

Experimental Setup This chapter details the experimental setup used to train RandLA-Net for Deep Ensembles, Flipout, and RandLA-Net for Deep Ensembles. In this thesis, we used the RandLA-Net model for 3D semantic segmentation proposed in [1].

Dataset In this thesis, we used Semantic3D as training dataset and more about the dataset is discussed in Section 4.1.

Training parameters This section will discuss the libraries used and training parameters of the RandLA-Net for Deep Ensembles, Flipout, and RandLA-Net for Deep Ensembles.

Python - 3.6

Tensorflow - 1.15.0

Tensorflow probability - 0.7.0

Open3d-python - 0.3.0 (training), 0.13.0 (visualizations)

RandLA-Net - Deep Ensembles For Deep Ensembles, we trained 20 randomly initialized instances of RandLA-Net. For Flipout, we trained 20 randomly initialized instances of RandLA-Net where the last three FC layers are made Flipout compatible. For RandLA-Net for Deep Ensembles, we trained 20 randomly initialized instances of RandLA-Net.