equations.

#### Value

An object of the gecon\_model class representing the model. Generic functions such as print and summary allow to show the model's elements. The get\_par\_values function return parameter values.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

32 list\_calibr\_eq

initval\_var

Setting initial values of variables.

# Description

The initval\_var function sets the initial values of the model's variables to values specified by the user. The initial values close to solution will help the nonlinear equations solver to find the solution.

# Usage

```
initval_var(model, init_var)
```

#### **Arguments**

model an object of the gecon\_model class.

init\_var a named list or vector of the initial values of variables.

## Value

An object of the gecon\_model class representing the model. Generic functions such as print and summary allow to show model elements. The get\_ss\_values function returns the steady-state (equilibrium) values of the model variables.

#### Author(s)

```
Karol Podemski <a range colong c
```

## **Examples**

list\_calibr\_eq

Find calibrating equations

# Description

The list\_calibr\_eq function returns calibrating equations with given indices.

# Usage

```
list_calibr_eq(model, no_eq = NULL)
```

## Arguments

model an object of the gecon model class.

no\_eq a numeric variable, specifies the indices of requested equations.

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#### Value

A character vector of requested equations.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

# **Examples**

list\_eq

Find model equations

## **Description**

The list\_eq function returns equations with the specified indices.

# Usage

```
list_eq(model, no_eq = NULL)
```

# **Arguments**

model an object of the gecon\_model class.

no\_eq a numeric variable, specifies the indices of requested equations.

## Value

A character vector of requested equations.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

34 load\_model

load\_model

Load model from .R file

# **Description**

The load\_model function loads the already generated .R file with the model and creates an object of the gecon\_model class.

#### Usage

```
load_model(model_file)
```

## **Arguments**

model\_file

the name of the .R file containing the model's functions and variables. It can be a name of file or a name of file ending with a .model.R extension.

#### **Details**

The .R file with the model specification has to be created first. It can be done by using the make\_model command and the gcn file model specification or manually.

#### Value

An object of the gecon\_model class representing the model. Generic functions such as print and summary allow to show the model's elements.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

## See Also

the  $make\_model$  function in order to create an R file with the model elements based on the model specification.

make\_model 35

make\_model

Make model from .gcn file

# **Description**

This function calls the dynamic library, parses the .gcn model file, generates an .R file, and loads it into a gecon\_model class object.

#### Usage

```
make_model(model_file)
```

# **Arguments**

model\_file

the name of the .gcn file containing model formulation. It must be ended with a .gcn extension.

## **Details**

Cf. gEcon manual, chapters "Model description language" and "Derivation of First Order Conditions".

#### Value

An object of the gecon\_model class representing the model. Generic functions such as print and summary allow to show the model elements.

## Note

When the function is called, an R file with the same name as the .gcn file is created in the the .gcn file directory. Additional files such as a Latex documentation or a log may be created when such an option is set to TRUE in the .gcn file.

#### Author(s)

```
Grzegorz Klima <gklima@users.sourceforge.net>
Karol Podemski <karol.podemski@gmail.com>
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### See Also

load\_model function to load already created .R file with model.

36 par\_info

par\_info

Information about parameters

## **Description**

The par\_info function allows to create an object of class gecon\_par\_info, containing information about given parameters of the chosen model. It allows to check type and value of a given set of parameters, and the incidence matrix.

#### Usage

```
par_info(model, par_names = NULL, all_parameters = FALSE)
```

#### **Arguments**

model an object of the gecon\_model class.

par\_names the names of the parameters of interest.

all\_parameters the logical value. If set to TRUE, the par\_names argument is overwritten with a vector of all parameters appearing in the model. The default value is FALSE.

#### **Details**

If the function result is not assigned to any variable, the information about the requested parameters is printed in the console.

#### Value

An object of gecon\_par\_info class.

# Author(s)

