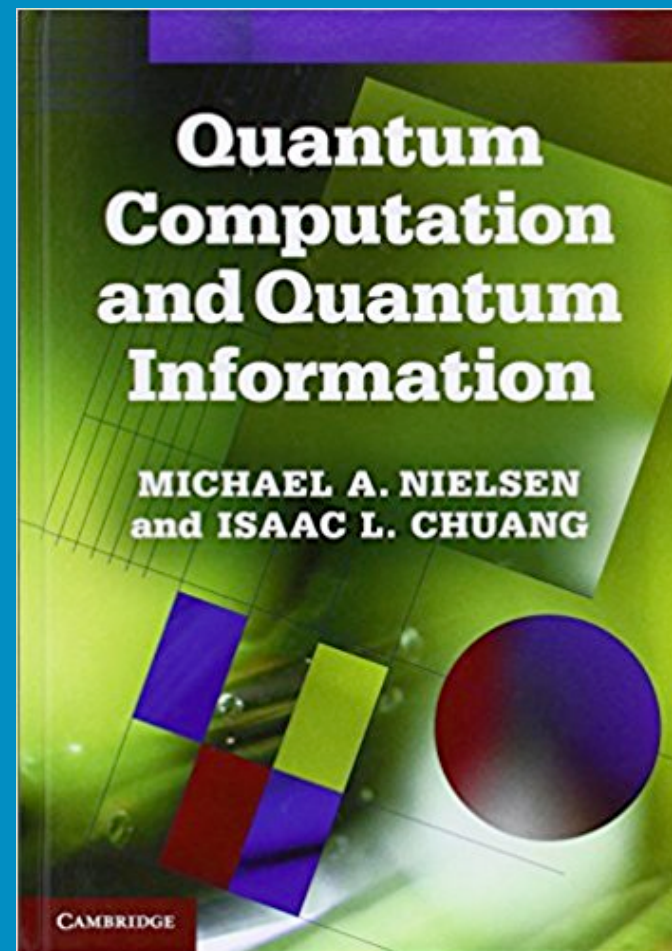




# Quantum Computing Modeling in Scala

**Constantin Gonciulea**  
Distinguished Engineer, JPMorgan Chase

Scale By the Bay, November 2018

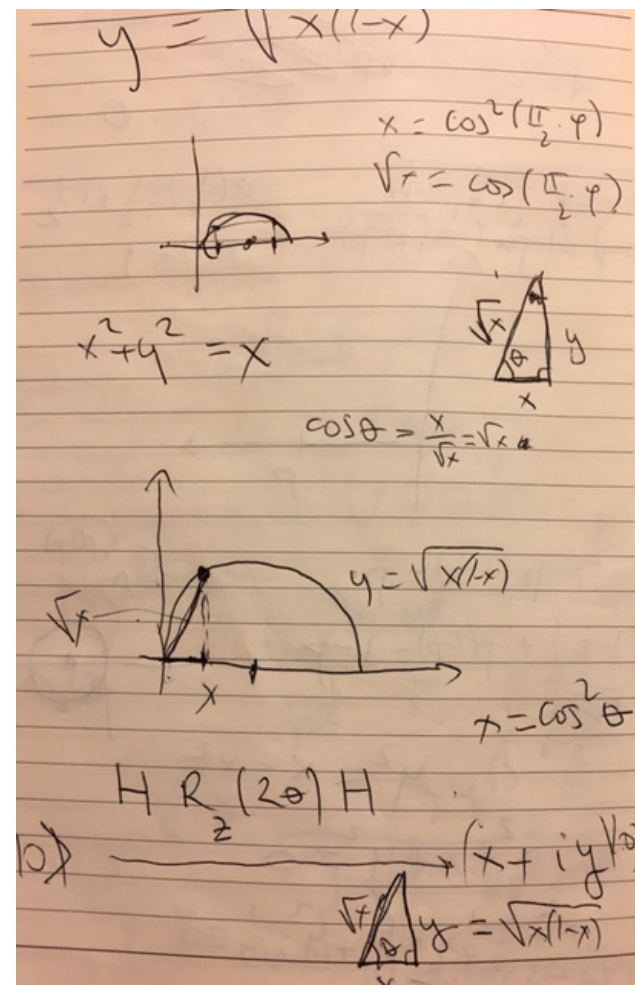


**The postulates of quantum mechanics were derived after a long process of trial and (mostly) error, which involved a considerable amount of guessing and fumbling by the originators of the theory.**



