Machine Learning in Graphs Node & Link Features

Acknowledgement: Jure Leskovec, Stanford University

Overview

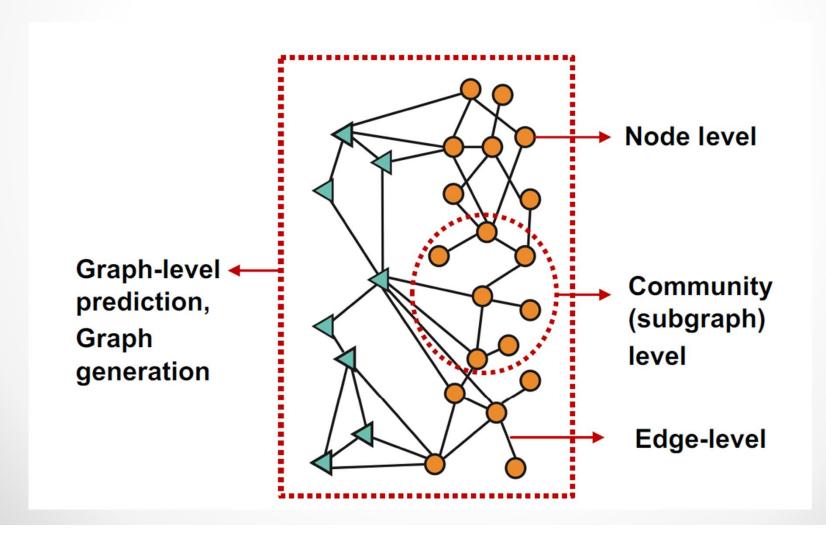
- Introduction
- Node-level Tasks and Features
- Link Prediction Task and Features

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Graph Machine Learning - Applications

Different types of Tasks

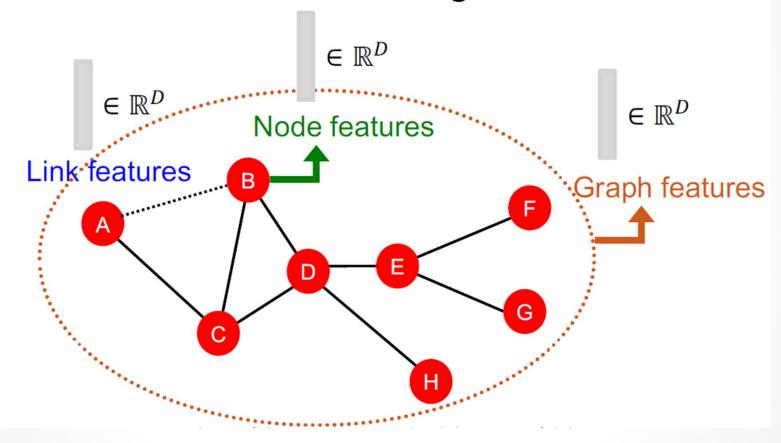


Classic Graph ML Tasks

- Node classification: Predict a property of a node
 - Example: Categorize online users / items
- Clustering: Detect if nodes form a community
 - Example: Social circle detection
- Link prediction: Predict whether there are missing links between two nodes
 - Example: Recommendation systems
- Graph classification: Categorize different graphs
 - Example: Molecule property prediction
- Other tasks:
 - Graph generation: Drug discovery
 - Graph evolution: Physical simulation
- Only some of these tasks are related to Social Network Analysis – focus of this course

Traditional ML Pipeline

- Design features for nodes/links/graphs
- Obtain features for all training data



Features can be of two types:

- 1) Attributes
- 2) Structural (Focus of this lecture)

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Traditional ML Pipeline

- Train an ML model:
 - Random forest
 - SVM
 - Neural network, etc.

$$\begin{array}{c|c} x_1 & \longrightarrow & y_1 \\ \vdots & \vdots & \vdots \\ x_N & \longrightarrow & y_N \end{array}$$

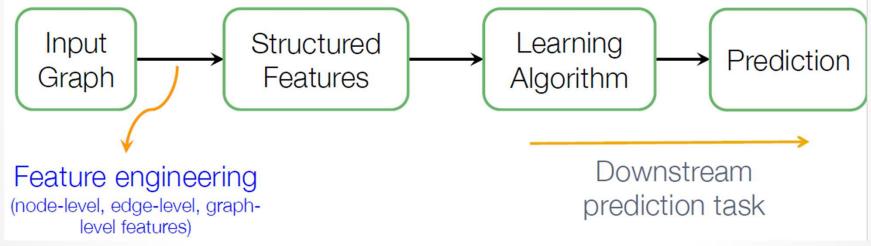
Apply the model:

 Given a new node/link/graph, obtain its features and make a prediction

$$x \rightarrow y$$

Traditional ML Pipeline for Graphs

Given an input graph, extract node, link and graph-level features, learn a model (SVM, neural network, etc.) that maps features to labels.



