

Question 1

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a general probability space, and suppose a random variable X on this space is measurable with respect to the trivial σ -algebra $\mathcal{F}_0 = \{\emptyset, \Omega\}$. Show that X is not random (i.e., there is a constant c such that $X(\omega) = c$ for all $\omega \in \Omega$). Such a random variable is called *degenerate*.

Answer

A random variable X is said to be measurable with respect to a σ -algebra \mathcal{G} if $\{\omega \in \Omega \mid X(\omega) \in B\} \subseteq \mathcal{G}$ for all Borel subsets of the range of X , B . Let X be a random variable measurable with respect to $\mathcal{F}_0 = \{\emptyset, \Omega\}$ and suppose there exists $\omega_1, \omega_2 \in \Omega$ for which $X(\omega_1) \neq X(\omega_2)$. Taking the Borel set $B_1 = \{X(\omega_1)\}$, it must be the case that $\{X \in B_1\}$ is not empty, and because X is measurable with respect to \mathcal{F}_0 , we are left to conclude $\{X \in B_1\} = \Omega$. This is a contradiction, though, as $X(\omega_2) \notin B_1$ implies $\omega_2 \notin \{X \in B_1\} = \Omega$. Thus, for all $\omega \in \Omega$, it must be the case that $X(\omega) = c$ for some c in the image of X .

If one assumes X takes values in the reals and has an associated law, an alternative proof could look like the following.

A random variable X is said to be measurable with respect to a σ -algebra \mathcal{G} if $\{\omega \in \Omega \mid X(\omega) \in B\} \subseteq \mathcal{G}$ for all Borel subsets B . For all $x \in \mathbb{R}$ (and therefore all Borel sets of the form $(-\infty, x)$), then, $\{X \leq x\} \in \mathcal{F}_0 \equiv \{\emptyset, \Omega\}$. Hence, $\mathbb{P}(X \leq x)$ takes one of two values:

$$\begin{aligned} \mathbb{P}(X \leq x) &= 0 & \text{if } \{X \leq x\} &= \{\omega \in \Omega \mid X(\omega) \leq x\} = \emptyset \\ \mathbb{P}(X \leq x) &= 1 & \text{if } \{X \leq x\} &= \{\omega \in \Omega \mid X(\omega) \leq x\} = \Omega \end{aligned}$$

Because $\lim_{x \rightarrow -\infty} \mathbb{P}(X \leq x) = 0$ and $\lim_{x \rightarrow \infty} \mathbb{P}(X \leq x) = 1$, there exists a $c \in \mathbb{R}$ for which $\mathbb{P}(X \leq c) = 1$ and $\mathbb{P}(X \leq x) = 0$ for all $x < c$. Thus

$$\mathbb{P}(X = c) = \lim_{\varepsilon \rightarrow 0} \mathbb{P}(c - \varepsilon < X \leq c) = \mathbb{P}(X \leq c) - \lim_{\varepsilon \rightarrow 0} \mathbb{P}(X \leq c - \varepsilon) = 1 - 0 = 1.$$

Question 2

Independence of random variables can be affected by changes of measure. To illustrate this point, consider the space of two coin tosses $\Omega_2 = \{HH, HT, TH, TT\}$, and let stock

prices be given by

$$\begin{aligned} S_0 &= 4 & S_1(H) &= 8 & S_2(HH) &= 16 \\ S_1(T) &= 2 & S_2(HT) &= S_2(TH) &= 4 \\ S_2(TT) &= 1. \end{aligned}$$

Consider two probability measures given by

$$\begin{aligned} \tilde{\mathbb{P}}(HH) &= 1/4 & \tilde{\mathbb{P}}(HT) &= 1/4 & \tilde{\mathbb{P}}(TH) &= 1/4 & \tilde{\mathbb{P}}(TT) &= 1/4 \\ \mathbb{P}(HH) &= 4/9 & \mathbb{P}(HT) &= 2/9 & \mathbb{P}(TH) &= 2/9 & \mathbb{P}(TT) &= 1/9. \end{aligned}$$

