

TWO PERSON BARGAINING PROBLEM

- Two players have the possibility of concluding a mutually beneficial agreement
- There is a conflict about which agreement to conclude
- No agreement may be imposed without the approval of the players

The solution should depend only on

- the payoffs they would expect if the negotiations were to fail
- the payoffs that are feasible in the process of negotiation

APPLICATIONS OF THE BARGAINING PROBLEM

1. Management - Labour arbitration
 2. International bilateral relations
 3. Duopoly markets
 4. Property settlement disputes
 5. Supply chain contracts
- ⋮

THE NASH BARGAINING PROBLEM

$$(F, \vartheta)$$

- feasible set $\subset \mathbb{R}^2$ - closed and convex

- F : feasible set $\subseteq \mathbb{R}^2$ - closed and convex
- $v = (v_1, v_2) \in \mathbb{R}^2$ Disagreement point
aka Default point; status-quo point
solution that will be implemented in case no agreement is reached
- $F \cap \{(x_1, x_2) \in \mathbb{R}^2 : x_1 \geq v_1; x_2 \geq v_2\}$
is non-empty and bounded.

Convexity of F

If $(x_1, x_2), (y_1, y_2) \in F$, then, for any $0 \leq \lambda \leq 1$,

$$\lambda(x_1, x_2) + (1-\lambda)(y_1, y_2) \in F$$

This is a natural requirement since the convex combination can be achieved by the correlated strategy

$$((x_1, x_2) : \lambda ; (y_1, y_2) : (1-\lambda))$$

F is closed

The limit of a sequence of feasible allocations is also feasible.

It will be odd if the limit lies outside the feasible set.

$$F \cap \{(x_1, x_2) \in \mathbb{R}^2 : x_1 \geq v_1; x_2 \geq v_2\}$$

is non-empty and bounded.

In this manner \exists at least one feasible

this means \exists at least one feasible allocation that is as good as (v_1, v_2) .

further, unbounded gains over (v_1, v_2) are not feasible.

Typical choices for F

$$F = \{(u_1(\alpha), u_2(\alpha)) : \alpha \in \Delta(S_1 \times S_2)\}$$

$$F = \{(u_1(\alpha), u_2(\alpha)) : \alpha \in \Delta(S_1 \times S_2) \text{ and } \alpha \text{ is IR}\}$$

$$F = \{(u_1(\alpha), u_2(\alpha)) : \alpha \text{ is a correlated equilibrium}\}$$

⋮

Disagreement Point: Typical choices

v_i^* = maxmin value of player i
(security value) (no regret value)

v_i^* = utility of player i under a
focal Nash equilibrium

v_i^* = utility of player i under a
rational threat equilibrium

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The Nash Axioms

Nash brilliantly proposed five axioms that a solution to the bargaining problem should ideally satisfy and showed that such a solution exists and is unique.

1. Individual Rationality
2. Strong Efficiency
3. Scale Co-Variance
4. Independence of Irrelevant Alternatives
5. Symmetry

Suppose a candidate solution is given by

$$(f_1(F, v), f_2(F, v)) \in \mathbb{R}^2$$

1. Individual Rationality

$$f_1(F, v) \geq v_1$$

$$f_2(F, v) \geq v_2$$

2. Strong Efficiency Axiom

$(x_1, x_2) \in F$ is strongly (Pareto) efficient if $\nexists y = (y_1, y_2) \in F \ni$

" \sim " \sim . and

if $\nexists y = (y_1, y_2) \in F$ such that

$y_1 > x_1 ; y_2 > x_2$; and

$y_1 > x_1$ or $y_2 > x_2$ or both

strong efficiency axiom says that $f(F, v) \in F$ and is strongly efficient.

This means there exists no other feasible solution that is strictly better for one player and not worse for the other player.

