



Matroids and combinatorial optimization

Combinatoria 2022/2023

Lorenzo Gregoris (1867373)

January 10, 2024



SAPIENZA
UNIVERSITÀ DI ROMA



Table of Contents

1 Introduction

- ▶ Introduction
- ▶ Indipendence systems and matroids
- ▶ Maximization and minimization problems
- ▶ Greedy algorithms



Combinatorial optimization

1 Introduction

Many combinatorial optimization problems can be formulated as follows:

- a set system (E, \mathcal{F}) , i.e. a finite set E and some $\mathcal{F} \subseteq 2^E$;
- a cost function $c : \mathcal{F} \mapsto \mathbb{R}$;

Find an element of \mathcal{F} whose cost is minimum or maximum.



Goal

1 Introduction

We will introduce **independence systems** and **matroids** and show that many combinatorial optimization problems can be described in this context.

The main reason why matroids are important is that a **simple greedy algorithm can be used for optimization over matroids.**



Table of Contents

2 Independence systems and matroids

- ▶ Introduction
- ▶ Independence systems and matroids
- ▶ Maximization and minimization problems
- ▶ Greedy algorithms



Independence systems

2 Independence systems and matroids

Definition (Independence system)

A set system (E, \mathcal{F}) is an **independence system** if and only if:

- (M1) $\emptyset \in \mathcal{F}$;
- (M2) if $X \subseteq Y$, $Y \in \mathcal{F}$ then $X \in \mathcal{F}$.



Independence systems

2 Independence systems and matroids

Definition (Independence system)

A set system (E, \mathcal{F}) is an **independence system** if and only if:

- (M1) $\emptyset \in \mathcal{F}$;
- (M2) if $X \subseteq Y$, $Y \in \mathcal{F}$ then $X \in \mathcal{F}$.

The elements of \mathcal{F} are called *independent*, the elements of $2^E \setminus \mathcal{F}$ *dependent*. Maximal independent sets are called **bases**. For $X \subseteq E$, the maximal independent subsets of X are called bases of X .



Example

2 Independence systems and matroids

Consider any finite subset E of a vector space V . We can define an independence system by choosing $\mathcal{F} = \{Y \in 2^E : Y \text{ are linearly independent}\}$.

This set system clearly satisfies (M1) (there is no way to obtain $\vec{0}$ from a linear combination of an empty set of vectors) and (M2).

Keeping in mind this example, we introduce some definitions.



Some definitions

2 Independence systems and matroids

Definition (Rank)

Let (E, \mathcal{F}) be an independence system. For $X \subseteq E$ we define the rank of X by:

$$r(X) := \max\{|Y| : Y \subseteq X, Y \in \mathcal{F}\}.$$

The rank of a finite collection of vectors X is just the size of any basis for X . Does this hold for any independence system? No.



Counter example

2 Independence systems and matroids

Consider the independence set system (E, \mathcal{F}) where $E = \{1, 2, 3\}$ and $\mathcal{F} = \{\emptyset, \{1, 2\}, \{1\}, \{2\}, \{3\}\}$

We have two basis for E with different cardinality!

This suggests that subsets of linearly independent vectors have another property, in addition to (M1) and (M2). This is the *augmentation property*: Given two finite subsets of linearly independent vectors X and Y such that $|X| < |Y|$, we can find some vectors of Y to add to X such that they have the same rank.



Matroids

2 Independence systems and matroids

Definition (Matroid)

An independence system is a **matroid** if and only if:

- (M3) if $X, Y \in \mathcal{F}$, $|X| < |Y|$ then $\exists y \in Y \setminus X$ such that $X \cup \{y\} \in \mathcal{F}$.

Introduced in a paper called "*On the Abstract Properties of Linear Dependence*" by Hassler Whitney in 1935.



Equivalent axiom

2 Independence systems and matroids

This new axiom captures the propriety we were looking for:

Theorem

$(M3) \iff$ For each $X \subseteq E$, all bases of X have the same cardinality.



Equivalent axiom

2 Independence systems and matroids

This new axiom captures the propriety we were looking for:

Theorem

$(M3) \iff$ For each $X \subseteq E$, all bases of X have the same cardinality.

