

Multidimensional arrays

Goldsmiths Computing

Motivation

Sometimes the data that you want to store is naturally expressed as a table with more than one dimension.

Definition

A multidimensional array is an array that is subscripted using more than one index

NB: the “multidimensional” in multidimensional arrays refers to the subscripting, **not** the data that is stored:

linear array of 3-component colours Vector

linear array of 3-dimensional vectors Vector

2d array of grayscale values Multidimensional array

3d array of temperature values Multidimensional array

Operations

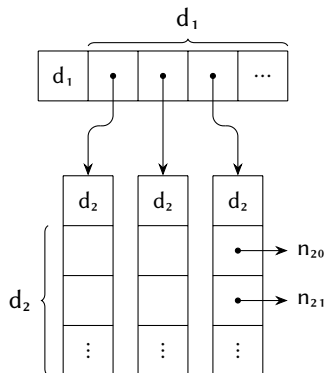
size return the number of elements in the multidimensional array

select[k,m,...,n] return the element at position k in the first dimension, m in the second, ..., and n in the last dimension

store![o,k,m,...,n] set the element at position k in the first dimension, m in the second, ..., and n in the last dimension to o.

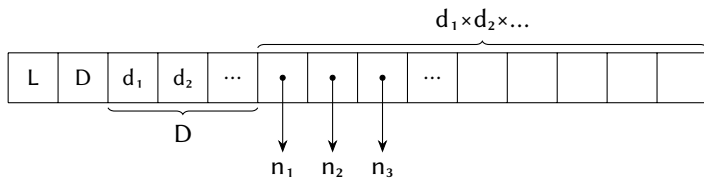
Implementation: Iliffe vector

Array of references to lower-dimensional arrays:



Implementation: dope vector

One-dimensional array with extra metadata (the “dope” on the array):



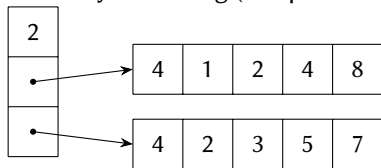
Implementation: example

Storing the 2×4 matrix

$$\begin{pmatrix} 1 & 2 & 4 & 8 \\ 2 & 3 & 5 & 7 \end{pmatrix}$$

Iliffe vector

Row-major ordering (compare earlier Iliffe vector diagram)



Implementation: example

Storing the 2×4 matrix

$$\begin{pmatrix} 1 & 2 & 4 & 8 \\ 2 & 3 & 5 & 7 \end{pmatrix}$$

dope vector

Row-major ordering

11	2	2	4	1	2	4	8	2	3	5	7
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Implementation: example

Storing the 2×4 matrix

$$\begin{pmatrix} 1 & 2 & 4 & 8 \\ 2 & 3 & 5 & 7 \end{pmatrix}$$

dope vector

Column-major ordering

11	2	2	4	1	2	2	3	4	5	8	7
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Size

Illife vector

Require: A :: two-dimensional (Illife) array

```
function SIZE( $A$ )  
    return LENGTH( $A$ ) × LENGTH( $A[0]$ )  
end function
```

dope vector

Require: A :: multidimensional (dope) array

```
function SIZE( $A$ )  
     $D \leftarrow A[0]$   
     $\text{result} \leftarrow 1$   
    for  $0 \leq d < D$  do  
         $\text{result} \leftarrow \text{result} \times A[1+d]$   
    end for  
    return  $\text{result}$   
end function
```

Select

Iliffe vector

Require: A :: multidimensional (Iliffe) array

Require: ks :: list of indices

function SELECT(A,ks)

if LENGTH(ks) = 1 **then**

return A[FIRST(ks)]

else

return SELECT(A[FIRST(ks)],REST(ks))

end if

end function

Select

dope vector

Require: A :: multidimensional row-major (dope) array

Require: ks :: tuple of indices

```
function SELECT( $A, ks$ )  
   $D \leftarrow A[0]$   
   $index \leftarrow 0$   
  for  $0 \leq d < D$  do  
     $index \leftarrow index \times A[1+d] + ks[d]$   
  end for  
  return  $A[1+D+index]$   
end function
```

Complexity analysis

time

Operations take time proportional to the number of dimensions D , but independent of the size of each dimension. For given D , all operations (size, select, store!) take time in $\Theta(1)$.

space

liffe vector space overhead proportional to the size of each dimension (worst case, space overhead in $\Theta(N)$)

dope vector space overhead proportional to the number of dimensions (for a given dimension, space overhead in $\Theta(1)$)

Multidimensional array (with dope vector) is an example of an implicit data structure