

LOKII

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Chapter 1

LOKII Arduino library

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1.1 Introduction

This [LOKII](#) Arduino library provides the library for use by GLAST developers.

There are examples to demonstrate [LOKII](#) basic functions :

- Face detection demo (demonstrate the use of face detection function)
examples/faceDetection/faceDetection.ino
- Color detection demo (demonstrate the use of color object tracking function)
examples/colorDetection/colorDetection.ino
- Speech Recognition demo (demonstrate the speaker independent speech dictation recognition)
examples/speechRecognition/speechRecognition.ino
- Text To Speech demo (demonstrate english text to speech function)
examples/Text-To-Speech/Text-To-Speech.ino
- SD_Create (create speaker dependent speech dictation group for speech recongition)
examples/SD_Create/SD_Create.ino
- songnote (demonstrate music note playback for three songs)
examples/songnote/songnote.ino
- music Tone (demonstrate music note playback for a single song)
examples/musicTone/musicTone.ino

- babyMonitor (A simple baby monitor using face detection and text-to-speech function)
examples/babyMonitor/babyMonitor.ino
 - tts_red_little_riding_hood (A simple storytelling demo with multiple characters using text-to-speech function)
examples/tts_red_little_riding_hood/tts_red_little_riding_hood.ino
 - arduino BLE Car (A showcase for robotic car using Arduino BLE board)
examples/arduinoBLECar/arduinoBLECar.ino
 - armTest using 6 external servo motors
examples/armTest/armTest.ino
 - smartDeviceTest (control 4 proprietary smart LEDs and 4 proprietary smart servo motors)
examples/smartDeviceTest/smartDeviceTest.ino
 - writeSmartID (write smart ID to the single smart device attached to [LOKII](#) Arduino board)
examples/writeSmartID/writeSmartID.ino
- For latest [LOKII](#) news, please check [LOKII website](#)

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

[LOKII](#) ??

Chapter 3

Class Documentation

3.1 LOKII Class Reference

Public Member Functions

- void [connect](#) ()
Init the LOKII system.
- void [setCameraMode](#) (int cameraState)
Set LOKII camera running mode for image processing function.
- int [waitForFaceResult](#) (int faceState)
Wait for face detected result.
- int [getFaceResult](#) (int attributeType)
Get face detected region attribute.
- int [waitForBlobResult](#) (bool isBlocking=true)
Wait (check) for color blob detection result.
- void [registerColor](#) ()
Register a custom color for color detection.
- int [getBlobResult](#) (int blobIndex, int attributeType)
Get color blob detected region attribute.
- int [getBlobCount](#) ()
Get color blob detected count.
- int [recordVideo](#) (String filename)
Start recording video from camera.
- int [stopRecordVideo](#) ()
Stop the video recording from camera.
- int [playVideo](#) (String filename)
Play video from TF card.
- int [stopPlayVideo](#) ()
Stop the video playback on screen.
- int [takePhoto](#) (String filename)
Take photo.
- int [displayPhoto](#) (String filename)
Display the jpeg photo.
- void [startSpeechRecognize](#) (int wordgroupIndex)
Start/Stop speech recognition

- int [waitForSpeechResult](#) ()
Wait for the recognized speech keywords index (BLOCKING)
- int [getSpeechResult](#) ()
Get recognized speech keywords index (NON-BLOCKING)
- int [createSDGroup](#) (int groupIndex, int numKeywords)
Create a Speaker Dependent (SD) custom speech recognition keyword groups.
- int [trainSDkeyword](#) (int groupIndex, int keywordsIndex)
Train a Speaker Dependent (SD) keyword

- int [checkSDComplete](#) (int groupIndex)
Check if Speaker Dependent training complete