# Why Scala?

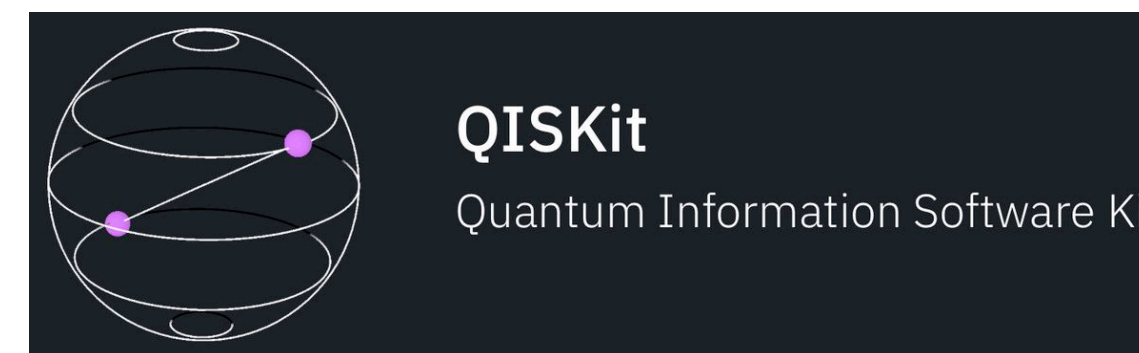
Higher To Lower Abstraction



Math



Scala Simulator



Python Simulator



Quantum Computer

# Quantum Postulates

What quantum state is, how it changes, how it is measured and composed

## State Space

A quantum system is completely described by its state vector



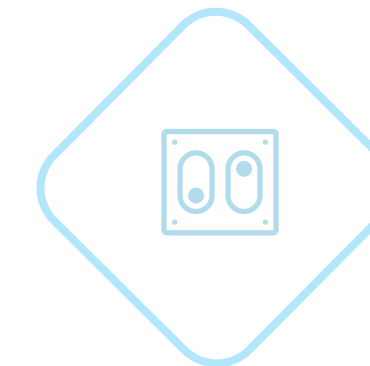
## Evolution

States at two different times are related by a unitary operator



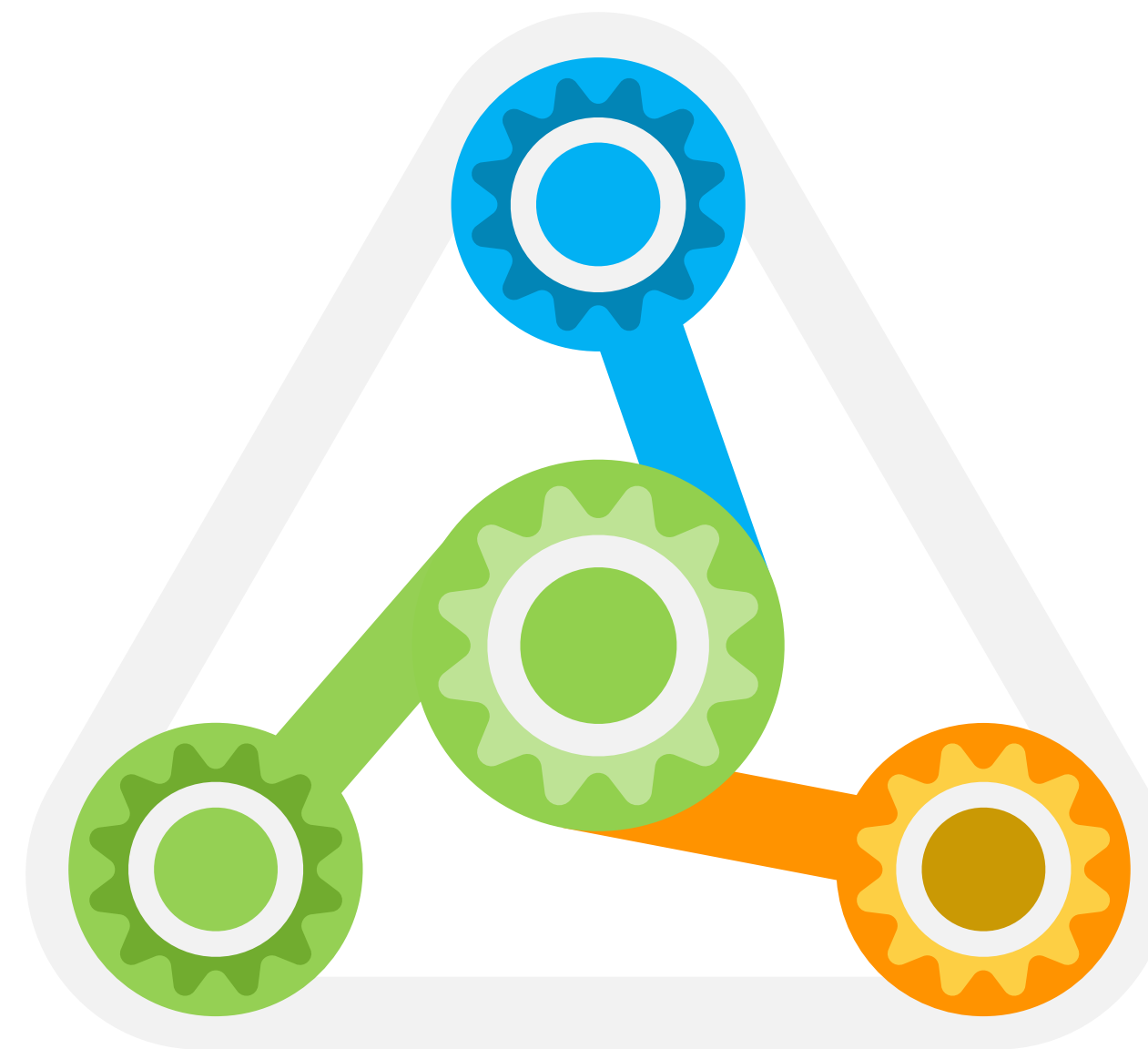
## Measurement

Only certain outcomes may occur in an experiment



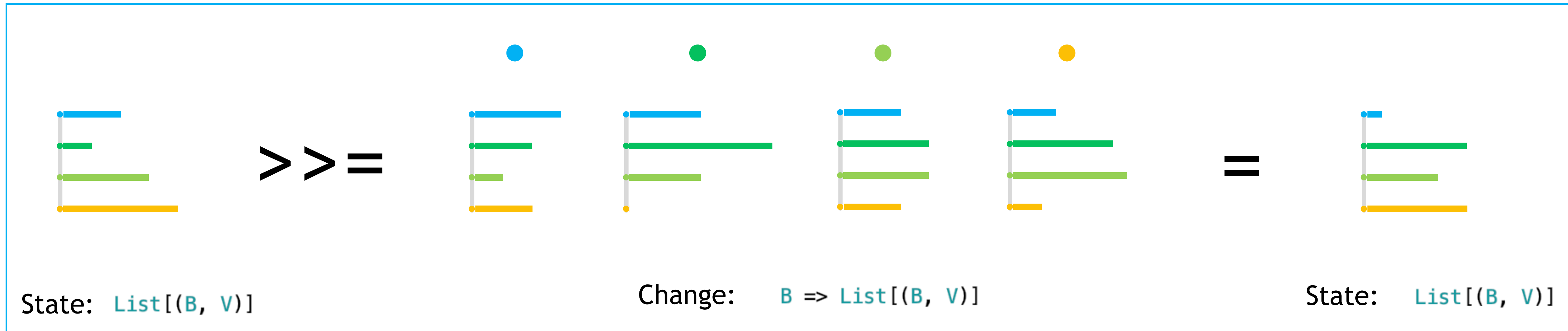
## Composition

The state space of a composite system is the tensor product of component states



# Monadic State Evolution

The system state is defined by labeled values (allocations)



Examples: resource allocation, accounting systems, probabilistic systems, quantum systems

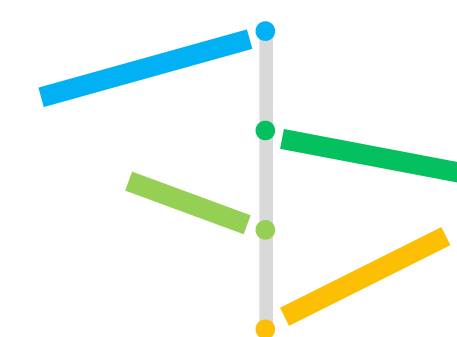
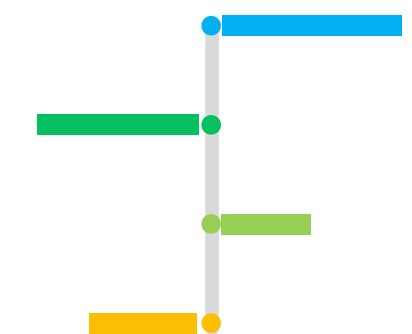
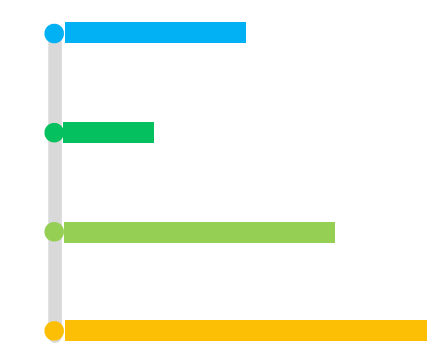
Compare with typical monads:

Container: `M[A]`      `>>=`      Change: `A => M[A]`      `=`      Container: `M[A]`

