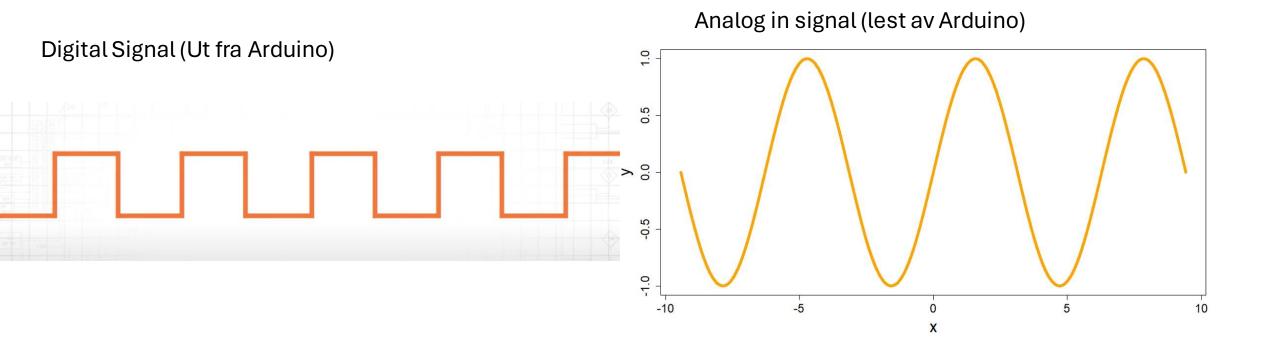


Radiokommunikasjon

Proof of concept

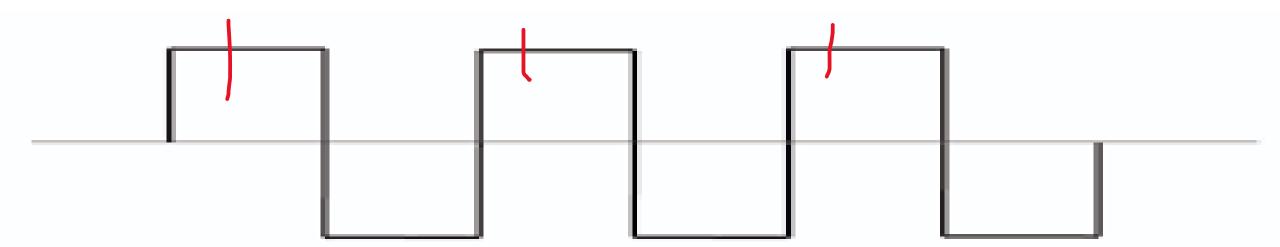
- -cheif engineer Kristoffer Loland
- -proffesor Marius Claudey
- -trainee Erlend Børli

