

5. Linear Programming

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Combinatorial Decision Making and Optimization

2nd cycle degree programme in Artificial Intelligence

University of Bologna, Academic Year 2023/24



Operations research

- Let's face (combinatorial) **decision making** and **optimization** from a different perspective
 - different paradigm, same **goal**: modeling and solving hard real-world optimization problems subject to different constraints
- Less “AI-oriented” and “logic-oriented”, more “**math-oriented**”
- Less “constraints-centered”, more “**inequalities-centered**”
- Based on **relaxations** and **cutting-planes** rather than propagation and search

Operations research

- **Operation Research (OR)** is a well-established field based on mathematical techniques for enhancing complex **decision-making**
- Originated in first half of 20th century for military purposes, nowadays OR finds **application** in several fields, e.g.:
 - Finance
 - Manufacturing and Logistics
 - Simulations and stochastic models
 - Transportation
 - ...
- OR strongly influenced by **linear programming** techniques and its variants (ILP, MIP, NLP...)
 - As for CP, “programming” does not mean “coding” in this context...

Linear programming

- Linear programming (LP) is based on systems of linear (in-)equalities
- We typically resort to LP when we need an optimal allocation for a limited number of resources
- LP is among the most relevant scientific advances of last century: several applications in disparate fields — not only scientific fields
 - Agriculture, sports, marketing, environment etc.
 - Delta claimed 100.000.000\$ saving per year using LP
 - H. Markowitz won Nobel prize for using LP to optimize portfolio profit
- Let's start with a toy example from MiniZinc tutorial
 - <https://www.minizinc.org/doc-2.5.5/en/modelling.html#an-arithmetic-optimisation-example>

Baking cakes

```
1 % We know how to make two sorts of cakes. A banana cake which takes 250g of
2 % self-raising flour, 2 mashed bananas, 75g sugar and 100g of butter, and a
3 % chocolate cake which takes 200g of self-raising flour, 75g of cocoa, 150g
4 % sugar and 150g of butter. We can sell a chocolate cake for $4.50 and a
5 % banana cake for $4.00. And we have 4kg self-raising flour, 6 bananas,
6 % 2kg of sugar, 500g of butter and 500g of cocoa. How many of each sort of
7 % cake should we bake for the fete to maximise the profit
8
9 var 0..100: b; % no. of banana cakes
10 var 0..100: c; % no. of chocolate cakes
11
12 % flour
13 constraint 250*b + 200*c <= 4000;
14 % bananas
15 constraint 2*b <= 6;
16 % sugar
17 constraint 75*b + 150*c <= 2000;
18 % butter
19 constraint 100*b + 150*c <= 500;
20 % cocoa
21 constraint 75*c <= 500;
22
23 % maximize our profit
24 solve maximize 400*b + 450*c;
25
26 output ["no. of banana cakes = \"(b)\n",
27         "no. of chocolate cakes = \"(c)\n"];
```

Geometric interpretation

- This is an example of linear problem: all the constraints are **linear inequalities** and we optimize a **linear function**
- Because only two variables are involved, we can **geometrically represent** the problem on the Cartesian plane
 - In **2** dim: equalities \equiv **straight-lines**, inequalities \equiv **half-plane**
 - In **n** dim: equalities \equiv **hyperplanes**, inequalities \equiv **half-spaces**
- **Feasible solution** \equiv assignment satisfying all the constraints \equiv points within the **intersection** of all half-spaces defined by inequalities
- Set of all solutions \equiv set of all feasible points \equiv **feasible region**
 - It is a **convex polyhedron**: it may be empty, bounded or unbounded
- **GOAL**: find a point within the feasible region where the objective function has **maximal** value

Geometric interpretation



Where is the feasible region? What point is optimal?

Drawn with <https://www.desmos.com/calculator>

Geometric interpretation



- By “*tuning the isolines*” of the objective function we find **optimal solution** $(3, 4/3)$, having **optimal value** $z = 400 \cdot 3 + 450 \cdot 4/3 = 1800$ \$
- This is **inconsistent** with the model specification, where $b, c \in \mathbb{Z}$
- No worries, for now let’s assume that we can sell slices of cake
 - If not, what would be the optimal solution?

Brewery problem

- Let's see another toy example: the **brewery problem**

- From <https://www.cs.princeton.edu/courses/archive/spr03/cs226/lectures/lp-4up.pdf>

- A small brewery needs to produce ale and beer with **limited resources**:

Beverage	Corn	Hops	Malt	Profit
Ale	5	4	35	13
Beer	15	4	20	23
Q.ty available	480	160	1190	

- How can they **maximize profits**?

- Devote all resources to ale: 34 barrels of ale \rightarrow 442\$
- Devote all resources to beer: 32 barrels of beer \rightarrow 736\$
- 7.5 barrels of ale, 29.5 barrels of beer \rightarrow 776\$
- 12 barrels of ale, 28 barrels of beer \rightarrow 800\$
- ...

Brewery problem

- Let's see another simple example: the **brewery problem**
 - From <https://www.cs.princeton.edu/courses/archive/spr03/cs226/lectures/lp-4up.pdf>
- A small brewery needs to produce ale and beer with **limited resources**:

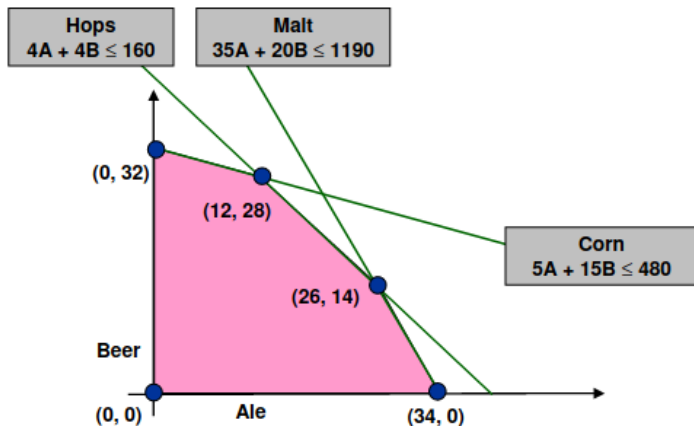
Beverage	Corn	Hops	Malt	Profit
Ale	5	4	35	13
Beer	15	4	20	23
Q.ty available	480	160	1190	

