

# CS425: Computer Networks

## Assignment 4: Routing Protocols (DVR and LSR)

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### Objective

Implement Distance Vector Routing (DVR) and Link State Routing (LSR) algorithms in C++ by reading an adjacency-matrix representation of a network and producing per-node routing tables.

### Repository Structure

```
.
routing_sim.cpp      % C++ source implementing DVR and LSR
Makefile             % (optional) build rules
input1.txt           % sample adjacency matrix input
input2.txt           % sample adjacency matrix input
input3.txt           % sample adjacency matrix input
input4.txt           % sample adjacency matrix input
A4.pdf               % problem statement
README.tex           % This LaTeX documentation
```

### Prerequisites

- C++17-compatible compiler (e.g. g++)
- Standard C++ library (no external dependencies)
- Unix-style shell (e.g. Bash) or equivalent

# Compilation

## Using Makefile

make

## Manual

```
g++ -std=c++17 routing_sim.cpp -o routing_sim
```

or

```
g++ routing_sim.cpp -o routing_sim
```

## Usage

```
./routing_sim <input_file>
```

**Example:**

```
./routing_sim inputfile.txt
```

## Input Format

1. First line: integer  $n$ , number of nodes.
2. Next  $n$  lines: each contains  $n$  space-separated integers (the adjacency matrix):
  - Off-diagonal 0 indicates no link (treated as infinite cost = 9999).
  - Value 9999 explicitly represents infinite cost.
  - Diagonal entries must be 0.

## Output Format

### Distance Vector Routing (DVR)

```
--- Distance Vector Routing Simulation ---
--- DVR iteration k ---
Node i Routing Table:
Dest    Cost    Next Hop
...
--- DVR Final Tables ---
```

### Link State Routing (LSR)

```
--- Link State Routing Simulation ---
Instructor: Adithya Vadapalli TA Incharge: Rishit and Yugul
CS425: Computer Networks A4: Routing Protocols (DVR and LSR)
Node i Routing Table:
```

Dest	Cost	Next Hop
...		

## Algorithm Overview

### Distance Vector Routing

1. Initialize each node's cost vector with direct link costs and next-hop pointers.
2. Repeatedly exchange vectors with neighbors and update via Bellman-Ford until convergence:

*if*  $dist_u[v] + dist_v[d] < dist_u[d]$  *then*  $dist_u[d] = dist_u[v] + dist_v[d]$ ,  $nextHop_u[d] = nextHop_u[v]$ .

3. Terminate when no changes occur.

### Link State Routing

1. Each node knows the full topology (adjacency matrix).
2. Run Dijkstra's algorithm from each node to compute shortest paths.
3. Backtrack predecessor array to determine first-hop next-hops.

## Code Workflow

### 1. Reading the Graph

- `readGraph(const string&)` opens the input file, reads  $n$ , then the  $n \times n$  matrix.
- Off-diagonal zeros ( $i \neq j$ ) are converted to `INF = 9999`; diagonal stays 0.

### 2. Distance Vector Routing (`simulateDVR`)

- Initialize `dist[i][j]` to direct costs, and `nextHop[i][j] = j` when a link exists.
- Iteratively "exchange" tables: for each node  $u$  and neighbor  $v$ , relax

$$dist_u[d] = \min(dist_u[d], dist_u[v] + dist_v[d]),$$

updating `nextHop_u[d]` accordingly.

- Repeat until no update; print tables each iteration and final.

### 3. Link State Routing (`simulateLSR`)

- For each source node  $s$ :
  1. Initialize `dist[s] = 0`, others = `INF`; `prev[] = -1`.
  2. Run standard Dijkstra's algorithm using the full adjacency matrix.

3. After computing `dist[]` and `prev[]`, backtrack from each destination  $d$  to  $s$  to find the first hop.
- Print routing table for each  $s$ .

#### 4. Main Function

- Parses command-line argument for input file.
- Calls `readGraph`, then `simulateDVR` and `simulateLSR`.