- void [setVolume](#) (int vol)
Set audio output volume level of [LOKII](#).
- void [playTTS](#) (String text, int voiceType, int speed, int pitch, int emotion)
Speak english text string.
- void [playSoundFile](#) (String filename, bool isBlocking)
Play sound file.
- void [stopSound](#) ()
Stop audio playback.
- int [checkAudioStatus](#) ()
Check audio status.
- int [recAudio](#) (String filename)
Start audio recording.
- int [stopRecAudio](#) (void)
stop audio recording
- int [playMIDI](#) (int note)
Play MIDI note.
- void [setMIDIBPM](#) (int bpmIn)
Set MIDI BPM duration.
- void [setSmartDeviceAdress](#) (int id) int getSmartDeviceCount(void)
Set the smart device id.
- void [setMotorPower](#) (int motorid, int state)
Turn ON/OFF a motor power (hardware exclusive function)
- void [moveMotor](#) (int motorid, int speed, int position, int direction)
Move motor (hardware exclusive function)
- int [readMotorPosition](#) (int motorid)
Read motor position (hardware exclusive function)
- void [recordMotor](#) (int numSeconds)
Record motors' position (hardware exclusive function)
- void [playbackMotor](#) ()
Playback motors' position (hardware exclusive function)
- int [stopRecordMotor](#) (void)
Stop motor's position recording (hardware exclusive function)
- void [setRGB](#) (int motorid, int r, int g, int b)
Set smart LED color (hardware exclusive function)
- int [setRCServo](#) (int motorid, int speed, int position)
Move RC servo (hardware exclusive function)
- int [setDCMotor](#) (int motorid, int speed, int direction)
Move DC motor (hardware exclusive function)

Public Attributes

- from requests import **Request**
- from requests import Session from requests exceptions import **ConnectionError**
- from requests import Session from requests exceptions import **Timeout**

3.1.1 Member Function Documentation

3.1.1.1 checkAudioStatus()

```
int LOKII::checkAudioStatus ( )
```

Check audio status.

Check the audio playback status of [LOKII](#) system

Returns

the audio status: 1 = audio is playing , 0 = no audio is playing, -1 = system busy, user should check the status again

3.1.1.2 checkSDComplete()

```
int LOKII::checkSDComplete (
    int groupIndex )
```

Check if Speaker Dependent training complete

Check if Speaker Dependent (SD) keyword group training is complete
i.e. all the keywordsIndex audio training is completed in the SD keyword group

Parameters

<i>groupIndex</i>	the index for training word groups (11-20 inclusively)
-------------------	--

Returns

result 1 - complete (All keywords are wel-trained) , 0 - incomplete (need more training samples)

3.1.1.3 connect()

```
void LOKII::connect ( )
```

Init the [LOKII](#) system.

Init the [LOKII](#) system with the SPI bus

3.1.1.4 createSDGroup()

```
int LOKII::createSDGroup (
    int groupIndex,
    int numKeywords )
```

Create a Speaker Dependent (SD) custom speech recognition keyword groups.

Create a speech recognition on specified keyword groups index (This speech recognition is speaker dependent for the training data)

Parameters

<i>groupIndex</i>	the index for training word groups (11-20 inclusively)
<i>numKeywords</i>	the number of keywords want to trained (1-5 inclusively)

Returns

result 1 - success , 0 - fail

3.1.1.5 displayPhoto()

```
int LOKII::displayPhoto (
    String filename )
```

Display the jpeg photo.

Display the jpeg photo stored in [LOKII](#) TF card to the LCD Screen.

Parameters

<i>filename</i>	the jpeg photo filename, for example, a.jpg
-----------------	---

Returns

result 1 for success, other for error

3.1.1.6 getBlobCount()

```
int LOKII::getBlobCount ( )
```

Get color blob detected count.

Get number of color blob detected result from the cache after issuing waitForBlobResult(isBlocking) function:

Returns

count the number of color blob in the cache

3.1.1.7 getBlobResult()

```
int LOKII::getBlobResult (
    int blobIndex,
    int attributeType )
```

Get color blob detected region attribute.

Get the color blob detected result from the cache after issuing waitForBlobResult(isBlocking) function:

Parameters

<i>blobIndex</i>	the zero-based index for the color blob (The index should be smaller than the total color object detected)
<i>attributeType</i>	Following attributeType can be specified: L_XPOS - x coordinate of the color blob centre L_YPOS - y coordinate of the color blob centre L_WIDTH - width of the color blob boundary L_HEIGHT - height of the color blob centre L_COLOR - color of the color blob , such as L_RED_COLOR ,L_GREEN_COLOR, L_BLUE_COLOR, L_CUSTOM_COLOR

All the above color attributeType are based on the LCD screen coordinate system with 320 x 240 pixel

Returns

result the color attribute result

3.1.1.8 getFaceResult()

```
int LOKII::getFaceResult (
    int attributeType )
```

Get face detected region attribute.