```
Karol Podemski <a href="mailto:karol.podemski@gmail.com">karol.podemski@gmail.com</a>,
Kaja Retkiewicz-Wijtiwiak <a href="mailto:kaja.retkiewicz@gmail.com">kaja.retkiewicz@gmail.com</a>
```

#### See Also

shock\_info for information about the shocks and var\_info for information about the variables.

plot\_simulation 37

# **Description**

The plot\_simulation function plots the simulations or saves them as .eps files in the model's subdirectory /plots.

#### Usage

```
plot_simulation(sim_obj, to_tex = NULL, to_eps = NULL)
```

## **Arguments**

sim_obj	an object of the gecon_simulation class.
to_tex	logical. If TRUE, the plots are added to a .tex file.
to_eps	logical. if TRUE, $plot(s)$ shall be saved as .eps file(s) in the model's subdirectory /plots.

#### Value

If the number of variables of interest is greater then five, more then one plots for each impulse are created (max. 5 variables on each plot). Separate plots are created for all the impulses, if the compute\_irf function has been used for generating simulations.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

38 random\_path

print-methods	Methods for Function print in gEcon package	

#### **Description**

Prints information about objects of the gecon\_simulation, gecon\_model, gecon\_var\_info, gecon\_shock\_info, and gecon\_par\_info classes.

# Methods

- signature(x = "gecon\_simulation") Prints the name of the model for which the simulations have been generated, information about the time span, shock, and variables used.
- signature(x = "gecon\_model") Shows the type of the model, the date of creation, the solving status, and more detailed information about the number of variables and parameters then the show generic.
- signature(x = "gecon\_var\_info") Prints all the available information (a short listing, the incidence matrix, the statistics) about the variables, retrieved from the model when creating a gecon\_var\_info-class object.
- signature(x = "gecon\_shock\_info") Prints all the available information (a short listing, the
  incidence matrix, the variance-covariance matrix) about the shocks, retrieved from the model
  when creating a gecon\_shock\_info-class object.
- signature(x = "gecon\_par\_info") Prints all the available information (a short listing, the values, the type, and the incidence) about the parameters, retrieved from the model when creating a gecon\_par\_info-class object.

random_path	Simulation of the model using a random path of shocks
-------------	---

# Description

This function draws random shocks from distribution with user specified covariance matrix and then simulates the behaviour of the system.

# Usage

```
random_path(model, shock_list = NULL, var_list = NULL, path_length = 100)
```

#### **Arguments**

model	an object of the gecon_model class.
shock_list	a list of shock names that should be taken into account. If not specified, the system of all the shocks is simulated.
var_list	a list of variables on which the impact of shocks is to be computed. By default, the impact of random path is evaluated for the state variables only.
path_length	the length of stochastic path, default value = 100.

set\_free\_par 39

#### **Details**

Cf. gEcon manual, chapter "Model analysis".

#### Value

An object of the gecon\_simulation class with simulated paths of variables.

## Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### See Also

the simulate\_model function enables user to specify her own path of shocks and simulate the impact. The function returns an object of the gecon\_simulation class. Generic functions such as print and summary provide information about the simulations. The plot\_simulation function allows to visualize the impact on variables.

# **Examples**

set\_free\_par

Setting free parameters of model

# Description

The set\_free\_par function specifies parameters of a gecon\_model class object.

#### Usage

```
set_free_par(model, free_par, reset = FALSE)
```

40 set\_shock\_cov\_mat

#### **Arguments**

model an object of class gecon\_model.

free\_par a named list or a vector of parameters.

reset logical value. If TRUE, the function allows to reset free parameters to values

specified in the .gcn file.

#### Value

An object of the gecon\_model class representing the model. If the reset option has been set to TRUE, the model's parameters will be set back to values from the .gcn file. Generic functions such as print and summary allow to show model elements. The get\_par\_values function returns parameter values currently in use.

# Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### **Examples**

set\_shock\_cov\_mat

Setting a variance-covariance matrix of stochastic shocks.

# **Description**

The set\_shock\_cov\_mat function allows to set a variance-covariance matrix for the model shocks.

#### Usage

