Math 5600

5/19/13 5/22/14

Recall fixed point iteration

 $X_{k+1} = g(X_k)$ 

Xo given

where  $f(x) = 0 \implies x = g(x)$ 

root fixed point

suppose the nort (or fixed point) is &

we saw that, with suitable smoothness assumptions, and  $e_k = \frac{1}{k} - \frac{1}{k}$ 

 $e_{k+1} = x_{k+1} - d = \frac{g(P)_{(a)}}{P!} e_k^P + HOT$ 

g(d)=d, g(d)=...=g(P-1)(d) =0 g(P)(d) + 0

- P is the order of the method

- The iteration will converge to & if we start sufficiently close to & and P7/ or P=1 and/g(d)/<1.

- we also saw a way of getting methods with arbitrarily large p by inverse interrebelies. - That approach requires that we know derivatives of F.

- They may not be available, and it may be unrecessenable to because to provide them.

- There are other ways to construct higher order methods.

- Aithen Acceleration (or Extrapolation)

we know that

lim 
$$\frac{d-x_{n+1}}{d-x_n} = \lim_{n \to 0} \frac{g(x)-g(x_n)}{d-x_n} = g(d)$$

for a convergent iteration.

- suppose g'(d) #0 |g'(d) | < 1

can we compute, or approximate, g'(d) and use our approximation to get a better sequence?

Let:

$$\lambda_{n} = \frac{x_{n} - x_{n-1}}{x_{n-1} - x_{n-2}} = \frac{g(x_{n-1}) - g(x_{n-2})}{x_{n-1} - x_{n-2}} \longrightarrow g(x)$$
since  $x_{n} \to x_{n-2}$ 

we can use In to improve convergence

(\*)

$$\lambda_n \propto g'(\alpha) \approx \frac{g(\alpha) - g(x_{n-1})}{\alpha - x_{n-1}} = \frac{\alpha - x_n}{\alpha - x_{n-1}}$$

Solving (\*) for a gives

$$\alpha \times \frac{x_{n} - \lambda_{n} \times_{n-1}}{1 - \lambda_{n}} = x_{n} + \frac{\lambda_{n}}{1 - \lambda_{n}} (x_{n} - x_{n-1})$$

- This suggests to define

$$X_{n} = X_{n} + \frac{\lambda_{n}}{1 - \lambda_{n}} (X_{n} - X_{n-1}) \tag{*}$$

We can use this formula to convert a linearly convergent sequence

×o, ×, ,×z,...

vith the scene limit

(\*) can be rewritten using 2 = xu-1-xu-> ×n - ×n-1  $X^{N} = X^{N} + \frac{X^{N-1} - X^{N-2}}{X^{N-1}}$  $(x_n - x_{n-1})$  $1-\frac{\times_{N}-\times_{N-1}}{\times_{N-1}-\times_{N-2}}$ (xu - xu-1) (xn-xn-1)-(xn-1-xn-2)  $= \times_{N} - \frac{(\Delta \times_{N})^{2}}{\Delta^{2} \times_{N}}$  $\Delta x_n = x_n - x_{n-1}$ 1 x = 1 x - 1 x 1 -1 - Because of this last form (\*) is also called Aitheus Deprecess of course, to use the method as described we have to have theat linewly convergent sequence X01 ×1, ×2:1--- ve can also de the conversion on the fly, however. - we compute  $x_n$  and then start fresh from there.

- writing 
$$Z_n = x_{n-2}$$
  
 $g(z_n) = x_{n-1}$   
 $g(g(z_n)) = x_n$   
 $z_{n+1} = x_n$ 

we get
$$z_{n+1} = g(g(z_{n})) - \frac{(g(g(z_{n})) - g(z_{n}))^{2}}{g(g(z_{n})) - 2g(z_{n}) + 2n}$$

- This method converges of order 2 (exercise)

how do we know when to stop?

we want to stop when  $1 \times_{\mu} - 2/2 \in$ for some user specified  $\varepsilon$  (like 10 m or 10 see) in term project.

$$\times_{n} - d \approx \lambda_{n} (\times_{n-1} - d)$$

$$= \lambda_{n} (\times_{n-1} - \times_{n} + \times_{n} - d)$$

$$(1-\lambda_n)(x_{n-d}) \approx \lambda_n(x_{n-1}-x_n)$$

- so stop when

$$\left| \times_{n} - d \right| \approx \left| \frac{\lambda_{n}}{1 - \lambda_{n}} \left( \times_{n-1} - \times_{n} \right) \right| \leq \varepsilon$$

- simplify 
$$\lambda_n = \frac{x_n - x_{n-1}}{x_{n-1} - x_{n-2}}$$

$$|x_{n}-x|^{2}$$
 $\frac{|x_{n}-x_{n-1}|}{|x_{n-1}-x_{n-2}|}$ 
 $(x_{n-1}-x_{n})$ 

$$= \left| \frac{\left( \times_{n} - \times_{n-1} \right)^{2}}{\times_{n} - 2 \times_{n,1} + \times_{n-2}} \right| < \varepsilon$$

- suppose the iteration converges of order P>1 - Then stop when 1×n-xn-,1 2 &

7)

- ue aun motivate tuis as follows:

$$e_{n-1} = x_{n-1} - d$$

$$= x_{n-1} - x_n + x_n - d$$

$$= x_{n-1} - x_n + C e_{n-1}^{p}$$

$$\stackrel{\text{Very small relative}}{\longrightarrow} t_0 e_{n-1}, ignore.$$

- | 50 | en-1/2 /xn-1-xn1

- our actual evrer is en which issmalle

- Query

$$e_n = x_n - d$$
  
=  $x_n - x_{n-1} + x_{n-1} - d$   
=  $x_n - x_{n-1} + \sqrt{e_n}$ 

$$e_{n-1} = x_{n-1} - \lambda$$

$$= x_{n-1} - x_n + x_n - \lambda$$

$$= x_{n-1} - x_n + e_{n-1}$$

$$= x_{n-1} - x_n + e_{n-1}$$
Tignore readily to en

Owny: consider the iterations

$$x_{u+1} = \sin x_u \qquad x_0 = 1$$

what does our theory cell us? what will actuelly happen

- Newton's Method applied to polynoming

- we need to evaluate p(xu) orde p(xu)

- Let me illustrate the ideas first with an example.

Suppose  $p(x) = 2x^3 - 3x^2 + x - \mu$ 

P(2) = 2.8 - 3.4 + 2 - 4 = 2

easier p(x) = ((2x-3)x+1)x-4

D-can be written like this:

2 -3 1 -4

=2 4 2

2 1 3 (2)

· Et 10

2 5 13

 $-|P'(x)| = 6x^2 - 6x + 1 \qquad P'(2) = 24 - 12 + 1 = 13$ 

coincidence!

not at all

Nested Multiplication Synthetic Division Horner's Scheme

the same

$$P(X) = \sum_{k=0}^{N} d_k X^k$$

Then we can do this by this recursion.

- Now consider synthetic division

$$p(x) = (x - x_0) q(x) + p(x_0)$$

- Then 
$$q(x) = \sum_{k=1}^{n} \beta_k x^{k-1}$$

- To see this note that

$$-\beta_n = d_n$$

Now note that  $p(x) = q(x) + (x-x_0)q(x)$ 

and hence 
$$p(x_0) = q(x_0)$$