# State Representation and Evolution

Unified monadic approach to classical, probabilistic and quantum state

```
trait UState[+This <: UState[This, B, V], B, V] {  
  protected val bins: List[(B, V)]  
  protected val m: Monoid[V]  
  
  protected val normalizeStateRule: List[(B, V)] => List[(B, V)] = identity  
  
  protected val combineBinsRule: List[(B, V)] => List[(B, V)] = { bvs =>  
    bvs.groupBy(_._1).toList.map {  
      case (b, vs) => (b, vs.map(_._2).foldLeft(m.empty)(m.combine))  
    }  
  }  
  protected val distributionRule: ((B, V), List[(B, V)]) => List[(B, V)]  
  
  def create(bins: List[(B, V)]): This  
  
  def normalize(): This = create(normalizeStateRule(bins))  
  
  def flatMap(f: B => List[(B, V)]): This = {  
    val updates: List[(B, V)] = bins.flatMap({ case (b, v) => distributionRule((b, v), f(b)) })  
    create(normalizeStateRule(combineBinsRule(updates)))  
  }  
  
  def >>=(f: B => List[(B, V)]): This = flatMap(f)  
}
```



State: `List[(B, V)]`

Change: `B => List[(B, V)]`



# Portfolio Balancing

Percentage based resource allocation

```
val bins: List[(String, Double)] = List("a" -> .2, "b" -> .1, "c" -> .3, "d" -> .4)

val m = RState[String](bins)
val changeA = List("a" -> .25, "b" -> .5, "c" -> .25)
val changeB = List("b" -> 1.0)
val changeC = List("c" -> 1.0)
val changeD = List("d" -> 1.0)

val state = m >=> Map("a" -> changeA, "b" -> changeB, "c" -> changeC, "d" -> changeD)

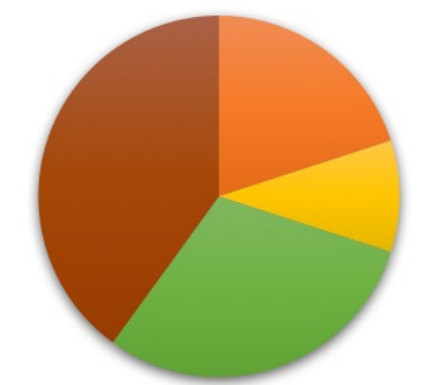
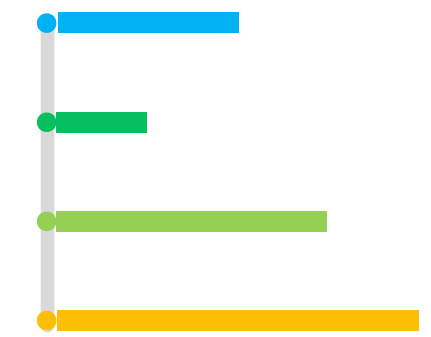
assert(state.bins.toSet == Set("a" -> .05, "b" -> .2, "c" -> .35, "d" -> .4))
```

## Implementation

```
case class RState[B](bins: List[(B, Double)]) extends UState[RState[B], B, Double] {
  val m = new Monoid[Double] {
    override val empty: Double = 0.0
    override val combine: (Double, Double) => Double = _ + _
  }

  override val distributionRule: ((B, Double), List[(B, Double)]) => List[(B, Double)] = {
    case ((b, v), cs) => cs.map { case (c, u) => (c, u * v) }
  }

  override def create(bins: List[(B, Double)]) = RState(bins)
}
```



Invariant: sum = 1

# Account Balances

State of a closed accounting system

```
val bins: List[(String, Double)] = List("a" -> 2, "b" -> 3, "c" -> 5, "d" -> -8, "e" -> -2)

val z = ZState[String](bins)
val changeA = List("a" -> -1.0, "b" -> 1.0)
val changeB = List("b" -> -2.0, "c" -> 1.0, "d" -> 1.0)

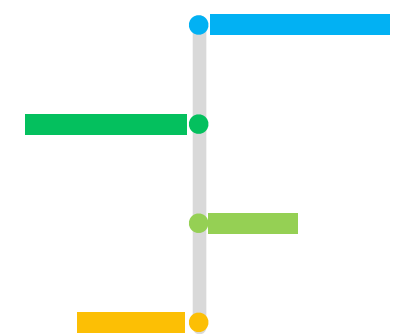
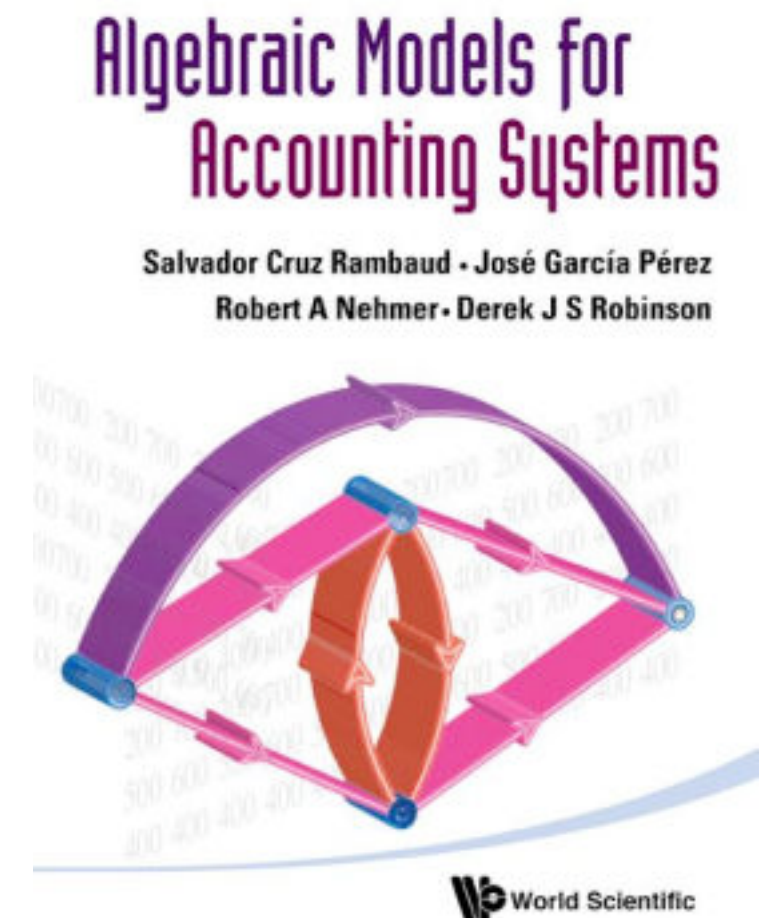
val state = z >=> Map("a" -> changeA, "b" -> changeB, "c" -> Nil, "d" -> Nil, "e" -> Nil)

assert(state.bins.toSet == Set("a" -> 1.0, "b" -> 2.0, "c" -> 6.0, "d" -> -7.0, "e" -> -2.0))
```

## Implementation

```
case class ZState[B](bins: List[(B, Double)]) extends UState[ZState[B], B, Double] {
  val m = new Monoid[Double] {
    override val empty: Double = 0.0
    override val combine: (Double, Double) => Double = _ + _
  }
  override val distributionRule: ((B, Double), List[(B, Double)]) => List[(B, Double)] = {
    case ((b, v), cs) => List((b -> v)) ++ cs
  }

  override def create(bins: List[(B, Double)]) = ZState(bins)
}
```



Invariant: sum = 0








# Probabilistic State






Each possible outcome is assigned a probability

Repeatedly rolling one of the 5 platonic solid dice yields the following sequence: 6, 6, 8, 7, 7, 5, 4.  
Guess which die was used?






