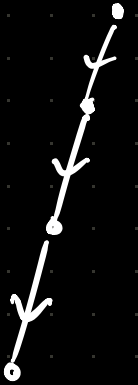
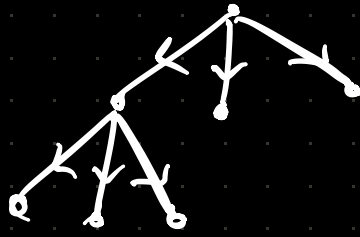


# Breadth-First Search (BFS)

DFS



BFS



The search tree is built **level-by-level** starting from the root.

Expand the vertex:

evaluating all the neighbors of the vertex at once.

This ACTION is called "expanding the vertex."

Tree Edges:

(visited, non-visited)

Non-Tree Edges:

(visited, visited)

\* Since the vertices are explored **level-by-level**, this is a **LEVEL-ORDERED TRAVERSAL**, and a **queue** is the datastructure used to store the neighbors of each vertex.

\* **QUEUE** contains the vertices at a particular level.

$u \rightarrow u.\text{color} : \{\text{white, Gray, Black}\}$   
 $u.d : \text{'distance' from root.}$

'No. of edges' from  $s$  to  $u$   
in BFS Tree.

(level no.) Root-level = 0 //

BFS ( $G, s$ )

① For each  $u \in V - \{s\}$

$u.\text{color} = \text{White};$

$u.d = \infty;$

$u.p = \text{NULL};$

②  $s.\text{color} = \text{Gray};$

$s.d = 0;$

$s.p = \text{NULL};$

③ Enqueue ( $Q, s$ ) { insert the start vertex  
 $s$  in  $Q$  }

while ( $Q \neq \emptyset$ )

$u = \text{Dequeue}(Q)$

For each  $v \in \text{Adj}(u)$

if ( $v.\text{color} == \text{White}$ )

$v.\text{color} = \text{Gray}$

$v.d = v.d + 1$

$v.p = u$

Enqueue ( $Q, v$ )

$u.\text{color} = \text{Black}$

\* The  $p$  attribute in each vertex will form the BFS Tree.



$\Rightarrow u = p.v$   
 $u$  is the parent of  $v$  in the BFS Tree