- Let's formulate this as a **LP problem**:

$$\begin{array}{ll} \text{maximize} & 13A + 23B \\ \text{subject to} & 5A + 15B \leq 480 \\ & 4A + 4B \leq 160 \\ & 35A + 20B \leq 1190 \\ & A, B \geq 0 \end{array}$$

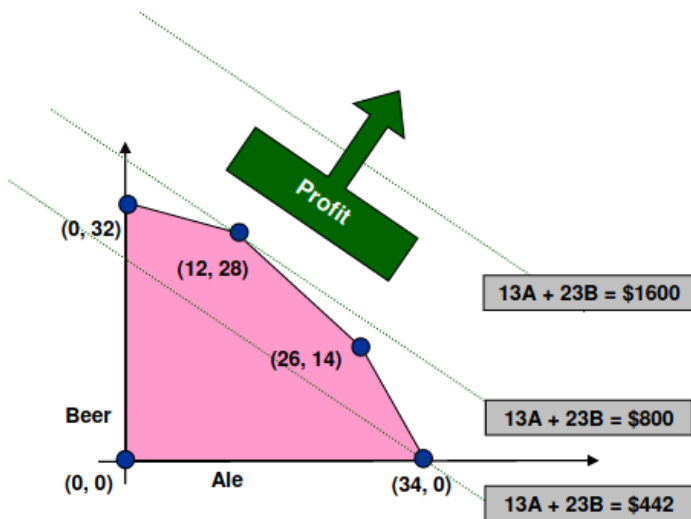
Geometry

The **feasible region** is:



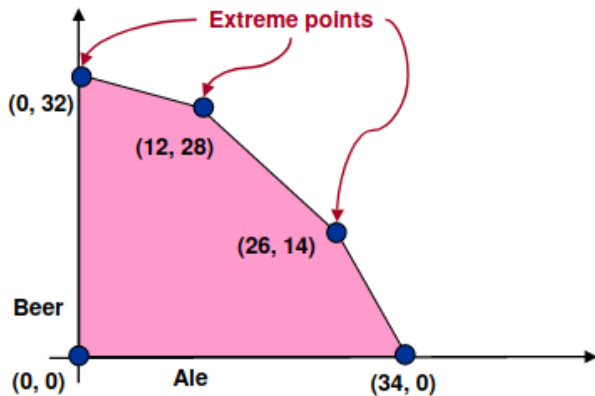
Geometry

We need to maximize $13A + 23B$:



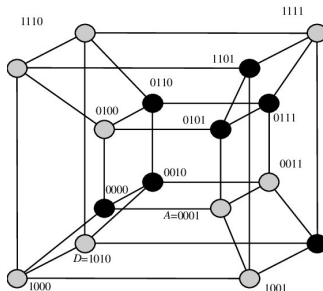
Geometry

Observation: the optimal solution necessarily occurs at **extreme point**



Geometry

- **Extreme point property**: if an optimal solution for a LP problem exists, then there is one at the **extreme point** of its feasible region
- **Good news**: the number of extreme points is **finite**
- **Bad news**: the number of extreme points can be **exponential**
 - E.g., the **n -dimensional hypercube** has exactly 2^n vertices



Canonical form

- A LP problem in **canonical form** has the form:

$$\begin{array}{ll}\max & \sum_{j=1}^n c_j x_j \\ \text{s.t.} & \sum_{j=1}^n a_{i,j} x_j \leq b_i \quad 1 \leq i \leq m \\ & x_j \geq 0 \quad 1 \leq j \leq n\end{array}$$

- m = no. of linear **constraints**, n = no. of non-negative **variables**
- $a_{i,j}, b_i, c_j \in \mathbb{R}$ are known **parameters**
- $\sum_{j=1}^n c_j x_j$ is the **objective function** to maximize
 - subject to m linear inequalities $\sum_{j=1}^n a_{i,j} x_j \leq b_i$
- **Matrix form**: $\max c \cdot x$ s.t. $Ax \leq b$ and $x \geq 0$
 - $c = \langle c_1, \dots, c_n \rangle$, $x = \langle x_1, \dots, x_n \rangle^t$, $b = \langle b_1, \dots, b_m \rangle^t$,

$$A = \begin{pmatrix} a_{1,1} & \dots & a_{1,n} \\ \dots & \dots & \dots \\ a_{m,1} & \dots & a_{m,n} \end{pmatrix}$$

Standard form

- A LP problem in **standard form** has the form:

$$\begin{array}{ll}\max & \sum_{j=1}^n c_j x_j \\ \text{s.t.} & \sum_{j=1}^n a_{i,j} x_j = b_i \quad 1 \leq i \leq m \\ & x_j \geq 0 \quad 1 \leq j \leq n\end{array}$$

- **Matrix form**: $\max c \cdot x$ s.t. $Ax = b$ and $x \geq 0$
- We can easily convert from canonical to **equivalent** standard form with **m slack variables** $y_1, \dots, y_m \geq 0$
 - From n -dimensional to **$(n + m)$ -dimensional** problem
- $\sum_{j=1}^n a_{i,j} x_j \leq b_i \implies \sum_{j=1}^n a_{i,j} x_j + y_i = b_i, y_i \geq 0$ for $i = 1, \dots, m$
 - Objective function does not change

Example

- The above brewery problem is already in **canonical form**:

$$\begin{array}{llll} \max & 13A & + & 23B \\ \text{s.t.} & 5A & + & 15B \leq 480 \\ & 4A & + & 4B \leq 160 \\ & 35A & + & 20B \leq 1190 \\ & A & , & B \geq 0 \end{array}$$

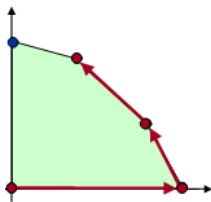
- The corresponding **standard form** is:

$$\begin{array}{llllllllll} \max & 13A & + & 23B & & & & & & \\ \text{s.t.} & 5A & + & 15B & + & S_C & & & & = 480 \\ & 4A & + & 4B & & & + & S_H & & = 160 \\ & 35A & + & 20B & & & & & + & S_M = 1190 \\ & A & , & B & , & S_C & , & S_H & , & S_M \geq 0 \end{array}$$

- How to find an optimal solution with $n > 2$ variables?