Example Suppose $f(F, v) = (4, 4)$

It should not happen that

$(5, 5) \in F$

$(5, 4) \in F$

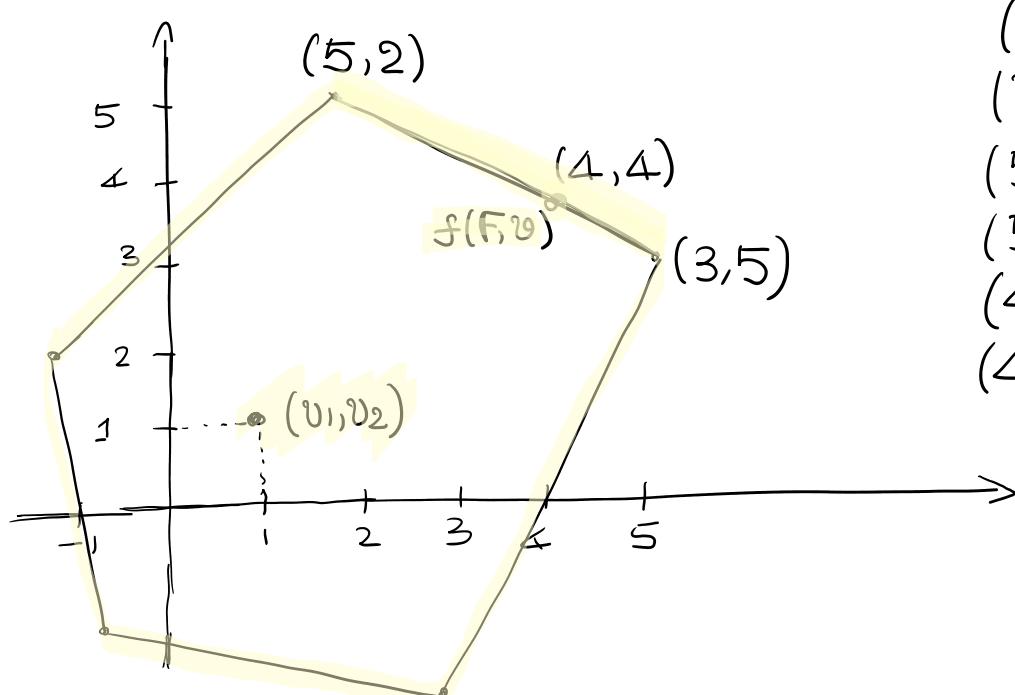
$(4, 5) \in F$

on the other hand, it can happen that

$(5, 2) \in F$

$(3, 5) \in F$

$(3, 3) \in F$



$(5, 2) \in F$

$(3, 5) \in F$

$(5, 5) \notin F$

$(5, 4) \notin F$

$(4, 5) \notin F$

$(4, 4) \geq (1, 1)$

3. Scale Co-Variance

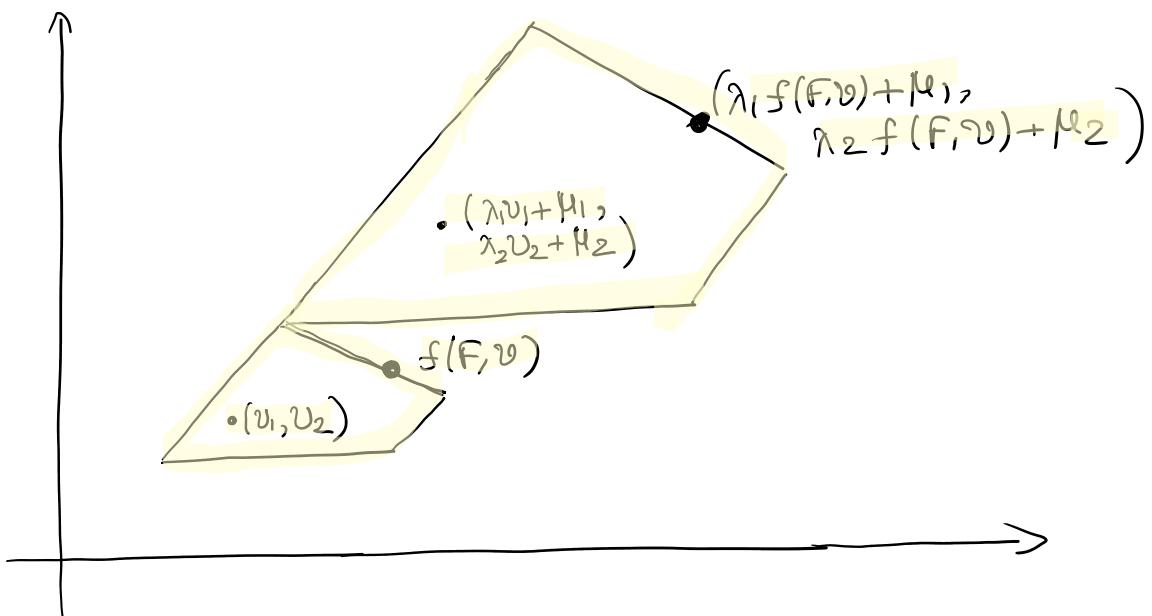
for any $\lambda_1, \lambda_2, \mu_1, \mu_2 \in \mathbb{R}$ with $\lambda_1 > 0, \lambda_2 > 0$,
define

$$\mathcal{G} = \left\{ (\lambda_1 x_1 + \mu_1, \lambda_2 x_2 + \mu_2) : (x_1, x_2) \in F \right\}$$

$$\omega = (\lambda_1 v_1 + \mu_1, \lambda_2 v_2 + \mu_2)$$

then the solution will also follow the same scaling:

$$f(\mathcal{G}, \omega) = (\lambda_1 f_1(F, v) + \mu_1, \lambda_2 f_2(F, v) + \mu_2)$$