Get the face detected result from the cache after issuing waitForFaceResult(faceState) function

Parameters

<i>attributeType</i>	Following attributeType can be specified: L_XPOS - x coordinate of the face centre L_YPOS - y coordinate of the face centre L_WIDTH - width of the face boundary L_HEIGHT - height of the face centre All the above face detected attributeType are based on the LCD screen coordinate system with 320 x 240 pixel
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Returns

result the face detected attribute result

3.1.1.9 getSpeechResult()

```
int LOKII::getSpeechResult ( )
```

Get recognized speech keywords index (NON-BLOCKING)

Get the recognized speech keywords index used in "startSpeechRecognize" functions if no recognized keywords, it will return -1

Returns

result the zero-based index of the recognized keywords or -1 for no speech recognized

3.1.1.10 moveMotor()

```
void LOKII::moveMotor (
    int motorid,
    int speed,
    int position,
    int direction )
```

Move motor (hardware exclusive function)

Move a smart servo (with 100 degree freedom) to target position under specified speed control

Parameters

<i>motorid</i>	the motor id
<i>speed</i>	the movement completion time in millisecond (100 -2000)
<i>position</i>	the target moving degree (1 -100)
<i>direction</i>	1

3.1.1.11 playbackMotor()

```
void LOKII::playbackMotor ( )
```

Playback motors' position (hardware exclusive function)

Playback smart servo motors positions which is previously recorded by [recordMotor\(int numSeconds\)](#) function

3.1.1.12 playMIDI()

```
int LOKII::playMIDI (
    int note )
```

Play MIDI note.

Play MIDI note (0 - 59) for a second For example: NOTE_C1 0 NOTE_C1S 1 NOTE_D1 2 NOTE_E1b 3 NOTE_E1 4 NOTE_F1 5 NOTE_F1S 6 NOTE_G1 7 NOTE_G1S 8 NOTE_A2 9 NOTE_B2b 10 NOTE_B2 11 if the note value is negative, [LOKII](#) will play a silence

Parameters

<i>note</i>	the MIDI integer value
-------------	------------------------

3.1.1.13 playSoundFile()

```
void LOKII::playSoundFile (
    String filename,
    bool isBlocking )
```

Play sound file.

Play MP3 sound file by specified the sound filename stored in [LOKII](#) TF card

Parameters

<i>filename</i>	sound file stored in TF card
<i>isBlocking</i>	0 - non-blocking, 1 - blocking until the sound file playback completed

3.1.1.14 playTTS()

```
void LOKII::playTTS (
    String text,
    int voiceType,
    int speed,
```

```
int pitch,
int emotion )
```

Speak english text string.

Speak english text using specified voice, speed, pitch, emotion setting using [LOKII](#) built-in text-to-speech engine

voice can be one of following value: L_DEFAULT 0 L_MAN 1 L_OLDMAN 2 L_OLDWOMAN 3 L_BOY 4 L_YOUNG GIRL 5 L_ROBOT 6 L_GIANT 7 L_DWARF 8 L_ALIEN 9

emotion can be one of following value: E_NATURAL 0 E_FRIENDLY 1 E_ANGRY 2 E_FURIOUS 3 E_DRILL 4 E_SCARED 5 E_EMOTIONAL 6 E_WEEPY 7 E_EXCITED 8 E_SURPRISED 9 E_SAD 10 E_DISGUSTED 11 E_WHISPER 12

Parameters

<i>text</i>	english text script
<i>voiceType</i>	voice can be 0 - 9 inclusively
<i>speed</i>	speed can be 1 - 10 inclusively
<i>pitch</i>	pitch can be 1 - 10 inclusively
<i>emotion</i>	emotion can be 0 - 12 inclusively

3.1.1.15 playVideo()

```
int LOKII::playVideo (
    String filename )
```

Play video from TF card.

Play MPEG-4 video file from [LOKII](#) TF card

Returns

result 1 for success, 0 for error

3.1.1.16 readMotorPosition()

```
int LOKII::readMotorPosition (
    int motorid )
```

Read motor position (hardware exclusive function)

Read a smart servo current position

Parameters

<i>motorid</i>	the motor id
----------------	--------------

Returns

position more position in degree (1 -100)

3.1.1.17 recAudio()

```
int LOKII::recAudio (
    String filename )
```

Start audio recording.

Start audio recording in mp3 format and save it to the TF card

Parameters

<i>filename</i>	filename for recording audio
-----------------	------------------------------

Returns

result 0 - fail, 1 - success

3.1.1.18 recordMotor()

```
void LOKII::recordMotor (
    int numSeconds )
```

Record motors' position (hardware exclusive function)

Record all smart servo motor position for specified numSeconds duration

Parameters

<i>numSeconds</i>	the duration in seconds (1- 30)
-------------------	---------------------------------

3.1.1.19 recordVideo()

```
int LOKII::recordVideo (
    String filename )
```

Start recording video from camera.