Priors:

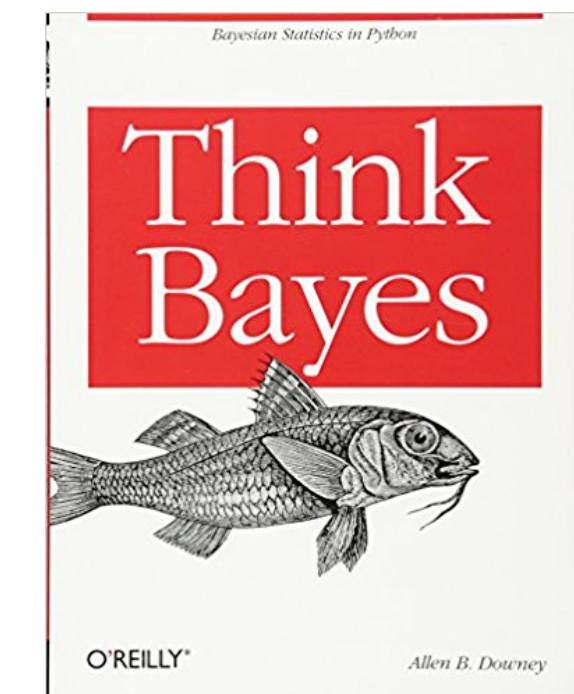
	4	0.2	#####
	6	0.2	#####
	8	0.2	#####
	12	0.2	#####
	20	0.2	#####

After a 6 is rolled:

	4	0.0	
	6	0.3921	#####
	8	0.2941	#####
	12	0.1960	#####
	20	0.1176	####

After 6, 8, 7, 7, 5, 4 are rolled after the first 6:

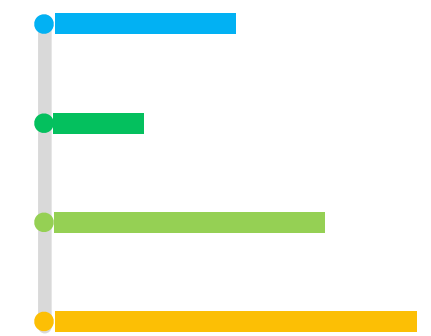
	4	0.0	
	6	0.0	
	8	0.9432	#####
	12	0.0552	##
	20	0.0015	



# Probabilistic State

Bayes Theorem

```
case class PState[B](bins: List[(B, Double)]) extends UState[PState[B], B, Double] {  
  val m = new Monoid[Double] {  
    override val empty: Double = 1.0  
    override val combine: (Double, Double) => Double = _ * _  
  }  
  
  override val distributionRule: ((B, Double), List[(B, Double)]) => List[(B, Double)] = {  
    case ((b, v), cs) => cs.map { case (c, u) => (c, u * v) }  
    //case ((b, v), cs) => List((b -> v)) ++ cs // both work  
  }  
  
  override val normalizeStateRule = { bvs: List[(B, Double)] =>  
    val sum = bvs.map(_._2).foldLeft(0.0)(_ + _)  
    if (sum == 1.0) bins else bvs.map {  
      case (b, v) => (b, v / sum)  
    }  
  }  
  
  override def create(bins: List[(B, Double)]) = PState(bins)  
}
```



Invariant: normalized sum = 1

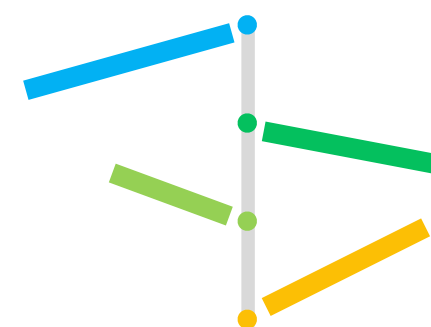
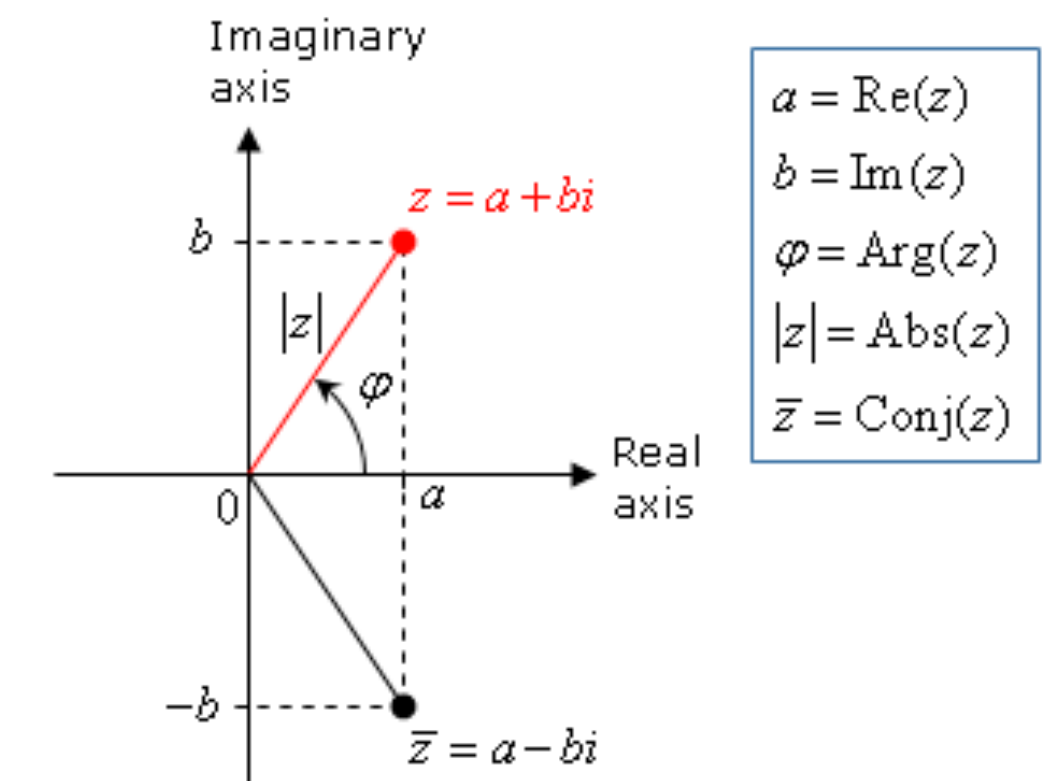
Change: data point likelihoods

```
val change = Map(  
  "a" -> List("a" -> 0.2),  
  "b" -> List("b" -> 0.7),  
  "c" -> List("c" -> 0.0))
```

