

# MTRN4230: ROBOTICS

Assignment 3

# **Supporting Documentation**

# Group 6

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# Project Gantt Chart

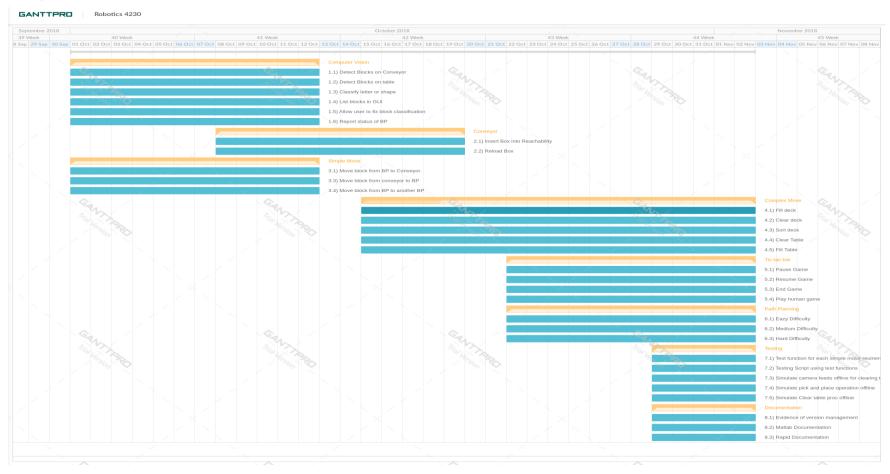


Figure 1: Gantt Chart for Assignment 3

# **Meeting Minutes**

# 10/10/18

Today the team discussed and delegated roles. Brief summary of roles:

# **TASKS WK10-12**

Leo Wong & Omar Idrees:

- Redesign GUI
- Computer vision 1.5,1.6

Justin Williams & Richard Park:

- upload images from today to github
- Computer vision (except 1.5,1.6)

Weber Ting & Prateek Rai:

- Conveyor
- Simple Move
- record weekly meetings minutes
- create Gantt chart

# **TASKS WK 12-15**

Leo Wong & Omar Idrees:

- tic-tac-toe GUI
- tic-tac-toe Al

Justin Williams & Richard Park:

• Path planning

Weber Ting & Prateek Rai:

- Complex Move
- Testing
- Documentation

# <u>17/10/18:</u>

# Omar & Leo:

• GUI (Framework completed)

### Weber & Prateek:

• Simple Move( Completed) and Gantt Chart(Completed)

### Justin & Richard:

Camera Calibration (Completed) and Converted Camera coordinate frame to world coordinate frame

# **Project Completion(17/10/18):**

TASK	COMPLETION PERCENTAGE
COMPUTER VISION	0%
CONVEYOR	0%
SIMPLE MOVE	100%
COMPLEX MOVE	0%
TIC TAC TOE	0%
PATH PLANNING	0%
TESTING	0%
DOCUMENTATION	0%

# 24/10/18:

#### Leo:

- Finished Fill Deck, Clear Deck and sort Deck
- Working on clear table and fill table

#### Omar:

- Finished Tic Tac Toe GUI
- Working on Tic Tac Toe PvP AI

### Justin and Richard:

• Fixing previous code for block detection

### Prateek:

• Simulating Robot block pick up

#### Weber:

Working on path planning

# Project Completion(24/10/18):

COMPUTER VISION	30%
CONVEYOR	0%
SIMPLE MOVE	100%
COMPLEX MOVE	60%

**COMPLETION PERCENTAGE** 

CONVEYOR	0%
SIMPLE MOVE	100%
COMPLEX MOVE	60%
TIC TAC TOE	20%
PATH PLANNING	0%
TESTING	0%
DOCUMENTATION	0%

## 31/10/18:

TASK

#### Leo:

• Finished clear table and fill table

#### Omar:

- Finished PvP AI
- Working on AI vs player

#### Weber:

- Finished easy and medium path planning and tested it
- Working on Hard path planning

## Prateek:

- Finished block pick up sim and clear table sim
- Working on camera feed sim and testing functions

#### Justin and Richard:

• Fixed code for block detection, completed conveyor block detection, detecting blocks on table and classification of blocks

# **Project Completion(31/10/18):**

TASK	COMPLETION PERCENTAGE
COMPUTER VISION	50%
CONVEYOR	100%
SIMPLE MOVE	100%
COMPLEX MOVE	100%
TIC TAC TOE	50%
PATH PLANNING	66%
TESTING	40%
DOCUMENTATION	0%

