

# Q & A

3) Within the terminological approach towards the representation of concepts/categories and individuals/instances, the candidate is invited to illustrate the notions of

- Disjointness over a set S of categories ( $S = \{c_1, c_2, \dots, c_n\}$ , where  $c_1 \dots c_n$  are categories)
- Exhaustive Decomposition of a category  $c$  into a set S of categories
- Partition of a category  $c$  into a set of categories S

The candidate is invited to illustrate these notions through a simple example

$$\text{Disjoint}(C) \Leftrightarrow \{ \forall c_1, c_2 \in C, c_1 \neq c_2 \Rightarrow c_1 \cap c_2 = \emptyset \}, \text{ example} \rightarrow \text{Disjoint}(\{\text{animals}, \text{vegetables}\})$$

$$\text{Exhaustive}(S, c) \Leftrightarrow \{ \forall i \in \mathbb{N} \Leftrightarrow \exists c_i \in S \wedge i \in \mathbb{N} \}, \text{ example} \rightarrow \text{Exhaustive}(\{\text{animals}, \text{vegetables}\}), \text{ exhaust in style}$$

$$\text{Partition}(S, c) \Leftrightarrow \text{Disjoint}(S) \wedge \text{Exhaustive}(S, c), \text{ example} \rightarrow \text{Partition}(\{\text{animals}, \text{vegetables}\}), \text{ exhaust in style}$$

2) The candidate is invited to introduce the vanilla meta-interpreter, and to explain its clauses.

```
value(+Value):-!.
value((A,B)):-!, value(A), value(B).
value(A):-clauses(A,B), value(B).
```

this meta-interpreter allow us to change "the rule of the game" manipulating the order of clauses execution and insert whatever we want.  
 the first line is the base case, whenever the value is the (soonly present in KB) this clause is true and disallow back track (cut).  
 the second line allow us to execute the two subgoals in left-most manner.  
 the third one take the clause of A and solve it recursively.

3) The candidate is invited to describe the predicates/terminology used in the definition of the Event Calculus Framework.

the event calculus framework allow us to use FOL with the concept of time. It uses the concept of point of time.  
 It is based on an ontology and two axioms.

the predicates are:

```
holdAt(F,T): the float F holds at time T.
happens(E,T): the event E happened at time T.
initiates(E,F,T): the float F caused by event E starts at time T.
terminates(E,F,T): the float F caused by event E ends at time T, T < T'.
dipped(T,F,T'): the float F dips below T' and T, T < T'.
initially(F): float F happened at beginning.
```

the domain specific axioms are:

$$\text{holdAt}(F, T) \Rightarrow \text{happens}(E, T) \wedge \text{initiates}(E, F, T) \wedge \neg \text{dipped}(T, F, +) \wedge F < T$$

$$\text{holdAt}(F, T) \Rightarrow \text{happens}(E, T) \wedge \text{terminates}(E, F, T) \wedge \neg \text{dipped}(O, F, T)$$

$$\text{holdAt}(F, T) \Rightarrow \text{initially}(F) \wedge \neg \text{dipped}(O, F, T)$$

$$\text{dipped}(T, F, T') \Rightarrow \text{happens}(E, T) \wedge \text{terminates}(E, F, T) \wedge T < T' < T$$

- 4) The candidate is invited to briefly introduce the notion of Semantic Networks, and to highlight some of the limits that were present in their original formulation.

Humans are used to reason about objects and classify them through categories, giving them some properties. Semantic networks are a structure to represent knowledge in these terms. They are categorized by nodes (or boxes) connected between labelled links. The links represent relations among:

- object-object
- category-category
- object-category (a-link)
- object/category - property

Limitations arise due to the semantics of this language. Despite FOL, there is missing the concept of higher, variable and extended quantifiers, disjunction and nested object function. Moreover an inheritance could happen due to the multiple inheritance.

- 3) The candidate is invited to briefly introduce the three different approaches (presented in the course), to deal with the reasoning with temporal information.

#### Structural calculus:

This approach was introduced in 1963 and aims to represent facts in temporal environment. The initial state is called situation, and if "a" is an action and "s" a situation,  $\text{Result}(s,a)$  is also a situation. Moreover it introduces the flat concept as " $\text{At}(x,t,s)$ ". Finally, we also have preconditions, defined as  $\phi(s) \Leftrightarrow \text{Pre}(s,a)$ . Given this, it uses also the successor state axioms ( $F^T \Leftrightarrow \text{Action}(\text{Last}, F) \vee (F \wedge \neg \text{Action}(\text{Last}, \neg F))$ ) with a different syntax.  $\text{Pos}(a,s) \Leftrightarrow (F(\text{Result}(s,a)) \Leftrightarrow a = \text{Action}(\text{Last}, F) \vee (\text{FC})) \wedge \neg \text{Action}(\text{Last}, \neg F)$ . It uses the unique action axiom, which allows the execution of only one action in a situation. So, the goal is defined as a set of flats and actions and intentions.

#### Event calculus

Based on the concept of points of time, uses a set of predicates composed in an ontology and two distinct axioms.