Symplex algorithm

- **Symplex algorithm** developed by G. Dantzig in 1947
- General idea: start at some **extreme point** and iteratively move to a **neighboring** one that **doesn't decrease** the objective value
 - If no such extreme point exists, we found an **optimal** solution



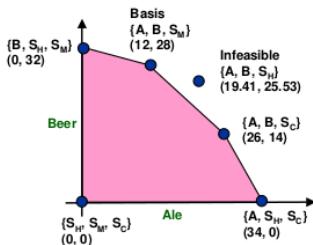
- It exploits **linear algebra** properties

Basis

- Given a LP problem P in standard form, a **basis** of P is a subset $\mathcal{B} = \{x_{i_1}, \dots, x_{i_m}\}$ of $m \leq n$ variables s.t. **columns** A^{i_1}, \dots, A^{i_m} form a $m \times m$ **invertible matrix** $A_{\mathcal{B}}$
 - E.g., if $A = \begin{pmatrix} 1 & 2 & 2 \\ 1 & 2 & 1 \end{pmatrix}$ then $\mathcal{B} = \{x_1, x_2\}$ is not a basis because $A_{\mathcal{B}} = \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix}$ is not invertible, while $\{x_1, x_3\}$ and $\{x_2, x_3\}$ are basis
- We can rewrite P by separating **basic** from **non-basic** variables:
 $\max(c_{\mathcal{B}}x_{\mathcal{B}} + c_{\mathcal{N}}x_{\mathcal{N}})$ s.t. $A_{\mathcal{B}}x_{\mathcal{B}} + A_{\mathcal{N}}x_{\mathcal{N}} = b$ and $x_{\mathcal{B}}, x_{\mathcal{N}} \geq 0$
 - $\mathcal{N} = \{x_1, \dots, x_n\} - \mathcal{B}$ are the non-basic variables of P
- By setting $x_{\mathcal{N}} = 0$, P becomes $\max(c_{\mathcal{B}}x_{\mathcal{B}})$ s.t. $A_{\mathcal{B}}x_{\mathcal{B}} = b$ hence $x_{\mathcal{B}} = A_{\mathcal{B}}^{-1}b \in \mathbb{R}^m$ with objective value $c_{\mathcal{B}}A_{\mathcal{B}}^{-1}b$. This solution is called a **basic solution** for \mathcal{B}

Basis

- A basic solution for \mathcal{B} is **feasible** iff $(\forall_{i=1}^m) (x_{\mathcal{B}})_i \geq 0$
 - **Basic feasible solution (BFS)** \equiv extreme point of feasible region
- A BFS for \mathcal{B} is **non-degenerate** iff $(\forall_{i=1}^m) (x_{\mathcal{B}})_i > 0$
 - If BFS non-degenerate, then it's represented by a **unique** basis
- Simplex method **iteratively** considers BFS $\tilde{x}_1, \tilde{x}_2, \dots$ s.t. $c\tilde{x}_k \geq c\tilde{x}_{k-1}$



Brewery example

- The brewery example in **standard form** is:

$$\begin{array}{llllllllll} \max & 13A & + & 23B & & & & & & \\ \text{s.t.} & 5A & + & 15B & + & S_C & & & & = 480 \\ & 4A & + & 4B & & & + & S_H & & = 160 \\ & 35A & + & 20B & & & & & + & S_M = 1190 \\ & A & , & B & , & S_C & , & S_H & , & S_M \geq 0 \end{array}$$

- Let's first pick an arbitrary feasible basis, e.g., $\mathcal{B} = \{S_C, S_H, S_M\}$
 - $A_{\mathcal{B}}$ is the 3×3 identity matrix, $\mathcal{N} = \{A, B\}$ so $A = B = 0$
- The BFS for \mathcal{B} is $S_C = 480, S_H = 160, S_M = 1190$ with obj. value 0
 - Feasible, but we may improve it with a new basis \mathcal{B}' adjacent to \mathcal{B}
 - $\mathcal{B}' = \mathcal{B} \cup \{x^{in}\} - \{x^{out}\}$ with $x^{in} \notin \mathcal{B}$ and $x^{out} \in \mathcal{B}$

Pivoting

- How to select entering variable x^{in} and leaving variable x^{out} ?
- We can choose the x^{in} which “increases more” the objective value
 - x^{in} will increase from 0 ($x^{in} \in \mathcal{N}$) to a value ≥ 0 ($x^{in} \in \mathcal{B}'$)
 - In the brewery example, a unit increase in A increases the obj. value of 13; a unit increase in B increases the obj. value of 23: $x^{in} = B$
- Then, choose x^{out} by ensuring that $\mathcal{B}' = \mathcal{B} \cup \{x^{in}\} - \{x^{out}\}$ is a feasible basis
 - Minimum ratio rule: x^{out} is in the row i minimizing ratio $\beta_i^{in} / \alpha_i^{in}$ where $\alpha_i^{in}, \beta_i^{in}$ are the x^{in} coefficient and known term in the i -th row
 - Otherwise, \mathcal{B}' not feasible
 - In the brewery ex. $\min\{480/15, 160/4, 1190/20\} = \min\{32, 40, 59.5\} = 32$ so $x^{out} = S_C$: the new basis will be $\mathcal{B}' = \{B, S_H, S_M\}$
 - Then, x^{in} is derived and its value replaced in all other equations

Pivoting

- Selecting x^{in} , x^{out} resp. means choosing a **pivot column** and a **pivot row** from the **tableau** representation of $\max(Z)$ s.t.:

$$\begin{array}{rclclclcl}
 13A & + & 23B & & & - & Z & = & 0 \\
 \hline
 5A & + & 15B & + & S_C & & & = & 480 \\
 4A & + & 4B & & & + & S_H & = & 160 \\
 35A & + & 20B & & & & + & S_M & = & 1190 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

- From 2nd row we get $B = \frac{480-5A-S_C}{15} = 32 - \frac{1}{3}A - \frac{1}{15}S_C$ and we substitute it in all other equations:

$$\begin{array}{rclclclcl}
 \frac{16}{3}A & - & \frac{23}{15}S_C & & & - & Z & = & -736 \\
 \hline
 \frac{1}{3}A & + & B & + & \frac{1}{15}S_C & & & = & 32 \\
 \frac{8}{3}A & & & - & \frac{4}{15}S_C & + & S_H & = & 32 \\
 \frac{85}{3}A & & & - & \frac{4}{3}S_C & & + & S_M & = & 550 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

