# Machine Learning

#### Classification - Part II

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#### Model Selection: Evaluation of a Classifier

Questions to be answered

- Which of the available models for classification is the best one?
- Which of the available algorithms is the best one?
- Which is the best parameters configuration?
- ⇒ Evaluation

# The Oil Slick example I

- Detect oil slick (failures, illegal dumping) from satellite images, for early alarm
- Radar satellite images
  - Dark regions whose size and shape depend on weather and sea conditions
  - Look—alike dark regions can also be caused by local weather conditions, such as high winds
  - Manual detection by experts is definitely expensive and slow
- Scarcity of training data: oil spills are, fortunately, rare
- Unbalanced nature of data: the negative examples (non-spills) are predominant over the positive ones

# The Oil Slick example II

- An automatic hazard detection system has been developed and marketed
  - Pre–selection of images for final manual processing
  - Necessary a tradeoff between undetected spills and false alarms
  - Evaluation of performance guides the tradeoff

# The training set

- In supervised learning the training set performance is overoptimistic
- We need a lower bound for performance obtained by independent tests
- Supervised data are usually scarce, we need to balance the use of them between:
  - train
  - validation, to tune the parameter (sometimes it is omitted)
  - test
- Evaluate how much the theory fits the data
- Evaluate the cost generated by prediction errors

### Learning and evaluation

- Empirically (and intuitively) the more training data we use the best performance we should expect
  - Statistically, we should expect a larger covering of the situation that can occur when classifying new data
- We must consider the effect of random changes
- The evaluation is independent from the algorithm used to generate the model

#### The meaning of the *test error*

- let us suppose that the test set is a good representation, on the average, of the entire dataset  $\mathcal{X}$  (i.e. run-time)
- ullet the relationship between the training set and  ${\mathcal X}$  will be subject to probabilistic variability
- the evaluation can be done either at different levels
  - general the whole performance of the classifier
  - local the local performance of a component of the model, i.e. a node of a decision tree
- if the test set error ratio is x, we should expect a run-time error  $x \pm ???$





#### Confidence interval in error estimation

#### Bernoulli process

- forecasting each element of the test set is like one experiment of a Bernoulli process
  - good prediction ⇒ success
  - bad prediction ⇒ error
- ullet the same as N independent binary random events of the same type
- f = S/N = empirical frequency of error
- which is *p* the probability of error?



# Empirical frequency and true frequency

- Deviations of the empirical frequency from the true frequency are due to noise
- Usually, noise is assumed to have a normal distribution around the true probability (for  $N \ge 30$ )
- We choose the confidence level, i.e. the probability that the true frequency of success is below the pessimistic frequency that we will compute

$$P\left(z_{\alpha/2}\leqslant rac{f-p}{\sqrt{p(1-p)/N}}\leqslant z_{1-\alpha/2}
ight)=1-lpha$$

#### Range error estimate

Wilson score interval

- z depends on the desired confidence level  $\alpha$
- ullet it is the abscissa delimiting the area 1-lpha for a normal distribution
  - i.e. the inverse of the standard cumulative normal distribution
- with a little of algebra

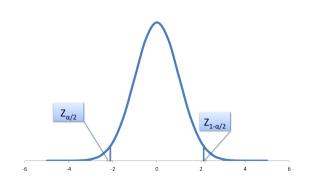
$$\frac{1}{1 + \frac{1}{N}z^2} \left[ f + \frac{1}{2N}z^2 \pm z\sqrt{\frac{1}{N}f(1 - f) + \frac{1}{4N^2}z^2} \right]$$

The pessimistic error is obtained by substituting  $\pm$  with +



#### Confidence level in error estimation

 $\alpha$  is the probability of a wrong estimate

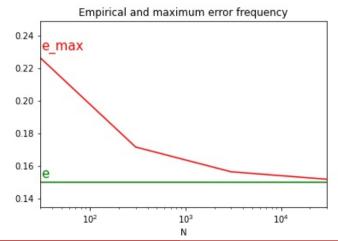


$1-\alpha$	Z
0.99	2.58
0.98	2.33
0.95	1.96
0.90	1.65
0.75	1.04
0.50	0.67

#### Confidence interval in error estimation

Increasing N, with constant empirical frequency, the uncertainty for p narrows.