4) Independence of Irrelevant Alternatives

If \mathcal{G} is closed and convex, then

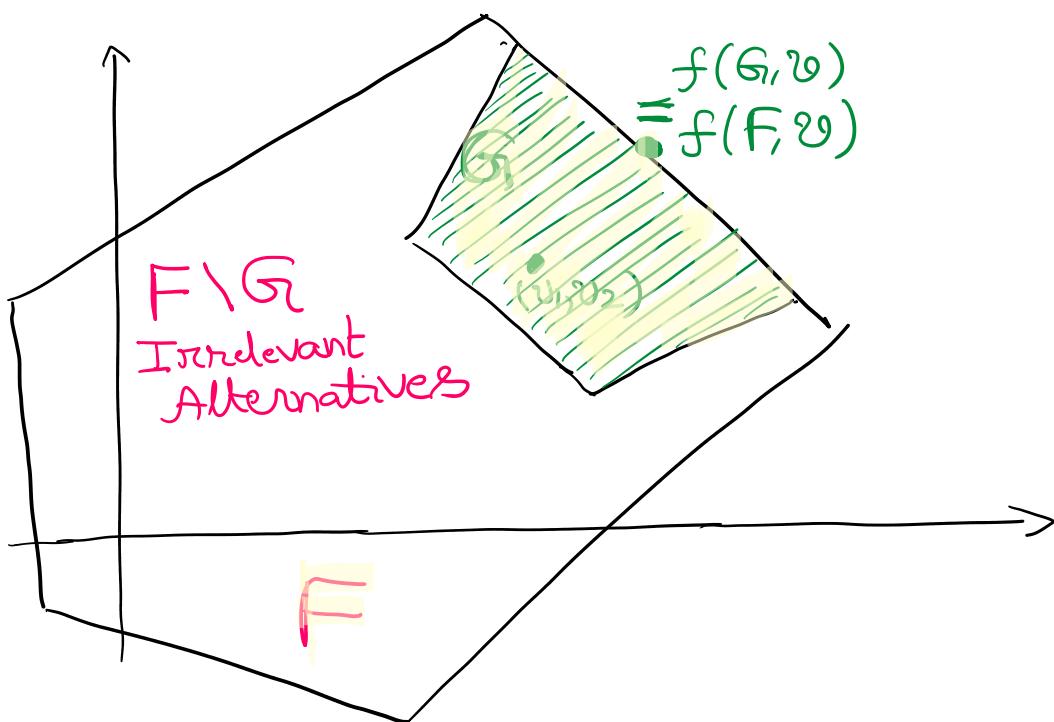
$$\mathcal{G} \subseteq F \text{ and } f(F, v) \in \mathcal{G}$$

(if $v \in F$)

$$G \subseteq F \text{ and } f(t, v) \in G$$

$$\Rightarrow f(G, v) = f(F, v)$$

if two persons, after careful negotiations are able to come up with a "sound" shortlisting of feasible alternatives, then they don't have to look beyond this subset for the final solution.



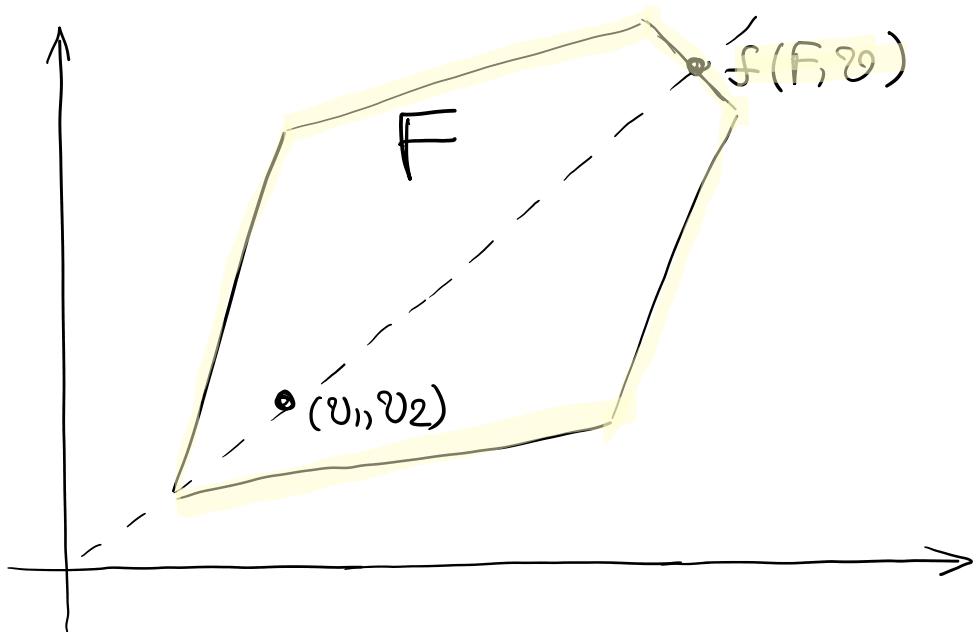
5. Symmetry

$$\left\{ (x_2, x_1) : (x_1, x_2) \in F \right\} = F \quad \text{and} \quad v_1 = v_2$$

$$\Rightarrow f_1(F, v) = f_2(F, v)$$

If the feasible set is "symmetric" and $v_1 = v_2$, then the solution will also be symmetric.