Machine Learning in Graphs

- Goal: Make predictions for a set of objects
- Design choices:
 - **Features:** d-dimensional vectors
 - Objects: Nodes, edges, sets of nodes, entire graphs
 - Objective function: What task are we aiming to solve?

Feature design:

- Using effective features over graphs is the key to achieving good test performance.
- Traditional ML pipeline uses hand-designed features.

For simplicity we focus on un-directed graphs

Machine Learning in Graphs

Machine learning in graphs:

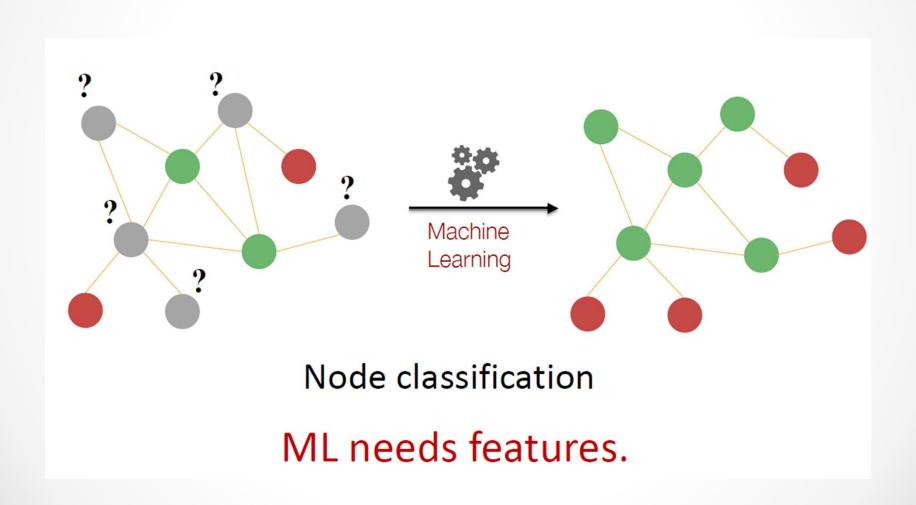
- ullet Given:G=(V,E)
- Learn a function: $f:V o\mathbb{R}$

How do we learn the function?

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Node-level Tasks



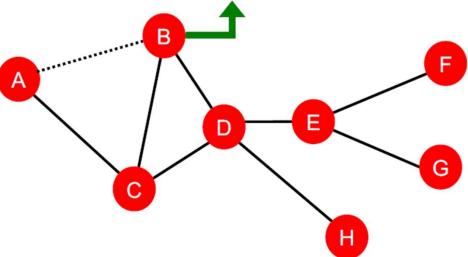
Node-level Features: Overview

Goal: Characterize the structure and position of a node in the network:

- Node degree
- Node centrality

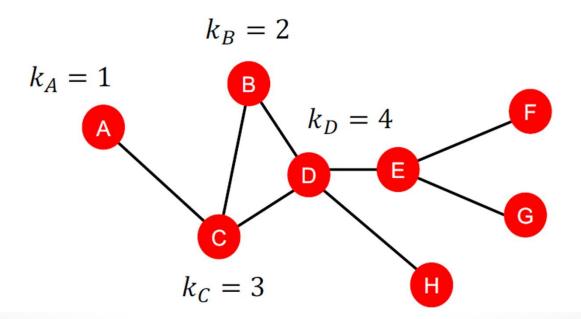
Clustering coefficient
 Node feature

Graphlets



Node Features: Node Degree

- The degree k_v of node v is the number of edges (neighboring nodes) the node has.
- Treats all neighboring nodes equally.



Node Features: Node Centrality

- Node degree counts the neighboring nodes without capturing their importance.
- Node centrality c_v takes the node importance in a graph into account
- Different ways to model importance:
 - Engienvector centrality
 - Betweenness centrality
 - Closeness centrality
 - and many others...