```
set_shock_cov_mat(model, shock_matrix, shock_order = NULL)
```

set\_shock\_distr\_par 41

## Arguments

model an object of the gecon\_model class.

shock\_matrix a symmetric, positive definite matrix with the dimensions (n \* n), where n is the

number of shocks in the model.

shock\_order a character vector specifying the order of shocks in the shock\_matrix. If not

specified, it is assumed that the order is in accordance with the internal order of the model. The default order can be displayed by using the shock\_info function

with the all\_shocks argument set to TRUE.

#### **Details**

The rows and columns of shock matrix must agree with the order of shocks stored in a gecon\_model-class object if the shock\_order argument is not supplied. This order can be checked by using the shock\_info function and the generic function print.

#### Value

An object of the gecon\_model class, which is representing the model. Generic functions such as print and summary allow to show the model elements. The shock\_info function returns names of shocks, information about which equations they appear in and the current variance-covariance matrix.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

# **Examples**

set\_shock\_distr\_par

Setting distribution parameters of model shocks

## **Description**

The set\_shock\_distr\_par function assigns distribution parameters (standard deviations, correlations of shocks etc) to shocks in an object of gecon\_model class.

# Usage

```
set_shock_distr_par(model, distr_par = NULL)
```

42 set\_shock\_distr\_par

#### **Arguments**

```
model an object of gecon_model class.

distr_par a list or vector of distribution parameters.
```

#### **Details**

By default, gEcon uses an identity matrix as the variance-covariance matrix for shocks. Valid parameter names should match any of the following patterns:

```
"sd( SHOCK_NAME )"
"var( SHOCK_NAME )"
"cov( SHOCK_NAME_1, SHOCK_NAME_2 )"
"cor( SHOCK_NAME_1, SHOCK_NAME_2 )"
```

There are two issues which the user should be careful about while using the set\_shock\_distr\_par function. First, in contrast to other parameters, shock distribution parameters require quotation marks to be assigned properly. If quotation marks are omitted, R parser treats elements of the distr\_par list or vector as functions and attempts to evaluate them, producing errors. Second, parameters passed to the distr\_par argument should not be specified twice.

#### Value

An object of the gecon\_model class representing the model.

#### Author(s)

```
Karol Podemski < karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak < kaja.retkiewicz@gmail.com>
```

shock\_info 43

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# **Description**

The shock\_info function allows to create an object of the gecon\_shock\_info class, which contains the information about the model's shocks (occurence in equations and the variance-covariance matrix).

# Usage

