Recorded at time: 23.097 world Broadcaster: /robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: 50.201 Buffer length: 0.0 Buffer length: 4.98 Most recent transform: 23.059 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 18.079 shoulder link base Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 23.059 Oldest transform: 18.079 upper arm link Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 23.059 Oldest transform: 18.079 forearm link Broadcaster: /robot state publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 23.059 Oldest transform: 18.079 wrist_1_link Broadcaster: /robot_state_publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 23.059 Oldest transform: 18.079 $wrist_2_{link}$ Broadcaster: /robot state publisher Average rate: $50.\overline{201}$ Buffer length: 4.98 Most recent transform: 23.059 Oldest transform: 18.079 wrist_3_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 ee link tool0

view frames Result