

Quintic splines

```
In[1]:= ClearAll["Global`*"]
```

This file explains the basic working of quintic splines, as we use them in the paper of Thomas Blanchet, Juliette Fournier and Thomas Piketty, "Generalized Pareto Curves: Theory and Applications", 2017.

Basis functions

Determine the basis functions by solving the appropriate linear system:

```
In[2]:= poly[x_] = Sum[a_i x^i, {i, 0, 5}]
```

```
Out[2]= a_0 + x a_1 + x^2 a_2 + x^3 a_3 + x^4 a_4 + x^5 a_5
```

```
In[3]:= coef = CoefficientList[poly[x], x]
```

```
Out[3]= {a_0, a_1, a_2, a_3, a_4, a_5}
```

```
In[4]:= h00[x_] = poly[x] /. First[Solve[{poly[0] == 1, poly[1] == 0,
poly'[0] == 0, poly'[1] == 0, poly''[0] == 0, poly''[1] == 0}, coef]];
```

```
In[5]:= h01[x_] = poly[x] /. First[Solve[{poly[0] == 0, poly[1] == 1,
poly'[0] == 0, poly'[1] == 0, poly''[0] == 0, poly''[1] == 0}, coef]];
```

```
In[6]:= h10[x_] = poly[x] /. First[Solve[{poly[0] == 0, poly[1] == 0,
poly'[0] == 1, poly'[1] == 0, poly''[0] == 0, poly''[1] == 0}, coef]];
```

```
In[7]:= h11[x_] = poly[x] /. First[Solve[{poly[0] == 0, poly[1] == 0,
poly'[0] == 0, poly'[1] == 1, poly''[0] == 0, poly''[1] == 0}, coef]];
```

```
In[8]:= h20[x_] = poly[x] /. First[Solve[{poly[0] == 0, poly[1] == 0,
poly'[0] == 0, poly'[1] == 0, poly''[0] == 1, poly''[1] == 0}, coef]];
```

```
In[9]:= h21[x_] = poly[x] /. First[Solve[{poly[0] == 0, poly[1] == 0,
poly'[0] == 0, poly'[1] == 0, poly''[0] == 0, poly''[1] == 1}, coef]];
```

Expressions of the basis functions:

```
In[10]:= TableForm[Map[# &, {h00[x], h01[x], h10[x], h11[x], h20[x], h21[x]}],
TableHeadings -> {"h00", "h01", "h10", "h11", "h20", "h21"}]
```

```
Out[10]//TableForm=
```

h00	$1 - 10 x^3 + 15 x^4 - 6 x^5$
h01	$10 x^3 - 15 x^4 + 6 x^5$
h10	$x - 6 x^3 + 8 x^4 - 3 x^5$
h11	$-4 x^3 + 7 x^4 - 3 x^5$
h20	$\frac{x^2}{2} - \frac{3 x^3}{2} + \frac{3 x^4}{2} - \frac{x^5}{2}$
h21	$\frac{x^3}{2} - x^4 + \frac{x^5}{2}$

Their first derivatives:

```
In[11]:= TableForm[Map[D[#, x] &, {h00[x], h01[x], h10[x], h11[x], h20[x], h21[x]}],
  TableHeadings -> {"h00", "h01", "h10", "h11", "h20", "h21"}]
```

Out[11]/TableForm=

h00	$-30x^2 + 60x^3 - 30x^4$
h01	$30x^2 - 60x^3 + 30x^4$
h10	$1 - 18x^2 + 32x^3 - 15x^4$
h11	$-12x^2 + 28x^3 - 15x^4$
h20	$x - \frac{9x^2}{2} + 6x^3 - \frac{5x^4}{2}$
h21	$\frac{3x^2}{2} - 4x^3 + \frac{5x^4}{2}$

Their second derivatives:

```
In[12]:= TableForm[Map[D[#, {x, 2}] &, {h00[x], h01[x], h10[x], h11[x], h20[x], h21[x]}],
  TableHeadings -> {"h00", "h01", "h10", "h11", "h20", "h21"}]
```

Out[12]/TableForm=

h00	$-60x + 180x^2 - 120x^3$
h01	$60x - 180x^2 + 120x^3$
h10	$-36x + 96x^2 - 60x^3$
h11	$-24x + 84x^2 - 60x^3$
h20	$1 - 9x + 18x^2 - 10x^3$
h21	$3x - 12x^2 + 10x^3$

Their third derivatives:

```
In[13]:= TableForm[Map[D[#, {x, 3}] &, {h00[x], h01[x], h10[x], h11[x], h20[x], h21[x]}],
  TableHeadings -> {"h00", "h01", "h10", "h11", "h20", "h21"}]
```