# Quantum State

Complex numbers (2 -dimensional vectors) as values

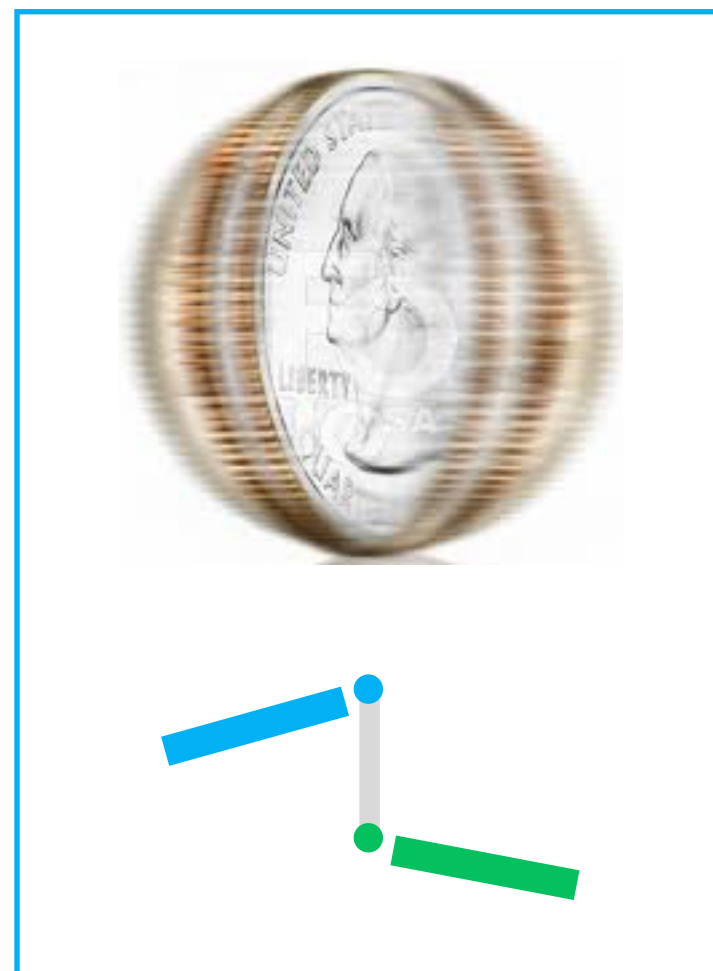
```
case class QState[B](bins: List[(B, Complex)]) extends UState[QState[B], B, Complex] {  
  val m = new Monoid[Complex] {  
    override val empty: Complex = Complex.zero  
    override val combine: (Complex, Complex) => Complex = Complex.plus  
  }  
  
  override val distributionRule: ((B, Complex), List[(B, Complex)]) => List[(B, Complex)] = {  
    case ((b, v), cs) => cs.map { case (c, u) => (c, u * v) }  
  }  
  
  override def create(bins: List[(B, Complex)]) = QState(bins)  
}
```



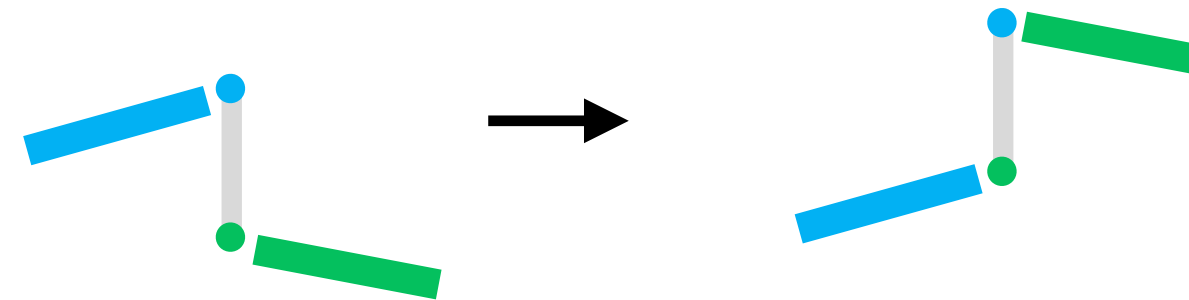
Invariant:  
sum of squared magnitudes  
= 1

# Quantum State Transformations

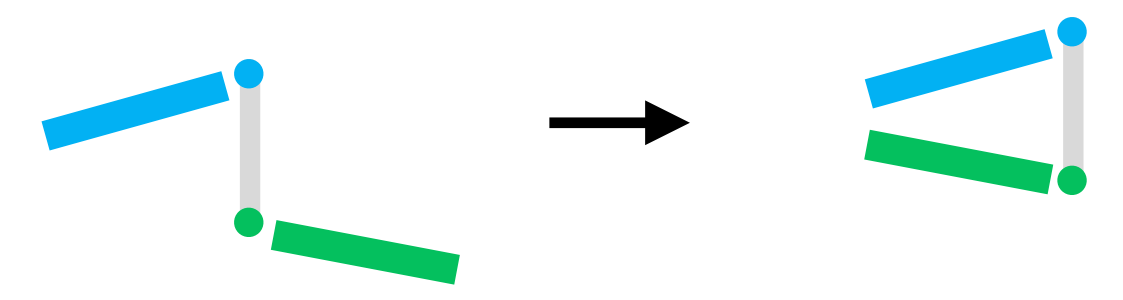
Standard single qubit transformations



X transformation

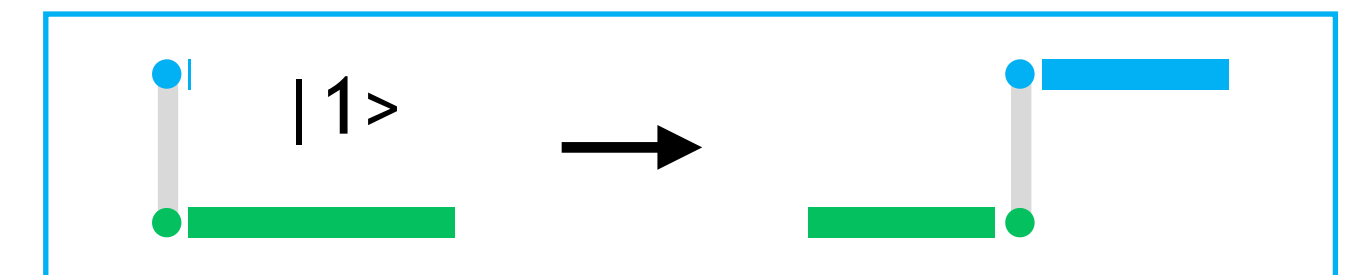
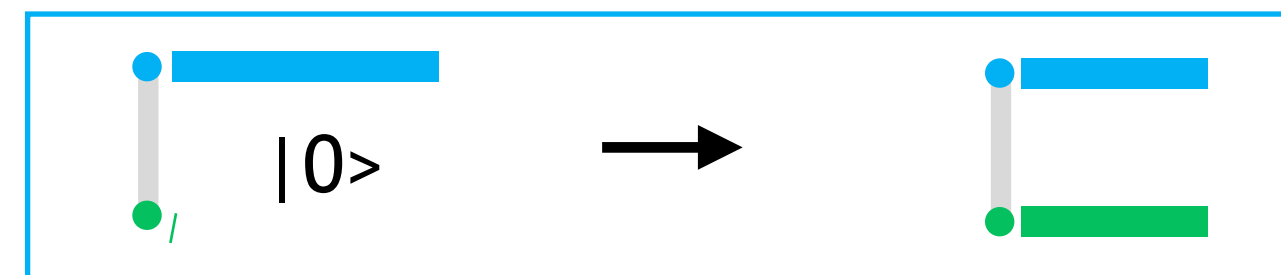


