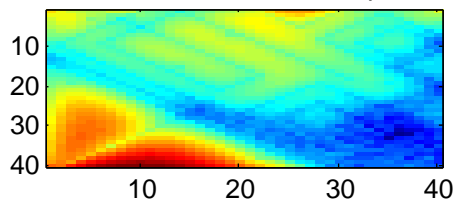
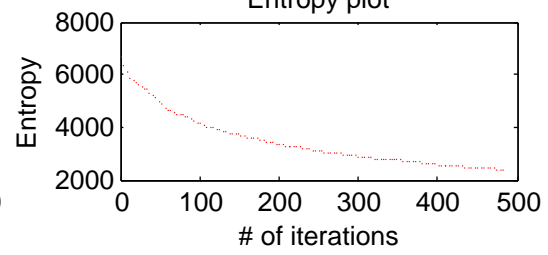


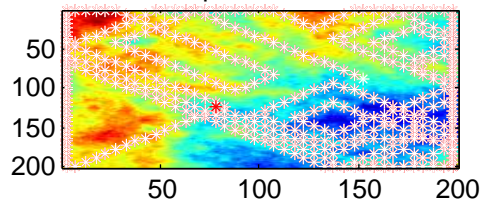
Mutual information map



Entropy plot



Robot path on the field



Temperature map from observations