Define the random variable

$$X = \begin{cases} 1 & \text{if } S_2 = 4 \\ 0 & \text{if } S_2 \neq 4 \end{cases}$$

- (a) List all the sets in $\sigma(X)$.
- (b) List all the sets in $\sigma(S_1)$.
- (c) Show that $\sigma(X)$ and $\sigma(S_1)$ are independent under the probability measure $\tilde{\mathbb{P}}$.
- (d) Show that $\sigma(X)$ and $\sigma(S_1)$ are not independent under the probability measure \mathbb{P} .
- (e) Under \mathbb{P} , we have $\mathbb{P}(S_1 = 8) = 2/3$ and $\mathbb{P}(S_1 = 2) = 1/3$. Explain intuitively why, if you are told that $X = 1$, you would want to revise your estimate of the distribution of S_1 .

Answer

- (a) The σ -algebra generated by X is $\sigma(X) = \{\emptyset, \Omega, \{HH, TT\}, \{HT, TH\}\}$.
- (b) The σ -algebra generated by S_1 is $\sigma(S_1) = \{\emptyset, \Omega, \{HH, HT\}, \{TH, TT\}\}$.
- (c) Note that it is sufficient to only consider the non-trivial events (i.e. those which are not \emptyset nor Ω). For those non-trivial events in $\sigma(X)$, we have

$$\tilde{\mathbb{P}}(\{HH, TT\}) = \tilde{\mathbb{P}}(HH) + \tilde{\mathbb{P}}(TT) = \frac{1}{4} + \frac{1}{4} = \frac{1}{2} \quad \text{and} \quad \tilde{\mathbb{P}}(\{HT, TH\}) = \frac{1}{2}.$$

Similarly, both non-trivial events in $\sigma(S_1)$ also occur with probability $1/2$. Hence for those non-trivial $A \in \sigma(X), B \in \sigma(S_1)$, we have $\tilde{\mathbb{P}}(A)\tilde{\mathbb{P}}(B) = (1/2)(1/4) = 1/4$.

In the tables below we show the joint events and their probabilities, respectively:

$\{A \cap B\}$	$\{HH, HT\}$	$\{TH, TT\}$	$\tilde{\mathbb{P}}(A \cap B)$	$\{HH, HT\}$	$\{TH, TT\}$
$\{HH, TT\}$	HH	TT	$\{HH, TT\}$	$1/4$	$1/4$
$\{HT, HT\}$	HT	TH	$\{HT, HT\}$	$1/4$	$1/4$

Since $\tilde{\mathbb{P}}(A \cap B) = \tilde{\mathbb{P}}(A)\tilde{\mathbb{P}}(B)$ for all $A \in \sigma(X), B \in \sigma(S_1)$, those σ -algebras are independent under $\tilde{\mathbb{P}}$.

- (d) The probabilities of the non-trivial events in $\sigma(X)$ are

$$\mathbb{P}(\{HH, TT\}) = \mathbb{P}(HH) + \mathbb{P}(TT) = \frac{4}{9} + \frac{1}{9} = \frac{5}{9} \quad \text{and} \quad \mathbb{P}(\{HT, TH\}) = \frac{4}{9},$$

whereas those in $\sigma(S_1)$ are $\mathbb{P}(\{HH, HT\}) = 2/3$ and $\mathbb{P}(\{TH, TT\}) = 1/3$. Below we use the same table setup as in part (c) to show the probabilities of the joint events:

$\{A \cap B\}$	$\{HH, HT\}$	$\{TH, TT\}$	$\widetilde{\mathbb{P}}(A \cap B)$	$\{HH, HT\}$	$\{TH, TT\}$
$\{HH, TT\}$	HH	TT	$\{HH, TT\}$	$4/9$	$2/9$
$\{HT, HT\}$	HT	TH	$\{HT, HT\}$	$2/9$	$1/9$

Take, for example, $A = \{HH, TT\} \in \sigma(X)$ and $B = \{HH, HT\} \in \sigma(S_1)$. We have

$$\frac{4}{9} = \mathbb{P}(\{A \cap B\}) \neq \mathbb{P}(A)\mathbb{P}(B) = \left(\frac{5}{9}\right) \left(\frac{2}{3}\right) = \frac{10}{27}.$$

Thus $\sigma(X)$ and $\sigma(S_1)$ are not independent under \mathbb{P} .