Z transformation



Hadamard transformation

```
val sq = toComplex(1 / math.sqrt(2))
val H = Map(
  "|0>" -> List("|0>" -> sq, "|1>" -> sq),
  "|1>" -> List("|0>" -> sq, "|1>" -> -sq)
)
```



Basis:

$$\begin{matrix} \text{blue} \\ \text{green} \end{matrix} = a \begin{matrix} \text{blue} \\ \text{blue} \end{matrix} + b \begin{matrix} \text{blue} \\ \text{green} \end{matrix}$$



# Quantum Postulates

What quantum state is, how it changes, how it is measured and composed

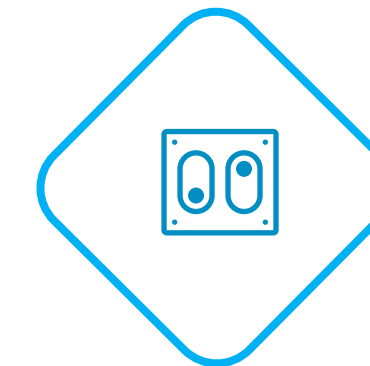
## State Space

A quantum system is completely described by its state vector



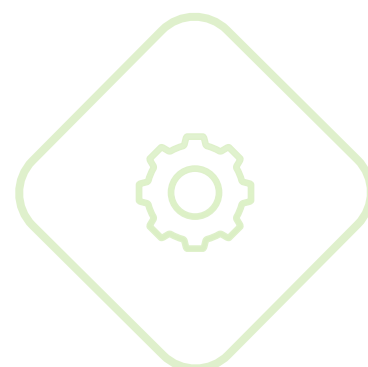
## Measurement

Only certain outcomes may occur in an experiment



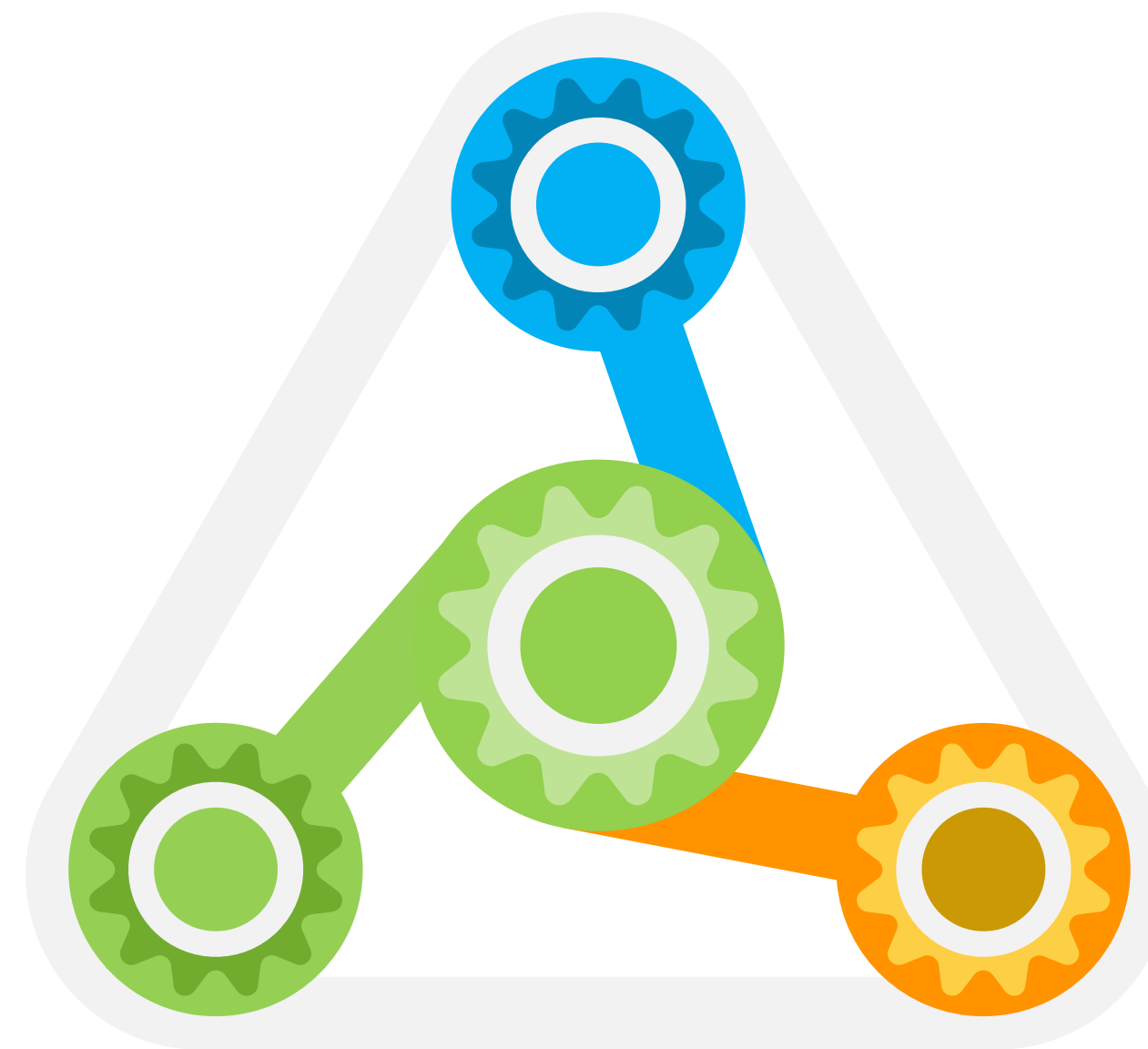
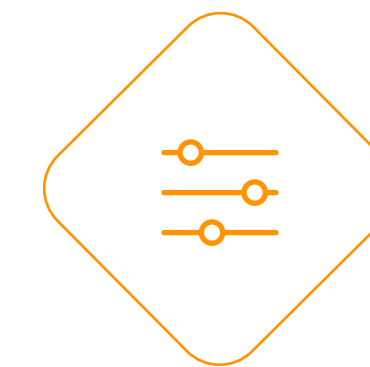
## Evolution