Pivoting

- Current basis $\{B, S_H, S_M\}$. What row/column should we select now?

$$\begin{array}{rclclclclcl}
 \frac{16}{3}A & - & \frac{23}{15}S_C & & & - & Z & = & -736 \\
 \hline
 \frac{1}{3}A & + & B & + & \frac{1}{15}S_C & & & = & 32 \\
 \frac{8}{3}A & & & - & \frac{4}{15}S_C & + & S_H & = & 32 \\
 \frac{85}{3}A & & & - & \frac{4}{3}S_C & & + & S_M & = & 550 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

Pivoting

- Current basis $\{B, S_H, S_M\}$. What row/column should we select now?

$$\begin{array}{rclclclclcl}
 \frac{16}{3}A & - & \frac{23}{15}S_C & & & - & Z & = & -736 \\
 \hline
 \frac{1}{3}A & + & B & + & \frac{1}{15}S_C & & & = & 32 \\
 \frac{8}{3}A & & & - & \frac{4}{15}S_C & + & S_H & = & 32 \\
 \frac{85}{3}A & & & - & \frac{4}{3}S_C & & + & S_M & = & 550 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

- A contributes more than S_C in increasing Z : 1st column chosen ($x^{in} = A$)
 - The coefficients in the obj. function row are called **reduced costs**

Pivoting

- Current basis $\{B, S_H, S_M\}$. What row/column should we select now?

$$\begin{array}{rclclclclcl}
 \frac{16}{3}A & - & \frac{23}{15}S_C & & & - & Z & = & -736 \\
 \hline
 \frac{1}{3}A & + & B & + & \frac{1}{15}S_C & & & = & 32 \\
 \frac{8}{3}A & & & - & \frac{4}{15}S_C & + & S_H & = & 32 \\
 \frac{85}{3}A & & & - & \frac{4}{3}S_C & & + & S_M & = & 550 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

- A contributes more than S_C in increasing Z : $x^{in} = A$
- The ratios for A are $\{32 \cdot 3, 32 \cdot \frac{3}{8}, 550 \cdot \frac{3}{85}\}$: 2nd row chosen ($x^{out} = S_H$)

Pivoting

- Current basis $\{B, S_H, S_M\}$. What row/column should we select now?

$$\begin{array}{rcccccccl}
 \frac{16}{3}A & - & \frac{23}{15}S_C & & & - & Z & = & -736 \\
 \hline
 \frac{1}{3}A & + & B & + & \frac{1}{15}S_C & & & = & 32 \\
 \frac{8}{3}A & & & - & \frac{4}{15}S_C & + & S_H & = & 32 \\
 \frac{85}{3}A & & & - & \frac{4}{3}S_C & & + & S_M & = & 550 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

- A contributes more than S_C in increasing Z : $x^{in} = A$
- The ratios for A are $\{32 \cdot 3, 32 \cdot \frac{3}{8}, 550 \cdot \frac{3}{85}\}$: $x^{out} = S_H$
- New basis: $\{A, B, S_M\}$. We derive $A = \frac{3}{8} \cdot (32 + \frac{4}{15}S_C - S_H) = 12 + \frac{1}{10}S_C - \frac{3}{8}S_H$ and substitute it in the other equations

Pivoting

- Current basis $\{A, B, S_M\}$. What row/column should we select now?

$$\begin{array}{rcccccccl}
 & - & S_C & - & 2S_H & & - & Z & = & -800 \\
 \hline
 & & B & + & \frac{1}{10}S_C & + & \frac{1}{8}S_H & & = & 28 \\
 A & & & - & \frac{1}{10}S_C & + & \frac{3}{8}S_H & & = & 12 \\
 & & & - & \frac{25}{6}S_C & - & \frac{85}{8}S_H & + & S_M & = 210 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

Optimality

- Current basis $\{A, B, S_M\}$. What row/column should we select now?

$$\begin{array}{rclclclcl}
 & - & S_C & - & 2S_H & & - & Z & = & -800 \\
 \hline
 & & B & + & \frac{1}{10}S_C & + & \frac{1}{800}S_H & & = & 28 \\
 A & & - & \frac{1}{10}S_C & + & \frac{1}{800}S_H & & & = & 12 \\
 & & - & \frac{25}{6}S_C & - & \frac{85}{8}S_H & + & S_M & = & 210 \\
 \hline
 A & , & B & , & S_C & , & S_H & , & S_M & \geq 0
 \end{array}$$

- All the **reduced costs** are ≤ 0 : increasing the value of corresponding variables won't increase the obj. value
- We cannot improve the current feasible solution \rightarrow we reached an **optimal** solution:
 - $S_C = S_H = 0$
 - $A = 12, B = 28, S_M = 210$
 - $-S_C - 2S_H - Z = -800 \implies Z = 800 - S_C - 2S_H = 800$

Optimality

- The simplex method performs an “**optimality check**”: if **all** the reduced costs are ≤ 0 , we reached an optimal solution
- This condition is **sufficient**: for any optimal solution there is at least a basis s.t. all the reduced costs are ≤ 0
- ...But it's **not necessary**: we may reach an optimal solution even if some reduced cost is > 0
- E.g., $\max(x_1)$ s.t. $x_3 = 1 - x_2, x_4 = -x_1, x_i \geq 0$ with basis $\mathcal{B} = \{x_3, x_4\}$ corresponds to solution $x_3 = 1, x_1 = x_3 = x_4 = 0$.
- If we switch to $\mathcal{B} = \{x_3, x_1\}$ we get $\max(-x_4)$ s.t. $x_3 = 1 - x_2, x_1 = -x_4$: optimality condition is OK but last solution not improved

Optimal region

- The **feasible region** for a LP problem P in **canonical** form is a set $\mathcal{F}_P = \{x \in \mathbb{R}^n \mid Ax \leq b, x \geq 0\}$ denoting a **convex polyhedron**
- The **optimal region** for a LP problem P in standard form is a set of solutions $\mathcal{O}_P = \{x^* \in \mathcal{F}_P \mid cx^* \geq cx, \forall x \in \mathcal{F}_P\}$
- Clearly $\mathcal{O}_P \subseteq \mathcal{F}_P$ and $\mathcal{F}_P = \emptyset \Rightarrow \mathcal{O}_P = \emptyset$
- If \mathcal{O}_P is **finite**, then $|\mathcal{O}_P| = 1$ (hence $|\mathcal{O}_P| > 1 \Rightarrow \mathcal{O}_P$ **infinite**)
 - if $x_1, x_2 \in \mathcal{O}_P$ and $x_1 \neq x_2$ then all points in segment $\overline{x_1 x_2}$ are in \mathcal{O}_P because $x_1, x_2 \in \mathcal{F}_P$ which is convex
- Is there any problem P such that $\mathcal{F}_P \neq \emptyset \wedge \mathcal{O}_P = \emptyset$?