Proof

\implies Suppose a subset $X \subseteq E$ has two bases of different size $|B_1| > |B_2|$, we can add elements of the bigger base to the small and still be an independent set, but B_2 was chosen to be maximal.



Equivalent axiom

2 Independence systems and matroids

This new axiom captures the propriety we were looking for:

Theorem

(M3) \iff For each $X \subseteq E$, all bases of X have the same cardinality.

Proof

\implies Suppose a subset $X \subseteq E$ has two bases of different size $|B_1| > |B_2|$, we can add elements of the bigger base to the small and still be an independent set, but B_2 was chosen to be maximal.

\impliedby Let $X, Y \in \mathcal{F}$ such that $|X| > |Y|$. This means Y can't be a basis for $Y \cup X$. This means there must be an $x \in X \setminus Y$ such that $Y \cup \{x\} \in \mathcal{F}$. \square



Bases

2 Independence systems and matroids

Given a set of bases we can construct the remaining independent sets by adding all of their subsets.



Bases

2 Independence systems and matroids

Given a set of bases we can construct the remaining independent sets by adding all of their subsets.

Given a set of bases, when they generate a matroid?



Bases

2 Independence systems and matroids

Given a set of bases we can construct the remaining independent sets by adding all of their subsets.

Given a set of bases, when they generate a matroid?

Theorem (Bases characterization)

Let E be a finite set and $\mathcal{B} \subseteq 2^E$. \mathcal{B} is the set of bases of some matroid (E, \mathcal{F}) if and only if:

- (B1) $\mathcal{B} \neq \emptyset$.
- (B2) For any $A, B \in \mathcal{B}$ and $a \in A \setminus B$ there exists $b \in B \setminus A$ such that $(A \setminus \{a\}) \cup \{b\} \in \mathcal{B}$.



Bases

2 Independence systems and matroids

Given a set of bases we can construct the remaining independent sets by adding all of their subsets.

Given a set of bases, when they generate a matroid?

Theorem (Bases characterization)

Let E be a finite set and $\mathcal{B} \subseteq 2^E$. \mathcal{B} is the set of bases of some matroid (E, \mathcal{F}) if and only if:

- (B1) $\mathcal{B} \neq \emptyset$.
- (B2) For any $A, B \in \mathcal{B}$ and $a \in A \setminus B$ there exists $b \in B \setminus A$ such that $(A \setminus \{a\}) \cup \{b\} \in \mathcal{B}$.

(B2) is called the *base exchange property*.



Proof \implies The set of bases of a matroid satisfies (B1) by (M1), and (B2): the set $A \setminus \{a\}$ is still independent for (M2), so by (M3) we can find an element in $B \setminus A$ to create a new basis.

\Leftarrow Combinatorial Optimization. Theory and Algorithms (Bernhard Korte, Jens Vygen), theorem 13.9, page 337. \square



Properties of the rank function

2 Independence systems and matroids

Theorem

Let \mathcal{M} be a matroid on a finite set E . The rank function r of \mathcal{M} has the following properties:

- (R1) $0 \leq r(X) \leq |X|$ for all $X \subseteq E$.
- (R2) If $X \subseteq Y \subseteq E$ then $r(X) \leq r(Y)$.
- (R3) For every $X, Y \subseteq E$ $r(X \cup Y) + r(X \cap Y) \leq r(X) + r(Y)$.



Properties of the rank function

2 Independence systems and matroids

Theorem

Let \mathcal{M} be a matroid on a finite set E . The rank function r of \mathcal{M} has the following properties:

- (R1) $0 \leq r(X) \leq |X|$ for all $X \subseteq E$.
- (R2) If $X \subseteq Y \subseteq E$ then $r(X) \leq r(Y)$.
- (R3) For every $X, Y \subseteq E$ $r(X \cup Y) + r(X \cap Y) \leq r(X) + r(Y)$.

Proof (R1) and (R2) follow from the definition, they are satisfied in any independence system.



Rank characterization

2 Independence systems and matroids

Given a finite set E and a function $r : 2^E \mapsto \mathbb{N}$, we can define a matroid in the following way:

$$\mathcal{F} := \{F \subseteq E : r(F) = |F|\}$$

Corollary

Let E be a finite set. A function $r : 2^E \mapsto \mathbb{N}$ is the rank function of a matroid on E if and only if r satisfies properties (R1), (R2) and (R3).