Out[13]/TableForm=

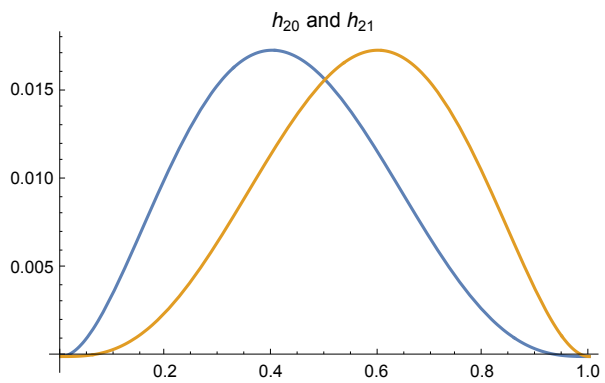
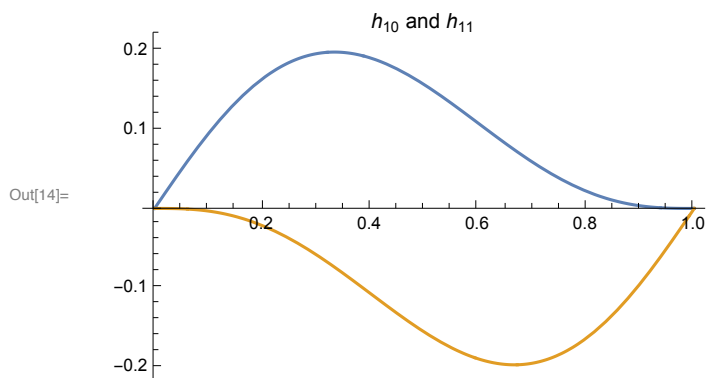
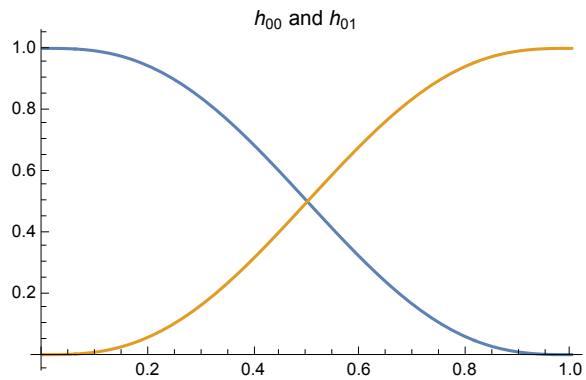
h00	$-60 + 360x - 360x^2$
h01	$60 - 360x + 360x^2$
h10	$-36 + 192x - 180x^2$
h11	$-24 + 168x - 180x^2$
h20	$-9 + 36x - 30x^2$
h21	$3 - 24x + 30x^2$

Plots of the basis functions:

```

In[14]:= GraphicsColumn[{Plot[{h00[x], h01[x]}, {x, 0, 1}, PlotLabel → "h00 and h01"],
  Plot[{h10[x], h11[x]}, {x, 0, 1}, PlotLabel → "h10 and h11"],
  Plot[{h20[x], h21[x]}, {x, 0, 1}, PlotLabel → "h20 and h21"}]}

```

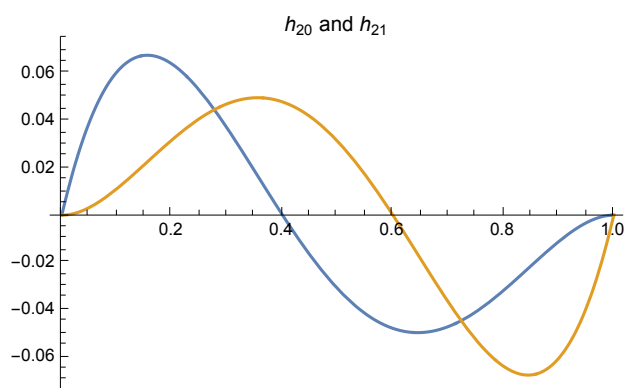
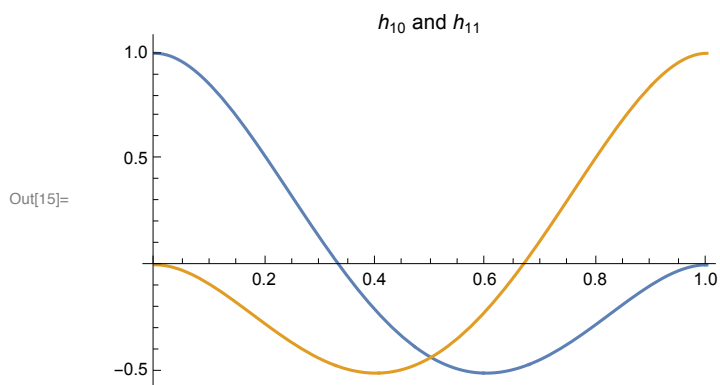
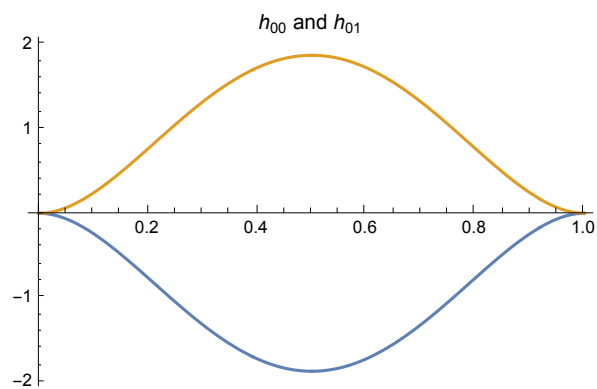


Their first derivatives:

```

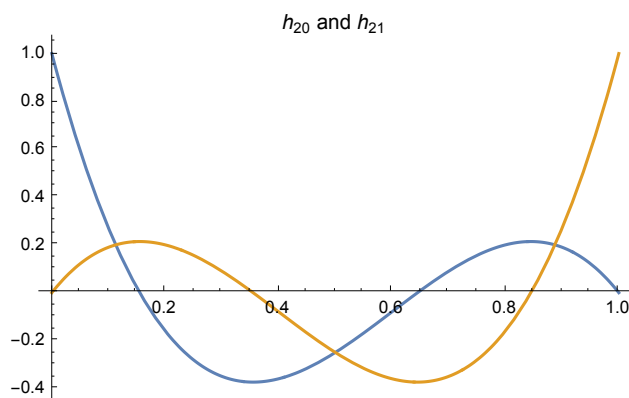
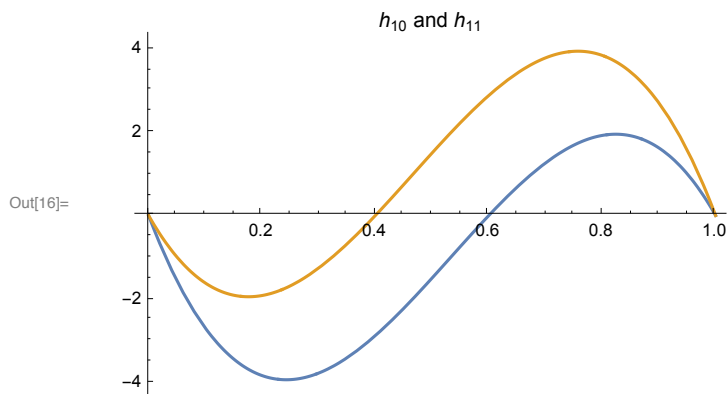
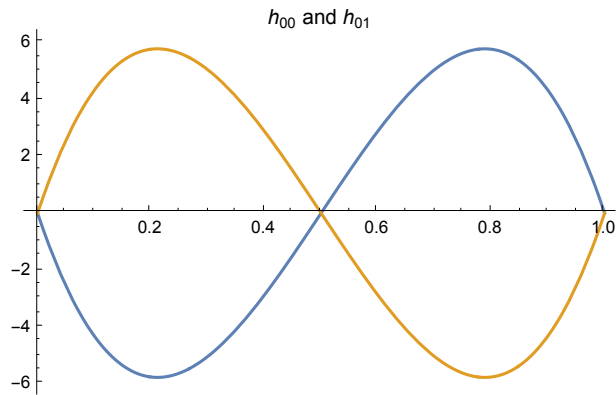
In[15]:= GraphicsColumn[
  {Plot[Evaluate[{h00'[x], h01'[x]}], {x, 0, 1}, PlotLabel → "h00' and h01'"],
  Plot[Evaluate[{h10'[x], h11'[x]}], {x, 0, 1}, PlotLabel → "h10' and h11'"],
  Plot[Evaluate[{h20'[x], h21'[x]}], {x, 0, 1}, PlotLabel → "h20' and h21'"]}