Example: e = 15%,  $\alpha = 0.05$ 



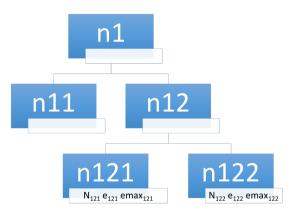
# Statistical pruning of DT with error estimation

#### The C4.5 strategy

- Consider a subtree near the leaves
- $\bullet$  Compute its maximum error  $e_l$  as a weighted sum of the maximum error of the leaves
- Compute the maximum error  $e_r$  of the root of the subtree transformed into a leaf
- Prune if  $e_r \leq e_l$
- With pruning, the error frequency increases, but the number of records in node also increases, therefore the maximum error can decrease

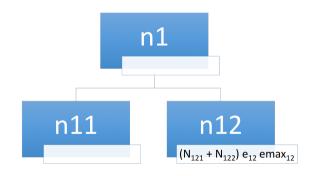


# DT before pruning



 $N_x = \text{Records in node}$   $e_x = \text{Error frequency in node}$   $emax_x = \text{Maximum error frequency in node}$ 

# DT after pruning



 $emax_x - e_x \text{ increases as } \textit{N}_x \text{ decreases}$  Pruning is done if  $(\textit{N}_{121} + \textit{N}_{121}) * emax_{12} < \textit{N}_{121} * emax_{121} + \textit{N}_{122} * emax_{122}$ 

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# Scikit-Learn allows to adjust pruning with one or more of the hyperparameters below

- max\_depth the maximum depth allowed for the tree; it is a horizontal cut, pruning all the branches below a given depth
- min\_samples\_split either the minimum absolute number of samples or the minimum fraction of samples (with respect to the entire population in the dataset) in a node to make a split, if the threshold is not exceeded the node becomes a leaf
- min\_samples\_leaf the minimum number of samples (or fraction, as above) required to be at a leaf node
- min\_impurity\_decrease a node will be split if this split induces a decrease of the impurity
  greater than or equal to this value; if the weighted sum of the descendant leaves do not
  decrease from the node under consideration more than this threshold then the node becomes a
  leaf

# Accuracy of a classifier

- The error frequency is the simplest indicator of the quality of a classifier
  - it is the sum of errors on any class divided by the number of tested records
- From now on, for simplicity, we will use the empirical error frequencies
  - remember that in real cases the maximum error frequencies should be used instead
- Accuracy and other more sophisticated indicators are used to:
  - compare different classifiers or parameter settings
  - estimate the run-time performance we can expect, and therefore the cost of errors

# The hyperparameters

Optimizing the model learned

- Every machine learning algorithm has one or more parameters than influence its behaviour
  - they are usually called hyperparameters
- Several train/test loops are in general necessary to find the best set of values for the hyperparameters
- It is crucial to obtain a highly reliable estimate of the run-time performance
- Sometimes it is necessary to find the best compromise between the optimisation step and the quality of the result

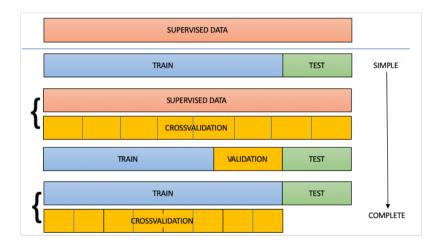
# Testing strategies

Getting the most out of the available supervised data

Problem: in every step the data should be *representative* of the data that will be classified run–time

- Holdout
  - splitting data into training set and test set
  - splitting data into training set, validation set and test set
- Cross validation
  - repeated tests with different splits

# The train/test process: some alternatives



#### Holdout



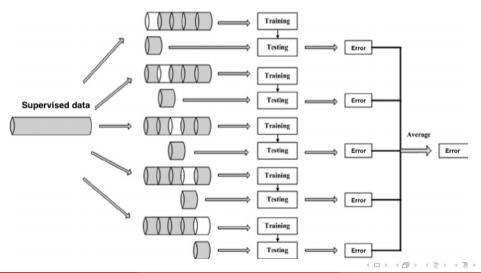
- A typical value of the training/test ratio is 2/1
- The split should be as random as possible
  - ullet It may happen that the proportion of classes in the supervised dataset  ${\mathcal X}$  is altered in the Training and Test sets, to prevent such cases the statistical sampling technique of stratification ensures the maintenance of the proportion of classes
- In this setting, the test set is used to obtain an *estimation* of the performance measures with new data