Proof Combinatorial Optimization. Theory and Algorithms (Bernhard Korte, Jens Vygen), Page 338. \square



Rank quotient

2 Independence systems and matroids

We introduce another definition of rank of subsets for independent set system, the size of the smallest base contained:

Definition (Lower rank)

Let (E, \mathcal{F}) be an independence system. For $X \subseteq E$ we define the lower rank by:

$$\rho(X) := \min\{|Y| : Y \subseteq X, Y \in \mathcal{F} \text{ and } Y \cup \{x\} \notin \mathcal{F} \ \forall x \in X \setminus Y\}.$$



Rank quotient

2 Independence systems and matroids

We introduce another definition of rank of subsets for independent set system, the size of the smallest base contained:

Definition (Lower rank)

Let (E, \mathcal{F}) be an independence system. For $X \subseteq E$ we define the lower rank by:

$$\rho(X) := \min\{|Y| : Y \subseteq X, Y \in \mathcal{F} \text{ and } Y \cup \{x\} \notin \mathcal{F} \ \forall x \in X \setminus Y\}.$$

Definition (Rank quotient)

The rank quotient of (E, \mathcal{F}) is defined by:

$$q(E, \mathcal{F}) := \min_{X \subseteq E} \frac{\rho(X)}{r(X)}$$



Properties of rank quotient

2 Independence systems and matroids

It follows from the definition that $q(E, \mathcal{F}) \leq 1$, and an independence system is a matroid if and only if $q(E, \mathcal{F}) = 1$, since this is equivalent to the statement that every bases for any $X \subseteq E$ has the same cardinality.

$$(E, \mathcal{F}) \text{ is a Matroid} \iff q(E, \mathcal{F}) = 1$$



Table of Contents

3 Maximization and minimization problems

- ▶ Introduction
- ▶ Indipendence systems and matroids
- ▶ Maximization and minimization problems
- ▶ Greedy algorithms



Maximization and minimization problems for IS

3 Maximization and minimization problems

Definition (Maximization problem)

Instance: A set system (E, \mathcal{F}) and a cost function $c : E \mapsto \mathbb{R}$.

Task: Find $X \in \mathcal{F}$ such that $c(X) := \sum_{e \in X} c(e)$ is maximum.



Maximization and minimization problems for IS

3 Maximization and minimization problems

Definition (Maximization problem)

Instance: A set system (E, \mathcal{F}) and a cost function $c : E \mapsto \mathbb{R}$.

Task: Find $X \in \mathcal{F}$ such that $c(X) := \sum_{e \in X} c(e)$ is maximum.

Definition (Minimization problem)

Instance: A set system (E, \mathcal{F}) and a cost function $c : E \mapsto \mathbb{R}$.

Task: Find a basis B such that $c(B) := \sum_{e \in B} c(e)$ is minimum.

Note: $c(\emptyset) = 0$.



Duality

3 Maximization and minimization problems

There is a natural duality between minimization and maximization problems on independence systems: finding a minimum cost basis B in (E, \mathcal{F}) is the same as finding the maximum cost complement $E \setminus B$. This suggests the following definition:



Duality

3 Maximization and minimization problems

There is a natural duality between minimization and maximization problems on independence systems: finding a minimum cost basis B in (E, \mathcal{F}) is the same as finding the maximum cost complement $E \setminus B$. This suggests the following definition:

Definition (Dual IS)

Let (E, \mathcal{F}) be an independence system. We define its **dual** (E, \mathcal{F}^*) so that the bases in \mathcal{F}^* are exactly the complements of the bases of \mathcal{F} .



Duality

3 Maximization and minimization problems

There is a natural duality between minimization and maximization problems on independence systems: finding a minimum cost basis B in (E, \mathcal{F}) is the same as finding the maximum cost complement $E \setminus B$. This suggests the following definition:

Definition (Dual IS)

Let (E, \mathcal{F}) be an independence system. We define its **dual** (E, \mathcal{F}^*) so that the bases in \mathcal{F}^* are exactly the complements of the bases of \mathcal{F} .