```



Their second derivatives:

```
In[16]:= GraphicsColumn[
  {Plot[Evaluate[{h00'[x], h01'[x]}], {x, 0, 1}, PlotLabel -> "h00 and h01"},
  Plot[Evaluate[{h10'[x], h11'[x]}], {x, 0, 1}, PlotLabel -> "h10 and h11"},
  Plot[Evaluate[{h20'[x], h21'[x]}], {x, 0, 1}, PlotLabel -> "h20 and h21"}]
```



Interpolation function

The interpolating function over $[0, 1]$ is a linear combination of those six basis functions:

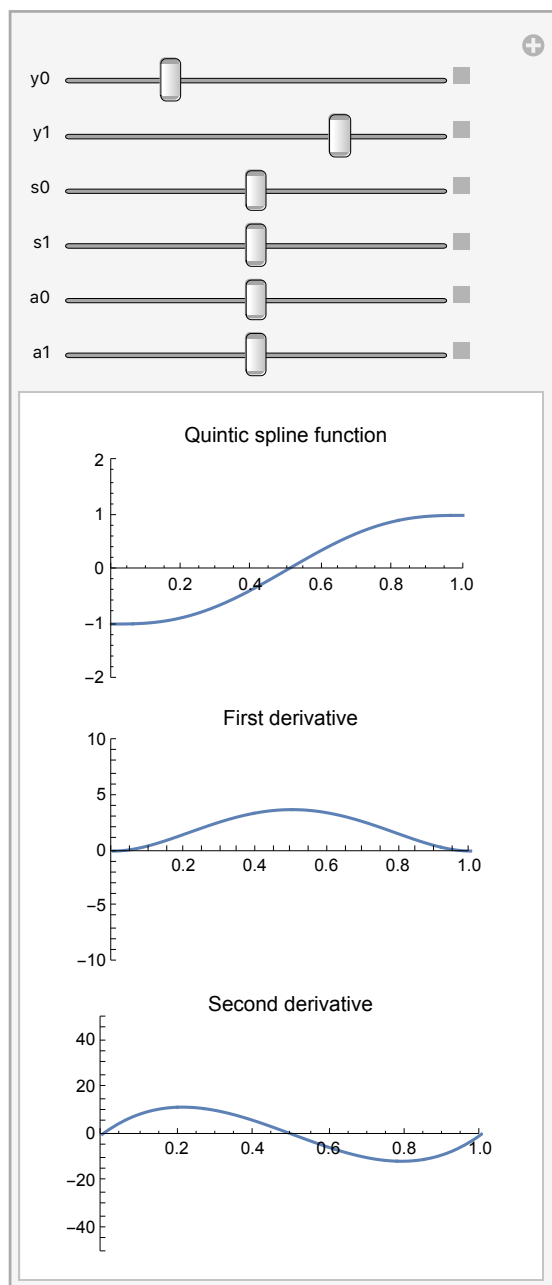
```
In[17]:= h[x_, y0_, y1_, s0_, s1_, a0_, a1_] =
  y0 * h00[x] + y1 * h01[x] + s0 * h10[x] + s1 * h11[x] + a0 * h20[x] + a1 * h21[x];
```

```

In[18]:= Manipulate[GraphicsColumn[{Plot[h[x, y0, y1, s0, s1, a0, a1], {x, 0, 1},
  PlotRange → {{0, 1}, {-2, 2}}, PlotLabel → "Quintic spline function"],
  Plot[Evaluate[D[h[x, y0, y1, s0, s1, a0, a1], x]], {x, 0, 1},
  PlotRange → {{0, 1}, {-10, 10}}, PlotLabel → "First derivative"],
  Plot[Evaluate[D[h[x, y0, y1, s0, s1, a0, a1], {x, 2}]], {x, 0, 1},
  PlotRange → {{0, 1}, {-50, 50}}, PlotLabel → "Second derivative"]],
  {{y0, -1}, -2, 2}, {{y1, 1}, -2, 2}, {{s0, 0}, -2, 2}, {{s1, 0}, -2, 2},
  {{a0, 0}, -20, 20}, {{a1, 0}, -20, 20}]

```

Out[18]=



We can extend this function to an arbitrary interval using an affine transformation:

```
In[19]:= f[x_] = y0 * h00[ $\frac{x - x0}{x1 - x0}$ ] + y1 * h01[ $\frac{x - x0}{x1 - x0}$ ] +
          s0 * (x1 - x0) * h10[ $\frac{x - x0}{x1 - x0}$ ] + s1 * (x1 - x0) * h11[ $\frac{x - x0}{x1 - x0}$ ] +
          a0 * (x1 - x0)^2 * h20[ $\frac{x - x0}{x1 - x0}$ ] + a1 * (x1 - x0)^2 * h21[ $\frac{x - x0}{x1 - x0}$ ];
```

Check that the function and its derivatives have the right values:

```
In[20]:= {f[x0], f[x1], f'[x0], f'[x1], f''[x0], f''[x1]}
Out[20]:= {y0, y1, s0, s1, a0, a1}
```

Regularity conditions to determine the parameters of the spline

To determine the parameters of the spline, we impose the requirement that the third derivative is continuous at the jointures. That leads to the most regular curve possible in the sense that the first derivative has the lowest curvature possible.

