

Math 5600

6/4/14

- Continuous Least Squares
- so far we have approximated functions by interpolation
- There are alternatives

$$f(x) \approx \sum_{i=0}^n \alpha_i b_i(x) = p(x)$$

- we approximate f by a linear combination of basis functions.
- The b_i may be polynomial, $b_i(x) = x^i$ but need not be

- How do we quantify $f(x) \approx p(x)$
- There are various ways of measuring the error

Examples $\int_a^b |f(x) - p(x)| dx = \min$

$$\max_{a \leq x \leq b} |f(x) - p(x)| = \min$$

$$\int_a^b (f(x) - p(x))^2 dx = \min$$

- The last is called (continuous, linear) Least squares.
- "continuous" means we have infinitely many points, $a \leq x \leq b$ (The alternative is "discrete" least squares)
- "Linear" means we use a linear combination of basis functions and we will get a linear system to solve.
- Examples for nonlinear LS..

$$f(x) \approx \alpha \sin(\beta x + \phi) \quad f(x) \approx \frac{\alpha_0 + \alpha_1 x}{\beta_0 + x}$$

$$f(x) \approx \alpha e^{\beta x}$$

- Let's see how to solve the linear problem.

- Example - $b_i(x) = x^i \quad 0 \leq x \leq 1$

$$\int_0^1 \left(f(x) - \sum_{j=0}^n \alpha_j x^j \right)^2 dx = \min$$

$$- F(\alpha_0, \dots, \alpha_n) = \int_0^1 \left(f(x) - \sum_{j=0}^n \alpha_j x^j \right)^2 dx = \min$$

- set the gradient to zero and solve

$$\frac{\partial F}{\partial \alpha_i} = -2 \int_0^1 \left(f(x) - \sum_{j=0}^n \alpha_j x^j \right) x^i dx = 0$$

- This becomes

$$\sum_{j=0}^n \alpha_j \int_0^1 x^j x^i dx = \int_0^1 f(x) x^i dx$$

$$\int_0^1 x^j x^i dx = \int_0^1 x^{i+j} dx = \frac{1}{i+j+1} \quad i, j = 0, \dots, n$$

- so we get the system

$$\sum_{j=0}^n \frac{1}{i+j+1} \alpha_j = \int_0^1 f(x) x^i dx \quad i = 0, \dots, n$$

$$\begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \dots & \frac{1}{n+1} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \dots & \frac{1}{n+2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{1}{n+1} & \frac{1}{n+2} & \frac{1}{n+3} & \dots & \frac{1}{2n+1} \end{bmatrix} \begin{bmatrix} d_0 \\ \vdots \\ d_n \end{bmatrix} = \begin{bmatrix} \int_0^1 f(x) dx \\ \vdots \\ \int_0^1 x^n f(x) dx \end{bmatrix}$$

$(n+1) \times (n+1)$ Hilbert Matrix

- Example $n=1$ $f(x) = e^x$

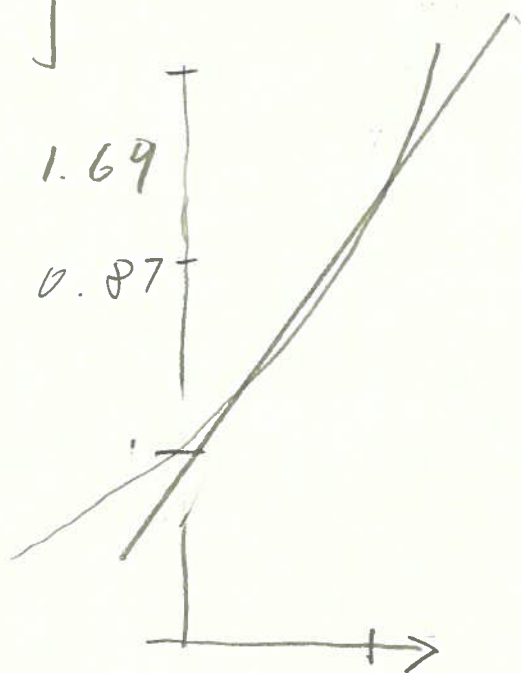
$$\int_0^1 e^x = e - 1 \quad \int_0^1 x e^x = 1$$

$$\begin{bmatrix} 1 & 1/2 \\ 1/2 & 1/3 \end{bmatrix} \begin{bmatrix} d_0 \\ d_1 \end{bmatrix} = \begin{bmatrix} e-1 \\ 1 \end{bmatrix}$$

$$d_0 = 18 - 6e \approx 1.69$$

$$d_1 = 4e - 10 \approx 0.87$$

makes sense



- Properties of the Hilbert Matrix:

- Let's redo the problem in general.

$$F(d_0, \dots, d_n) = \int_a^b \left(f(x) - \sum_{j=0}^n d_j b_j(x) \right)^2 dx = \min$$

$$\frac{\partial F}{\partial d_j} = -2 \int_a^b \left(f(x) - \sum_{i=0}^n d_i b_i(x) \right) b_j(x) dx = 0$$

- we get the linear system

$$\sum_{j=0}^n d_j \int_a^b b_i(x) b_j(x) dx = \int_a^b f(x) b_i(x) dx$$

- we don't have to write a polynomial in standard form. How about

$$b_0(x) = 1$$

$$b_1(x) = 2x - 1$$

$$b_2(x) = 6x^2 - 6x + 1$$

$$\left[\int_a^b b_i(x) b_j(x) dx \right] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/5 \end{bmatrix}$$

- The matrix is diagonal!

- much nicer!

- Does $\int_a^b b_i(x) b_j(x) dx$

remind you of anything?

$$\int_a^b u(x) v(x) dx \quad \text{versus} \quad u^T v$$

u, v vectors

- we have an inner product (or dot product)!

(f, g) is an inner product if

$$(f, g) = (g, f)$$

$$(f+g, h) = (f, h) + (g, h)$$

$$(f, f) \geq 0$$

$$(f, f) = 0 \Rightarrow f = 0$$

(say we restrict ourselves
to continuous functions
 f and g)

- Examples:

$$(f, g) = \int_a^b w(x) f(x) g(x) dx \quad w(x) > 0$$

$$(f, g) = \int_a^b f(x) g(x) + f'(x) g'(x) dx$$

$$(f, g) = \int_a^b f(x) g(x) dx + f(c) g(c)$$

- Two functions f and g are orthogonal with respect to a given inner product if

$$(f, g) = 0$$

- Let's do our linear system again in terms of inner products.

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$$F(\alpha_0, \dots, \alpha_n) = \left(f - \sum_{j=0}^n \alpha_j b_j, f - \sum_{j=0}^n \alpha_j b_j \right)$$

$$= (f, f) - 2 \sum_{j=0}^n \alpha_j (b_j, f) + \sum_{i=0}^n \sum_{j=0}^n \alpha_i \alpha_j (b_i, b_j)$$

$$\frac{\partial F}{\partial \alpha_i} = -2(b_i, f) + 2 \sum_{j=0}^n \alpha_j (b_i, b_j) = 0$$

- same system as before.
- It would be nice if the linear system was diagonal, i.e., the basis functions are orthogonal.