# Cross Validation (k-fold)

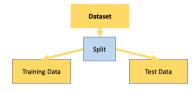
- The training set is randomly partitioned into *k* subsets
  - If necessary, use stratified partitioning
- k iterations using one of the subsets for test and the others for training
- Combine the result of tests
- Generate the final model using the entire training set
- Optimal use of the supervised data
  - ullet each record is used k-1 times for training and once for testing
- Typical value: k = 10

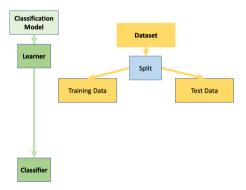


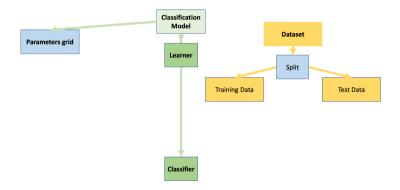
# **Cross Validation**

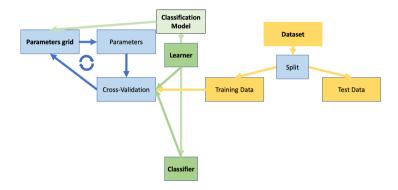


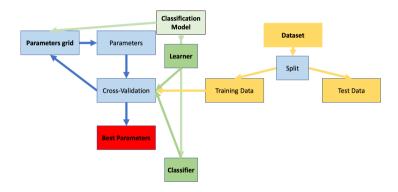
Dataset

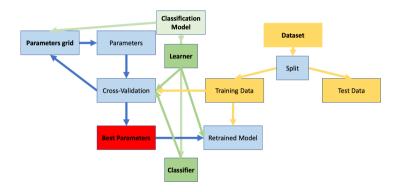


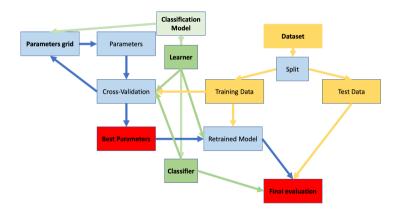












# Cross Validation – pros and cons

- $\odot$  The train/test loop is repeated k times
- $\odot$  The estimate of the performance is averaged on k runs
  - ⇒ more reliablity
- All the examples are used once for testing
- © The final model is obtained using all the examples
  - $\Rightarrow$  best use of the examples

#### Leave one out

- Extreme case of cross validation, with k = N
- No random partitioning
- It is intrinsically non-stratified

#### Bootstrap

- A statistical sampling technique
- Sampling of N records with replacement
  - each record can be selected, even if it has been selected in previous samples
- Some records will never be selected: they will be used for test

$$e = 0.632e_{test} + 0.368e_{training}$$

$$\left(1-\frac{1}{N}\right)^N\approx e^{-1}\approx 0.368$$

# Train, Validation, Test – pros and cons

- © The train/validation loop is faster than the Cross Validation
- © The optimisation of the hyperparameters is done with the validation set, independent from the final evaluation
  - ⇒ more reliable than the simple holdout
- The test is done on a portion of the examples
  - ⇒ less reliable with respect to Cross Validation

Performance measures of a classifier

## Binary prediction

For simplicity: Positive/Negative

• success rate = accuracy

$$\frac{TP + TN}{N_{test}}$$

error rate

		Predicted class		
		Pos	Neg	
True	Pos	TP	FN	
class	Neg	FP	TN	

1 -success rate

### Is accuracy enough?

- Is the accuracy the only performance indicator for a classifier? Other possible indicators:
  - Velocity
  - Robustness w.r.t. noise
    - i.e. training data with bad class label
  - Scalability
  - Interpretability
- A classification error can have different consequences, depending on the class of the individual
  - when forecasting an illness a false positive can be less dangerous than a false negative
    - unless the cares or the additional examinations are dangerous or invasive
  - consider the cost of retiring a machinery as damaged, while it is ok (false positive) and the cost of an unpredicted failure (false negative)