The work done here was a little excessive, of course. We really just needed one joint event $A \cap B$, $A \in \sigma(X)$, $B \in \sigma(S_1)$, to show that the two σ -algebras are not independent.

- (e) Having been told $X = 1$, we know that one of the events in $\{TH, HT\}$ occurred. These events are equally likely under \mathbb{P} , so with the information that it's a 50-50 chance the first coin flip is tails, one might want to shift more of the estimated mass of S_1 's distribution to that outcome. This is all downstream of our conclusion in part (d): X and S_1 are not independent under \mathbb{P} , so information about one random variable gives us information about the other.

Question 3 - Rotating the Axes

Let X and Y be independent standard normal random variables. Let θ be a constant, and define the random variables

$$V = X \cos \theta + Y \sin \theta \quad \text{and} \quad W = -X \sin \theta + Y \cos \theta.$$

Show that V and W are independent standard normal random variables.

Answer

Note that $\cos \theta$ and $\sin \theta$ are simply constants, as θ is assumed to be one. Hence the mean of V is $\mathbb{E}V = \cos \theta \mathbb{E}X + \sin \theta \mathbb{E}Y = 0 + 0$ by the linearity of the expectations operator. The variance of V is $\text{Var}V = \cos^2 \theta \text{Var}X + \sin^2 \theta \text{Var}Y = (\sin^2 \theta + \cos^2 \theta)(1) = 1$. Finally, as V is a linear combination of independent normals, it is also a normally distributed random variable. For the same reasons, W is a mean-zero normal random variable with unit variance.

It remains to be shown that $\text{Cov}(V, W) = \mathbb{E}[VW] = 0$, which is a sufficient condition for the normal random variables V and W to be independent. We have

$$\begin{aligned} VW &= (Y^2 - X^2) \sin \theta \cos \theta + XY(\cos^2 \theta - \sin^2 \theta) \\ \implies \mathbb{E}[VW] &= (\text{Var}Y - \text{Var}X) \sin \theta \cos \theta + \mathbb{E}X \mathbb{E}Y(\cos^2 \theta - \sin^2 \theta) = 0, \end{aligned}$$

where the first equality in the second line uses the assumed independence of X and Y .

Question 4

In Example 2.2.8, X is a standard normal random variable and Z is an independent random variable satisfying

$$\mathbb{P}(Z = 1) = \mathbb{P}(Z = -1) = \frac{1}{2}.$$

We defined $Y = XZ$ and showed that Y is standard normal. We established that although X and Y are uncorrelated, they are not independent. In this exercise we use moment-generating functions to show that Y is standard normal and X and Y are not independent.

- (i) Establish the joint moment-generating function formula

$$\mathbb{E}[e^{uX+vY}] = e^{\frac{1}{2}(u^2+v^2)} \frac{e^{uv} + e^{-uv}}{2}.$$

- (ii) Use the formula above to show that $\mathbb{E}[e^{vY}] = e^{\frac{1}{2}v^2}$. This is the moment-generating function for a standard normal random variable, and thus Y must be a standard normal random variable.
 (iii) Use the formula in (i) and Theorem 2.2.7(iv) to show that X and Y are not independent.

