

# Assignment 4

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## Question 1

- Predicted outputs as a function of inputs,

$$\begin{aligned}h_1 &= \text{sigmoid}(w_{21}^1 x_2 + B) \\h_2 &= \text{sigmoid}(w_{12}^1 x_1 + w_{22}^1 x_2 + B) \\h_3 &= \text{ReLU}(w_{23}^1 x_2 + w_{33}^1 x_3 + B) \\h_4 &= \text{ReLU}(w_{24}^1 x_2 + B) \\\hat{y}_1 &= w_{11}^2 h_1 + w_{31}^2 h_3 \\&= w_{11}^2 \text{sigmoid}(w_{21}^1 x_2 + B) + w_{31} \text{ReLU}(w_{23}^1 x_2 + w_{33}^1 x_3 + B) \\\hat{y}_2 &= w_{22}^2 h_2 + w_{42}^2 h_4 \\&= w_{22}^2 \text{sigmoid}(w_{12}^1 x_1 + w_{22}^1 x_2 + B) + w_{42}^2 \text{ReLU}(w_{24}^1 x_2 + B)\end{aligned}$$

- After one forward pass,

$$\begin{aligned}h_1 &= \text{sigmoid}(w_{21}^1 x_2 + B) = \text{sigmoid}(0.25 * 0.1 + 0.6) \\&= \text{sigmoid}(0.625) = 0.6513 \\h_2 &= \text{sigmoid}(w_{12}^1 x_1 + w_{22}^1 x_2 + B) = \text{sigmoid}(0.55 * 0.15 + 0.6) \\&= \text{sigmoid}(0.7025) = 0.6687 \\h_3 &= \text{ReLU}(w_{23}^1 x_2 + w_{33}^1 x_3 + B) = \text{ReLU}(0.1 * 0.1 + 0.6 * 0.05 + 0.6) \\&= \text{ReLU}(0.64) = 0.64 \\h_4 &= \text{ReLU}(w_{24}^1 x_2 + B) = \text{ReLU}(0.05 * 0.1 + 0.6) \\&= \text{ReLU}(0.605) = 0.605 \\\hat{y}_1 &= w_{11}^2 h_1 + w_{31}^2 h_3 = 0.7 * 0.6513 + 0.33 * 0.64 = 0.6671 \\\hat{y}_2 &= w_{22}^2 h_2 + w_{42}^2 h_4 = 0.45 * 0.6687 + 0.8 * 0.605 = 0.7849\end{aligned}$$

- Mean-squared error,

$$\begin{aligned}mse &= \frac{1}{2}(y_1 - \hat{y}_1)^2 + \frac{1}{2}(y_2 - \hat{y}_2)^2 \\&= \frac{1}{2}(0.31 - 0.6671)^2 + \frac{1}{2}(0.27 - 0.7849)^2 = 0.1963\end{aligned}$$

- One pass of backpropagation,

$$L(loss) = mse = \frac{1}{2}(0.31 - \hat{y}_1)^2 + \frac{1}{2}(0.27 - \hat{y}_2)^2$$

$$w_{31}^2 = w_{31}^2 - \alpha \frac{\partial L}{\partial w_{31}^2}$$

$$w_{21}^1 = w_{21}^1 - \alpha \frac{\partial L}{\partial w_{21}^1}$$

$$\frac{\partial L}{\partial w_{31}^2} = \frac{\partial L}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial w_{31}^2} = (0.6671 - 0.31)(0.64) = 0.2285$$

$$\frac{\partial L}{\partial w_{21}^1} = \frac{\partial \hat{y}_2}{\partial \hat{y}_1} \frac{\partial \hat{y}_1}{\partial h_1} \frac{\partial h_1}{\partial w_{21}^1} = (0.6671 - 0.31)(0.7)(0.02271) = 0.0056$$

$$\therefore w_{31}^2 = 0.33 - 0.5 * 0.2285 = 0.2157$$

$$w_{21}^1 = 0.25 - 0.5 * 0.0056 = 0.2472$$

## Question 2

$$f(x_1, x_2) = \tanh\left(\frac{x_1}{x_2}\right) + \text{sigmoid}(x_1)$$

The above function can be considered as neural network with the type,

Input Layer:  $x_1, x_2$

Hidden Layer:  $h_1, h_2$ , where  $h_1 = x_1/x_2, h_2 = x_1$

Output Layer:  $y$ , where  $y = \phi_1(h_1) + \phi_2(h_2)$ ,  $\phi_1(x) = \tanh(x)$ ,  $\phi_2(x) = \text{sigmoid}(x)$

### Reverse mode automatic differentiation

1. Derivative of output node with respect to the nearest layer:

$$\frac{\partial y}{\partial \phi_1(h_1)} = 1, \frac{\partial y}{\partial \phi_2(h_2)} = 1 \text{ as the output node activation function is the identity function}$$

2. Derivative of activation function with respect to corresponding node:

$$\begin{aligned} \frac{\partial \phi_1(h_1)}{\partial h_1} &= \frac{\partial \tanh(h_1)}{\partial h_1} \\ \frac{\partial \phi_2(h_2)}{\partial h_2} &= \frac{\partial \text{sigmoid}(h_2)}{\partial h_2} \end{aligned}$$

3. Derivative of hidden layers with respect to input:

$$\begin{aligned} \frac{\partial h_1}{\partial x_1} &= \frac{1}{x_2}, \frac{\partial h_1}{\partial x_2} = -\frac{x_1}{x_2^2} \\ \frac{\partial h_2}{\partial x_1} &= 1, \frac{\partial h_2}{\partial x_2} = 0 \end{aligned}$$

The final derivative can be computed by

$$\begin{aligned} \frac{\partial f(x_1, x_2)}{\partial x_1} &= \frac{\partial y}{\partial x_1} = \frac{\partial y}{\partial \phi_1(h_1)} \cdot \frac{\partial \phi_1(h_1)}{\partial h_1} \cdot \frac{\partial h_1}{\partial x_1} + \frac{\partial y}{\partial \phi_2(h_2)} \cdot \frac{\partial \phi_2(h_2)}{\partial h_2} \cdot \frac{\partial h_2}{\partial x_1} \\ \frac{\partial f(x_1, x_2)}{\partial x_2} &= \frac{\partial y}{\partial x_2} = \frac{\partial y}{\partial \phi_1(h_1)} \cdot \frac{\partial \phi_1(h_1)}{\partial h_1} \cdot \frac{\partial h_1}{\partial x_2} \left( \text{as } \frac{\partial h_2}{\partial x_2} = 0 \right) \end{aligned}$$