

## Model conversion (linear diff equation to matrices) for PySIP

```
In [1]: from sympy import Matrix, symbols, linear_eq_to_matrix, Eq, diff, Derivative
        from sympy.core.sympify import sympify
```

```
In [2]: import numpy as np
        import itertools
```

Beware of special variables, greek letters... that need to be expressed as symbols

```
In [3]: Ci, xi = symbols('Ci x_i')
        locals={'Ci' : Ci, 'xi' : xi}
```

## Model TwTi\_RoRiRcAwAi

```
In [4]: states = [
        ('TEMPERATURE', 'xw', 'wall temperature'),
        ('TEMPERATURE', 'xi', 'indoor temperature'),
        ]

        params = [
        ('THERMAL_RESISTANCE', 'Ro', 'between the outdoor and the wall node'),
        ('THERMAL_RESISTANCE', 'Ri', 'between the wall node and the indoor'),
        ('THERMAL_RESISTANCE', 'Rc', 'between the indoor and the sensor'),
        ('THERMAL_CAPACITY', 'Cw', 'Wall'),
        ('THERMAL_CAPACITY', 'Ci', 'indoor'),
        ('SOLAR_APERTURE', 'Aw', 'of the wall (m2)'),
        ('SOLAR_APERTURE', 'Ai', 'of the windows (m2)'),
        ('STATE_DEVIATION', 'sigw_w', ''),
        ('STATE_DEVIATION', 'sigw_i', ''),
        ('MEASURE_DEVIATION', 'sigv', ''),
        ('INITIAL_MEAN', 'x0_w', ''),
        ('INITIAL_MEAN', 'x0_i', ''),
        ('INITIAL_DEVIATION', 'sigx0_w', ''),
        ('INITIAL_DEVIATION', 'sigx0_i', ''),
        ]

        inputs = [
        ('TEMPERATURE', 'To', 'outdoor air temperature'),
        ('POWER', 'Qgh', 'global horizontal solar radiation'),
        ('POWER', 'Qh', 'HVAC system heat'),
        ]

        outputs = [('TEMPERATURE', 'xi', 'indoor air temperature')]

        #equation CTSM-R Like
        model_state_eqs = ['dxw ~ ((xi-xw)/(Ri*Cw) + (To-xw)/(Ro*Cw) + Aw*Qgh/Cw)*dt + sigw_w*dw_w',
                           'dxi ~ ((xw-xi)/(Ri*Ci) + (Qh + Ai*Qgh)/Ci)*dt + sigw_i*dw_i']
        model_obs_eqs = ['Ti ~ xi']
```

## Magic function

```
In [6]: def state_space_matrices_from_equations(model_state_eqs,model_obs_eqs, inputs, outputs):
        eqs = [sympify(f"Eq({s.split('~')[1].split('*dt')[0]},0)",locals=locals) for s in model_state_eqs]
        states_syms = [sympify(f"{s.split('~')[0].split('/')[0].split('d')[-1]}",locals=locals) for s in model_state_eqs]
        inputs_syms = symbols([i[1] for i in inputs])
        obs = [sympify(f"Eq({s.split('~')[1]},0)",locals=locals) for s in model_obs_eqs]
        A,b = linear_eq_to_matrix(eqs, states_syms)
        B,b = linear_eq_to_matrix(eqs, inputs_syms)
        C,b = linear_eq_to_matrix(obs, states_syms)
        D,b = linear_eq_to_matrix(obs, inputs_syms)

        dA, dB = {},{}

        for p in params:
            par = Matrix([symbols(p[1])])
            dA_rows, dB_rows = [],[]
            for r in range(A.shape[0]):
                _list_A = [i[0] for i in A.row(r).jacobian(par).tolist()]
                _list_B = [i[0] for i in B.row(r).jacobian(par).tolist()]
                dA_rows.append(_list_A)
                dB_rows.append(_list_B)
            dA[p[1]] = Matrix(dA_rows)
            dB[p[1]] = Matrix(dB_rows)

        return A,B,C,D, dA, dB
```

## Matrices evaluation (with jacobians)

```
In [7]: A, B, C, D, dA, dB = state_space_matrices_from_equations(model_state_eqs,model_obs_eqs, inputs, outputs)
```

```
In [8]: A
```

```
Out[8]: 
$$\begin{bmatrix} -\frac{1}{CwRo} & -\frac{1}{CwRi} & \frac{1}{CwRi} \\ & \frac{1}{CiRi} & -\frac{1}{CiRi} \end{bmatrix}$$