Answer

- (i) From the Law of Total Expectation, we have $\mathbb{E}[e^{uX+vY}] = \mathbb{E}[e^{uX+vY} | Z = 1]\mathbb{P}(Z = 1) + \mathbb{E}[e^{uX+vY} | Z = -1]\mathbb{P}(Z = -1)$. Substituting $Y = XZ$ into these expressions, we have

$$\mathbb{E}[e^{uX+vY}] = \frac{1}{2}\mathbb{E}[e^{(u+v)X}] + \frac{1}{2}\mathbb{E}[e^{(u-v)X}].$$

The moment-generating function of a standard normal random variable X is $\mathbb{E}[e^{sX}] = e^{\frac{1}{2}s^2}$. Evaluating this at $s = u \pm v$, we have the desired result:

$$\mathbb{E}[e^{uX+vY}] = \frac{1}{2}e^{\frac{1}{2}(u+v)^2} + \frac{1}{2}e^{\frac{1}{2}(u-v)^2} = e^{\frac{1}{2}(u^2+v^2)} \frac{e^{uv} + e^{-uv}}{2}.$$

- (ii) Evaluate the joint moment-generating function from (i) at $u = 0$:

$$\mathbb{E}[e^{vY}] = \mathbb{E}[e^{(0)X+vY}] = e^{\frac{1}{2}((0)^2+v^2)} \frac{e^{(0)v} + e^{-(0)v}}{2} = e^{\frac{1}{2}v^2}.$$

- (iii) Theorem 2.2.7 states, among other things, that random variables X and Y are independent if and only if their moment-generating functions factor as $\mathbb{E}[e^{uX+vY}] = \mathbb{E}[e^{uX}]\mathbb{E}[e^{vY}]$. Factoring a portion of $\mathbb{E}[e^{uX+vY}]$ to resemble $\mathbb{E}[e^{vY}]$, it is clear the remainder is *not* $\mathbb{E}[e^{uX}]$:

$$\mathbb{E}[e^{uX+vY}] = e^{\frac{1}{2}v^2} e^{\frac{1}{2}u^2} \frac{e^{uv} + e^{-uv}}{2} = \mathbb{E}[e^{vY}] \underbrace{e^{\frac{1}{2}u^2} \frac{e^{uv} + e^{-uv}}{2}}_{\neq \mathbb{E}[e^{uX}]}.$$

Thus, we conclude X and Y are not independent.

Question 5

Let (X, Y) be a pair of random variables with joint density function

$$f_{X,Y}(x, y) = \begin{cases} \frac{2|x|+y}{\sqrt{2\pi}} \exp\left\{-\frac{(2|x|+y)^2}{2}\right\} & \text{if } y \geq -|x| \\ 0 & \text{if } y < -|x|. \end{cases}$$

Show that X and Y are standard normal random variables and that they are uncorrelated but not independent.

Answer

We recover the density of X by integrating out Y . First, consider

$$f_X(x) = \int f_{X,Y}(x, y) dy = \int_{-|x|}^{\infty} \frac{2|x|+y}{\sqrt{2\pi}} \exp\left\{-\frac{(2|x|+y)^2}{2}\right\} dy = \frac{1}{\sqrt{2\pi}} \int_{|x|}^{\infty} u e^{-\frac{u^2}{2}} du.$$

The last equality above follows from the substitution $u = 2|x| + y$. This integral evaluates to

$$f_X(x) = -\frac{1}{\sqrt{2\pi}} e^{-v} \Big|_{\frac{1}{2}|x|^2}^{\infty} = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2},$$

which is the density of a standard normal random variable.

The process for recovering the marginal density of Y is the same, although a little more involved. Let $\mathbf{1}_A$ be the indicator function for the statement A , so that

$$f_Y(y) = \int f_{X,Y}(x, y) dx = \int \mathbf{1}_{y \leq |x|} \frac{2|x|+y}{\sqrt{2\pi}} \exp\left\{-\frac{(2|x|+y)^2}{2}\right\} dx.$$

We split this integral into two parts, based on the sign of y relative to zero:

$$f_Y(y) = \int_{-|x|}^{\infty}$$

Question 6

Consider a probability space Ω with four elements, which we call a, b, c , and d (i.e. $\Omega = \{a, b, c, d\}$). The σ -algebra \mathcal{F} is the collection of all subsets of Ω ; i.e. $\mathcal{F} = 2^\Omega$. We define a probability measure \mathbb{P} by specifying that

$$\mathbb{P}(a) = \frac{1}{6}, \quad \mathbb{P}(b) = \frac{1}{3}, \quad \mathbb{P}(c) = \frac{1}{4}, \quad \mathbb{P}(d) = \frac{1}{4},$$

and, as usual, the probability of every other set in \mathcal{F} is the sum of the probabilities of the elements in the set, e.g. $\mathbb{P}(a, b, c) = \mathbb{P}(a) + \mathbb{P}(b) + \mathbb{P}(c) = 3/4$.

