

Stability of Algorithms:-

- ① Desirable :- Exact solutions to numerical problems
- ② Reality :- Problems are continuous while computer arithmetic is discrete
- ③ Stability tells us what it means to get the best answer even if this is not the exact answer!

Algorithm:-

An abstract way to think about solving a problem is evaluating function

$$f: X \rightarrow Y \quad X: \text{vector space of data}$$

$$y = f(x) \quad Y: \text{vector space of solutions}$$

where $x \in X, y \in Y$

An algorithm can be viewed as a different

function \tilde{f} that usually takes the same data $x \in X$ and maps it to a result which is a collection of floating point numbers that belongs to Y .

Accuracy:- A good algo should have an \tilde{f} that closely approximates the underlying problem f .

→ Absolute error of computation :-

$$\|\tilde{f}(x) - f(x)\|$$

→ Relative error of computation :-

$$\frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|}$$

We say that \tilde{f} is an accurate algorithm for f if for all relevant input

data x ,

Forward relative error

$$\left| \frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} \right| = O(\epsilon_m)$$

"On the order
of machine
epsilon"

If f is ill-conditioned
 i.e. $\max_{\delta x} \frac{\|\delta f\|}{\|f\|} = \hat{K}$ is very large

$$\frac{\|\delta x\|}{\|x\|} \approx O(\epsilon_m)$$

$$\frac{\|\delta f\|}{\|f\|} \leq K O(\epsilon_m)$$

Very ambitious to design an algo
 if such that relative error in
 computation is $O(\epsilon_m)$

Instead of aiming for accuracy of
 an algo, the most we can aim is
 for stability!

We can say that an algorithm \tilde{f} for
 solving a problem f is stable if for
 all (relevant) input data x

$$\frac{\|\tilde{f}(x) - f(\tilde{x})\|}{\|f(\tilde{x})\|} = O(\epsilon_m)$$

for some \tilde{x} satisfying $\frac{\|\tilde{x} - x\|}{\|x\|} \leq C \epsilon_m$

i.e A stable algorithm gives nearly right answers to nearly right question.

Backward stability :-

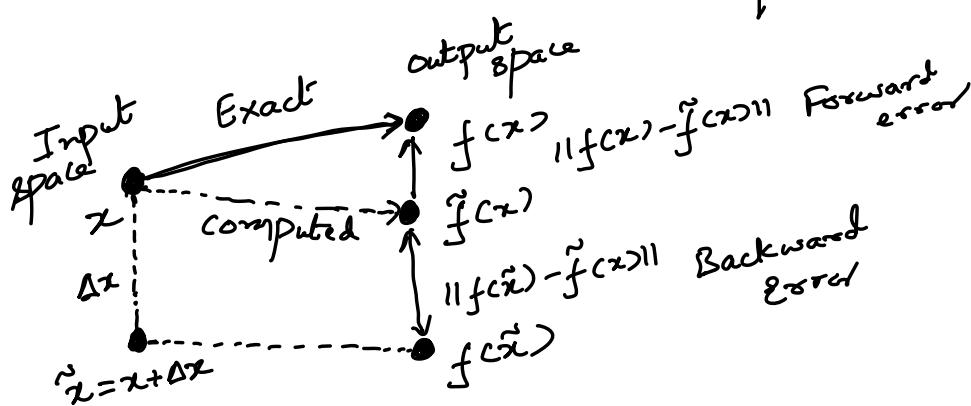
Backward error:- $\|f(\tilde{x}) - \tilde{f}(x)\|$

What is the input \tilde{x} for which my algo with input x has exactly computed a solution for

$$f(\tilde{x}) = \tilde{f}(x)$$

Then such an algo \tilde{f} for problem f is backward stable. (i.e Backward error is zero)

i.e Exactly right answers to a nearly right question!



Stability of Floating point arithmetic operations!