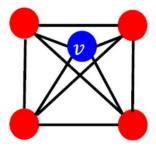
Clustering Coefficient

• Measures how connected v's neighboring nodes are:

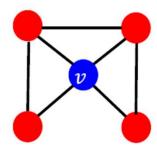
$$e_v = \frac{\#(\text{edges among neighboring nodes})}{\binom{k_v}{2}} \in [0,1]$$

#(node pairs among k_v neighboring nodes)

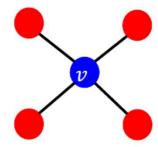
Examples:



$$e_{v} = 1$$



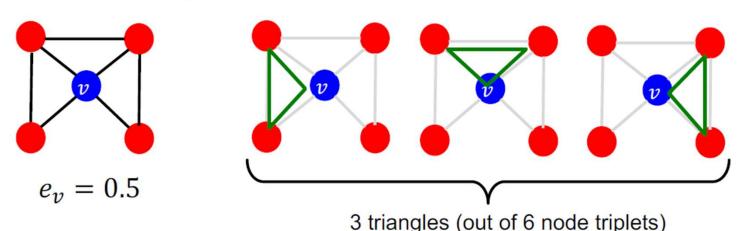
$$e_{\nu} = 0.5$$



$$e_v = 0$$

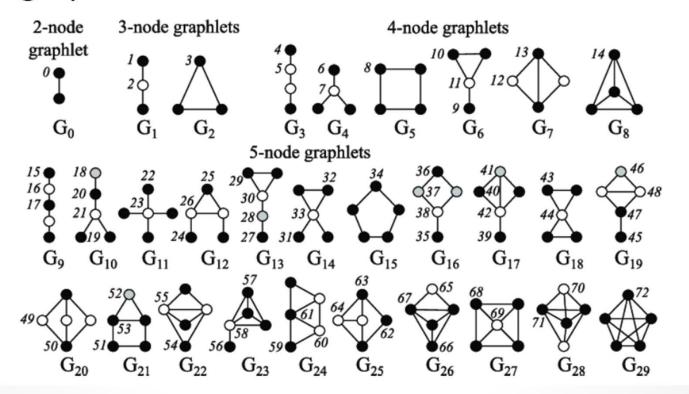
Social Networks have a lot of triangles

 Observation: Clustering coefficient counts the #(triangles) in the ego-network



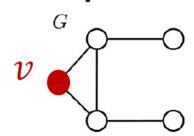
 We can generalize the above by counting #(pre-specified subgraphs, i.e., graphlets).

Graphlets: Rooted connected non-isomorphic subgraphs:

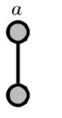


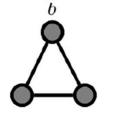
- Graphlet Degree Vector (GDV): Graphlet-base features for nodes
- Degree counts #(edges) that a node touches
- Clustering coefficient counts #(triangles) that a node touches.
- GDV counts #(graphlets) that a node touches

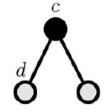
- Graphlet Degree Vector (GDV): A count vector of graphlets rooted at a given node.
- Example:



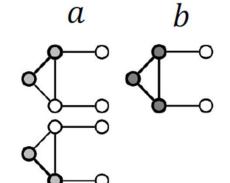
List of graphlets



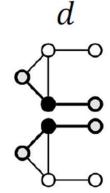




Graphlet instances:



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GDV of node v:

a, *b*, *c*, *d* [2,1,0,2]

- Considering graphlets on 2 to 5 nodes we get:
 - Vector of 73 coordinates is a signature of a node that describes the topology of node's neighborhood
 - Captures its interconnectivities out to a distance of 4 hops
- Graphlet degree vector provides a measure of a node's local network topology:
 - Comparing vectors of two nodes provides a more detailed measure of local topological similarity than node degrees or clustering coefficient.

Node Level Features: Summary

We have introduced different ways to obtain node features.