We next define two random variables, X and Y , by the formulas

$$\begin{aligned} X(a) &= 1, & X(b) &= 1, & X(c) &= -1, & X(d) &= -1, \\ Y(a) &= 1, & Y(b) &= -1, & Y(c) &= 1, & Y(d) &= -1. \end{aligned}$$

We then define $Z = X + Y$.

- (i) List the sets in $\sigma(X)$.
- (ii) Determine $\mathbb{E}[Y | X]$ (i.e. specify the values of this random variable for a, b, c , and d). Verify the partial-averaging property is satisfied.
- (iii) Determine $\mathbb{E}[Z | X]$. Again verify the partial-averaging property.
- (iv) Compute $\mathbb{E}[Z | X] - \mathbb{E}[Y | X]$. Citing the appropriate properties of conditional expectation from Theorem 2.3.2, explain why you get X .

Answer

- (i) The σ -algebra generated by X is $\sigma(X) = \{\emptyset, \Omega, \{a, b\}, \{c, d\}\}$.
- (ii) Given the σ -algebra specified in (i), evaluating the expectation of Y conditional on a or b is equivalent to $\mathbb{E}[Y | X = 1]$; it is the same for $\{c, d\}$ and $\mathbb{E}[Y | X = -1]$. Hence,

$$\mathbb{E}[Y | X = 1] = \frac{1}{\mathbb{P}(X=1)} [(1)\mathbb{P}(a) + (-1)\mathbb{P}(b)] = \frac{1}{1/2} \left[\frac{1}{6} - \frac{1}{3} \right] = -\frac{1}{3}$$

and

$$\mathbb{E}[Y | X = -1] = \frac{1}{\mathbb{P}(X=-1)} [(1)\mathbb{P}(c) + (-1)\mathbb{P}(d)] = \frac{1}{1/2} \left[\frac{1}{4} - \frac{1}{4} \right] = 0.$$

The law of total expectation implies

$$\begin{aligned} \mathbb{E}[Y] &= \mathbb{E}[Y | X = 1]\mathbb{P}(X = 1) + \mathbb{E}[Y | X = -1]\mathbb{P}(X = -1) \\ &= \left(-\frac{1}{3}\right) \left(\frac{1}{2}\right) + (0) \left(\frac{1}{2}\right) = -\frac{1}{6}. \end{aligned}$$

On the other hand, by direct evaluation of $\mathbb{E}[Y]$ we have

$$\mathbb{E}[Y] = (1)\mathbb{P}(a) + (-1)\mathbb{P}(b) + (1)\mathbb{P}(c) + (-1)\mathbb{P}(d) = (1)\frac{1}{6} + (-1)\frac{1}{3} = -\frac{1}{6}.$$

- (iii) From the linearity of the expectations operator and the fact that X is measurable with respect to $\sigma(X)$, we have

$$\mathbb{E}[Z | X] = \mathbb{E}[Y + X | X] = \mathbb{E}[Y | X] + \mathbb{E}[X | X] = \mathbb{E}[Y | X] + X.$$