# A summary of measures I

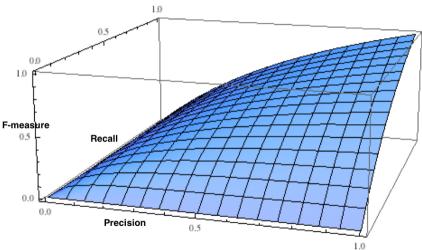
```
Precision – TP/(TP + FP)
                     the rate of true positives among the positive
                     classifications
 Recall - TP/(TP + FN)
                     the rate of the positives that I can catch (a.k.a.
                     Sensitivity)
Specificity – TN/(TN + FP)
                     the rate of the negatives that I can catch
```

# A summary of measures II

F1-score – the armonic mean of precision and recall, a.k.a. balanced

$$F = 2 \frac{\mathsf{prec} \cdot \mathsf{rec}}{\mathsf{prec} + \mathsf{rec}}$$

### F-measure



### Which measure should we use?

#### A rule of thumb

- Accuracy gives an initial feeling of the effectiveness of the classifier, but can be heavily misleading when classes are highly imbalanced
  - it considers globally all the classes, also when C>2 (non-binary case, also called *multi-class*)
- F1—score is *always* interesting, because has higher values when precision and recall are reasonably balanced
- if the the costs of errors on positives and negatives are significantly different, then it is necessary to evaluate precision and recall.
- for multi-class problems see page 47.

### Multi-class case

- The table of page 38 is easily extended and is called confusion matrix
- Each cell contains the number of test records of class i and predicted as class j
- The numbers in the main diagonal are the "true" predictions

### Confusion matrix with three classes, say a, b, c

 $T_x = \text{true number of } x \text{ labels in the dataset } \underset{P_i}{\text{precision}}_i = \frac{TP_i}{P_i}$ 

 $P_x = \text{total number of } x \text{ predictions by a}$ given classifier, say  $\overline{C}$ 

 $TP_x$  = number of true predictions for class x given by classifier  $\overline{C}$ 

 $FP_{i-j}$  = number of false prediction for class i predicted as j

$$\text{accuracy} = \frac{\sum_{i} TP_{i}}{N}$$
 $\text{precision}_{i} = \frac{TP_{i}}{P_{i}}$ 
 $\text{recall}_{i} = \frac{TP_{i}}{T_{i}}$ 

		Predicted class				
		а	Ь	С	Total	
True class	а	$TP_a$	$FP_{a-b}$	$FP_{a-c}$	T <sub>a</sub>	
	Ь	$FP_{b-a}$	$TP_b$	$FP_{b-c}$	$T_b$	
	С	$FP_{c-a}$	$FP_{c-b}$	$TP_c$	$T_c$	
	Total	$P_a$	$P_b$	$P_c$	N	

### Multi-class evaluation I

The number of classes is more than two

- precision, recall and f1-score are intrinsically defined for a single class;
- in binary classification they are commonly referred to the so-called positive class;
- in multi-class cases, the scorers of 'scikit-learn' produce an array of values, one for each class
- when a single value is necessary to optimise the hyper parameters, as in 'GridSearchCV', if we need to maximise one of precision, recall, f1–score an average value is required

### Multi-class evaluation II

The number of classes is more than two

averaging of measure f for classes  $c_i \in C$ , each class with frequency  $C_i$ 

- macro average:  $f(C) = \frac{\sum f(c_i)}{C}$
- weighted average:  $f(C) = \frac{\sum f(c_i) * C_i}{C}$
- with macro average the measure of each class has the same impact on the average value, therefore in case of imbalancing the minority classes have influence bigger than their size
- with wighted average the measure of each class influences the result in proportion with its size, therefore in case of imbalancing the minority classes have smaller influence

### Beyond pure counting

Taking into account the "a priori" information

- Is it likely to obtain a correct prediction by chance?
- Example: early diagnosis
  - let us consider a disease affecting 2% of patients
  - a prediction saying always "no disease" has 98% precision, which, in general would be a good result
  - the evaluation of a prediction should take this as a baseline, and, possibly, look for improvements

## Example of confusion matrix

- Confusion matrix of classifier  $\overline{C}$  on a given dataset
- 140 correct predictions
- The predicted proportion of classes is 100:60:40

