

## Cholesky Factorization

Symmetric positive definite matrix:-

Recall  $A \in \mathbb{R}^{m \times m}$  is symmetric  
if  $A = A^T$

Such a matrix also satisfies

$$\text{for } \underline{x}, \underline{y} \in \mathbb{R}^m \quad \underline{x}^T A \underline{y} = (\underline{x}^T A \underline{y})^T \\ = \underline{y}^T A^T \underline{x}$$

$$\boxed{(\underline{x}, A \underline{y}) = (A \underline{x}, \underline{y})}$$

If  $(\underline{x}, A \underline{y}) = (A \underline{x}, \underline{y})$  for all  
 $\underline{x}, \underline{y} \in \mathbb{R}^m$

then  $A = A^T$

→ 'A' is said to be symmetric  
positive definite matrix if in addition  
to  $A = A^T$ ,  $\underline{x}^T A \underline{x} > 0 \quad \forall \text{ non-zero } \underline{x} \in \mathbb{R}^m$

Note:- If  $A \in \mathbb{R}^{m \times m}$  is symmetric positive definite (S.P.D) and  $X \in \mathbb{R}^{m \times n}$  ( $m \geq n$ ) ( $X$  is full rank) then the matrix  $X^T A X$  is S.P.D

Proof:-  $\Rightarrow (X^T A X)^T = \underset{n \times m}{X^T} \underset{m \times m}{A} \underset{m \times n}{X} = \underset{n \times m}{X^T} \underset{m \times m}{A} \underset{m \times n}{X}$

A non-zero  $y \in \mathbb{R}^n, y \neq 0$

$$y^T (X^T A X) y = (X y)^T A (X y) > 0$$

(Since  $X y = 0$  only for  $y = 0$  and  $A$  is S.P.D)

if choose  $X$  such that each column of  $X$  has 1 in each column and zeros elsewhere, we can express any

$n \times n$  principal submatrix of  $A$  to be of form  $X^T A X$  for this choice of  $X$

(i) For a S.P.D,  $a_{ii} > 0$  for all  $i$   
( $a_{ii}$  is diagonal entry of the matrix  $A$ )

(ii) Eigenvalues of S.P.D matrix are also positive.

$$A\underline{u} = \lambda \underline{u} \quad \text{for } \underline{u} \neq 0 \quad (\lambda \text{ is eigenvalue, } \underline{u} \text{ is eigenvector})$$

We have  $\underline{x}^T A \underline{x} > 0$  if  $\underline{x} \neq 0$

If I choose my  $\underline{x}$  to be the eigenvector

$$\begin{aligned} \underline{u}^T A \underline{u} &> 0 \\ \Rightarrow \underline{u}^T (\lambda \underline{u}) &> 0 \\ \Rightarrow \boxed{\lambda > 0} \end{aligned}$$

(iii) elements with largest modulus lie on the main diagonal!

\* Symmetric Gaussian Elimination

$$A = \begin{bmatrix} 1 & \omega^T \\ \omega & K \end{bmatrix}$$

$$\underline{L}_1 \underline{A} = \begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{K} - \underline{\omega} \underline{\omega}^T \end{bmatrix} \underline{W}$$

Gaussian elimination would continue by zeroing out second column and so on!

$$\underline{L}_1 \underline{A} = \underline{W}$$

$$\underline{A} = \underline{L}_1^{-1} \underline{W}$$

$$= \begin{bmatrix} 1 & \underline{0}^T \\ \underline{\omega} & \underline{I} \end{bmatrix} \begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{K} - \underline{\omega} \underline{\omega}^T \end{bmatrix}$$

In order to maintain symmetry Cholesky factorization zeros out first row to match zeros introduced in first column.

$$\underline{L}_1 \underline{A} \underline{U}_1 = \begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{K} - \underline{\omega} \underline{\omega}^T \end{bmatrix} \underline{U}_1 = \begin{bmatrix} 1 & \underline{0}^T \\ 0 & \underline{K} - \underline{\omega} \underline{\omega}^T \end{bmatrix}$$

$\underbrace{\begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{K} - \underline{\omega} \underline{\omega}^T \end{bmatrix}}_{\underline{L}_1 \underline{A}}$

$$\begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{K} - \underline{\omega}\underline{\omega}^T \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & \underline{0}^T \\ 0 & \underline{K} - \underline{\omega}\underline{\omega}^T \end{bmatrix}}_{\underline{U}} \underbrace{\begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{I} \end{bmatrix}}_{\underline{U}_1^{-1}}$$

$L_1 A =$

$$\underline{A} = \begin{bmatrix} 1 & \underline{\omega}^T \\ \underline{\omega} & \underline{K} \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} 1 & \underline{0}^T \\ \underline{\omega} & \underline{I} \end{bmatrix} \begin{bmatrix} 1 & \underline{0}^T \\ 0 & \underline{K} - \underline{\omega}\underline{\omega}^T \end{bmatrix} \begin{bmatrix} 1 & \underline{\omega}^T \\ 0 & \underline{I} \end{bmatrix}}$$

The idea behind Cholesky factorization is to continue this process, zeroing columns and rows of  $\underline{A}$  symmetrically until  $\underline{A}$  is reduced to an identity matrix!