Unboundedness

- Simply consider $\max(x)$ s.t. $x \geq 0$: we have $\mathcal{F}_P = [0, +\infty)$ but there is no $x^* \in \mathcal{R}$ s.t. $x^* \geq x$ for all $x \in \mathcal{F}_P$: $\mathcal{O}_P = \emptyset$
- In these cases P is said **unbounded**: no optimal solution exists
 - \mathcal{F}_P is an **unbounded polyhedron**
- Simplex method also performs an “**unboundedness check**”
- With the tableau method seen above, we must ensure that **no column** j has reduced cost $\gamma_j > 0$ and coefficients $\alpha_{i,j} \leq 0$ for $i = 1, \dots, m$
 - In the literature you can find different but equivalent formulations

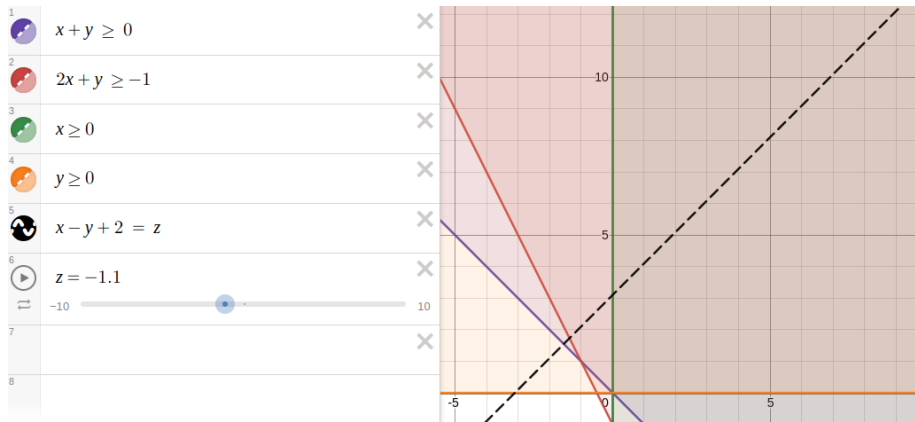
Unboundedness

- For example, consider $\max(x - y + 2)$ s.t. $x + y \geq 0$, $2x + y \geq -1$, $x, y \geq 0$. The tableau of the problem can be written as:

$$\begin{array}{rccccccc} & x & - & y & & & - & Z & = & -2 \\ \hline - & x & - & y & + & S_1 & & & = & 0 \\ - & 2x & - & y & & & + & S_2 & = & 1 \\ \hline x & , & y & , & S_1 & , & S_2 & & \geq & 0 \end{array}$$

- With $\mathcal{B} = \{S_1, S_2\}$ we have a BFS with $x = y = 0$ and obj. value 2
 - Degenerate solution ($S_1 = 0$)
- Reduced cost of x is $1 > 0$ and its row coefficients are $-1, -2 \leq 0$: the problem is **unbounded**: x can be arbitrarily increased

Unboundedness



- E.g., from each feasible solution (\tilde{x}, \tilde{y}) we can always derive a **better** solution $(\tilde{x} + k, \tilde{y})$ for each $k > 0$

Simplex steps

Given LP P in **standard form**, we can (roughly) summarize the simplex method as:

0. Let $k \leftarrow 0$, let \mathcal{B}_0 a **feasible base** for P and go to 1.
1. If BFS of \mathcal{B}_k is **optimal** then **STOP**, else go to 2.
2. If P **unbounded** then **STOP**, else go to 3.
3. Select an **entering** variable $x^{in} \notin \mathcal{B}_k$ and go to 4.
4. Select a **leaving** variable $x^{out} \in \mathcal{B}_k$ and go to 5.
5. Let $\mathcal{B}_{k+1} = \mathcal{B}_k \cup \{x^{in}\} - \{x^{out}\}$ and **reformulate** P accordingly.
Let $k \leftarrow k + 1$ and go back to 1.

- The former baking example in standard form is:

$$\begin{array}{llllll} \max & 400B & + & 450C & & \\ \text{s.t.} & 250B & + & 200C & + & S_1 = 4000 \\ & 2B & & & + & S_2 = 6 \\ & 75B & + & 150C & + & S_3 = 2000 \\ & 100B & + & 150C & + & S_4 = 500 \\ & & & 75C & + & S_5 = 500 \\ & B & , & C & , & S_i \geq 0 \quad i = 1, \dots, 5 \end{array}$$

- Exercise:** Find the optimal solution through the simplex method.

Simplex properties

- If **all** the possible BFS are **non-degenerate**, the simplex method always **terminates** in a finite number of steps
 - The no. of vertices is **finite** and at each step we move from one vertex to another always **strictly improving** the obj. value
- Otherwise, possible **stalling**: we repeatedly change base without improving the obj. value (common in large scale applications)
 - **Termination** can be guaranteed by setting **rules** preventing possible (but unlikely) infinite loops $\mathcal{B}_k \rightarrow \mathcal{B}_{k+1} \rightarrow \cdots \rightarrow \mathcal{B}_k$
- **Worst-case** time-complexity of simplex method is $O(2^n)$ but in practice is typically **polynomial**
- Alternative: **interior point** methods (polynomial) or approximation algorithms
 - Interior point better than simplex for problems with lots of vertices