Proof of consept

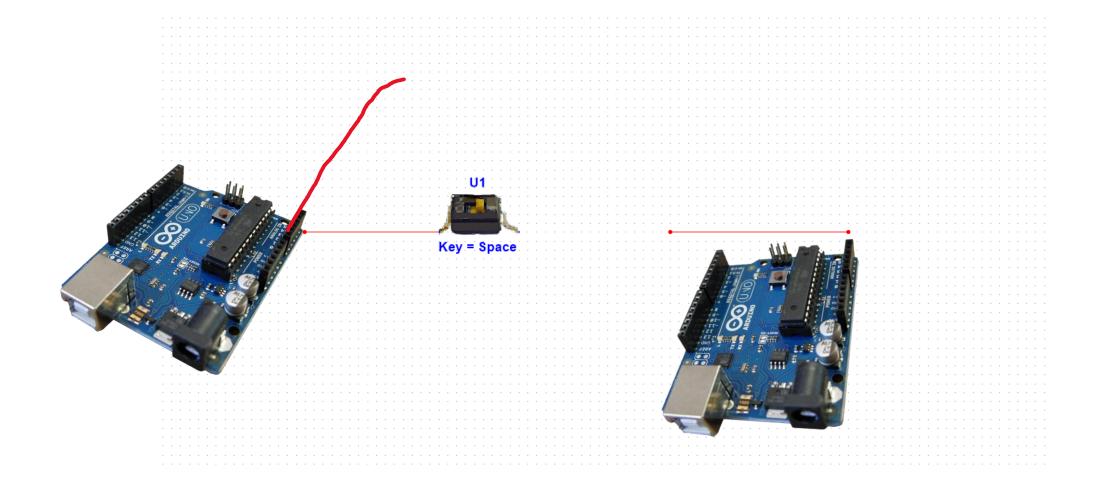


Frekvens

- Sender og mottaker må ha forskjellig frekvens
- Forskjellig klokkesignal

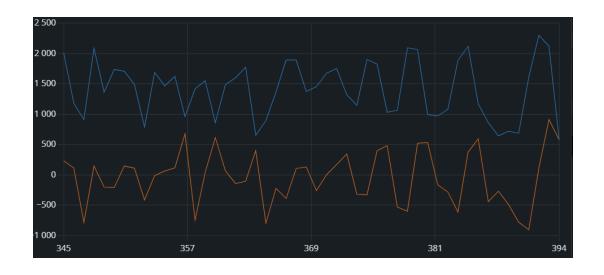


Kretstegning

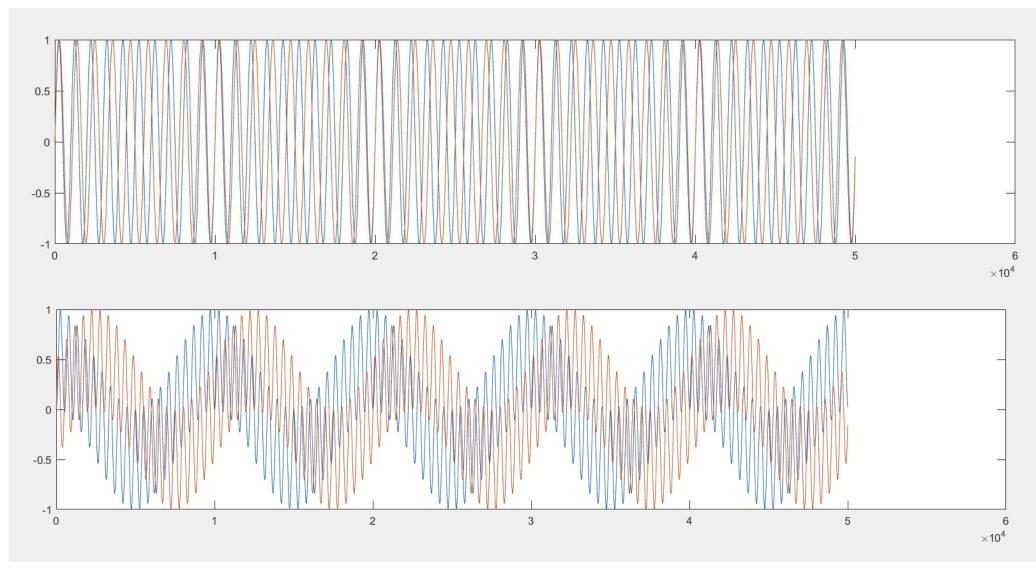


Begrensinger

- Kan ikke variere avstander
- Svært små avstander
- Sårbar for interferens

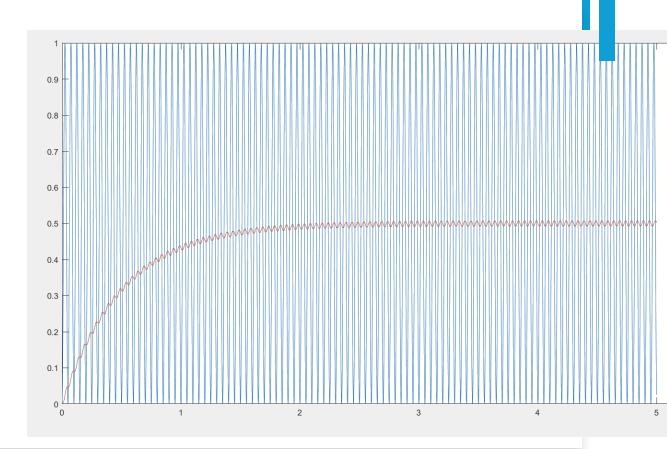


Sampling ideelt (matlab)