We start by defining two splines over the knots (x_1, x_2, x_3) . The spline over (x_1, x_2) is f_1 , and the one over (x_2, x_3) is f_2 .

```
In[21]:= f1[x_] = y1 * h00[ $\frac{x - x1}{x2 - x1}$ ] + y2 * h01[ $\frac{x - x1}{x2 - x1}$ ] +
          s1 * (x2 - x1) * h10[ $\frac{x - x1}{x2 - x1}$ ] + s2 * (x2 - x1) * h11[ $\frac{x - x1}{x2 - x1}$ ] +
          a1 * (x2 - x1)^2 * h20[ $\frac{x - x1}{x2 - x1}$ ] + a2 * (x2 - x1)^2 * h21[ $\frac{x - x1}{x2 - x1}$ ];
```

```
In[22]:= f2[x_] = y2 * h00[ $\frac{x - x2}{x3 - x2}$ ] + y3 * h01[ $\frac{x - x2}{x3 - x2}$ ] +
          s2 * (x3 - x2) * h10[ $\frac{x - x2}{x3 - x2}$ ] + s3 * (x3 - x2) * h11[ $\frac{x - x2}{x3 - x2}$ ] +
          a2 * (x3 - x2)^2 * h20[ $\frac{x - x2}{x3 - x2}$ ] + a3 * (x3 - x2)^2 * h21[ $\frac{x - x2}{x3 - x2}$ ];
```

Get the system in matrix form:

```
In[23]:= system = CoefficientArrays[{f1'''[x2] == f2'''[x2]}, {a1, a2, a3}];
```

```
In[24]:= system[[1]] // Normal
```

```
Out[24]= 
$$\left\{ -\frac{24 s_1}{(-x_1 + x_2)^2} - \frac{36 s_2}{(-x_1 + x_2)^2} + \frac{36 s_2}{(-x_2 + x_3)^2} + \right.$$


$$\left. \frac{24 s_3}{(-x_2 + x_3)^2} - \frac{60 y_1}{(-x_1 + x_2)^3} + \frac{60 y_2}{(-x_1 + x_2)^3} + \frac{60 y_2}{(-x_2 + x_3)^3} - \frac{60 y_3}{(-x_2 + x_3)^3} \right\}$$

```

```
In[25]:= system[[2]] // Normal
```

```
Out[25]= 
$$\left\{ \left\{ -\frac{3}{-x_1 + x_2}, \frac{9}{-x_1 + x_2} + \frac{9}{-x_2 + x_3}, -\frac{3}{-x_2 + x_3} \right\} \right\}$$

```

We need two additional equations for the system to be uniquely determined. At the lower end (first knot), we impose the third derivative equal to zero.

```
In[26]:= systemfirst = CoefficientArrays[{f1'''[x1] == 0}, {a1, a2, a3}];
```

```
In[27]:= systemfirst[[1]] // Normal
```

$$\text{Out[27]} = \left\{ -\frac{36 s_1}{(-x_1 + x_2)^2} - \frac{24 s_2}{(-x_1 + x_2)^2} - \frac{60 y_1}{(-x_1 + x_2)^3} + \frac{60 y_2}{(-x_1 + x_2)^3} \right\}$$

```
In[28]:= systemfirst[[2]] // Normal
```

$$\text{Out[28]} = \left\{ \left\{ -\frac{9}{-x_1 + x_2}, \frac{3}{-x_1 + x_2}, 0 \right\} \right\}$$

At the upper end (last knot), we estimate the second derivative directly using a two-points difference:

```
In[29]:= systemlast = CoefficientArrays[ $\left\{ f_1''[x_1] = \frac{s_3 - s_2}{x_3 - x_2} \right\}$ , {a1, a2, a3}];
```

```
In[30]:= systemlast[[1]] // Normal
```

$$\text{Out[30]} = \left\{ -\frac{s_2 + s_3}{-x_2 + x_3} \right\}$$

```
In[31]:= systemlast[[2]] // Normal
```

$$\text{Out[31]} = \{ \{1, 0, 0\} \}$$

Calculate explicit solution for testing purposes:

```
In[32]:= Simplify[Solve[ $\left\{ f_1'''[x_2] = f_2'''[x_2], f_1'''[x_1] = 0, f_2''[x_3] = \frac{s_3 - s_2}{x_3 - x_2} \right\}$ ,  
{a1, a2, a3}]] // InputForm
```

```
Out[32]/InputForm=
```