Start MPEG-4 video recording and save to internal TF card

Returns

result 1 - success , 0 - fail

3.1.1.20 registerColor()

```
void LOKII::registerColor ( )
```

Register a custom color for color detection.

Train [LOKII](#) to recognize a custom color object which is posited at the centre of the LCD screen region The trained custom color can then be recognized by `setCameraMode(L_CAM_RECOGNIZE_CUSTOM)` function To have a good training process, make sure : 1) the color object is not reflective 2) the color object size is around 30

3.1.1.21 setCameraMode()

```
void LOKII::setCameraMode (
    int cameraState )
```

Set [LOKII](#) camera running mode for image processing function.

Set [LOKII](#) camera to perform image processing functions.

Parameters

<i>cameraState</i>	define the image processing function L_CAM_RECOGNIZE_RGB - perform Red/Green/Blue color detection in camera live stream L_CAM_RECOGNIZE_CUSTOM - perform self-trained color detection in camera live stream L_CAM_FACE_DETECT - perform frontal face detection in camera live stream L_CAM_PREVIEW - set camera to preview mode, no image processing is performed
--------------------	---

3.1.1.22 setDCMotor()

```
int LOKII::setDCMotor (
    int motorid,
    int speed,
    int direction )
```

Move DC motor (hardware exclusive function)

Move a DC motor connected on a [LOKII](#) smart motor control board

Parameters

<i>motorid</i>	the motor id
<i>speed</i>	green color channel brightness (0-31, 0 - stop motor, 1-slowest , 31 - fastest PWM speed)
<i>direction</i>	0 - clockwise, 1 - anti-clockwise

Returns

0 - success , other value - fail

3.1.1.23 setMIDIBPM()

```
void LOKII::setMIDIBPM (
    int bpmIn )
```

Set MIDI BPM duration.

Set MIDI Beat Per Minute (BPM) setting between 30 - 100

Parameters

<i>bpmIn</i>	the BPM value
--------------	---------------

3.1.1.24 setMotorPower()

```
void LOKII::setMotorPower (
    int motorid,
    int state )
```

Turn ON/OFF a motor power (hardware exclusive function)

Set a smart motor power state, either turn on the motor or turn off the motor

Parameters

<i>motorid</i>	the motor smart device id
<i>state</i>	the power state, 0 - OFF, 1 - ON

3.1.1.25 setRCServo()

```
int LOKII::setRCServo (
    int motorid,
    int speed,
    int position )
```

Move RC servo (hardware exclusive function)

Move a RC servo motor attached on [LOKII](#) smart motor board (For example, MG90S, MG996R)

Parameters

<i>motorid</i>	the motor id
<i>speed</i>	speed (0 1-20)
<i>position</i>	blue color channel brigtness (1-200)

Returns

0 - success , other value - fail

3.1.1.26 setRGB()

```
void LOKII::setRGB (
    int motorid,
    int r,
    int g,
    int b )
```

Set smart LED color (hardware exclusive function)

Set a smart LED color using primitive Red, Green, Blue color settting

Parameters

<i>motorid</i>	the motor id
<i>r</i>	red color channel brigtness (0-255)
<i>g</i>	green color channel brigtness (0-255)
<i>b</i>	blue color channel brigtness (0-255)

3.1.1.27 setSmartDeviceAddress()

```
void LOKII::setSmartDeviceAdress (
    int id )
```

Set the smart device id.

Set the smart device id (address) In order to set the smart device id, make use only single smart device is attached in the [LOKII](#) smart device bus physically.

Parameters

<i>id</i>	the smart device id ranged between 0 - 100 inclusively
-----------	--

Returns

Get smart devices count

Get the number of smart devices attached in the [LOKII](#) system.

Returns

The number of smart device

3.1.1.28 setVolume()

```
void LOKII::setVolume (
    int vol )
```

Set audio output volume level of [LOKII](#).