They can be categorized as:

- Importance-based features:
 - Node degree
 - Different node centrality measures
- Structure-based features:
 - Node degree
 - Clustering coefficient
 - Graphlet count vector

Importance-based Features

- Capture the importance of a node is in a graph
 - Node degree:
 - Simply counts the number of neighboring nodes
 - Node centrality:
 - Models importance of neighboring nodes in a graph
 - Different modeling choices: eigenvector centrality, betweenness centrality, closeness centrality
- Useful for predicting influential nodes in a graph
- Example:
 - Predicting celebrity users in a social network

Structure-based Features

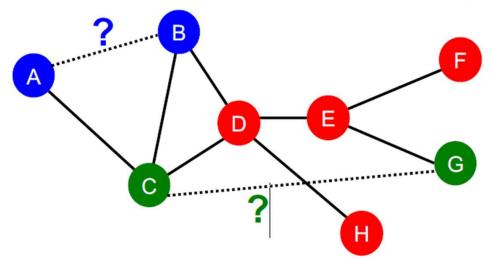
- Capture topological properties of local neighborhood around a node.
 - Node degree:
 - Counts the number of neighboring nodes
 - Clustering coefficient:
 - Measures how connected neighboring nodes are
 - Graphlet degree vector:
 - Counts the occurrences of different graphlets
- Useful for predicting a particular role a node plays in a graph
- Example:
 - Predicting protein functionality in a protein-protein interaction network.

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Link-Level Prediction Task

- The task is to predict new links based on existing links.
- At test time, all node pairs (no existing links)
 are ranked, and top K node pairs are predicted.
- The key is to design features for a pair of nodes.



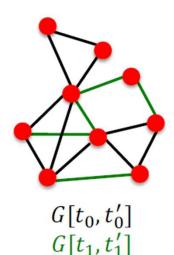
Just concatenating features of node 1 and node 2 will not be satisfactory - does not capture relationship between the 2 nodes

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Link Prediction as a Task

Two formulations of the link prediction task:

- 1) Links missing at random:
 - Remove a random set of links and then aim to predict them
- 2) Links over time:
 - Given $G[t_0, t'_0]$ a graph on edges up to time t'_0 , output a ranked list Lof links (not in $G[t_0, t'_0]$) that are predicted to appear in $G[t_1, t'_1]$



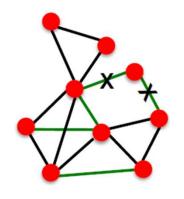
Evaluation:

- $n = |E_{new}|$: # new edges that appear during the test period $[t_1, t_1']$
- \blacksquare Take top n elements of L and count correct edges
- 1) Suitable for static networks (like Protein interaction networks)
- 2) Suitable for dynamic networks (like Social networks)

Link Prediction via Proximity

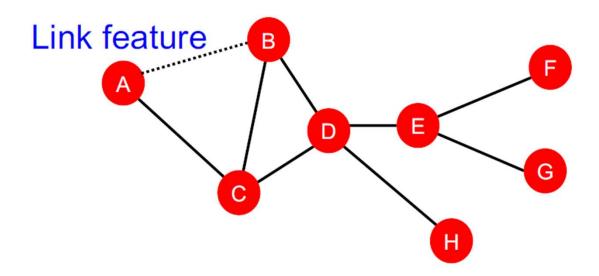
Methodology:

- For each pair of nodes (x,y) compute score c(x,y)
 - For example, c(x,y) could be the # of common neighbors of x and y
- Sort pairs (x,y) by the decreasing score c(x,y)
- Predict top n pairs as new links
- See which of these links actually appear in $G[t_1, t'_1]$



Link-Level Features: Overview

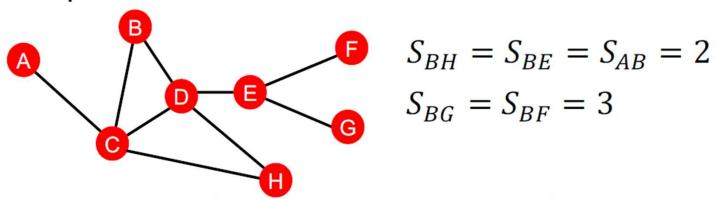
- Distance-based feature
- Local neighborhood overlap
- Global neighborhood overlap



Distance-based Features

Shortest-path distance between two nodes

Example:



- However, this does not capture the degree of neighborhood overlap:
 - Node pair (B, H) has 2 shared neighboring nodes, while pairs (B, E) and (A, B) only have 1 such node.