Filter

- Skille mellom lav og høy
- RC Filter
- Prosent forskjell
- Gjennomsnitt



```
70
       void lavpassfilter(long* x, int n, float dt, float RC) {
71
         // Digital RC low pass filter
72
         // Variables:
73
         // input data - x
74
         // time interval - dt
75
         // time constant RC
76
         float alfa = dt / (RC + dt);
77
        y[0] = x[0];
78
79
        for (int i = 1; i < n; i++) {
80
          y[i] = alfa * x[i] + (1 - alfa) * y[i - 1];
81
82
83
```

Arduino serial plotter

- På-Av
- På
- På-av-på
- Stor variasjon



Kommunikasjon

- Vanskelig å definere start mtp interferens
- Bits
- ASCII

```
void loop() {
       if (Serial.available() > 0) { // Check if data is available to read
         String inputString = Serial.readString(); // Read the string from serial monitor
         Serial.print("ASCII bytes: ");
         Serial.print("00000010 "); // Start of text
         for (int i = 0; i < inputString.length()-1; i++) {</pre>
           printBinary((byte)inputString[i]); // Print ASCII byte of each character
11
           Serial.print(" ");
12
13
14
         Serial.print("00000011 "); // End of text
15
17
     void printBinary(int num) {
        // Print each bit of the binary representation
       for (int i = 7; i >= 0; i--) {
         Serial.print((num >> i) & 1); // Print each bit of the binary representation
21
22
23
```

```
int analogPin = A1;
      uint8_t knapp = 8;
      long p2;
      long p3;
      long produkt;
      long produktSiste;
      float prosentdifferanse;
      unsigned char resultat;
      int signTab2[] = \{1,1,-1,-1\};
      int signTab3[] = \{1, -1, -1, 1\};
14
      #define MAX SIZE 100 // Define the maximum size of your data array
      long produktArray[MAX_SIZE]; // Array to store produkt values
      int index = 0; // Index to keep track of where to store the next value
      float y[MAX SIZE]; // Output array
      void setup() {
       // put your setup code here, to run once:
       Serial.begin(9600);
        pinMode(utsignalkort, OUTPUT);
       pinMode(knapp, INPUT_PULLUP);
24
 58
            Serial.print(p2);
 59
            Serial.print(", ");
 60
            Serial.print(p3);
            Serial.print(", ");
 61
 62
            Serial.print(produkt);
 63
            Serial.print(", ");
 64
            Serial.print(y[MAX_SIZE-1]);
 65
            Serial.println("");
 66
 67
```

int utsignalkort = 2;

4

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22

```
p2=0;
p3=0;
if (digitalRead(knapp) == HIGH) {
  for (int i = 0; i < 1000; i++) {
   for (int j = 0; j < 4; j++) {
     if (signTab2[j] == 1) {
       digitalWrite(utsignalkort, HIGH);
        digitalWrite(utsignalkort, LOW);
      int sensorValue = analogRead(analogPin); // Read analog pin
      p2 = signTab2[j] * sensorValue + p2;
      p3 = signTab3[j] * sensorValue + p3;
produktSiste = produkt;
produkt = p2 * p2 + p3 * p3;
produktArray[index] = produkt; // Store produkt in the array
index = (index + 1) % MAX SIZE; // Increment the index for the next round, wrap around if necessary
lavpassfilter(produktArray, MAX_SIZE, 0.1, 10);
```

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Forbedring

- Kontrollere frekvens med interrupts
- Bedre filtrering og lesing av bits
- Check bits
- Bedre hardware
- Bedre kode