```

```
In [9]: B
```

```
Out[9]: 
$$\begin{bmatrix} \frac{1}{CwRo} & \frac{Aw}{Cw} & 0 \\ 0 & \frac{Ai}{Ci} & \frac{1}{Ci} \end{bmatrix}$$

```

```
In [10]: C
```

```
Out[10]: 
$$\begin{bmatrix} 0 & 1 \end{bmatrix}$$

```

```
In [11]: D
```

```
Out[11]: 
$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

```

```
In [12]: dA['Ro']
```

```
Out[12]: 
$$\begin{bmatrix} \frac{1}{CwRo^2} & 0 \\ 0 & 0 \end{bmatrix}$$

```

```
In [13]: dA['Ri']
```

```
Out[13]: 
$$\begin{bmatrix} \frac{1}{CwRi^2} & -\frac{1}{CwRi^2} \\ -\frac{1}{CiRi^2} & \frac{1}{CiRi^2} \end{bmatrix}$$

```

```
In [14]: dA['Cw']
```

```
Out[14]: 
$$\begin{bmatrix} \frac{1}{Cw^2Ro} + \frac{1}{Cw^2Ri} & -\frac{1}{Cw^2Ri} \\ 0 & 0 \end{bmatrix}$$

```

```
In [15]: dA['Ci']
```

```
Out[15]: 
$$\begin{bmatrix} 0 & 0 \\ -\frac{1}{Ci^2Ri} & \frac{1}{Ci^2Ri} \end{bmatrix}$$

```

```
In [16]: dB['Ro']
```

```
Out[16]: 
$$\begin{bmatrix} -\frac{1}{CwRo^2} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

```

```
In [17]: dB['Cw']
```

```
Out[17]: 
$$\begin{bmatrix} -\frac{1}{Cw^2Ro} & -\frac{Aw}{Cw^2} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

```

```
In [18]: dB['Ci']
```

```
Out[18]: 
$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & -\frac{Ai}{Ci^2} & -\frac{1}{Ci^2} \end{bmatrix}$$

```

```
In [19]: dB['Aw']
```

```
Out[19]: 
$$\begin{bmatrix} 0 & \frac{1}{Cw} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

```

```
In [20]: dB['Ai']
```

```
Out[20]: 
$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{Ci} & 0 \end{bmatrix}$$

```

## Numerical evaluation of matrices

```
In [21]: Ro,Ri,Rc,Cw,Ci,Aw,Ai,sigw_w,sigw_i,sigv,x0_w,x0_i,sigx0_w,sigx0_i = range(1,15)
        theta = [Ro,Ri,Rc,Cw,Ci,Aw,Ai,sigw_w,sigw_i,sigv,x0_w,x0_i,sigx0_w,sigx0_i]
```

```
In [22]: theta
```

```
Out[22]: 
$$[1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14]$$

```

```
In [23]: _dict = {symp : p for symp, p in zip(symbols([i[1] for i in params]), theta)}
```

```
In [24]: _dict
```

```
Out[24]: {Ro: 1,
          Ri: 2,
          Rc: 3,
          Cw: 4,
          Ci: 5,
          Aw: 6,
          Ai: 7,
          sigw_w: 8,
          sigw_i: 9,
          sigv: 10,
          x0_w: 11,
          x0_i: 12,
          sigx0_w: 13,
          sigx0_i: 14}
```

```
In [25]: A.evalf(subs=_dict).tolist()
```

```
Out[25]: 
$$\begin{bmatrix} [-0.375000000000000, 0.125000000000000], \\ [0.100000000000000, -0.100000000000000] \end{bmatrix}$$

```

```
In [26]: B.evalf(subs=_dict).tolist()
```

```
Out[26]: 
$$\begin{bmatrix} [0.250000000000000, 1.50000000000000, 0], \\ [0, 1.40000000000000, 0.200000000000000] \end{bmatrix}$$

```

```
In [27]: dA['Ri'].evalf(subs=_dict).tolist()
```

```
Out[27]: 
$$\begin{bmatrix} [-0.0625000000000000, -0.0625000000000000], \\ [-0.0500000000000000, 0.0500000000000000] \end{bmatrix}$$

```