		Predicted class			
		а	b	С	Total
True class	а	88	14	18	120
	b	10	40	10	60
	С	2	6	12	20
	Total	100	60	40	200

# Confusion matrix of a random classifier $R_{\overline{C}}$

#### A virtual experiment

- A random classifier  $R_{\overline{C}}$  producing the same proportion of classes as  $\overline{C}$ 
  - the horizontal *margin* is the same as  $\overline{C}$
- The rows have all the same proportion as the horizontal margin
- 82 predictions are exact by chance
  - the sum of the main diagonal of  $R_{\overline{C}}$

		Predicted class			
		a	b	С	Total
True class	а	60	36	24	120
	b	30	18	12	60
	С	10	6	4	20
	Total	100	60	40	200

### Taking into account the random component

- The improvement of  $\overline{C}$  over  $R_{\overline{C}}$  is 140 82 = 58
- The improvement of the perfect classifier is 200 82 = 118
- We define  $\kappa(\overline{C})$  the improvement of the classifier at hand w.r.t. the improvement of the perfect classifier

$$\kappa(\overline{C}) = 58/118 = 0.492$$



### $\kappa$ statistic [Cohen (1960)]

- Evaluates the concordance between two classifications
  - in our case between the predicted and the true one
- Probability of concordance  $Pr(c) = \frac{TP_a + TP_b + TP_c}{N}$
- Probability of random concordance  $Pr(r) = \frac{T_a*P_a+T_b*P_b+T_c*P_c}{N^2}$
- $\bullet$   $\kappa$  is the ratio between the concordance exceeding the random component and the maximum surplus possible

$$-1 \leqslant \kappa = \frac{\operatorname{\mathsf{Pr}}\left(c\right) - \operatorname{\mathsf{Pr}}\left(r\right)}{1 - \operatorname{\mathsf{Pr}}\left(r\right)} \leqslant 1$$



### Range of $\kappa$

- 1 for perfect agreement
  - $TP_a + TP_b + TP_c = N$
- -1 for total disagreement
  - $TP_a + TP_b + TP_c = 0$  and there is a perfect swap between predictions and true labels
    - if all classes have non–zero counts -1 is possible only if the number of labels is two
- 0 for random agreement

$$\kappa = \frac{\text{Poor Slight Fair Moderate Substantial Almost perfect}}{0.0 .20 .40 .60 .80 1.0}$$



#### The cost of errors

- Our decisions are driven by predictions
- Bad predictions imply a cost
- Examples
  - grant a loan to a person who turns out to be a bad payer costs more than denying a loan to a person that could be a good payer
  - a false "oil spill" alarm is less expensive than an undetected spill
  - a wrong "fault prediction" in an industrial plant is in general less expensive than an unexpected fault disabling the plant and creating damages
  - in direct marketing, sending advertisement material without redemption is less harmful than the loss of business if a promising customer is ignored

### Cost sensitive learning I

#### Weight the errors

- Alternative 1: alterate the proportion of classes in the supervised data, duplicating the examples for which the classification error is higher
  - In this way, the classifier will became more able to classify the classes for which the classification error cost is higher
  - ullet This solution is useful also when the classes are *imbalanced*, that is the frequencies of the class labels in  ${\mathcal X}$  are not equal

## Cost sensitive learning II

- Alternative 2: some learning schemes allow to add weights to the instances
  - e.g. the DecisionTreeClassifier of Scikit-Learn has the hyperparameter class\_weight: it allows to define a dictionary, with one key per distinct class, specifying the relative weight to be assigned to each class, the optimisation of the fitting will be adjusted accordingly
    - the balance option balances the classes automatically

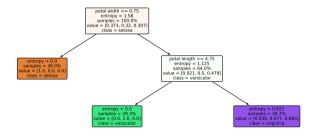
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## Predicting probabilities of classes I

- Many classifiers produce, rather than a class label (*crisp* prediction), a tuple of probabilities, one for each possible class, (*probabilistic*, or *soft* prediction)
- The adequacy of one output or the other depends on the application domain
  - when an immediate decision is required the crisp output is necessary
  - when the classification is part of a process including several evaluation/action steps the probabilistic output can be more appropriated