The predicates are:

$\text{Holds}(F,T)$ : the flat holds at the T

$\text{Happens}(E,T)$ : the event E happened at the T

$\text{InHolds}(E,F,T)$ : the event E causes F to hold at the T

$\text{Terminates}(t,F,T)$ : the event t causes F to cease at the T

$\text{Initially}(t)$ : flat t holds at the 0

$\text{ClipEnd}(T_1,F,T)$ : F has terminally between  $T_1$  and T,  $T_1 < T$ .

Moreover the axioms are:

$\cdot \text{HoldAt}(t,F,T) \wedge \text{Happens}(E,t) \wedge \text{InHolds}(E,F,T) \wedge T_1 < T \rightarrow \text{ClipEnd}(T_1,F,T)$ .

$\cdot \text{HoldsAt}(T,F,T) \wedge \text{Initially}(T) \wedge \neg \text{ClipEnd}(T,F,T)$ .

$\cdot \text{ClipEnd}(T,F,T) \wedge \text{Happens}(E,T) \wedge (T_1 < T < T_2) \rightarrow \text{ClipEnd}(T_1,F,T_2)$ .

This approach allows to reason with events' actions synchrony, but is not safe if places contains variables due to the NAT problem.

#### Allen's logic

Finally, this approach introduces the duration-based representation.

Introducing the concept of interval which begins and ends in a certain time point / 13

predicates could be defined such as Meet, Before, After, During, Overlap, Starts, Finishes, Equals.

- 4) The candidate is invited to briefly introduce the Description Logics, and in particular the principal operators of the ALC fragment (AND operator; ALL operator; [EXISTS 1 r] operator; concept complement (negation)).

Description Logics is a family of logics based on constructs implementable by them is reasoning process. Indeed, human thinks object as belong to categories, size or weight, measure or breeders. Moreover objects are also composed by parts, which interacts among them. De includes 3 elements: concept, roles, constraints, and logic operators like product, conjunction and numbers.

ALC is a type of DL and is based upon 4 fundamental operators:

AND:  $A \text{ AND } B$ , represents the set of individuals which belong to both concept A and B. Also called intersection. E.G: STUDENT and TEACHER represent all the individuals being both of them, i.e. teachers.

ALL:  $\forall R.C$ , represents all the individuals related to concept C. A enabled Smart is the set of values which follows a certain type of constraint. There is at least one individual which works for a certain concept.

EXISTS 1 r:  $\exists^1_R.C$ , says that there is at least one individual related to concept C. e.g: ?- pork(X).carn. This is at least one individual which works for a certain concept.

NOT: complements all the individuals related to bleg in a class: not student are all the professor for example.

- 2) The candidate is invited to shortly describe the RETE algorithm.

The RETE Algorithm, was developed in 70's as a way to optimize the performance of rule-based expert systems. It compares each fact with each rule using an high degree of parallelism.

A main implementation of expert system compares each fact with each rule using an high degree of parallelism.

This algorithm works as follows:

Rules are typically represented as a set of conditions and actions. Each condition specifies a pointer to next operator.

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- 1) The candidate is invited to present the notion of the cut "!" operator in the Prolog language. Moreover, the candidate should illustrate its usage through a very short example.

Prolog is a reasoning logic language. It's based on backtracking and SLD algorithm. If it, it starts to point

the query from the available KB. It attempts each way and backtracks the decision tree when reaches the failure.

The cut operator is used to assist the backtracking after a determined instruction enough to search for other possible solution and path. It's useful and to repeat the if else statement.

```
even(N,Result):- K is N mod 2, K == 0, !, Result = true.
```

```
even( _,Result),! ,Result = false.
```

- 2) The candidate is invited to briefly introduce the Knowledge Graph paradigms, and which are the main differences w.r.t. the Semantic Web proposal.

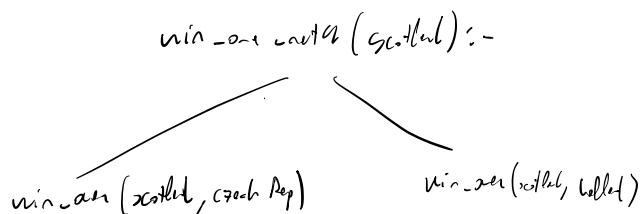
In the early start of Web, this was seen as a pool of infotext where the network was accessible to everyone. But, nonetheless, all this infotext, there was no way to, automate the reasoning process of a computer. Thus the Infotext was using a common structure with descriptive information between linked pages. A first proposal was the semantic web approach; each web relation was described through a triplet like: subject, relation, predicate. Instead of ontology, (owl) bsm to define the relationships and categories of infotext and a query language (sparql) to return infotexts. Knowledge graph are an extension of this approach, avoiding the triplets constraint and be more flexible about relations. It has a less formalized structure allowing to represent the relations as in the real world. This approach is useful by Google to return answers to the user's queries quickly and be more friendly to leave him after a quick click, returning also the probable targets.

- 1) Given the following LPAD program:

```
win_one_match(Team) :-  
    win_over(Team, _).  
  
win_over(scotland, czechRep):0.3.  
win_over(scotland, holland):0.2.
```

Which is the probability of the query `win_one_match(scotland)` ?