It's clear that $(E, \mathcal{F}^{**}) = (E, \mathcal{F})$.



So which sets are in \mathcal{F}^* ?



So which sets are in \mathcal{F}^* ? Every subset of the dual basis \mathcal{B}^* , this means:

$$\mathcal{F}^* = \{F \subseteq E : \exists B \in \mathcal{B} \text{ s.t. } B \cap F = \emptyset\}$$



Properties of the dual

3 Maximization and minimization problems

Theorem

Let (E, \mathcal{F}) be an independence system, (E, \mathcal{F}^*) its dual, and let r and r^* be the corresponding rank functions.

1. (E, \mathcal{F}) is a matroid if and only if (E, \mathcal{F}^*) is a matroid.
2. If (E, \mathcal{F}) is a matroid, then $r^*(E) = |F| + r(E \setminus F) - r(E)$ for $F \subseteq E$.



Proof We only give a proof of 2. The idea to prove 1. is via the rank function characterization: verify that r^* satisfies (R1), (R2) and (R3).



Proof We only give a proof of 2. The idea to prove 1. is via the rank function characterization: verify that r^* satisfies (R1), (R2) and (R3).

Let (E, \mathcal{F}) be a matroid with bases \mathcal{B} and (E, \mathcal{F}^*) its dual.

$$r^*(F) = \max_{I \subseteq F, I \in \mathcal{F}^*} |I|$$



Proof We only give a proof of 2. The idea to prove 1. is via the rank function characterization: verify that r^* satisfies (R1), (R2) and (R3).

Let (E, \mathcal{F}) be a matroid with bases \mathcal{B} and (E, \mathcal{F}^*) its dual.

$$\begin{aligned} r^*(F) &= \max_{I \subseteq F, I \in \mathcal{F}^*} |I| \\ &= \max_{B \in \mathcal{B}} |F \cap (E \setminus B)| \end{aligned}$$



Proof We only give a proof of 2. The idea to prove 1. is via the rank function characterization: verify that r^* satisfies (R1), (R2) and (R3).

Let (E, \mathcal{F}) be a matroid with bases \mathcal{B} and (E, \mathcal{F}^*) its dual.

$$\begin{aligned} r^*(F) &= \max_{I \subseteq F, I \in \mathcal{F}^*} |I| \\ &= \max_{B \in \mathcal{B}} |F \cap (E \setminus B)| \\ &= \max_{B \in \mathcal{B}} |F \setminus B| \end{aligned}$$



Proof We only give a proof of 2. The idea to prove 1. is via the rank function characterization: verify that r^* satisfies (R1), (R2) and (R3).

Let (E, \mathcal{F}) be a matroid with bases \mathcal{B} and (E, \mathcal{F}^*) its dual.

$$\begin{aligned} r^*(F) &= \max_{I \subseteq F, I \in \mathcal{F}^*} |I| \\ &= \max_{B \in \mathcal{B}} |F \cap (E \setminus B)| \\ &= \max_{B \in \mathcal{B}} |F \setminus B| \\ &= |F| - \min_{B \in \mathcal{B}} |F \cap B| \end{aligned}$$



Proof We only give a proof of 2. The idea to prove 1. is via the rank function characterization: verify that r^* satisfies (R1), (R2) and (R3).

Let (E, \mathcal{F}) be a matroid with bases \mathcal{B} and (E, \mathcal{F}^*) its dual.

$$\begin{aligned} r^*(F) &= \max_{I \subseteq F, I \in \mathcal{F}^*} |I| \\ &= \max_{B \in \mathcal{B}} |F \cap (E \setminus B)| \\ &= \max_{B \in \mathcal{B}} |F \setminus B| \\ &= |F| - \min_{B \in \mathcal{B}} |F \cap B| \\ &= |F| - |B| + \max_{B \in \mathcal{B}} |(E \setminus F) \cap B| \\ &= |F| - r(E) + r(E \setminus F) \quad \square \end{aligned}$$



Examples

3 Maximization and minimization problems

- *Maximum weight stable set problem:* given a graph G and weights $c : V(G) \mapsto \mathbb{R}$, find a stable set $X \subseteq V(G)$ of maximum weight. Here $E = V(G)$ and $\mathcal{F} = \{F \subseteq E : F \text{ is stable in } G\}$.