$$\begin{aligned} \{ \{ a_1 \rightarrow & (7 s_3 (x_1 - x_2)^3 (x_2 - x_3) + s_2 (x_1 - x_2) (x_2 - x_3) (13 x_1^2 + x_2^2 + 12 x_3^2 \\ & 2 x_1 (x_2 + 12 x_3)) + 4 (s_1 (x_1 - x_2) (9 x_1 - 2 x_2 - 7 x_3) (x_2 - x_3)^2 - \\ & 5 (3 x_2 x_3^2 (y_1 - y_2) + 2 x_3^3 (-y_1 + y_2) + 3 x_1 (x_3^2 (y_1 - y_2) + \\ & 2 x_2 x_3 (-y_1 + y_2) + x_2^2 (y_1 - y_3)) + x_1^3 (y_2 - y_3) + x_2^3 (-y_1 + y_3) + \\ & 3 x_1^2 x_2 (-y_2 + y_3))) / ((x_1 - x_2)^2 (9 x_1 - x_2 - 8 x_3) (x_2 - x_3)^2), \\ a_2 \rightarrow & (21 s_3 (x_1 - x_2)^3 (x_2 - x_3) + s_2 (x_1 - x_2) (x_2 - x_3) * \\ & (39 x_1^2 - 78 x_1 x_2 + 11 x_2^2 + 56 x_2 x_3 - 28 x_3^2) - \\ & 4 (3 s_1 (x_1 - x_2) (x_2 - x_3)^3 - 5 (-2 x_3^3 (y_1 - y_2) + \\ & x_2 (6 x_3^2 (y_1 - y_2) + 9 x_1^2 (y_2 - y_3)) + x_2^3 (2 y_1 + y_2 - 3 y_3) + \\ & 3 x_1^3 (-y_2 + y_3) + x_2^2 (-6 x_3 y_1 - 9 x_1 y_2 + 6 x_3 y_2 + 9 x_1 y_3))) / \\ & ((x_1 - x_2)^2 (9 x_1 - x_2 - 8 x_3) (x_2 - x_3)^2), a_3 \rightarrow (s_2 - s_3) / (x_2 - x_3) \} \} \end{aligned}$$

Constraint on the spline

The interpolation method requires certain conditions on the spline to get a nondecreasing quantile function. We search for a lower bound of the polynomial

$$f''(x_0 + x(x_1 - x_0)) + f'(x_0 + x(x_1 - x_0))(1 - f'(x_0 + x(x_1 - x_0))) \text{ over } [0, 1].$$

```
In[33]:= g = f''[x0 + x (x1 - x0)] + f'[x0 + x (x1 - x0)] (1 - f'[x0 + x (x1 - x0)]);
```

```
In[34]:= gcoefs = Simplify[CoefficientList[g, x]];
```

We rewrite the polynomial in its Bernstein form:

```
In[35]:= tobernstein[k_] :=
```

$$\text{Sum}[\text{Part}[gcoefs, r + 1] * \text{Binomial}[k, r] / \text{Binomial}[\text{Length}[gcoefs] - 1, r], \{r, 0, k\}]$$

```
In[36]:= bernsteincoefs = FullSimplify[Map[tobernstein, Range[0, Length[gcoefs] - 1]]];
```

Hence, we require all the following expressions to be non-negative:

In[37]:= **TableForm[bernsteincoefs]**

Out[37]//TableForm=

$$\begin{aligned}
 & a_0 + s_0 - s_0^2 \\
 & a_0 + s_0 - s_0^2 + \frac{(x_0 - x_1) (24 s_1 + 2 s_0 (18 + a_0 (x_0 - x_1)^2) + (x_0 - x_1) (3 a_1 + a_0 (-9 - x_0 + x_1))) + 60 (-y_0 + y_1)}{8 (x_0 - x_1)^2} \\
 & -480 (y_0 - y_1) + (x_0 - x_1) (16 s_0^2 (x_0 - x_1) - (a_0 (34 + 5 x_0 - 5 x_1) + 3 a_1 (-6 + x_0 - x_1) + 2 a_0^2 (x_0 - x_1)^2) (x_0 - x_1) + 24 s_1 (7 - x_0 + x_1) + 60 (y_0 - y_1)) \\
 & -300 (y_0 - y_1) + (x_0 - x_1) (96 s_0^2 (x_0 - x_1) + 4 s_1 (15 - 6 a_0 x_0^2 + x_1 (11 - 6 a_0 x_1) + x_0 (-11 + 12 a_0 x_1)) + 2 s_0 ((-18 a_0 + 5 a_1) x_0^2 + 2 x_0 (-5 + 2 a_1 x_0) \\
 & -100 a_0 x_0^2 + 100 a_1 x_0^2 - 20 a_0 x_0^3 + 20 a_1 x_0^3 + 9 a_0^2 x_0^4 - 26 a_0 a_1 x_0^4 + 9 a_1^2 x_0^4 + 576 s_0^2 (x_0 - x_1)^2 + 576 s_1^2 (x_0 - x_1)^2 - 200 a_0 x_0 x_1 - 200 a_1 x_0 x_1 \\
 & (x_0 - x_1) (96 s_1^2 (x_0 - x_1) + 4 s_0 (-15 + 6 a_1 x_0^2 + x_0 (-11 + 22 s_1 - 12 a_1 x_1) + x_1 (11 - 22 s_1 + 6 a_1 x_1)) - (x_0 - x_1) (a_0 (-1 + x_0 (-5 + 3 a_1 x_0) + 5 a_1 x_0) \\
 & 480 (y_0 - y_1) - (x_0 - x_1) ((34 a_1 + a_1 (-5 + 2 a_1 (x_0 - x_1)) (x_0 - x_1) - 3 a_0 (6 + x_0 - x_1)) (x_0 - x_1) + 16 s_1^2 (-x_0 + x_1) - 24 s_0 (-7 + (-1 + 2 s_1) x_0 + x_1) \\
 & - (x_0 - x_1) (24 s_0 + 8 s_1^2 (x_0 - x_1) - (3 a_0 + a_1 (-1 + x_0 - x_1)) (x_0 - x_1) + 2 s_1 (18 + a_1 x_0^2 - 2 x_0 (2 + a_1 x_1) + x_1 (4 + a_1 x_1))) + 60 (y_0 - y_1)) \\
 & 8 (x_0 - x_1)^2 \\
 & a_1 + s_1 - s_1^2
 \end{aligned}$$