Hence,

$$\mathbb{E}[Z | X = 1] = \mathbb{E}[Y | X = 1] + (1) = \frac{2}{3}$$

and

$$\mathbb{E}[Z | X = -1] = \mathbb{E}[Y | X = -1] + (-1) = -1.$$

By the law of total expectation and direct computation, respectively, we have

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Question 7

Let Y be an integrable random variable on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and let \mathcal{G} be a sub- σ -algebra of \mathcal{F} . Based on the information in \mathcal{G} , we can form the estimate $\mathbb{E}[Y|\mathcal{G}]$ of Y and define the error of the estimation $\text{Err} = Y - \mathbb{E}[Y|\mathcal{G}]$. This is a random variable with expectation zero and some variance $\text{Var}(\text{Err})$. Let X be some other \mathcal{G} -measurable random variable, which we can regard as another estimate of Y . Show that

$$\text{Var}(\text{Err}) \leq \text{Var}(Y - X).$$

In other words, the estimate $\mathbb{E}[Y|\mathcal{G}]$ minimizes the variance of the error among all estimates based on the information in \mathcal{G} .

Answer

Define the constant $\mu = \mathbb{E}[Y - X]$, and note that the variance of $Y - X$ is then written as $\text{Var}(Y - X) = \mathbb{E}[(Y - X - \mu)^2]$. Judiciously inserting a $\mathbb{E}[Y|\mathcal{G}] - \mathbb{E}[Y|\mathcal{G}]$ term, we further have

$$\mathbb{E}[(Y - X - \mu)^2] = \mathbb{E}\left[\left((Y - \mathbb{E}[Y|\mathcal{G}]) + (\mathbb{E}[Y|\mathcal{G}] - X - \mu)\right)^2\right].$$

Multiplying this out, we have

$$\begin{aligned} \text{Var}(Y - X) &= \mathbb{E}[(Y - X - \mu)^2] \\ &= \mathbb{E}[(\text{Err} - 0)^2] + \mathbb{E}[(\mathbb{E}[Y|\mathcal{G}] - X - \mu)^2] + 2\mathbb{E}[\text{Err}(\mathbb{E}[Y|\mathcal{G}] - X - \mu)] \end{aligned}$$

Since the Err random variable has zero mean, the first term on the right-hand side above is $\text{Var}(\text{Err})$. The second term is weakly greater than zero, and we will show below that the last term is exactly zero.

Towards that end, we condition an inner expectation operator on \mathcal{G} to arrive at

$$\begin{aligned} \mathbb{E}[\text{Err}(\mathbb{E}[Y|\mathcal{G}] - X - \mu)] &= \mathbb{E}[\mathbb{E}[\text{Err}(\mathbb{E}[Y|\mathcal{G}] - X - \mu)|\mathcal{G}]] \\ &= \mathbb{E}[\mathbb{E}[\text{Err}|\mathcal{G}](\mathbb{E}[Y|\mathcal{G}] - X - \mu)]. \end{aligned}$$

The final equality follows from the \mathcal{G} -measurability of X , the fact that $\mathbb{E}[Y|\mathcal{G}]$ is known conditioned on \mathcal{G} , and that μ is a constant. Turning to $\mathbb{E}[\text{Err}|\mathcal{G}]$, we immediately have that

$$\mathbb{E}[\text{Err}|\mathcal{G}] = \mathbb{E}[Y - \mathbb{E}[Y|\mathcal{G}]|\mathcal{G}] = \mathbb{E}[Y|\mathcal{G}] - \mathbb{E}[Y|\mathcal{G}] = 0.$$

Thus, the cross-term $\mathbb{E}[\text{Err}(\mathbb{E}[Y|\mathcal{G}] - X - \mu)]$ evaluates to zero. This implies that

$$\text{Var}(Y - X) = \text{Var}(\text{Err}) + \underbrace{\mathbb{E}[(\mathbb{E}[Y|\mathcal{G}] - X - \mu)^2]}_{\geq 0} + 0.$$

Because the second term is weakly greater than zero, we can conclude that

$$\text{Var}(\text{Err}) \geq \text{Var}(Y - X),$$

and we are done.

Question 8

Let X and Y be integrable random variables on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$. Then $Y = Y_1 + Y_2$, where $Y_1 = \mathbb{E}[Y|X]$ is $\sigma(X)$ -measurable and $Y_2 = Y - \mathbb{E}[Y|X]$. Show that Y_2 and X are uncorrelated. More generally, show that Y_2 is uncorrelated with every $\sigma(X)$ -measurable random variable.

