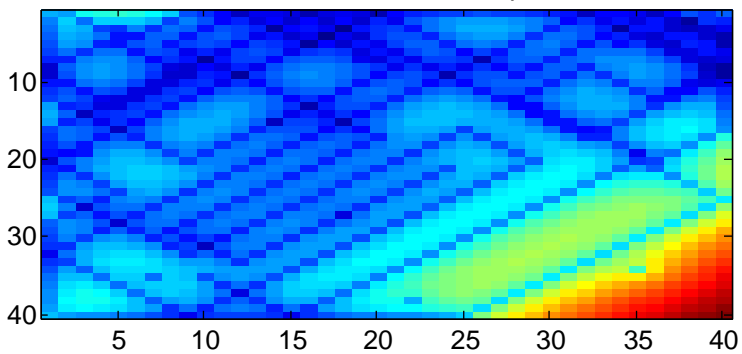
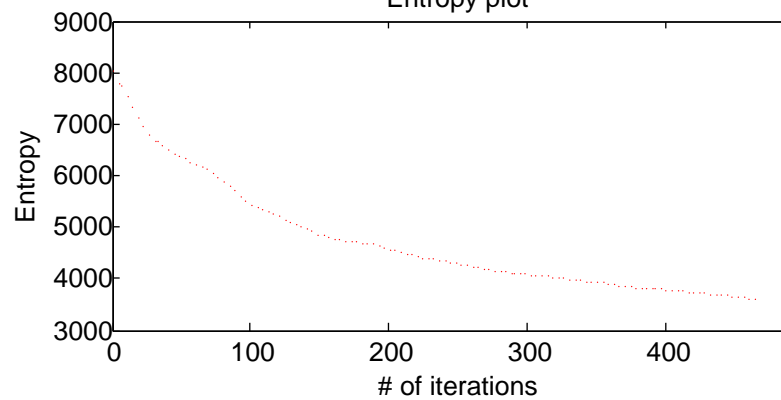


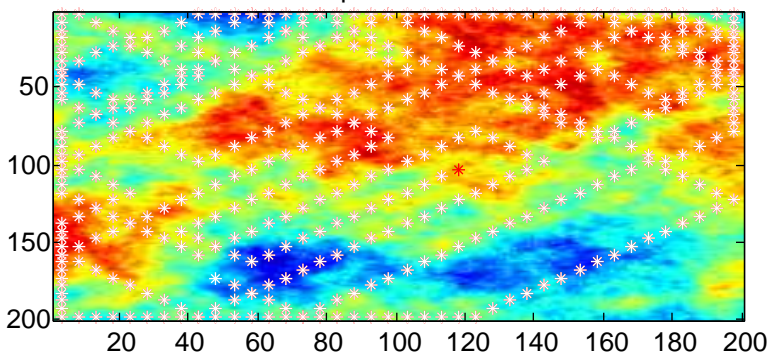
Mutual information map



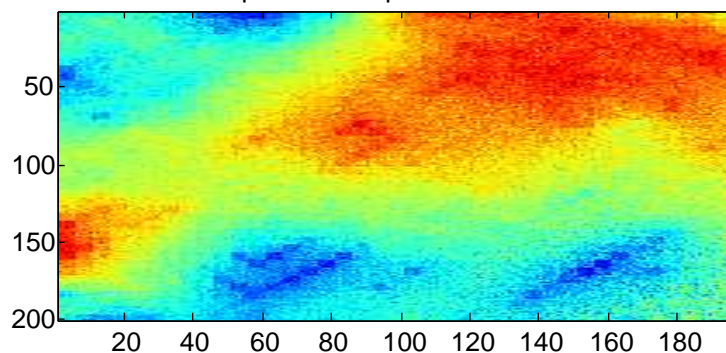
Entropy plot



Robot path on the field



Temperature map from observations



RMSE error