### Crisp values sometimes hide probabilities

- For example, when a leaf of a decision tree has non–zero counts for the minority classes a less–than–one probability, the probabilities of the examples falling in that leaf can be assigned on the basis of the fractions of the training data elements in that leaf belonging to each class
- Consider the rightmost leaf in the figure (it is the pruned tree of the first module on Classification)



<sup>1</sup> Since it is quite common to have leaves with a small number of examples and/or minority classes with frequencies near to zero, smoothing techniques are used to adjust the probabilities

### Probabilities to crisp

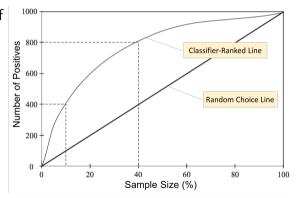
- Probabilities can be converted to a crisp value with different techniques, depending on the number of classes (binary or multiclass)
  - binary set a threshold for the positive class
  - multiclass output the class with the maximum probability

# Binary - Lift Chart

- Used to evaluate various scenarios, depending on the application
- Consider a dataset with 1000 positives and apply a probabilistic classification scheme
- Sort all the classified elements for decreasing probability of positive class
- Make a hi-dimensional chart with axes x =sample size, y =number of positives in sample
- Only the rank is important, not the specific probability

### Lift Chart

- The straight line plots the number of positives obtained with a random choice of a sample of test data
- The curve plots the number of positives obtained drawing a fraction of test data with decreasing probability
- The larger the area between the two curves, the best the classification model



### **ROC Curve**

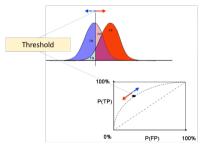
Receiver-Operator Characteristic

History: interpretation of radar signals during WWII

- Tradeoff between hit rate and false alarm in a noisy channel
- The noise can be such that the recognition of the transmission is altered
- The noise alters the two levels according to a gaussian distribution
- Problem: set the positive/negative threshold in order to maximize the tradeoff above, according to application—dependent requirements

#### **ROC Curve**

- With less noise the two gaussian curves are better separated
- Moving the threshold towards right increases both the rate of true positives and false positives caught
- The area between the non-discrimination line and the ROC curve is a quality index of the line
- The maximum area is the upper left triangle



a Image from Wikipedia

 $\mathsf{TN} = \mathsf{blue} + \mathsf{cyan} = \mathsf{probability} \ \mathsf{of} \ \mathsf{a} \ \mathsf{negative} \ \mathsf{to} \ \mathsf{be} \ \mathsf{caught}$ 

 $\mathsf{FN} = \mathsf{cyan} = \mathsf{probability}$  of a negative to be missed

 $\mathsf{FP} = \mathsf{pink} + \mathsf{purple} = \mathsf{probability}$  of a positive to be missed

TP = red + purple = probability of a positive to be caught

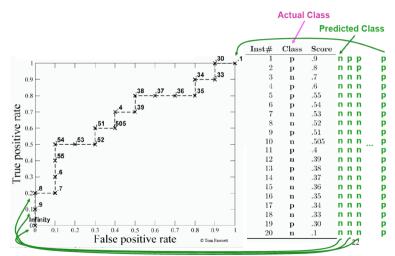
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### ROC for a soft classifier

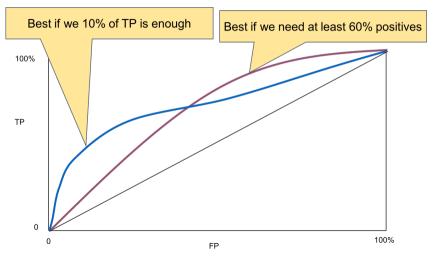
- The soft classifier can be converted into a crisp one by choosing a threshold ⇒ predict positive if the probability of the test record exceeds the threshold
- Varying the threshold the behavior of the classifier changes, by changing the ratio of TP and FP
- Threshold steps allow to track the ROC curve
  - sort the test elements by decreasing positive probability
  - set the threshold to the highest probability, set TP and FP to zero
  - repeat
    - ullet update the number of TP and FP with probability from the threshold to 1
    - draw a point in the curve
    - move to next top probability of positive
  - end repeat



### Drawing the ROC curve for a soft classifier



# Drawing the ROC curve for a soft classifier



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