```
shock_info(model, shock_names = NULL, all_shocks = FALSE)
```

# **Arguments**

model an object of the gecon\_model class.

shock\_names the names of shocks of interest.

all\_shocks the logical value. If set to TRUE, the shock\_names argument is overwritten with the vector of all shocks appearing in the model. The default value is FALSE.

# Value

An object of the gecon\_shock\_info-class class.

## Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

44 simulate\_model

	show-methods	Methods for show Function in gEcon package	
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# **Description**

This method shows objects of the gecon\_simulation, gecon\_model, gecon\_var\_info, gecon\_shock\_info, and gecon\_par\_info classes.

#### Methods

- signature(object = "gecon\_simulation") Shows the name of the model for which the simulations have been created, information about time span, shocks, and variables used.
- signature(object = "gecon\_model") Shows the type of the model, the date of creation, the solving status, and the information about number of variables and parameters.
- signature(object = "gecon\_var\_info") Prints information about variables' incidence and the
  results that have been already obtained for the variables.
- signature(object = "gecon\_shock\_info") Prints the incidence matrix and the variance-covariance matrix of shocks, retrieved from the model when creating gecon\_shock\_info object.
- signature(object = "gecon\_par\_info") Prints information about parameters' type, value, and
  the incidence matrix.

tion of the model
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# **Description**

The simulate\_model function simulates model based on realisations of shock values given by the user. In particular it enables to compute the impact of negative shocks.

# Usage

#### Arguments

model	an object of the gecon_model class.
shock_list	the shock names for the rows shock_m specified by the user. The default names are the names of the first shocks from the list of shocks up to the number of shock_m matrix rows.
var_list	the list of variables for which the impact has to be computed. By default, the impact of shocks is evaluated for the state variables only.
shock_m	a matrix or vector of shocks given by the user. Values for different shocks should be stored in rows and values for periods in columns.

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the number of periods for which, shocks in the shock\_m function have been specified. The default values are from 1 to the number of columns of the shock matrix.

path\_length the number of periods for which the model is simulated. The default number is 40.

sim\_type the type of simulation performed on model. It does not have to be specified when user invokes this function directly.

model\_name the name of the gecon\_model-class object based on which simulations are created. The user does not have to specify the name explicitly (by default, the variable is deparsed and name is retrieved automatically). It does not have to be

#### **Details**

The random\_path and compute\_irf functions are wrappers for this function. They generate a path of shock(s) values and pass it on to simulate\_model function, which performs computations and returns relevant results.

specified when user invokes this function directly.

#### Value

An object of the gecon\_simulation class with simulated paths of variables.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

# See Also

the random\_path function to use random path of shocks for the simulation of the model. The function returns an object of the gecon\_simulation class. Generic functions such as print and summary provide information about the simulations. The plot\_simulation function allows to visualize the impact on variables.

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Solve the model in a linearised form (1st order perturbation)

## **Description**

This function solves the model in a linearised form using Christopher Sims' gensys solver.

# Usage

## **Arguments**

model an object of the gecon\_model class.

loglin an option to log-linearise the perturbation. If FALSE, the model is only lin-

earised.

not\_loglin\_var a vector of variables that will not be log-linearised.

norm\_tol the tolerance for residuals of model (default 1e-08).

solver the name linear RE solver. The default solver is Christopher Sims' solver. Cur-

rently no other solvers are available.

#### **Details**

Cf. gEcon manual, chapter "Solving the model in linearised form".

## Value

an object of the gecon\_model class representing the model. Generic functions such as print and summary allow to show the model elements. The get\_pert\_solution function returns computed recursive laws of motion for the model's variables. The check\_bk function displays the eigenvalues of the system and checks the Blanchard-Kahn conditions.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### References

Sims, Ch. A. (2002), "Solving Linear Rational Expectations Models.", Computational Economics

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```
rbc <- solve_pert(rbc)
get_pert_solution(rbc)

# solve in linearised form
rbc <- solve_pert(rbc, loglin = FALSE)
get_pert_solution(rbc)

# solve with all variables except L_s log-linearised
rbc <- solve_pert(rbc, not_loglin_var=c('L_s'))
get_pert_solution(rbc)</pre>
```

steady\_state

Compute the steady state (equilibrium) of the dynamic (static) model

# Description

The steady\_state function solves for the steady state of a dynamic model (equilibrium for static model) and calibrates the chosen parameters using a set of solvers from the nleqsly package.

## Usage

#### **Arguments**

model an object of the gecon\_model class.

solver the name of nonlinear equations solver. In the current version only an interface to slv1\_nleqslv function has been implemented.

use\_jac the option to use the Jacobian generated by the symbolic library. If FALSE, numerical derivatives are computed.

calibration if FALSE, calibrating equations will not be taken into account in the computation of the steady state (equilibrium in case of static model). The initial values of calibrated parameters will be then treated as their values.

options\_list

a list containing one or more of the following fields:

- method a character, can be set to "Newton" or "Broyden", the default option is "Newton".
- global a character, search strategy can be set to "dbldog", "pwldog", "qline", "gline", "none". The default option is "qline".
- xscalm a character, a method of scaling x. It can be set to "fixed", "auto". The default option is "fixed".
- max\_iter a numeric value denoting max. number of iterations. The default value is 150.
- tol a numeric value setting the numeric tolerance for a solution. The default value is 1e-6.

solver\_status the information about the solver exit code.

#### **Details**

Cf. gEcon Manual, chapter "Deterministic steady state & calibration".