Two-phase method

- So far we assumed that we can always find a **feasible base**
 - How to choose an initial **feasible base** B_0 ?
 - What if the problem is **unsatisfiable**?
- The **two-phase method** finds (if any) an initial base for a standard problem P by first solving an “**artificial**” **problem** P' derived from P by adding **fresh variables** s_1, \dots, s_m
- **2nd phase** problem P : $\max(cx)$ s.t. $Ax = b, x \geq 0$
- **1st phase** problem P' : $\max(-\sum_{i=1}^m s_i)$ s.t.
 - $\sum_{j=1}^n a_{i,j}x_j + s_i = b_i$ for $i \in \{k \in \{1, \dots, m\} \mid b_k \geq 0\}$
 - $\sum_{j=1}^n a_{i,j}x_j - s_i = b_i$ for $i \in \{k \in \{1, \dots, m\} \mid b_k < 0\}$
 - $s_i, x_j \geq 0$

Two-phase method

- 1st phase problem P' : $\max(-\sum_{i=1}^m s_i)$ s.t.
 - $\sum_{j=1}^n a_{i,j}x_j + s_i = b_i$ for $i \in \{k \in \{1, \dots, m\} \mid b_k \geq 0\}$
 - $\sum_{j=1}^n a_{i,j}x_j - s_i = b_i$ for $i \in \{k \in \{1, \dots, m\} \mid b_k < 0\}$
 - $s_i, x_j \geq 0$

- E.g., if P is:

$$\max(x_1 + 2x_2) \quad \text{s.t.}$$

$$-x_1 - x_2 + x_3 = -1$$

$$x_1 + x_2 + x_4 = 2$$

$$x_1, \dots, x_4 \geq 0$$

- Then P' is:

$$\max(-s_1 - s_2) \quad \text{s.t.}$$

$$-x_1 - x_2 + x_3 - s_1 = -1$$

$$x_1 + x_2 + x_4 + s_2 = 2$$

$$x_1, \dots, x_4, s_1, s_2 \geq 0$$

Two-phase method

- Note that objective $-\sum_{i=1}^m s_i$ is always ≤ 0 and $\mathcal{B}' = \{s_1, \dots, s_m\}$ is always a **feasible basis** corresponding to BFS $x_j = 0, s_i = |b_i|$
 - Hence, $\mathcal{F}_{P'} \neq \emptyset$ and $\mathcal{O}_{P'} \neq \emptyset$ (P' upper-bounded by 0)

- So we **reformulate** P' w.r.t. \mathcal{B}' . In the example above we get:

$$\max(-3 - 2x_1 + 2x_2 - x_3 + x_4) \text{ s.t.}$$

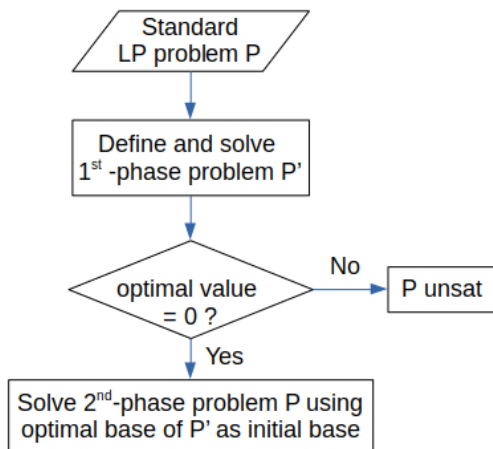
$$s_1 = 1 - x_1 - x_2 + x_3$$

$$s_2 = 2 - x_1 - x_2 - x_4$$

$$x_1, \dots, x_4, s_1, s_2 \geq 0$$

- Then we solve P' with the simplex method. A nice property is that $\mathcal{F}_P \neq \emptyset \iff \sum_{i=1}^m s_i = 0$:
 - If the optimal value of P' is < 0 , then P is **unsatisfiable**,
 - Otherwise, from the basis corresponding to the optimal solution of P' we get an **initial basis** for P by **removing** s_i variables

Two-phase method



Duality

- Let's now tackle the brewery problem from a different angle

Beverage	Corn	Hops	Malt	Profit
Ale	5	4	35	13
Beer	15	4	20	23
Q.ty available	480	160	1190	

- An **entrepreneur** wants to buy individual resources (corn, hops, malt) **from** brewer at **minimum cost**
- The brewer won't sell resources if $5C + 4M + 35H < 13$ (Ale profit) and $15C + 4M + 20H < 23$ (Beer profit)
- What would be the **minimum unit cost** for corn, hops, malt given the resource availability and the brewer's constraints?

Duality

- Let's now tackle the brewery problem from a different angle

Beverage	Corn	Hops	Malt	Profit
Ale	5	4	35	13
Beer	15	4	20	23
Q.ty available	480	160	1190	

- The entrepreneur LP problem can be formulate as:

$$\begin{array}{llllllll} \text{minimize} & 480C & + & 160H & + & 1190M & & \\ \text{subject to} & 5C & + & 4H & + & 35M & \geq & 13 \\ & 15C & + & 4H & + & 20M & \geq & 23 \\ & C & , & H & , & M & \geq & 0 \end{array}$$

- Optimal solution: $C = 1, H = 2, M = 0$ with total cost 800\$
 - Exercise: transform in canonical and standard form

Duality

- The entrepreneur problem is the **dual** of the brewery problem
- Resource **evaluation** rather than allocation
- Two different perspectives, but **same optimal value**
 - Brewer knows that she can earn **at most 800\$**
 - Entrepreneur knows that she has to spend **at least 800\$**
- The **duality** concept is important (not only) in LP and can be extended to general (N)LP problems

Duality

- Let $P : \max(cx)$ s.t. $Ax = b, x \geq 0$ with $b \in \mathbb{R}^m, x \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ the **primal** problem
- Its **dual** problem $\mathcal{D}(P) : \min(by)$ s.t. $A^t y \geq c$ with $y \in \mathbb{R}^m$ has:
 - a variable y_i for each constraint $\sum_{j=1}^n a_{i,j}x_j = b_i$ of P , $i = 1, \dots, m$
 - a constraint $\sum_{i=1}^m a_{j,i}y_i \leq c_j$ for each variable x_j of P , $j = 1, \dots, n$
- Exercise:** find the dual of following primal problem:

$$\begin{array}{rcll} \max & x_1 & + & x_2 \\ \text{s.t.} & 3x_1 & + & 2x_2 + x_3 & = & 5 \\ & 4x_1 & + & 5x_2 & + & x_4 & = & 4 \\ & & + & x_2 & & + & x_5 & = & 2 \\ & x_1 & , & x_2 & , & x_3 & , & x_4 & , & x_5 & \geq & 0 \end{array}$$