The candidate should illustrate the Distribution Semantics by showing the "worlds", the probability of each world, and the formula used to compute the overall probability.



$W_1$	$WO\_czech\ up\ T$
	$\neg O\_holland\ T$

$W_1$	$WO\_czech\ up\ F$
	$\neg O\_holland\ T$

$W_1$	$WO\_czech\ up\ T$
	$\neg O\_holland\ F$

$W_1$	$WO\_czech\ up\ F$
	$\neg O\_holland\ F$

$$= 0.3 \cdot 0.7 + 0.7 \cdot 0.2 + 0.3 \cdot 0.8 =$$

$$= 0.46$$

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Exam A

1) The candidate is invited to write a prolog predicate `count/2` that, given as input a term representing a predicate, it will return the number of solutions for the goal of proving that input predicate. For simplicity, it will be assumed that the proof procedure of the predicate passed as parameter will always terminate in a finite time.

For example:

```
p(a).
p(b).
p(c).
```

and the query:

```
count(p(X), Result).
```

The expected answer is:

```
Yes, Result = 3.
```

This is because there are three different ways for proving the goal `p(X)`.

---

`count(Fail, Result) :- findall(Goal, Goal, Solutions), length(Solutions, Result).`

- 1) The candidate is invited to describe the (operational) semantics of the predicates `setof`, `bagof`, and `findall`. Moreover, the description should be illustrated by some short examples.

*Setof, bagof and findall are three built-in search order formula in prolog. The first two make a list of objects satisfying:  $\forall x \in S, p(x)$  is true. where S is the list, p(x) is an random predicate present in KB. The differ between them is the power of repetition. When the predicate has two parameters, for example, the query is satisfied like:  $\forall x \in S, \exists y, p(x,y)$  is true corresponding to  $\text{set}(x, p(x,y), S)$ , not using the list of X where Y is necessarily quantified. In order to do this, we have to write  $\text{set}(x, \text{gen}(p(x,y)), S)$  or  $\text{findall}(x, p(x,y), S)$ . In this way we can generate by a random value of Y:  $\forall x \in S, \exists y, p(x,y)$  is true.*

- 1) The candidate is invited to describe how negation is tackled in Prolog, what is NAF, what is SLDNF, and the issues related with NAF over terms containing unbounded variables.

Due to the curta assumption in Prolog and SLD algorithm, the logic doesn't allow to derive negative information.

To overcome this problem, Prolog adapt Negation as Failure rule.

Given a program P, we have  $\text{PF}(P)$  the set of atoms for which the proof fails in a fail tree

$$\text{NF}(P) = \{\neg A \mid A \in \text{FF}(P)\}$$

If an atom A belongs to  $\text{PF}(P)$ , is not logical consequence of P.

To solve this, contrary also update atoms, SLDNF was proposed.

- Given a list of goals  $L_1 \dots L_n$ :

- Do not select any negative literal if is not ground.
- If the literal atom is positive, apply normal SLD.

• If  $L_i \equiv \neg A$  (A ground) and A fails in first tree,  $L_i$  is a problem.

The problem with unbound variables are that it could lead to a form of analysis of inconsistency, consider that it's not possible to prove either truth or failure.

- 2) The candidate is invited to describe the distribution semantics adopted in LPAD, using also a short program to illustrate such semantics.

LPAD is a Prolog library which allows to reason upon uncertainty and probability.

Given the code:

```
meaty(X); 0.7 :- flour(X).  
meaty(X); 0.3 :- has-fun(X).
```

The probability is calculated summing all the possible worlds where one of the statements is true.

Not the probability to meaty of X has flour is 0.7, while if it has fun is 0.3. So, the probability to meaty of X has not flour is 0.3 and not fun 0.2. the distributed world are when meaty or is true and neither

so the probability is calculated like conditional probability. A query like  $(\text{meaty}(\text{bob}) \mid \text{flour}(\text{bob}) \vee \text{has-fun}(\text{bob})) =$

$$0.7 \cdot 0.3 + 0.7 \cdot 0.7 + 0.3 \cdot 0.7 = 0.64$$

- 2) The candidate is invited to Forward reasoning in rule-based systems, and to highlight the difference w.r.t. backward reasoning.

forward reasoning  $\rightarrow$  a way to infer a fact given the initial state. Doing this process, it can create new solutions in order to reach the goal. In contrast backward reason starts from the goal and looks for existing facts to prove it, finally the given problem is solved. A forward way rule-based system is the RETE Algorithm.

- 3) The candidate is invited to introduce the notions of close world assumption and open world assumption, and to briefly discuss how Prolog and Description Logics deal with these aspects.

CWA and OWA deals with the degree of truth in KB.

In CWA, the KB is considered to be complete, so when a fact is missing, it is considered to be false. Prolog assumes this assumption, whenever it encounters a fact not present in KB, it considers it false and backtracks. It could be possible through a metaprogram to ask the user to expand the KB.

On the other hand, OWA consider what is not in KB as unknown.

Description Logics deals with this example, so whenever a fact is not known, it doesn't make false the entire logic.

infers, it doesn't make false the entire logic.