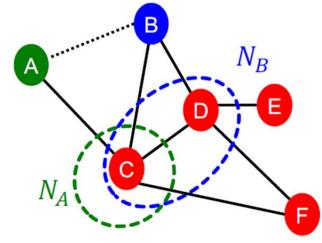
Local Neighborhood Overlap

Captures # neighboring nodes shared between two nodes v_1 and v_2 :

- **Common neighbors:** $|N(v_1) \cap N(v_2)|$
 - Example: $|N(A) \cap N(B)| = |\{C\}| = 1$
- Jaccard's coefficient: $\frac{|N(v_1) \cap N(v_2)|}{|N(v_1) \cup N(v_2)|}$
 - Example: $\frac{|N(A) \cap N(B)|}{|N(A) \cup N(B)|} = \frac{|\{C\}|}{|\{C,D\}|} = \frac{1}{2}$
- Adamic-Adar index:

$$\sum_{u \in N(v_1) \cap N(v_2)} \frac{1}{\log(k_u)}$$

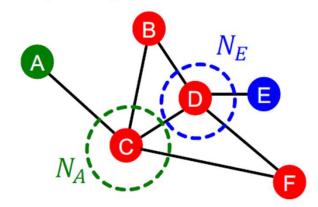
• Example: $\frac{1}{\log(k_C)} = \frac{1}{\log 4}$



- 1/log(Sum of degree of common neighbors)
- Importance of a neighbor decrease with increase in its degree
- Works well in Social Networks

Global Neighborhood Overlap

- Limitation of local neighborhood features:
 - Metric is always zero if the two nodes do not have any neighbors in common.



$$N_A \cap N_E = \phi$$
$$|N_A \cap N_E| = 0$$

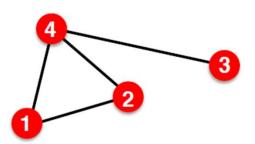
- However, the two nodes may still potentially be connected in the future.
- Global neighborhood overlap metrics resolve the limitation by considering the entire graph.

Global Neighborhood Overlap

- Katz index: count the number of paths of all lengths between a given pair of nodes.
- Q: How to compute #paths between two nodes?
- Use powers of the graph adjacency matrix!

Power of Adjacency Matrices

- Computing #paths between two nodes
 - Recall: $A_{uv} = 1$ if $u \in N(v)$
 - Let $oldsymbol{P}_{uv}^{(K)} = ext{\#paths of length } oldsymbol{K}$ between $oldsymbol{u}$ and $oldsymbol{v}$
 - We will show $P^{(K)} = A^k$
 - $P_{uv}^{(1)} = \text{#paths of length 1 (direct neighborhood)}$ between u and $v = A_{uv}$ $P_{12}^{(1)} = A_{12}$



$$A = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$$

Power of Adjacency Matrices

- How to compute $P_{uv}^{(2)}$?
 - Step 1: Compute #paths of length 1 between each of u's neighbor and v
 - Step 2: Sum up these #paths across u's neighbors

$$P_{uv}^{(2)} = \sum_{i} A_{ui} * P_{iv}^{(1)} = \sum_{i} A_{ui} * A_{iv} = A_{uv}^{2}$$

Node 1's neighbors

#paths of length 1 between Node 1's neighbors and Node 2 $P_{12}^{(2)} = A_{12}^2$

$$A^2 = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} \times \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 2 & 1 & 1 & 1 \\ 1 & 2 & 1 & 1 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & 3 \end{pmatrix}$$

Katz Index

- Katz index: count the number of paths of all lengths between a pair of nodes.
- How to compute #paths between two nodes?
- Use adjacency matrix powers!
 - A_{uv} specifies #paths of length 1 (direct neighborhood) between u and v.
 - A_{uv}^2 specifies #paths of length 2 (neighbor of neighbor) between u and v.
 - And, A_{uv}^{l} specifies #paths of length l.

Katz Index

Katz index between v_1 and v_2 is calculated as Sum over all path lengths

$$S_{v_1v_2} = \sum_{l=1}^{\infty} \beta^l A_{v_1v_2}^l$$
 #paths of length l between v_1 and v_2 $0 < \beta < 1$: discount factor

Katz index matrix is computed in closed-form:

$$S = \sum_{i=1}^{\infty} \beta^i A^i = (I - \beta A)^{-1} - I,$$

$$= \sum_{i=0}^{\infty} \beta^i A^i$$
by geometric series of matrices

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Link-Level Features: Summary

Distance-based features:

 Uses the shortest path length between two nodes but does not capture how neighborhood overlaps.

Local neighborhood overlap:

- Captures how many neighboring nodes are shared by two nodes.
- Becomes zero when no neighbor nodes are shared.

Global neighborhood overlap:

- Uses global graph structure to score two nodes.
- Katz index counts #paths of all lengths between two nodes.

References

Social Network Analysis Tanmoy Chakraborty. Chapter 9