

MATH 676 PROJECT: S_N SUMMARY

LOGAN HARBOUR

1 Problem definition

Begin with the spatial domain $\mathcal{D} \in \mathbb{R}^2$ in which $\delta\mathcal{D}$ is on the boundary of \mathcal{D} . The set of propagation directions \mathcal{S} is the unit disk.

The linear Boltzmann equation for one-group transport is

$$\boldsymbol{\Omega} \cdot \nabla \Psi(\boldsymbol{\Omega}, \mathbf{x}) + \sigma_t(\mathbf{x})\Psi(\boldsymbol{\Omega}, \mathbf{x}) - \sigma_s(\mathbf{x})\Phi(\mathbf{x}) = q(\mathbf{x}), \quad \forall(\boldsymbol{\Omega}, \mathbf{x}) \in \mathcal{S} \times \mathcal{D}, \quad (1.1a)$$

$$\Phi(\boldsymbol{\Omega}, \mathbf{x}) = \Phi^{\text{inc}}(\boldsymbol{\Omega}, \mathbf{x}), \quad \forall(\boldsymbol{\Omega}, \mathbf{x}) \in \mathcal{S} \times \delta\mathcal{D}, \quad \boldsymbol{\Omega} \cdot \mathbf{n}(\mathbf{x}) < 0, \quad (1.1b)$$

where Φ is the scalar flux, defined by

$$\Phi = \frac{1}{2\pi} \int_{\mathcal{S}} \Phi(\boldsymbol{\Omega}, \mathbf{x}) d\boldsymbol{\Omega}.$$

2 S_N discretization

Introduce the S_N discretization, which replaces the angular flux with a discrete angular flux, as

$$\psi(\mathbf{x}) = [\psi_1(\mathbf{x}), \psi_2(\mathbf{x}), \dots, \psi_{N_\Omega}(\mathbf{x})]^T. \quad (2.1)$$

We then introduce the quadrature rule $\{(\boldsymbol{\Omega}_d, \omega_d), d = 1, \dots, N_\Omega\}$ where $\sum_d \omega_d = 2\pi$. With said quadrature rule, we have

$$\int_{\mathcal{S}} f(\boldsymbol{\Omega}, \mathbf{x}) d\boldsymbol{\Omega} \approx \sum_{d=1}^{N_\Omega} w_d f(\boldsymbol{\Omega}_d, \mathbf{x}).$$

This discretization allows us to write the system in Equation (1.1) as

$$\boldsymbol{\Omega}_d \cdot \nabla \psi_d(\mathbf{x}) + \sigma_t(\mathbf{x})\psi_d(\mathbf{x}) - \sigma_s(\mathbf{x})\phi(\mathbf{x}) = q(\mathbf{x}), \quad \forall \mathbf{x} \in \mathcal{D} \quad (2.2a)$$

$$\psi_d(\mathbf{x}) = \psi_j^{\text{inc}}(\mathbf{x}), \quad \forall \mathbf{x} \in \delta\mathcal{D}, \quad \boldsymbol{\Omega}_d \cdot \mathbf{n}(\mathbf{x}) < 0, \quad (2.2b)$$

where the discrete scalar flux, ϕ , is

$$\phi(\mathbf{x}) = \frac{1}{2\pi} \sum_{d=1}^{N_\Omega} w_d \psi_d(\mathbf{x}).$$

3 Discontinuous Galerkin discretization

Define \mathbb{T}_h as the set of all active cells of the triangulation for \mathcal{D} and \mathbb{F}_h as the set of all active interior faces. Define a discontinuous approximation space for the scalar flux based on the mesh \mathbb{T}_h as

$$V_h \in \{v \in L^2(\mathcal{D}) \mid \forall K \in \mathbb{T}_h, v|_K \in P_K\}, \quad (3.1)$$

where the finite-dimensional space P_K is assumed to contain \mathbb{P}_k , the set of polynomials of degree at most k . The discrete space for the angular flux consists of copies of V_h for each of the discrete ordinates, as

$$W_h = (V_h)^{N_\Omega}. \quad (3.2)$$

Multiply Equation (2.2b) by the test function $v_d \in V_h$ and integrate as

$$\sum_{K \in \mathbb{T}_h} [(\mathbf{\Omega}_d \cdot \nabla \psi_d, v_d)_K + (\sigma_t \psi_d, v_d)_K - (\sigma_s \phi, v_d)_K = (q, v_d)_K] , \quad (3.3)$$

and integrate the first term by parts to obtain

$$\sum_{K \in \mathbb{T}_h} [(-\mathbf{\Omega}_d \cdot \nabla v_d, \psi_d)_K + (\psi_d \mathbf{\Omega}_d \cdot \mathbf{n}, v_d)_{\delta K} + (\sigma_t \psi_d, v_d)_K - (\sigma_s \phi, v_d)_K = (q, v_d)_K] , \quad (3.4)$$

where \mathbf{n} is the outward normal. Note that the surface integration in Equation (3.4) is double-valued due to the discontinuous approximation. We introduce the upwind approximation

$$\psi_d \mathbf{\Omega}_d \cdot \mathbf{n} = \psi_d^+ \mathbf{\Omega}_d \cdot \mathbf{n} , \quad (3.5)$$

where ψ_d^+ is the upwind value of ψ_d , that is, the value from the side of the face in which $\mathbf{\Omega} \cdot \mathbf{n} \geq 0$. The weak form is then defined as

$$\sum_{K \in \mathbb{T}_h} [(-\mathbf{\Omega}_d \cdot \nabla v_d, \psi_d)_K + (\psi_d^+ \mathbf{\Omega}_d \cdot \mathbf{n}, v_d)_{\delta K} + (\sigma_t \psi_d, v_d)_K - (\sigma_s \phi, v_d)_K = (q, v_d)_K] . \quad (3.6)$$