In[38]:= **Map[InputForm[Simplify[D[#, a1]]] &, bernsteincoefs] // TableForm**

Out[38]//TableForm=

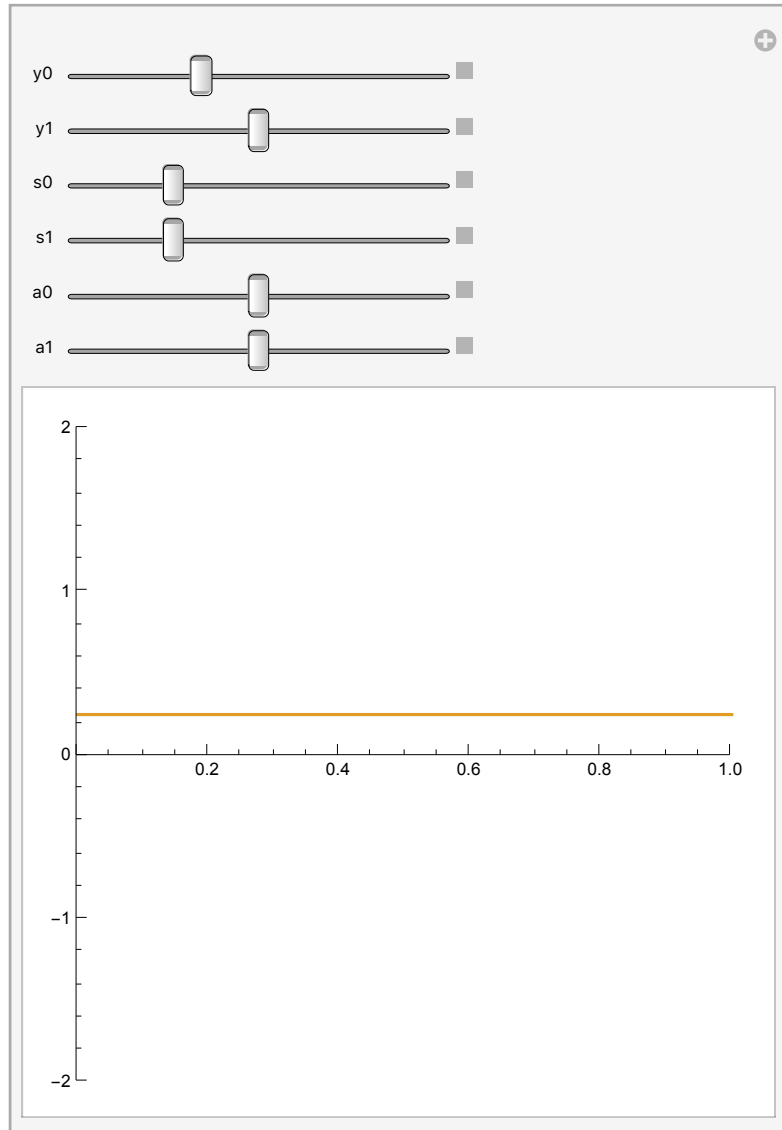
$$\begin{aligned}
 & 0 \\
 & 3 / 8 \\
 & (3 * (6 + (-1 + 2 * s_0) * x_0 + x_1 - 2 * s_0 * x_1)) / 56 \\
 & (1 - 3 * a_0 * x_0^2 + (5 - 10 * s_0) * x_1 - 3 * a_0 * x_1^2 + x_0 * (-5 + 10 * s_0 + 6 * a_0 * x_1)) / 56 \\
 & ((13 * a_0 - 9 * a_1) * x_0^2 + 2 * (5 + 44 * s_0 + 36 * s_1) * x_1 + (13 * a_0 - 9 * a_1) * x_1^2 - 2 * (35 + 3 * a_0 * x_0^2 + 6 * a_1 * x_0^2 + 24 * s_0 * (x_0 - x_1) + 36 * s_1 * (x_0 - x_1) + 6 * a_0 * x_0 * x_1 \\
 & (-34 - 4 * a_1 * x_0^2 + 5 * (-1 + 2 * s_1) * x_1 - 4 * a_1 * x_1^2 + x_0 * (5 - 10 * s_1 + 8 * a_1 * x_1) \\
 & (-1 + x_0 - 2 * s_1 * x_0 + (-1 + 2 * s_1) * x_1)) / 8 \\
 & 1
 \end{aligned}$$

In[39]:= $\phi[x_, x0_, x1_, y0_, y1_, s0_, s1_, a0_, a1_] = g;$

In[40]:= $\psi[x0_, x1_, y0_, y1_, s0_, s1_, a0_, a1_] = \text{Min}[\text{bernsteincoefs}];$

We can check the bound for different values of the parameters.

```
In[41]:= Manipulate[Plot[{ $\phi[x, 0, 1, y_0, y_1, s_0, s_1, a_0, a_1]$ ,  $\psi[0, 1, y_0, y_1, s_0, s_1, a_0, a_1]$ },
  {x, 0, 1}, PlotRange -> {{0, 1}, {-2, 2}}, AspectRatio -> 1],
  {{y0, 2}, 1, 4}, {{y1, 2.5}, 1, 4}, {{s0, 1/2}, 0, 2},
  {{s1, 1/2}, 0, 2}, {{a0, 0}, -10, 10}, {{a1, 0}, -10, 10}]
```



```
In[42]:= Map[InputForm[Simplify[#]] &, CoefficientList[g, x]] // TableForm
```

Out[42]/TableForm=

```
a0 + s0 - s0^2
a0 * (-9 + (-1 + 2 * s0) * x0 + x1 - 2 * s0 * x1) + (3 * (a1 * x0^2 + 12 * s0 * (x0 - x1) + 8 *
- (a0^2 * (x0 - x1)^2) - (9 * a0 * (-4 + (-1 + 2 * s0) * x0 + x1 - 2 * s0 * x1)) / 2 + (3 * (a1
9 * a0^2 * (x0 - x1)^2 - a0 * (10 + 3 * a1 * x0^2 - 6 * (1 + 4 * s0 + 4 * s1) * x1 + 3 * a1 * x1
- 15 * s0 - 294 * s0^2 - 15 * s1 - 402 * s0 * s1 - 144 * s1^2 + (5 * a0 * (x0 - x1)) / 2 + 221 *
1152 * s0^2 + 1776 * s0 * s1 + 672 * s1^2 + 240 * a1 * s0 * (x0 - x1) + 180 * a1 * s1 * (x0 - x
- 1564 * s0^2 - 2692 * s0 * s1 - 1144 * s1^2 + 609 * a0 * s0 * (x0 - x1) + 531 * a0 * s1 * (x0 -
10 * (96 * s0^2 + 180 * s0 * s1 + 84 * s1^2 + 28 * a1 * s0 * (x0 - x1) + 26 * a1 * s1 * (x0 - x1
(-25 * (6 * s0 * x0 + 6 * s1 * x0 - a0 * x0^2 + a1 * x0^2 - 6 * s0 * x1 - 6 * s1 * x1 + 2 * a0 * x0
```