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#### Value

An object of the gecon\_model class representing the model. Generic functions such as print and summary allow to show model elements. The get\_ss\_values and get\_par\_values functions return the steady state (equilibrium) and parameter values respectively.

#### Author(s)

```
Karol Podemski <karol.podemski@gmail.com>,
Kaja Retkiewicz-Wijtiwiak <kaja.retkiewicz@gmail.com>
```

#### See Also

nleqslv for the detailed description of the nleqslv solver capabilities. If the steady state has not been found, the get\_residuals function can be used to check initial and final residuals.

# **Examples**

```
# copy model to current working directory
file.copy(from = file.path(system.file("examples", package = 'gEcon'),
           'rbc.gcn'), to = getwd())
# make and load model
rbc <- make_model('rbc.gcn')</pre>
# compute the steady state and calibrate alpha
rbc <- initval_calibr_par(rbc, list(alpha = 0.33))</pre>
rbc <- steady_state(rbc, use_jac=TRUE,</pre>
                         options_list=list(method='Broyden', global='gline',
                                           max_iter = 300, tol = 1e-7)
get_ss_values(rbc)
# compute steady state not taking alpha calibration into account
rbc <- initval_calibr_par(rbc, list(alpha = 0.4))</pre>
rbc <- steady_state(rbc, calibration=FALSE, use_jac=FALSE,</pre>
                        options_list=list(method='Newton', global='gline',
                                           max_iter = 100, tol = 1e-5)
get_ss_values(rbc)
```

summary-methods

Summary Method for gecon\_model objects in gEcon package

#### **Description**

This method summarizes the objects of the gecon\_simulation, gecon\_model, gecon\_var\_info, gecon\_shock\_info, and gecon\_par\_info classes.

# Methods

signature(object = "gecon\_simulation") Prints a summary of a gecon\_simulation class object consisting of a shock matrix and the simulation for each shock.

signature(object = "gecon\_model") Prints a summary of a gecon\_model class object consisting of all the computed statistics and values.

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signature(object = "gecon\_var\_info") Prints all the available information (short listing, the incidence matrix, the statistics) about the variables, retrieved from the model when creating a gecon\_var\_info-class object.

- signature(object = "gecon\_shock\_info") Prints all the available information (short listing,
  the incidence matrix , the variance-covariance matrix) about the shocks, retrieved from the
  model when creating a gecon\_shock\_info-class object.
- signature(object = "gecon\_par\_info") Prints all the available information (short listing, the values, the type, and the incidence) about the parameters, retrieved from the model when creating a gecon\_par\_info-class object.

var\_info

Information about variables

#### **Description**

The var\_info function allows to create an object of gecon\_var\_info class, which contains information about the chosen variables. It allows to check which equations given variables appear in. In addition, this function prints the already computed statistics of the given set of variables.

#### Usage

```
var_info(model, var_names = NULL, all_variables = FALSE)
```

#### Arguments

model an object of the gecon\_model class.
var\_names the names of the variables of interest.

all\_variables the logical value. If set to TRUE, the var\_names argument is overwritten with a

vector of all variables appearing in the model. The default value is FALSE.

#### **Details**

The var\_info function may be useful in debugging model and quick retrieval of information when the model is large. If the object returned by the function is not assigned to any variable, the information about the requested parameters is printed to the console. One or more of the following elements may be printed:

- incidence information.
- steady-state (equilibrium) values,
- variables info (which ones are log-linearised and which are state variables),
- state variables impact on the chosen variables,
- shocks impact on the chosen variables,
- · moments,
- correlations,

depending on which operations have been performed on gecon\_model class object.

#### Value

An object of gecon\_var\_info-class class.

var\_info

#### Note

The function only displays the elements of a model that have been already set or computed. Eg. if the model has been solved but the statistics have not been computed, the correlations will not be passed to the gecon\_var\_info class.

# Author(s)

```
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```

## See Also

```
shock_info for information about the shocks.
get_ss_values, get_pert_solution, get_moments to extract the steady-state (equilibrium) values, the solution, and various moments and statistics of the model.
```

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