Question 9

Let X be a random variable.

- (i) Given an example of a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, a random variable X defined on this probability space, and a function f so that the σ -algebra generated by $f(X)$ is not the trivial σ -algebra $\{\emptyset, \Omega\}$ but is strictly smaller than the σ -algebra generated by X .
- (ii) Can the σ -algebra generated by $f(X)$ ever be strictly larger than the σ -algebra generated by X ?

Question 10

Let X and Y be random variables (on some unspecified probability space $(\Omega, \mathcal{F}, \mathbb{P})$), assume they have a joint density $f_{X,Y}(x, y)$, and assume $\mathbb{E}[|Y|] < \infty$. In particular, for every Borel subset C of \mathbb{R}^2 , we have

$$\mathbb{P}((X, Y) \in C) = \int_C f_{X,Y}(x, y) dx dy.$$

In elementary probability, one learns to compute $\mathbb{E}[Y|X = x]$, which is a *nonrandom* function of the *dummy variable* x , by the formula

$$\mathbb{E}[Y | X = x] = \int_{-\infty}^{\infty} y f_{Y|X}(y|x) dy,$$

where $f_{Y|X}(y|x)$ is the *conditional density* defined by

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x, y)}{f_X(x)}.$$

The denominator in this expression, $f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, \eta) d\eta$, is the *marginal density* of X , and we must assume it is strictly positive for every x . We introduce the symbol $g(x)$ for the function $\mathbb{E}[Y|X = x]$ defined above; i.e.,

$$g(x) = \int_{-\infty}^{\infty} y f_{Y|X}(y|x) dy = \int_{-\infty}^{\infty} \frac{y f_{X,Y}(x, y)}{f_X(x)} dy.$$

In measure-theoretic probability, conditional expectation is a *random variable* $\mathbb{E}[Y|X]$. This exercise is to show that when there is a joint density for (X, Y) , this random variable can be obtained by substituting the random variable X in place of the dummy variable x in the function $g(x)$. In other words, this exercise is to show that

$$\mathbb{E}[Y|X] = g(X).$$

(We introduced the symbol $g(x)$ in order to avoid the mathematically confusing expression $\mathbb{E}[Y|X = X]$.)

Since $g(X)$ is obviously $\sigma(X)$ -measurable, to verify that $\mathbb{E}[Y|X] = g(X)$, we need only check that the partial-averaging property is satisfied. For every Borel-measurable function h mapping \mathbb{R} to \mathbb{R} and satisfying $\mathbb{E}[|h(X)|] < \infty$, we have

$$\mathbb{E}[h(X)] = \int_{-\infty}^{\infty} h(x) f_X(x) dx.$$

This is Theorem 1.5.2 in Chapter 1. Similarly, if h is a function of both x and y , then

$$\mathbb{E}[h(X, Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(x, y) f_{X,Y}(x, y) dx dy$$

whenever (X, Y) has a joint density $f_{X,Y}(x, y)$. You may use both expressions, $\mathbb{E}[h(X)]$ and $\mathbb{E}[h(X, Y)]$, in your solution to this problem.

Let A be a set in $\sigma(X)$. By the definition of $\sigma(X)$, there is a Borel subset B of \mathbb{R} such that $A = \{\omega \in \Omega \mid X(\omega) \in B\}$ or, more simply, $A = \{X \in B\}$. Show the partial-averaging property

$$\int_A g(X) d\mathbb{P} = \int_A Y d\mathbb{P}.$$

Question 11

- (i) Let X be a random variable on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, and let W be a non-negative $\sigma(X)$ -measurable random variable. Show there exists a function g such that $W = g(X)$.
- (ii) Let X be a random variable on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, and let Y be a nonnegative random variable on this space. We do not assume that X and Y have a joint density. Nonetheless, show there is a function g such that $\mathbb{E}[Y|X] = g(X)$.