Set audio output volume level between 0 -10 inclusively 0 = silence 10 = max sound level

Parameters

<i>vol</i>	volume level (0 -10)
------------	------------------------

3.1.1.29 startSpeechRecognize()

```
void LOKII::startSpeechRecognize (
    int wordgroupIndex )
```

Start/Stop speech recognition

Start speech recognition for trained word groups in Speaker Independent mode (SI) (index can be 1, 2, 3, 4) index 1 is number group for "0", "1", "2", "3", "4", "5", "6", "7", "8", "9", "10"

2 is action group for "Action", "Move", "Turn", "Run", "Look", "Attack", "Stop", "Hello" 3 is movement group for "Turn Left", "Turn Right", "Move Up", "Move Down", "Go Forward", "Go Backward" 4 is command group for "Tell me a joke", "play me a song", "stop the music", "take a photo", "show me a photo", "track my face", "follow the ball", "recrod motor motion", "playback motor", "list commands"

if index specified is 11 -20 inclusively, it will start speech recognition in custom training data (Speaker Dependent)

if index = 0, it means STOP the speech recognition

Parameters

<i>wordgroupIndex</i>	the index for word groups, either 0 , 1, 2, 3,4
-----------------------	---

3.1.1.30 stopPlayVideo()

```
int LOKII::stopPlayVideo ( )
```

Stop the video playback on screen.

Stop the video playback

Returns

result 0 for success

3.1.1.31 stopRecAudio()

```
int LOKII::stopRecAudio (
    void )
```

stop audio recording

Returns

result 0

3.1.1.32 stopRecordMotor()

```
int LOKII::stopRecordMotor (
    void )
```

Stop motor's position recording (hardware exclusive function)

Stop smart servo motors positions recording which is triggered by [recordMotor\(int numSeconds\)](#) function

3.1.1.33 stopRecordVideo()

```
int LOKII::stopRecordVideo ( )
```

Stop the video recording from camera.

Stop the video recording and save it into internal TF card

Returns

result 0 for success

3.1.1.34 stopSound()

```
void LOKII::stopSound ( )
```

Stop audio playback.

Stop the audio playback from [playSoundFile\(\)](#) function in non-blocking mode.

3.1.1.35 takePhoto()

```
int LOKII::takePhoto (
    String filename )
```

Take photo.

Take a photo from camera live stream and stored it in [LOKII](#) TF card.

Parameters

<i>filename</i>	the jpeg photo filename, for example, a.jpg
-----------------	---

Returns

result 1 for success, other for error

3.1.1.36 trainSDkeyword()

```
int LOKII::trainSDkeyword (
    int groupIndex,
    int keywordsIndex )
```

Train a Speaker Dependent (SD) keyword

Train a speaker dependent audio on a specified index group using [LOKII](#) built-in microphone (This speech recognition is speaker dependent for the training data)

For each keyword audio, it is recommended to train for at least 3 audio samples to get a better training result.

Parameters

<i>groupIndex</i>	the index for training word groups (11-20 inclusively)
<i>keywordsIndex</i>	the index for the keywords want to trained (1-5 inclusively)

Returns

result 1 - complete , 0 - incomplete (require more training samples)

3.1.1.37 waitForBlobResult()

```
int LOKII::waitForBlobResult (
    bool isBlocking = true )
```

Wait (check) for color blob detection result.

Wait or check for color blob detection result after issuing setCameraMode(L_CAM_RECOGNIZE_RGB) or setCameraMode(L_CAM_RECOGNIZE_CUSTOM) After this function call, a copy of the color result will be cached

Parameters

<i>isBlocking</i>	define the color blob detection behavior if isBlocking = L_OFF, this function will return immediately regardless of color blob detected (NON-BLOCKING) if isBlocking = L_ON, this function will hold until at least one color object is detected. (BLOCKING)
-------------------	---

Returns

result number of color object detected

3.1.1.38 waitForFaceResult()

```
int LOKII::waitForFaceResult (
    int faceState )
```

Wait for face detected result.

Wait or check for face detected result after issuing setCameraMode(L_CAM_FACE_DETECT) After this function call, a copy of the face result will be cached

Parameters

<i>faceState</i>	define the face detection behavior
------------------	------------------------------------

if faceState = L_OFF, this function will return immediately regardless of face detected (NON-BLOCKING)

if faceState = L_ON, this function will hold until a face is detected. (BLOCKING)

Returns

result 1 - face detected , 0 - face not detected (in NON-BLOCKING mode only)

3.1.1.39 waitForSpeechResult()

```
int LOKII::waitForSpeechResult ( )
```

Wait for the recognized speech keywords index (BLOCKING)

Wait for the recongnized speech keywords index used in "startSpeechRecognize" functions

Returns

result the zero-based index of the recognized keywords

The documentation for this class was generated from the following file:

- LOKII.h