Examples

3 Maximization and minimization problems

- *Maximum weight stable set problem*: given a graph G and weights $c : V(G) \mapsto \mathbb{R}$, find a stable set $X \subseteq V(G)$ of maximum weight. Here $E = V(G)$ and $\mathcal{F} = \{F \subseteq E : F \text{ is stable in } G\}$.
- *TSP*: given a complete undirected graph G and weights $c : E(G) \mapsto \mathbb{R}^+$, find a minimum weight Hamiltonian circuit in G . Here $\mathcal{F} = \{F \subseteq E : F \text{ is a subset of edges in an Hamiltonian circuit in } G\}$.



Examples

3 Maximization and minimization problems

- *Maximum weight stable set problem:* given a graph G and weights $c : V(G) \mapsto \mathbb{R}$, find a stable set $X \subseteq V(G)$ of maximum weight. Here $E = V(G)$ and $\mathcal{F} = \{F \subseteq E : F \text{ is stable in } G\}$.
- *TSP:* given a complete undirected graph G and weights $c : E(G) \mapsto \mathbb{R}^+$, find a minimum weight Hamiltonian circuit in G . Here $\mathcal{F} = \{F \subseteq E : F \text{ is a subset of edges in an Hamiltonian circuit in } G\}$.
- *MST:* given a connected undirected graph G and weights $c : E(G) \mapsto \mathbb{R}$, find a minimum weight spanning tree in G . Here $E = E(G)$ and the elements of \mathcal{F} are the edge sets of the forests in G .



The first two problems are NP -hard, while the last one is in P . The independence systems of the first two problems are not matroids, while the last one is! This isn't a coincidence, we will show that simple (polynomial) algorithms solve optimization problems on matroids.



The IS of MST is a matroid

3 Maximization and minimization problems

Proposition

The set system (E, \mathcal{F}) , where E is the set of edges of some undirected graph G and $\mathcal{F} := \{F \subseteq E : (V(G), F) \text{ is a forest}\}$ is a matroid.



The IS of MST is a matroid

3 Maximization and minimization problems

Proposition

The set system (E, \mathcal{F}) , where E is the set of edges of some undirected graph G and $\mathcal{F} := \{F \subseteq E : (V(G), F) \text{ is a forest}\}$ is a matroid.

Proof It is obvious that is an independence system, it remains to show that (M3) holds. We will prove its contrapositive.



The IS of MST is a matroid

3 Maximization and minimization problems

Proposition

The set system (E, \mathcal{F}) , where E is the set of edges of some undirected graph G and $\mathcal{F} := \{F \subseteq E : (V(G), F) \text{ is a forest}\}$ is a matroid.

Proof It is obvious that is an independence system, it remains to show that (M3) holds. We will prove its contrapositive. Let $X, Y \in \mathcal{F}$, and suppose $Y \cup \{x\} \notin \mathcal{F}$ for all $x \in X \setminus Y$. We show $|X| \leq |Y|$. For each $x = \{u, v\} \in X$, u and v are in the same connected component of $(V(G), Y)$. Hence each connected component $Z \subseteq (V(G), X)$ is a subset of a connected component of $(V(G), Y)$. So the number of connected component p of the forest $(V(G), X)$ is greater or equal to the number q of connected components of the forest $(V(G), Y)$. But $|V(G)| - |X| = p \geq q = |V(G)| - |Y|$, implying $|X| \leq |Y|$. \square



Table of Contents

4 Greedy algorithms

- ▶ Introduction
- ▶ Indipendence systems and matroids
- ▶ Maximization and minimization problems
- ▶ Greedy algorithms



Greedy algorithms

4 Greedy algorithms

Again, let (E, \mathcal{F}) be an independence system and $c : E \mapsto \mathbb{R}^+$ (non-negative weights). We consider the **Maximization problem** for (E, \mathcal{F}, c) and formulate two “greedy” algorithms.



Greedy algorithms

4 Greedy algorithms

Again, let (E, \mathcal{F}) be an independence system and $c : E \mapsto \mathbb{R}^+$ (non-negative weights). We consider the **Maximization problem** for (E, \mathcal{F}, c) and formulate two “greedy” algorithms.