States at two different times are related by a unitary operator




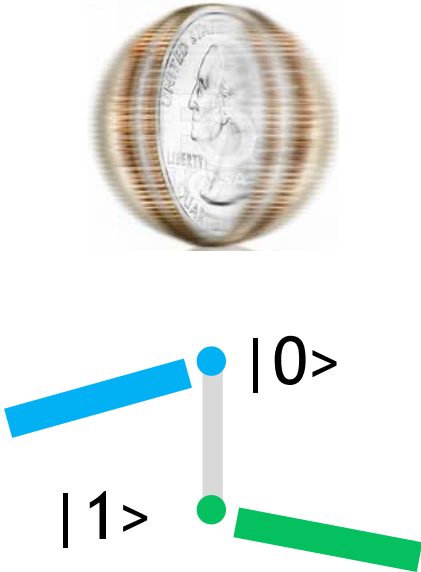



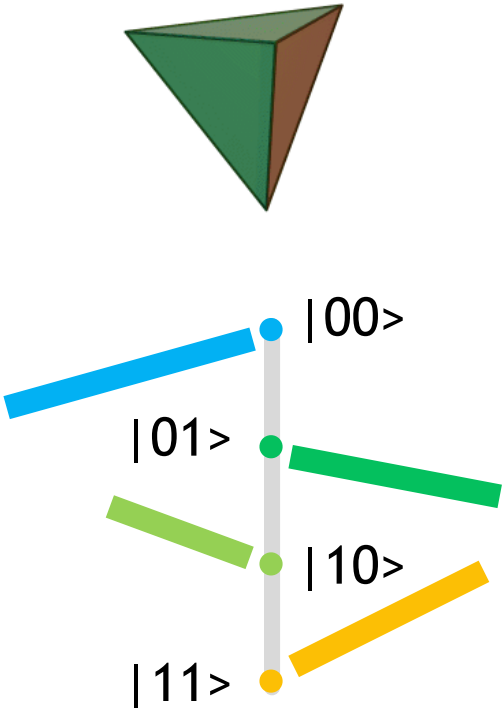








## Composition

The state space of a composite system is the tensor product of component states



# Composition and Measurement

Qubits, superposition, entanglement

Qubits	Quantum State	Measurement Outcomes
	One amplitude for each possible outcome	The probability of an outcome is the squared magnitude of its associated amplitude
		<div><div><div></div><div> 0&gt;</div></div><div><div></div><div> 1&gt;</div></div></div> <div> </div>
		<div><div><div></div><div> 00&gt;</div></div><div><div></div><div> 01&gt;</div></div><div><div></div><div> 10&gt;</div></div><div><div></div><div> 11&gt;</div></div></div> <div><div></div><div></div><div></div><div></div></div>

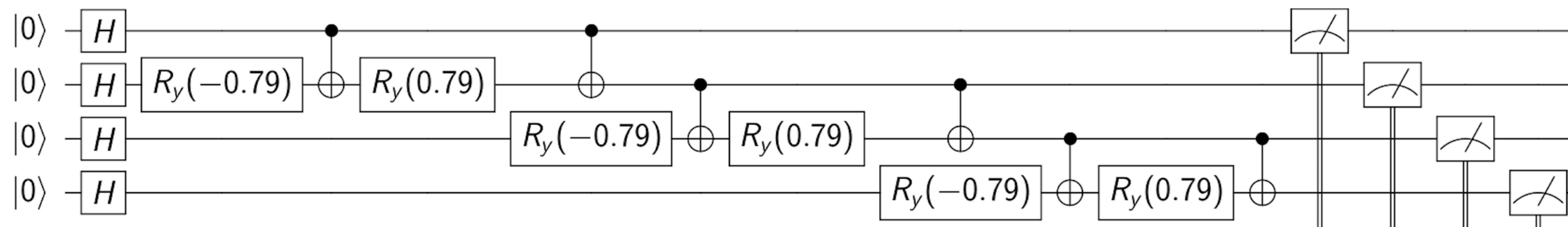
# Calculating Fibonacci Numbers

Counting binary words with no consecutive ones

```
def fib(n: Int): QState = {  
  var state = pure(Word.fromInt(0, n))  
  for (i <- 0 until n) state = state >>= wire(i, H)  
  for (i <- 0 until n - 1) state = state >>= controlled(i, i + 1, ZERO)  
  state  
}
```

Circuit implementation:

```
for (i <- 0 until n - 1) state = state >>= wire(i + 1, Ry(-math.Pi/4)) >>=  
  controlled(i, i + 1, X) >>= wire(i + 1, Ry(math.Pi/4)) >>= controlled(i, i + 1, X)
```



F(1) = 2  
F(2) = 3  
F(3) = 5  
F(4) = 8  
F(5) = 13  
F(6) = 21  
F(7) = 34  
F(8) = 55  
F(9) = 89  
F(10) = 144  
F(11) = 233  
F(12) = 377  
F(13) = 610  
F(14) = 987  
F(15) = 1597

# Thank You

## Code

<https://github.com/logicalguess/quantum-scale>

## Credits

<https://github.com/jliszka/quantum-probability-monad>

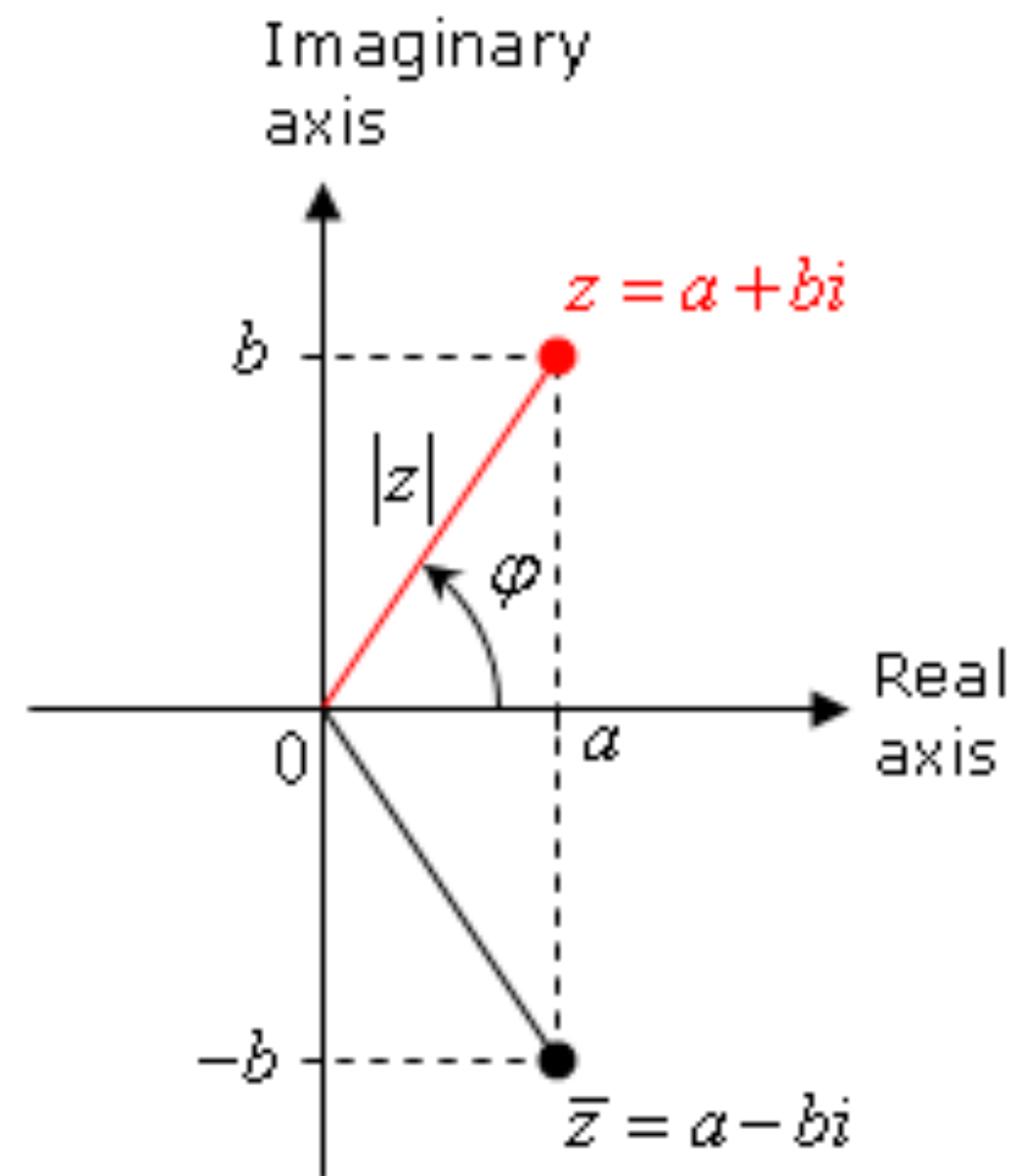
<https://sigfpe.wordpress.com/2007/03/04/monads-vector-spaces-and-quantum-mechanics-pt-ii/>