Optimization problem to satisfy the constraint

In[43]:= A = Simplify[

Integrate[((f[x] /. {y0 → y0new, y1 → y1new, s0 → s0new, s1 → s1new, a0 → a0new,
a1 → a1new}) - f[x])^2, {x, x0, x1}]]

Out[43]= $-\frac{1}{27720}$

$$\begin{aligned} & (x_0 - x_1) \left(416 s_1^2 x_0^2 - 832 s_1 s_{1new} x_0^2 + 416 s_{1new}^2 x_0^2 + 52 a_0 s_1 x_0^3 - 52 a_{0new} s_1 x_0^3 + \right. \\ & 69 a_1 s_1 x_0^3 - 69 a_{1new} s_1 x_0^3 - 52 a_0 s_{1new} x_0^3 + 52 a_{0new} s_{1new} x_0^3 - 69 a_1 s_{1new} x_0^3 + \\ & 69 a_{1new} s_{1new} x_0^3 + 3 a_0^2 x_0^4 - 6 a_0 a_{0new} x_0^4 + 3 a_{0new}^2 x_0^4 + 5 a_0 a_1 x_0^4 - \\ & 5 a_{0new} a_1 x_0^4 + 3 a_1^2 x_0^4 - 5 a_0 a_{1new} x_0^4 + 5 a_{0new} a_{1new} x_0^4 - 6 a_1 a_{1new} x_0^4 + \\ & 3 a_{1new}^2 x_0^4 + 416 s_0^2 (x_0 - x_1)^2 + 416 s_{0new}^2 (x_0 - x_1)^2 - 832 s_1^2 x_0 x_1 + \\ & 1664 s_1 s_{1new} x_0 x_1 - 832 s_{1new}^2 x_0 x_1 - 156 a_0 s_1 x_0^2 x_1 + 156 a_{0new} s_1 x_0^2 x_1 - \\ & 207 a_1 s_1 x_0^2 x_1 + 207 a_{1new} s_1 x_0^2 x_1 + 156 a_0 s_{1new} x_0^2 x_1 - 156 a_{0new} s_{1new} x_0^2 x_1 + \\ & 207 a_1 s_{1new} x_0^2 x_1 - 207 a_{1new} s_{1new} x_0^2 x_1 - 12 a_0^2 x_0^3 x_1 + 24 a_0 a_{0new} x_0^3 x_1 - \\ & 12 a_{0new}^2 x_0^3 x_1 - 20 a_0 a_1 x_0^3 x_1 + 20 a_{0new} a_1 x_0^3 x_1 - 12 a_1^2 x_0^3 x_1 + \\ & 20 a_0 a_{1new} x_0^3 x_1 - 20 a_{0new} a_{1new} x_0^3 x_1 + 24 a_1 a_{1new} x_0^3 x_1 - 12 a_{1new}^2 x_0^3 x_1 + \\ & 416 s_1^2 x_1^2 - 832 s_1 s_{1new} x_1^2 + 416 s_{1new}^2 x_1^2 + 156 a_0 s_1 x_0 x_1^2 - 156 a_{0new} s_1 x_0 x_1^2 + \\ & 207 a_1 s_1 x_0 x_1^2 - 207 a_{1new} s_1 x_0 x_1^2 - 156 a_0 s_{1new} x_0 x_1^2 + 156 a_{0new} s_{1new} x_0 x_1^2 - \\ & 207 a_1 s_{1new} x_0 x_1^2 + 207 a_{1new} s_{1new} x_0 x_1^2 + 18 a_0^2 x_0^2 x_1^2 - 36 a_0 a_{0new} x_0^2 x_1^2 + \\ & 18 a_{0new}^2 x_0^2 x_1^2 + 30 a_0 a_1 x_0^2 x_1^2 - 30 a_{0new} a_1 x_0^2 x_1^2 + 18 a_1^2 x_0^2 x_1^2 - \\ & 30 a_0 a_{1new} x_0^2 x_1^2 + 30 a_{0new} a_{1new} x_0^2 x_1^2 - 36 a_1 a_{1new} x_0^2 x_1^2 + 18 a_{1new}^2 x_0^2 x_1^2 - \\ & 52 a_0 s_1 x_1^3 + 52 a_{0new} s_1 x_1^3 - 69 a_1 s_1 x_1^3 + 69 a_{1new} s_1 x_1^3 + 52 a_0 s_{1new} x_1^3 - \\ & 52 a_{0new} s_{1new} x_1^3 + 69 a_1 s_{1new} x_1^3 - 69 a_{1new} s_{1new} x_1^3 - 12 a_0^2 x_0 x_1^3 + \\ & 24 a_0 a_{0new} x_0 x_1^3 - 12 a_{0new}^2 x_0 x_1^3 - 20 a_0 a_1 x_0 x_1^3 + 20 a_{0new} a_1 x_0 x_1^3 - \\ & 12 a_1^2 x_0 x_1^3 + 20 a_0 a_{1new} x_0 x_1^3 - 20 a_{0new} a_{1new} x_0 x_1^3 + 24 a_1 a_{1new} x_0 x_1^3 - \\ & 12 a_{1new}^2 x_0 x_1^3 + 3 a_0^2 x_1^4 - 6 a_0 a_{0new} x_1^4 + 3 a_{0new}^2 x_1^4 + 5 a_0 a_1 x_1^4 - \\ & 5 a_{0new} a_1 x_1^4 + 3 a_1^2 x_1^4 - 5 a_0 a_{1new} x_1^4 + 5 a_{0new} a_{1new} x_1^4 - 6 a_1 a_{1new} x_1^4 + \\ & 3 a_{1new}^2 x_1^4 + 1812 s_1 x_0 y_0 - 1812 s_{1new} x_0 y_0 + 281 a_0 x_0^2 y_0 - 281 a_{0new} x_0^2 y_0 + \\ & 181 a_1 x_0^2 y_0 - 181 a_{1new} x_0^2 y_0 - 1812 s_1 x_1 y_0 + 1812 s_{1new} x_1 y_0 - 562 a_0 x_0 x_1 y_0 + \\ & 562 a_{0new} x_0 x_1 y_0 - 362 a_1 x_0 x_1 y_0 + 362 a_{1new} x_0 x_1 y_0 + 281 a_0 x_1^2 y_0 - \\ & 281 a_{0new} x_1^2 y_0 + 181 a_1 x_1^2 y_0 - 181 a_{1new} x_1^2 y_0 + 10860 y_0^2 - 1812 s_1 x_0 y_{0new} + \\ & 1812 s_{1new} x_0 y_{0new} - 281 a_0 x_0^2 y_{0new} + 281 a_{0new} x_0^2 y_{0new} - 181 a_1 x_0^2 y_{0new} + \\ & 181 a_{1new} x_0^2 y_{0new} + 1812 s_1 x_1 y_{0new} - 1812 s_{1new} x_1 y_{0new} + 562 a_0 x_0 x_1 y_{0new} - \\ & 562 a_{0new} x_0 x_1 y_{0new} + 362 a_1 x_0 x_1 y_{0new} - 362 a_{1new} x_0 x_1 y_{0new} - \\ & 281 a_0 x_1^2 y_{0new} + 281 a_{0new} x_1^2 y_{0new} - 181 a_1 x_1^2 y_{0new} + 181 a_{1new} x_1^2 y_{0new} - \\ & 21720 y_0 y_{0new} + 10860 y_{0new}^2 + 3732 s_1 x_0 y_1 - 3732 s_{1new} x_0 y_1 + 181 a_0 x_0^2 y_1 - \\ & 181 a_{0new} x_0^2 y_1 + 281 a_1 x_0^2 y_1 - 281 a_{1new} x_0^2 y_1 - 3732 s_1 x_1 y_1 + 3732 s_{1new} x_1 y_1 - \\ & 362 a_0 x_0 x_1 y_1 + 362 a_{0new} x_0 x_1 y_1 - 562 a_1 x_0 x_1 y_1 + 562 a_{1new} x_0 x_1 y_1 + \\ & 181 a_0 x_1^2 y_1 - 181 a_{0new} x_1^2 y_1 + 281 a_1 x_1^2 y_1 - 281 a_{1new} x_1^2 y_1 + 6000 y_0 y_1 - \\ & 6000 y_{0new} y_1 + 10860 y_1^2 + s_{0new} (x_0 - x_1) \left(69 a_0 x_0^2 - 69 a_{0new} x_0^2 + 52 a_1 x_0^2 - \right. \\ & 52 a_{1new} x_0^2 + 532 s_1 (x_0 - x_1) - 532 s_{1new} (x_0 - x_1) - 138 a_0 x_0 x_1 + \\ & 138 a_{0new} x_0 x_1 - 104 a_1 x_0 x_1 + 104 a_{1new} x_0 x_1 + 69 a_0 x_1^2 - 69 a_{0new} x_1^2 + \\ & 52 a_1 x_1^2 - 52 a_{1new} x_1^2 + 3732 y_0 - 3732 y_{0new} + 1812 y_1 - 1812 y_{1new} \left. \right) - \\ & s_0 (x_0 - x_1) \left(-532 s_{1new} x_0 + 69 a_0 x_0^2 - 69 a_{0new} x_0^2 + 52 a_1 x_0^2 - 52 a_{1new} x_0^2 + \right. \\ & 832 s_{0new} (x_0 - x_1) + 532 s_1 (x_0 - x_1) + 532 s_{1new} x_1 - 138 a_0 x_0 x_1 + \end{aligned}$$