$+, -, \times, /$ (classical arithmetic operations)

Floating point analogues $\oplus, \ominus, \otimes, \oslash$

Recall Floating point axioms :-

$$f(x) = x(1+\varepsilon) \text{ where } |\varepsilon| < \varepsilon_M$$

$$x \otimes y = x * y(1+\varepsilon) \text{ where } |\varepsilon| < \varepsilon_M$$

Example 1:-

Floating point arithmetic for \ominus

$$f(\underline{x}) = x_1 - x_2$$

$$f(x_1, x_2) = x_1 - x_2$$

$$x_1 \rightarrow f(x_1) ; x_2 \rightarrow f(x_2)$$

$$f(x_1) = x_1(1+\varepsilon_1) ; f(x_2) = x_2(1+\varepsilon_2)$$

$$\varepsilon_1, \varepsilon_2 \text{ satisfy } |\varepsilon_1|, |\varepsilon_2| = O(\varepsilon_M)$$

$$\text{Algo} : f(x_1) \ominus f(x_2)$$

$$\Rightarrow [x_1(1+\varepsilon_1)] \ominus [x_2(1+\varepsilon_2)]$$

$$f(x_1) \ominus f(x_2) = [x_1(1+\varepsilon_1) - x_2(1+\varepsilon_2)](1+\varepsilon_3) \quad \text{where } |\varepsilon_3| = O(\varepsilon_M)$$

$$\begin{aligned}
 &= x_1(1+\varepsilon_1)(1+\varepsilon_3) - x_2(1+\varepsilon_2)(1+\varepsilon_3) \\
 &= x_1(\underbrace{1+\varepsilon_1+\varepsilon_3}_{\varepsilon_4} + \varepsilon_1\varepsilon_3) - x_2(\underbrace{1+\varepsilon_2+\varepsilon_3}_{\varepsilon_5} + \underbrace{\varepsilon_2\varepsilon_3}_{\varepsilon_6}) \\
 &= x_1(1+\varepsilon_4) - x_2(1+\varepsilon_5) \quad \text{where } |\varepsilon_4|, |\varepsilon_5| \leq \frac{2\varepsilon_M + O(\varepsilon_M^2)}{2\varepsilon_M + O(\varepsilon_M^2)} \\
 &\quad = O(\varepsilon_M)
 \end{aligned}$$

$$\begin{aligned}
 \tilde{f}(x_1, x_2) &= f(x_1) \odot f(x_2) \\
 &= \tilde{x}_1 - \tilde{x}_2 = f(\tilde{x}_1, \tilde{x}_2) \\
 &\text{Algo is backward stable!}
 \end{aligned}$$

Example 2:- Outer product between two vectors :-

$$\begin{aligned}
 \underline{x} \in \mathbb{R}^m, \underline{y} \in \mathbb{R}^n \\
 \text{compute outer product } \underline{A} = \underline{x} \underline{y}^T
 \end{aligned}$$

$$\begin{aligned}
 \tilde{f}(\underline{x}, \underline{y}) &= \tilde{A}_{ij} \\
 &= f(x_i) \odot f(y_j) \\
 &\quad \uparrow \text{rank 1 matrix}
 \end{aligned}$$

$$\begin{aligned}
 \tilde{A}_{ij} &= f(x_i) \odot f(y_j) \\
 &= [f(x_i) \times f(y_j)] (1 + \varepsilon_{ij}) \\
 &= [x_i(1 + \varepsilon_i^i) y_j(1 + \varepsilon_j^j)] (1 + \varepsilon_{ij}) \\
 &= x_i y_j (1 + \varepsilon_i^i) (1 + \varepsilon_j^j) (1 + \varepsilon_{ij})
 \end{aligned}$$

$$\begin{aligned}
 &= x_i y_j \underbrace{(1 + \varepsilon_1^{ij} + \varepsilon_2^{ij} + \varepsilon_1^{ij} \varepsilon_2^{ij})}_{(1 + \varepsilon_3^{ij})} (1 + \varepsilon_3^{ij}) \\
 &= x_i y_j \underbrace{(1 + \varepsilon_4^{ij})}_{(1 + \varepsilon_3^{ij})} (1 + \varepsilon_3^{ij}) \quad \leftarrow \textcircled{1} \\
 &\text{I want to verify} \\
 &\tilde{f}(x, y) = \tilde{x} \tilde{y}^T \quad \leftarrow \textcircled{*} \\
 &= (\underline{x} + \delta \underline{x})(\underline{y} + \delta \underline{y})^T
 \end{aligned}$$

This algo is not backward stable
 because from eqn ①, it is not
 possible for my algo always to
 give a perturbed rank 1 matrix
 of the form $\tilde{x} \tilde{y}^T$
 Is this algo stable? Exercise!

Example 3:

Adding 1 to floating point numbers!