Duality

- Let $P : \max(cx)$ s.t. $Ax = b, x \geq 0$ with $b \in \mathbb{R}^m, x \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ the **primal** problem
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 - a constraint $\sum_{i=1}^m a_{j,i}y_i \leq c_j$ for each variable x_j of P , $j = 1, \dots, n$
- Exercise:** find the dual of following primal problem:

$$\begin{array}{llllllllll} \max & x_1 & + & & x_2 & & & & & & \\ \text{s.t.} & 3x_1 & + & & 2x_2 & + & & x_3 & & & = 5 & (y_1) \\ & 4x_1 & + & & 5x_2 & & & & + & x_4 & = 4 & (y_2) \\ & & & + & x_2 & & & & & + & x_5 & = 2 & (y_3) \\ & x_1 & , & x_2 & , & x_3 & , & x_4 & , & x_5 & \geq 0 \\ & (con_1) & , & (con_2) & , & (con_3) & , & (con_4) & , & (con_5) & & \end{array}$$

Duality

- Let $P : \max(cx)$ s.t. $Ax = b, x \geq 0$ with $b \in \mathbb{R}^m, x \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ the **primal** problem
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- Exercise:** find the dual of following primal problem:

$$\begin{array}{llll} \max & x_1 + x_2 & \text{s.t.} & \implies \min & 5y_1 + 4y_2 + 2y_3 & \text{s.t.} \\ 3x_1 + 2x_2 + x_3 & = 5 & (y_1) & 3y_1 + 4y_2 & \geq 1 \\ 4x_1 + 5x_2 + x_4 & = 4 & (y_2) & 2y_1 + 5y_2 + y_3 & \geq 1 \\ x_2 + x_5 & = 2 & (y_3) & y_1 & \geq 0 \\ x_1, x_2, x_3, x_4, x_5 & \geq 0 & & y_2 & \geq 0 \\ & & & y_3 & \geq 0 \end{array}$$

Duality

- Let $P : \max(cx)$ s.t. $Ax = b, x \geq 0$ with $b \in \mathbb{R}^m, x \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ the **primal** problem
- Its **dual** problem $\mathcal{D}(P) : \min(by)$ s.t. $A^t y \geq c$ with $y \in \mathbb{R}^m$ has:
 - a variable y_i for each constraint $\sum_{j=1}^n a_{i,j}x_j = b_i$ of P , $i = 1, \dots, m$
 - a constraint $\sum_{i=1}^m a_{j,i}y_i \leq c_j$ for each variable x_j of P , $j = 1, \dots, n$
- What about the **dual** of the **dual**?

$$\begin{array}{llll} \max & x_1 + x_2 & \text{s.t.} & \implies \\ & 3x_1 + 2x_2 + x_3 = 5 & (y_1) & \\ & 4x_1 + 5x_2 + x_4 = 4 & (y_2) & \\ & x_2 + x_5 = 2 & (y_3) & \\ & x_1, x_2, x_3 \geq 0 & & \end{array} \quad \begin{array}{llll} \min & 5y_1 + 4y_2 + 2y_3 & \text{s.t.} & \implies \\ & 3y_1 + 4y_2 \geq 1 & (x_1) & \\ & 2y_1 + 5y_2 + y_3 \geq 1 & (x_2) & \\ & y_1 \geq 0 & (x_3) & \\ & y_2 \geq 0 & (x_4) & \\ & y_3 \geq 0 & (x_5) & \end{array}$$

Duality properties

- $\mathcal{D}(\mathcal{D}(P)) = P$: the dual of the dual is the **primal**
- **Weak duality**: the cost of **any** feasible solution of the primal is \leq the cost of any solution of the dual: $(\forall x \in \mathcal{F}_P, \forall y \in \mathcal{F}_{\mathcal{D}(P)}) \quad cx \leq by$
 - by is an **upper bound** for obj. value of P
 - cx is a **lower bound** for obj. value of $\mathcal{D}(P)$
 - by “decreases” until a **minimum** value eventually reached ↘
 - cx “increases” until a **maximum** value eventually reached ↗
 - If P unbounded, $\mathcal{D}(P)$ unfeasible: $(\mathcal{F}_P \neq \emptyset \wedge \mathcal{O}_P = \emptyset) \Rightarrow \mathcal{F}_{\mathcal{D}(P)} = \emptyset$
 - if $\mathcal{D}(P)$ unbounded, P unfeasible: $(\mathcal{F}_{\mathcal{D}(P)} \neq \emptyset \wedge \mathcal{O}_{\mathcal{D}(P)} = \emptyset) \Rightarrow \mathcal{F}_P = \emptyset$
- **Strong duality**: if primal and dual are feasible they have **same optimal** values: $\mathcal{F}_P, \mathcal{F}_{\mathcal{D}(P)} \neq \emptyset \Rightarrow (\forall x^* \in \mathcal{O}_P, \forall y^* \in \mathcal{O}_{\mathcal{D}(P)}) \quad cx^* = by^*$
 - Remember brewery example?

Possible cases

- Note that primal unbounded \implies dual unfeasible but in general
primal unfeasible $\not\Rightarrow$ dual unbounded
 - E.g., $P : \max(2x_1 - x_2)$ s.t. $x_1 - x_2 \leq 1, -x_1 + x_2 \leq -2, x_1, x_2 \geq 0$ is unfeasible, and so is $\mathcal{D}(P)$
 - Exercise: prove it!
- In summary (\checkmark = possible, \times = impossible):

	$\mathcal{D}(P)$ bounded	$\mathcal{D}(P)$ unbounded	$\mathcal{D}(P)$ unfeasible
P bounded	\checkmark	\times	\times
P unbounded	\times	\times	\checkmark
P unfeasible	\times	\checkmark	\checkmark

Dual simplex

- We can avoid to compute $\mathcal{D}(P)$ to apply the (primal) simplex on $\mathcal{D}(P)$ by running on P the dual simplex (C.E. Lemke, 1954)
 - C.E. Lemke, 1954
- Primal simplex: from feasible to optimal basis, preserving feasibility
- Dual simplex: from optimal basis (reduced costs ≤ 0 , not necessarily feasible) to feasible basis, while preserving optimality
 - x^{out} = variable with minimum negative value
 - x^{in} = variable with maximum negative ratio
- Primal-dual: hybrid approach

Why duality?