$$\begin{aligned}
& 138 a_{0\text{new}} x_0 x_1 - 104 a_1 x_0 x_1 + 104 a_{1\text{new}} x_0 x_1 + 69 a_0 x_1^2 - 69 a_{0\text{new}} x_1^2 + \\
& 52 a_1 x_1^2 - 52 a_{1\text{new}} x_1^2 + 3732 y_0 - 3732 y_{0\text{new}} + 1812 y_1 - 1812 y_{1\text{new}} \Big) - \\
& 3732 s_1 x_0 y_{1\text{new}} + 3732 s_{1\text{new}} x_0 y_{1\text{new}} - 181 a_0 x_0^2 y_{1\text{new}} + 181 a_{0\text{new}} x_0^2 y_{1\text{new}} - \\
& 281 a_1 x_0^2 y_{1\text{new}} + 281 a_{1\text{new}} x_0^2 y_{1\text{new}} + 3732 s_1 x_1 y_{1\text{new}} - \\
& 3732 s_{1\text{new}} x_1 y_{1\text{new}} + 362 a_0 x_0 x_1 y_{1\text{new}} - 362 a_{0\text{new}} x_0 x_1 y_{1\text{new}} + \\
& 562 a_1 x_0 x_1 y_{1\text{new}} - 562 a_{1\text{new}} x_0 x_1 y_{1\text{new}} - 181 a_0 x_1^2 y_{1\text{new}} + \\
& 181 a_{0\text{new}} x_1^2 y_{1\text{new}} - 281 a_1 x_1^2 y_{1\text{new}} + 281 a_{1\text{new}} x_1^2 y_{1\text{new}} - \\
& 6000 y_0 y_{1\text{new}} + 6000 y_{0\text{new}} y_{1\text{new}} - 21720 y_1 y_{1\text{new}} + 10860 y_{1\text{new}}^2 \Big)
\end{aligned}$$