The first one, called **Best-In** builds the solution choosing at each step the best possible element.



Greedy algorithms

4 Greedy algorithms

Again, let (E, \mathcal{F}) be an independence system and $c : E \mapsto \mathbb{R}^+$ (non-negative weights). We consider the **Maximization problem** for (E, \mathcal{F}, c) and formulate two “greedy” algorithms.

The first one, called **Best-In** builds the solution choosing at each step the best possible element.

The second, called **Worst-Out** at each step removes the worst element, until a feasible solution is attained.



Greedy algorithms

4 Greedy algorithms

Again, let (E, \mathcal{F}) be an independence system and $c : E \mapsto \mathbb{R}^+$ (non-negative weights). We consider the **Maximization problem** for (E, \mathcal{F}, c) and formulate two “greedy” algorithms.

The first one, called **Best-In** builds the solution choosing at each step the best possible element.

The second, called **Worst-Out** at each step removes the worst element, until a feasible solution is attained.

They both employ the use of an oracle to decide if a given subset $X \subseteq E$ is feasible.



The best-in greedy algorithm for maximization

4 Greedy algorithms

Best-In-Greedy algorithm

Input: An independence system (E, \mathcal{F}) , given by an independence oracle, weights $c : E \mapsto \mathbb{R}^+$.

Output: A set $F \in \mathcal{F}$.

1. Sort E such that $c(e_1) \geq c(e_2) \geq \dots \geq c(e_n)$.
2. Set $F \leftarrow \emptyset$.
3. **For** $i = 1$ to n **do**:
 If $F \cup \{e_i\} \in \mathcal{F}$ **then** set $F \leftarrow F \cup \{e_i\}$



The best-in greedy algorithm for maximization

4 Greedy algorithms

Best-In-Greedy algorithm

Input: An independence system (E, \mathcal{F}) , given by an independence oracle, weights $c : E \mapsto \mathbb{R}^+$.

Output: A set $F \in \mathcal{F}$.

1. Sort E such that $c(e_1) \geq c(e_2) \geq \dots \geq c(e_n)$.
2. Set $F \leftarrow \emptyset$.
3. **For** $i = 1$ to n **do**:
 If $F \cup \{e_i\} \in \mathcal{F}$ **then** set $F \leftarrow F \cup \{e_i\}$

The output F of Best-In-Greedy algorithm will be a basis for E .



The worst-out greedy algorithm for maximization

4 Greedy algorithms

The second algorithm requires a more complicated oracle. Given a set $F \subseteq E$, this oracle decides whether F contains a basis. Let us call such an oracle a basis-superset oracle.

Worst-out-Greedy algorithm

Input: An independence system (E, \mathcal{F}) , given by a basis-superset oracle, weights $c : E \mapsto \mathbb{R}^+$.

Output: A basis $F \in \mathcal{F}$.

1. Sort E such that $c(e_1) \leq c(e_2) \leq \dots \leq c(e_n)$.
2. Set $F \leftarrow E$.
3. **For** $i = 1$ to n **do**:
 If $F \setminus \{e_i\}$ contains a basis **then** set $F \leftarrow F \setminus \{e_i\}$



Greedy algorithms for minimization

4 Greedy algorithms

One can analogously formulate both greedy algorithms for the Minimization problem.



Greedy algorithms for minimization

4 Greedy algorithms

One can analogously formulate both greedy algorithms for the Minimization problem. It is easy to see that the Best-In for the Maximization problem for (E, \mathcal{F}, c) corresponds to Worst-Out for the Minimization problem for (E, \mathcal{F}^*, c) : adding an element to F in Best-In corresponds to removing an element from F in Worst-out.



Greedy algorithms for minimization

4 Greedy algorithms

One can analogously formulate both greedy algorithms for the Minimization problem. It is easy to see that the Best-In for the Maximization problem for (E, \mathcal{F}, c) corresponds to Worst-Out for the Minimization problem for (E, \mathcal{F}^*, c) : adding an element to F in Best-In corresponds to removing an element from F in Worst-out. This is the dual relationship discussed before.