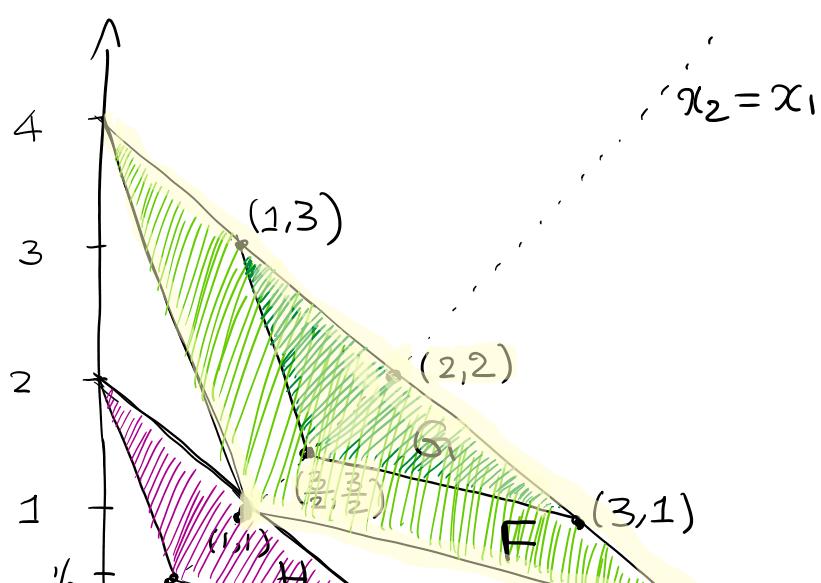
symmetric.

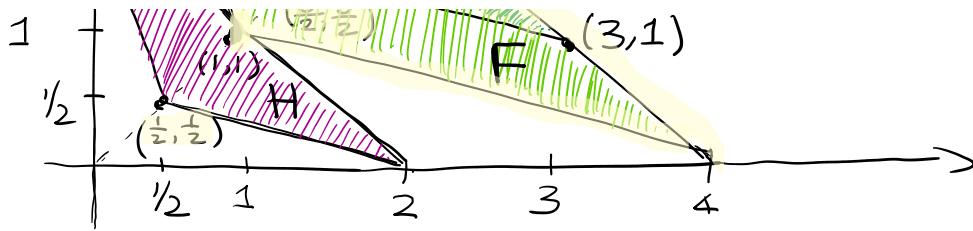


The Nash Bargaining Solution

There exists a unique function f that satisfies axioms (1), (2), (3), (4), (5), given by

$$f(F, v) \in \operatorname{argmax}_{\substack{(x_1, x_2) \in F \\ x_1 \geq v_1 \\ x_2 \geq v_2}} (x_1 - v_1)(x_2 - v_2)$$





$F = \text{closed, convex set} - \text{convex hull}$
 enclosing points $(1,1), (4,0), (0,4)$

$$v = (1,1)$$

$$f(F, v) = (2,2) \quad \text{IIR, Efficiency, Symmetry}$$

Suppose $\lambda_1 = \lambda_2 = \frac{1}{2}$; $\mu_1 = \mu_2 = 1$
 Then we get the space (convex and closed):
 $G = \left\{ (\lambda_1 x_1 + \mu_1, \lambda_2 x_2 + \mu_2) : (x_1, x_2) \in F \right\}$

G is the convex hull enclosed by the points
 $(\frac{3}{2}, \frac{3}{2}), (1,3)$, and $(3,1)$.

Scaled default point $w = (\frac{3}{2}, \frac{3}{2})$.

By scale covariance, we get

$$f(G, w) = (2,2)$$

This can also be derived from IIR since
 $G \subseteq F$ and $f(F, v) \in G$.

Suppose $\lambda_1 = \lambda_2 = \frac{1}{2}$ and $\mu_1 = \mu_2 = 0$, we get
 H which is the convex hull enclosed by
 $(\frac{1}{2}, \frac{1}{2}), (2,0)$, and $(0,2)$. Now

$$f(H, (\frac{1}{2}, \frac{1}{2})) = (1,1) \text{ by scale covariance.}$$