- **Theoretical** purposes
 - E.g., finding a **feasible** solution is **as hard as** finding the **optimal** one: if we can find a solution for $\max(cx)$ s.t. $Ax = b, x \geq 0$ in $T(n, m)$ time, we can find one for $Ax = b, x \geq 0, A^t y \geq c, cx = by$ in $O(T(n, m))$
- **Prove infeasibility** of the primal problem (via dual simplex)
- **Bounding** the objective function (maybe with parallel solving)
 - Primal gives **lower** bound, dual gives **upper** bound
- **Exploiting** alternative/hybrid approaches
 - (primal-)dual simplex, (logic-based) Benders' decomposition
- **Sensitivity analysis**

Sensitivity analysis

- **Sensitivity analysis** refers to how the optimal solution of a problem is affected by **changes** in the input **parameters**
 - **Post-optimality** analysis
- If x^* is the optimal solution for standard LP problem P , will x^* be still **feasible** and/or **optimal** for a **perturbed** problem $\bar{P} \neq P$?
- $\bar{P} : \max(cx)$ s.t. $Ax = b, x \geq 0$ can be obtained from P by **altering**:
 - The **known term**: $b \rightsquigarrow \bar{b} = b + \Delta b$
 - The **objective function** coefficients: $c \rightsquigarrow \bar{c} = c + \Delta c$
 - The **variables** coefficients: $A \rightsquigarrow \bar{A} + \Delta A$

Sensitivity analysis

- **Known term:** Changing $b \rightsquigarrow \bar{b} = b + \Delta b$ can affect both the **feasibility** and **optimality** of current solution

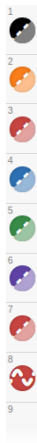
Beverage	Corn	Hops	Malt	Profit
Ale	5	4	35	13
Beer	15	4	20	23
Q.ty available	480	160	1190	

- E.g., for brewery problem if corn availability **decreases** from 480 to 479 the optimal solution $A = 12, B = 28$ is **not feasible** anymore and the objective value drops from 800 to 790 ($A = 13, B = 27$)
 - If hops decreases 1 unit, objective value drops to 787 ($A = 11, B = 28$)
 - If malt decreases up to 210 units, $A = 12, B = 28$ **still optimal**
 - In fact, $S_C = S_H = 0$ and $S_M = 210$ in the original optimal solution

Changing known term

- For brewery problem, **increasing b** doesn't affect feasibility, but can **improve** the obj. value
 - $\Delta b < 0 \rightarrow$ narrowing \mathcal{F}_P , $\Delta b > 0 \rightarrow$ extending \mathcal{F}_P
- In this case:
 - Increasing corn of ≥ 10 units improves the obj. value
 - Increasing hops of ≥ 4 units improves the obj. value
 - Increasing malt only **never improves** the obj. value
- Changing known term of $P \equiv$ changing objective function of $\mathcal{D}(P)$
- We can compute the impact of Δb on P **without re-solving** P : if \mathcal{B} is an **optimal basis** for P , $\bar{x}_{\mathcal{B}} = A_{\mathcal{B}}^{-1}\bar{b} = A_{\mathcal{B}}^{-1}b + A_{\mathcal{B}}^{-1}\Delta b$
 - If feasible ($\bar{x}_{\mathcal{B}} \geq 0$), the objective value $c_{\mathcal{B}}A_{\mathcal{B}}^{-1}\bar{b}$ can change as well

Geometric interpretation



1 $0 \leq x \leq 100$

2 $0 \leq y \leq 100$

3 $250x + 200y \leq 4000$

4 $2x \leq 6$

5 $75x + 150y \leq 2000$

6 $100x + 150y \leq 500$

7 $75y \leq 500$

8 $400x + 450y = 0$



Baking example: what ingredients should we (*not*) **buy** first to increase profit? If we can't buy, which ones should we **sell** without altering profit?

Changing costs

- **Cost coefficients:** Changing $c \rightsquigarrow \bar{c} = c + \Delta c$ can't affect **feasibility**, but may involve:
 - Loss of **optimality** of current solution
 - Different **objective value** for current solution (still optimal)
- E.g., in the brewery example if the profit of beer is **39** instead of 23 the optimal solution will be still **$A = 12, B = 28$**
 - But total profit would be **1248** instead of 800!
 - The same applies if beer profit drops to **14** (total profit 548)
- If beer profit is outside **$[14, 39]$** the solution changes as well
 - E.g., if beer profit = 13 then **$A = 26, B = 14$** is more convenient
- Again, we don't need to re-solve P to assess the impact of Δc

Changing constraints

- The impact of changing a coefficient $A \rightsquigarrow \bar{A} = A + \Delta A$ depends on whether $\bar{a}_{i,j}$ refers to a variable x_j in the **optimal basis**:
- If not, $x_j = 0$ so the current solution is still feasible and its value won't change. But the obj. function can change: we **may lose optimality**
- If yes, we can't say much: we need to **re-solve** with \bar{A}
- E.g., if the ale production would now require 4 units of corn instead of 5, then $A = 12, B = 28$ still feasible but no more optimal
 - $A = 11, B = 29$ would be better in this case (total profit 810)

Take-home messages

- Linear programming (LP) is one of the main areas of Operations Research (OR) field
- LP is about solving problems with linear constraints/objective function in a canonical or standard form
- The feasible region for a LP is a convex polyhedron
 - it can be empty, bounded, unbounded
- The simplex algorithm is a well-known method to tackle LP problems
 - Worst-case exponential, typically polynomial
 - Worst-case polynomial algorithms exist for LP problems

Take-home messages

- Simplex works by moving from one **extreme point** of the feasible region to a “not-worse one” up to an optimal point
 - **Interior point** methods traversing feasible region may scale better
- **Two-phase method** to check feasibility and get initial basis
- We can solve the **dual** of a LP problem: different perspective, **same optimal value**
- **Sensitivity analysis** to assess the effect of **perturbations** of the original problem
 - **Post-optimality** analysis, often doable without re-solving the problem

- <https://www.cs.princeton.edu/courses/archive/spr03/cs226/lectures/lp-4up.pdf>
- CDMO course a.y. 2020/21
- ...