# <u>7/11/18</u>:

#### Leo:

- Finished testing complex move
- Will be assisting other team members

#### Omar:

• Finishing off tic tac toe Ai vs player with Weber

#### Weber:

• Finished hard path and tested all of path planning

### Prateek:

- finished sim for camera feeds and testing functions
- working on testing script and documentation

#### Justin and Richard:

- Finished computer vision
- working on improving detection and classification

# **Project Completion(7/11/18):**

TASK	COMPLETION PERCENTAGE
COMPUTER VISION	90%
CONVEYOR	100%
SIMPLE MOVE	100%
COMPLEX MOVE	100%
TIC TAC TOE	70%
PATH PLANNING	100%
TESTING	60%
DOCUMENTATION	0%

# Version Management:

Version management for the code and other files was done using Git Hub. Below is a small snippet of the version changes that took place in this project. Please note that this is only a small fraction version changes done by group members to provide evidence of version management and hence, does not contain some group members' names.

Graph	Description	Date	Author	Commit
•	🔰 origin/master 🔰 origin/HEAD Add files via upload	13 Nov 2018 19:37	RyokuH <4222805	04f498e
÷	ho	13 Nov 2018 19:23	omar-al-ouf <oma< td=""><td>ba08c3d</td></oma<>	ba08c3d
	Merge branch 'master' of https://github.com/loewang/MTRN4230-robotics	13 Nov 2018 18:55	omar-al-ouf <oma< td=""><td>1fe7431</td></oma<>	1fe7431
† I	update	13 Nov 2018 18:55	omar-al-ouf <oma< td=""><td>050e222</td></oma<>	050e222
†	Add files via upload	13 Nov 2018 18:48	wnsdud360 <wnsd< td=""><td>086cf3f</td></wnsd<>	086cf3f
•	Update Ass3GUI/RemoveBlockConveyor.m	13 Nov 2018 18:28	Leo <c1yhw@hotn< td=""><td>5ee4632</td></c1yhw@hotn<>	5ee4632
K	Merge branch 'master' of https://github.com/loewang/MTRN4230-robotics	13 Nov 2018 17:45	Leo <c1yhw@hotn< td=""><td>e46604f</td></c1yhw@hotn<>	e46604f
† I	update	13 Nov 2018 17:45	Leo <c1yhw@hotn< td=""><td>ed4f0db</td></c1yhw@hotn<>	ed4f0db
•	Add files via upload	13 Nov 2018 17:27	wnsdud360 <wnsd< td=""><td>c1d7275</td></wnsd<>	c1d7275
l <del>†</del>	Update tableDetect.m	13 Nov 2018 17:08	wnsdud360 <wnsd< td=""><td>8a18d1f</td></wnsd<>	8a18d1f
l <del>†</del>	Add files via upload	13 Nov 2018 17:06	wnsdud360 <wnsd< td=""><td>19845b9</td></wnsd<>	19845b9
l <del>†</del>	Add files via upload	13 Nov 2018 16:51	juustinw <4328971	7ba4057
l <del>†</del>	Add files via upload	13 Nov 2018 15:52	RyokuH <4222805	b929d39
l†	Add files via upload	13 Nov 2018 15:30	juustinw <4328971	324b077
	Add files via upload	13 Nov 2018 0:29	juustinw <4328971	408a971
•	Add files via upload	13 Nov 2018 0:26	juustinw <4328971	acfb406
†	Add files via upload	13 Nov 2018 0:25	juustinw <4328971	5f046bf
†	update	12 Nov 2018 22:36	Leo <c1yhw@hotn< td=""><td>147214e</td></c1yhw@hotn<>	147214e
†	Add files via upload	12 Nov 2018 20:21	juustinw <4328971	05f746c
†	Add files via upload	12 Nov 2018 13:17	wnsdud360 <wnsd< td=""><td>686295a</td></wnsd<>	686295a
†	Create test	12 Nov 2018 13:16	wnsdud360 <wnsd< td=""><td>55f549c</td></wnsd<>	55f549c
†	Update Ass3GUI/cameraConveyorParams.mat	12 Nov 2018 11:43	Leo <c1yhw@hotn< td=""><td>252e572</td></c1yhw@hotn<>	252e572
•	Added Help functions	12 Nov 2018 11:15	prateekrai4 <3248.	21a3814

Figure 2: SourceTree of the GitHub repository showing implementation and use of version management