\* Cholesky Factorization!

Let us consider  $a_{11} \neq 0, a_{11} > 0$   
 $\alpha = \sqrt{a_{11}}$

$$\begin{aligned}
 \underline{A} &= \begin{bmatrix} a_{11} & \underline{\omega}^T \\ \underline{\omega} & \underline{K} \end{bmatrix} \\
 &= \underbrace{\begin{bmatrix} \alpha & \underline{0}^T \\ \frac{1}{\alpha} \underline{\omega} & \underline{I} \end{bmatrix}}_{\underline{R}_1^T} \underbrace{\begin{bmatrix} 1 & \underline{0}^T \\ \underline{0} & \underline{K} - \frac{1}{\alpha} \underline{\omega} \underline{\omega}^T \end{bmatrix}}_{\underline{A}_1} \underbrace{\begin{bmatrix} \alpha & \frac{1}{\alpha} \underline{\omega}^T \\ \underline{0} & \underline{I} \end{bmatrix}}_{\underline{R}_1}
 \end{aligned}$$

$$\underline{A} = \underline{R}_1^T \underline{A}_1 \underline{R}_1$$

If  $\left( \underline{K} - \frac{1}{\alpha} \underline{\omega} \underline{\omega}^T \right)_{11} > 0$ , we can  
again factorize  $\underline{A}_1 = \underline{R}_2^T \underline{A}_2 \underline{R}_2$

we can repeat this process,

$$\underline{A} = \underbrace{\underline{R}_1^T \underline{R}_2^T \dots \underline{R}_m^T}_{\underline{R}^T} \underline{I} \underbrace{\underline{R}_m \dots \underline{R}_2 \underline{R}_1}_{\underline{R}}$$

We get factorization of the form

$$\underline{A} = \underline{R}^T \underline{R} \quad \text{where } \underline{R} \text{ is upper triangular and } r_{jj} > 0$$

Note:- How do we know (1,1) entry of  $K - \frac{1}{a_{11}} \underline{w} \underline{w}^T$  is positive?

Since  $A$  is symmetric positive definite matrix  $K - \frac{1}{a_{11}} \underline{w} \underline{w}^T$  is lower right principal submatrix of  $\underbrace{R_1^{-T} A R_1^{-1}}_{(S.P.D.)}$

$$\underline{A} = \underline{R}_1^T \underline{A}_1 \underline{R}_1$$

$$\underline{A}_1 = \underline{R}_1^{-T} \underline{A} \underline{R}_1^{-1}$$

By induction, the same argument shows that all matrices  $A_j$  that appear during factorization are S.P.D and this process does not break down!

Thm:- Every S.P.D matrix  $\underline{A} \in \mathbb{R}^{n \times n}$  has a unique Cholesky factorization  $\underline{A} = \underline{R}^T \underline{R}, r_{ij} \geq 0$

Algo

$$\underline{R} = \underline{A}$$

for  $k = 1:m$   
for  $j = k+1:m$

$$R(j, j:m) = R(j, j:m)$$

end

$$- \frac{R(k, k:m)}{R(k, k)}$$

$$R(k, k:m) = \frac{R(k, k:m)}{\sqrt{R(k, k)}}$$

end

The operation count of Cholesky factorization is  $\sim \frac{1}{3} m^3$

Thm:- Let  $\underline{A} \in \mathbb{R}^{m \times m}$  is S.P.D for  $\epsilon m$  sufficiently small, Cholesky algorithm is guaranteed to run to completion  
i.e no  $r_{kk} \leq 0$  will arise,



and generates  $\tilde{R}$  satisfies

$$\tilde{R}^T \tilde{R} = A + \delta A; \quad \frac{\|\delta A\|}{\|A\|} = O(\epsilon_m)$$

for  $\delta A \in \mathbb{R}^{m \times m}$

If  $A$  is ill-conditioned  $\tilde{R}$  will generally not be close to  $R$ , at best we can have

$$\frac{\|\tilde{R} - R\|}{\|R\|} = O(K(A) \epsilon_m)$$

But product  $\tilde{R}^T \tilde{R}$  is much more accurate!

Solving  $Ax = b$  using Cholesky if  $A$  is S.P.D is the standard way!