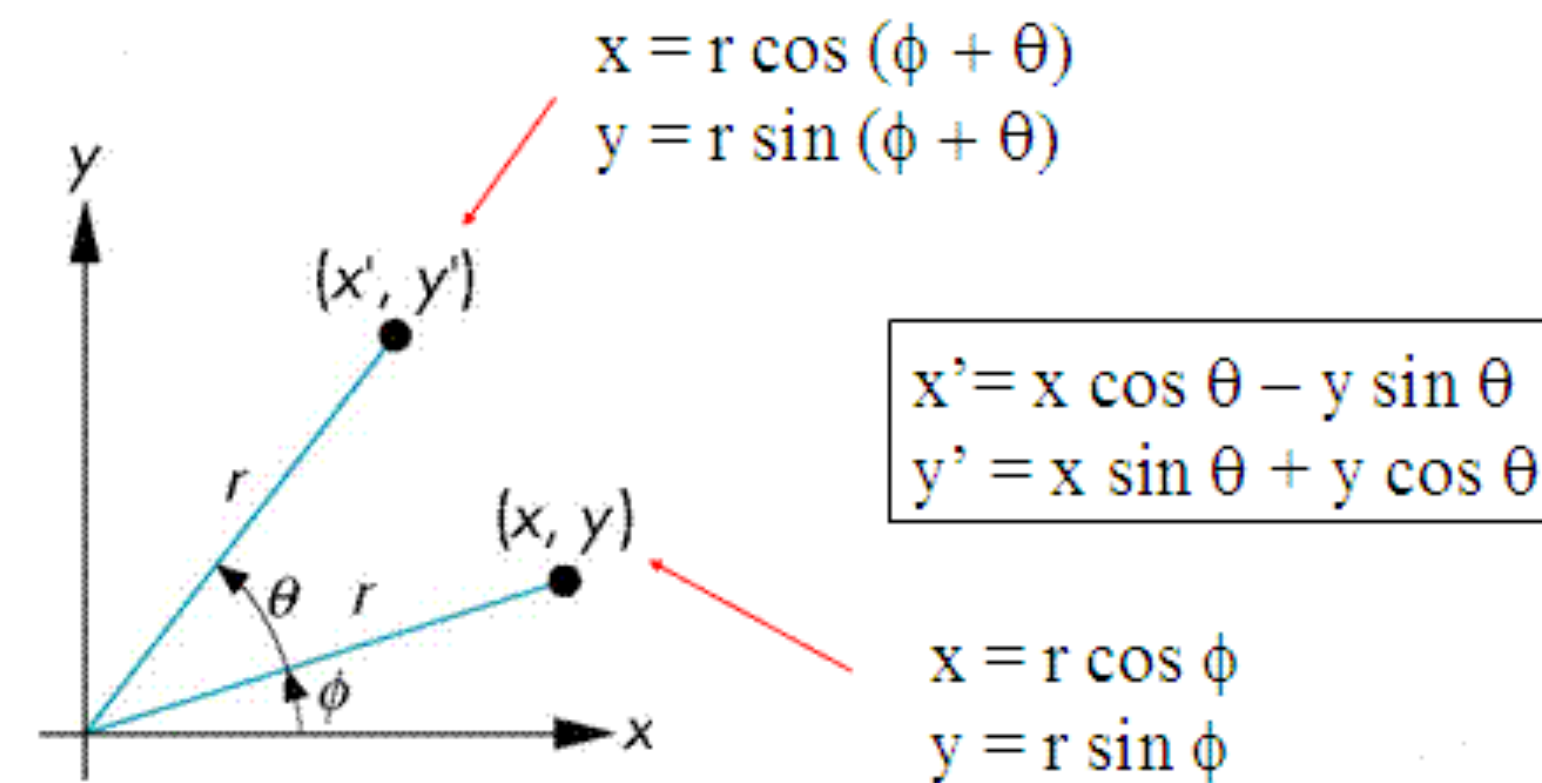
# Appendix

# Complex Numbers

Complex numbers (2 -dimensional vectors) as values



$$\begin{aligned} a &= \operatorname{Re}(z) \\ b &= \operatorname{Im}(z) \\ \varphi &= \operatorname{Arg}(z) \\ |z| &= \operatorname{Abs}(z) \\ \bar{z} &= \operatorname{Conj}(z) \end{aligned}$$



<http://www.thefouriertransform.com/math/complexmath.php>

# Elementary Gates

## Elementary Gates

```
"X" should "swap the amplitudes of |0> and |1>" in forAll { s: QState =>
  val t: QState = X(s)

  assert(t(S0) == s(S1))
  assert(t(S1) == s(S0))
}
```

```
"Y" should "swap the amplitudes of |0> and |1>, multiply each amplitude by i, and negate the amplitude of |1>" in forAll { s: QState =>
  val t: QState = Y(s)

  assert(t(S0) == - s(S1) * Complex.i)
  assert(t(S1) == s(S0) * Complex.i)
}
```

```
"Z" should "negate the amplitude of |1>, leaving the amplitude of |0> unchanged" in forAll { s: QState =>
  val t: QState = Z(s)

  assert(t(S0) == s(S0))
  assert(t(S1) == -s(S1))
}
```

# Rotations

## Rotations around the Y axis

```
"Ry(theta)" should "mix the amplitudes of |0> and |1> (like vector rotation)" in
forall { ts: (Double, QState) =>
  val theta = ts._1
  val state = ts._2

  val y: QState = Ry(theta)(state)

  // same formula as 2-dimensional vector rotation (but with half angle)
  val t0 = state(S0) * math.cos(theta/2) - state(S1) * math.sin(theta/2)
  val t1 = state(S0) * math.sin(theta/2) + state(S1) * math.cos(theta/2)

  assert(y(S0) == t0)
  assert(y(S1) == t1)
}
```

```
"Ry(pi/2)" should "equal HZ" in forall { state: QState =>

  val y: QState = state >=> Ry(math.Pi/2)
  val h: QState = state >=> Z >=> H

  assert(y(S0).toString == h(S0).toString)
  assert(y(S1).toString == h(S1).toString)
}
```

```
"Ry(theta)" should "be a weighted average of I and Ry(pi)" in
forall { ts: (Double, QState) =>
  val theta = ts._1
  val state = ts._2

  val A: Gate = I * math.cos(theta / 2) + Ry(math.Pi) *
math.sin(theta / 2)

  val z: QState = Ry(theta)(state)
  val a: QState = A(state)

  assert(z(S0).toString == a(S0).toString)
  assert(z(S1).toString == a(S1).toString)
}
```