Let $x \in \mathbb{R}$ and $f(x) = x + 1$

$$\tilde{f}(x) = f(x) \oplus 1$$

$$\begin{aligned}
 \tilde{f}(x) &= f(f(x) + 1)(1 + \varepsilon_1) \\
 &= (x(1 + \varepsilon_1) + 1)(1 + \varepsilon_1) \\
 &= (1 + x + x\varepsilon_1)(1 + \varepsilon_1)
 \end{aligned}$$

$$= 1 + x + x\varepsilon_2 + \varepsilon_1 + \varepsilon_1 x + x\varepsilon_2\varepsilon_1$$

$$= 1 + x \left[1 + \varepsilon_1 + \varepsilon_2 + \frac{\varepsilon_1}{x} \right] \quad - \textcircled{2}$$

For backward stability is $\tilde{f}(x) = f(\tilde{x})$

$$= \tilde{x} + 1$$

$$= x(1+\varepsilon) + 1 ?$$

From eq $\textcircled{2}$

$$1 + x \left[1 + \varepsilon_1 + \varepsilon_2 + \left(\frac{\varepsilon_1}{x} \right) \right]$$

As $x \rightarrow 0$ $\varepsilon \not\approx O(\varepsilon_m)$

This is not backward stable

Unstable Algo:-

- Calculation of eigenvalues of a matrix by finding roots of characteristic polynomial
- Since λ is eigenvalue of a matrix A , then the characteristic polynomial is $p(\lambda) = \det(A - \lambda I) = 0$ roots $p(\lambda) = 0$ are eigenvalues of A

Algo :-

- ① Find the coefficients of $P(\lambda) = \det(A - \lambda I)$
- ② Find its roots

The problem of finding roots of a polynomial given its coefficients is an ill-conditioned problem!
i.e. roots are sensitive to small errors in polynomial coefficients!

Eg:- $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ Recall $\kappa = \frac{\|A\|_2}{\lambda}$
Eigenvalues of A are not sensitive to perturbations of the entries. If we design a stable algo, we should be able to compute eigenvalues with relative error of $O(\epsilon_M)$

Let us see the order of error in roots if we compute the roots of characteristic polynomial for the above problem:

$$\Rightarrow x^2 - 2x + 1$$

Let us analyse the error in roots
for perturbation in the
coefficient p for $x^2 - px + 1$

$$\text{Roots} := p \pm \frac{\sqrt{p^2 - 4}}{2}$$

Let us say my error in estimating
the coefficient p be $|e| < \epsilon_m$

$$\tilde{p} = p(1+e)$$

$$\begin{aligned}\text{New Roots} := & \frac{\tilde{p}(1+e) \pm \sqrt{[\tilde{p}(1+e)]^2 - 4}}{2} \\ & = \frac{p(1+e) \pm \sqrt{p^2(1+e)^2 - 4}}{2}\end{aligned}$$

For our problem at hand $p = 2$

$$\begin{aligned}\text{New roots for } p=2 := & \frac{2(1+e) \pm \sqrt{4(1+e)^2 - 4}}{2} \\ & = (1+e) \pm \sqrt{e^2 + 2e - 1} \\ \Rightarrow (1+e) \pm \sqrt{e^2 + 2e}\end{aligned}$$

$$\text{Error in root: } \frac{|(1+\epsilon) \pm \sqrt{2\epsilon} - 1|}{|\lambda|}$$

Dominant

$$\text{Error in my root} \approx O(\sqrt{\epsilon_m})$$

$$\epsilon_m \approx 10^{-12}$$

$$\sqrt{\epsilon_m} \approx 10^{-6}$$

Accuracy of Backward stable Algo:-

Thm:- If a backward stable algo is applied to solve a problem f with condition number K , the relative forward errors satisfy

$$\frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} = O(K(x)\epsilon_m)$$

Pf:- By definition of backward stability we have $\tilde{f}(x) = f(\tilde{x})$

$$\text{for } \frac{\|\tilde{x} - x\|}{\|x\|} = O(\epsilon_m)$$

we also know

$$K(x) = \max_{\tilde{x}} \frac{\|\delta f\|}{\frac{\|\delta x\|}{\|x\|}}$$

$$\left(\frac{\|f(\tilde{x}) - f(x)\|}{\|f(x)\|} \right) \leq K(x)$$

$$\frac{\|\tilde{x} - x\|}{\|x\|}$$

$$\text{But B.S., } f(\tilde{x}) = \tilde{f}(x)$$

$$\frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} \leq K(x) \frac{\|\tilde{x} - x\|}{\|x\|}$$

$$\uparrow O(\epsilon_m)$$

$$O(K(x) \epsilon_m)$$