Quality of the solution

4 Greedy algorithms

Theorem (Jenkyns 1976, Korte and Hausmann 1978)

Let (E, \mathcal{F}) be an independence system. For $c : E \mapsto \mathbb{R}^+$ we denote by $G(E, \mathcal{F}, c)$ the cost of some solution found by the Best-In-Greedy for the Minimization problem, and by $OPT(E, \mathcal{F}, c)$ the cost of an optimum solution. Then

$$q(E, \mathcal{F}) \leq \frac{c(G)}{c(OPT)} \leq 1$$

for all $c : E \mapsto \mathbb{R}^+$. There is a cost function where the lower bound is attained.



Quality of the solution

4 Greedy algorithms

Theorem (Jenkyens 1976, Korte and Hausmann 1978)

Let (E, \mathcal{F}) be an independence system. For $c : E \mapsto \mathbb{R}^+$ we denote by $G(E, \mathcal{F}, c)$ the cost of some solution found by the Best-In-Greedy for the Minimization problem, and by $OPT(E, \mathcal{F}, c)$ the cost of an optimum solution. Then

$$q(E, \mathcal{F}) \leq \frac{c(G)}{c(OPT)} \leq 1$$

for all $c : E \mapsto \mathbb{R}^+$. There is a cost function where the lower bound is attained.

Proof Let $E = \{e_1, \dots, e_n\}$ and $c(e_1) \geq c(e_2) \geq \dots \geq c(e_n)$. Let G_n be the solution found by Best-In-Greedy, while O_n is an optimum solution.



We define $E_j := \{e_1, \dots, e_j\}$, $G_j := G_n \cap E_j$ and $O_j := O_n \cap E_j$. Set $d_n := c(e_n)$ and $d_j := c(e_j) - c(e_{j+1})$ for $j = 1, \dots, n-1$. Since $O_j \subseteq O_n$, $O_j \in \mathcal{F}$ by (M2). We have $|O_j| \leq r(E_j)$.



We define $E_j := \{e_1, \dots, e_j\}$, $G_j := G_n \cap E_j$ and $O_j := O_n \cap E_j$. Set $d_n := c(e_n)$ and $d_j := c(e_j) - c(e_{j+1})$ for $j = 1, \dots, n-1$.

Since $O_j \subseteq O_n$, $O_j \in \mathcal{F}$ by (M2). We have $|O_j| \leq r(E_j)$. Since G_j is a basis for E_j , we have $|G_j| \geq \rho(E_j)$. With these two inequalities we conclude that



We define $E_j := \{e_1, \dots, e_j\}$, $G_j := G_n \cap E_j$ and $O_j := O_n \cap E_j$. Set $d_n := c(e_n)$ and $d_j := c(e_j) - c(e_{j+1})$ for $j = 1, \dots, n-1$.

Since $O_j \subseteq O_n$, $O_j \in \mathcal{F}$ by (M2). We have $|O_j| \leq r(E_j)$. Since G_j is a basis for E_j , we have $|G_j| \geq \rho(E_j)$. With these two inequalities we conclude that

$$\begin{aligned} c(G_n) &= \sum_{j=1}^n (|G_j| - |G_{j-1}|) c(e_j) \\ &= \sum_{j=1}^n |G_j| d_j \\ &\geq \sum_{j=1}^n \rho(E_j) d_j \end{aligned}$$



$$\begin{aligned} &\geq q(E, \mathcal{F}) \sum_{j=1}^n r(E_j) d_j \\ &\geq q(E, \mathcal{F}) \sum_{j=1}^n |O_j| d_j \\ &= q(E, \mathcal{F}) \sum_{j=1}^n (|O_j| - |O_{j-1}|) c(e_j) \\ &= q(E, \mathcal{F}) c(O_n) \end{aligned}$$

this proves the inequality.



We now prove that the lower bound is tight. Choose $F \subseteq E$ and bases B_1, B_2 of F such that $\frac{|B_1|}{|B_2|} = q(E, \mathcal{F})$, define the cost function:

$$c(e) := \begin{cases} 1 & \text{for } e \in F \\ 0 & \text{for } e \in E \setminus F \end{cases}$$

If we sort e_1, \dots, e_n such that $B_1 = \{e_1, \dots, e_{|B_1|}\}$ the algorithm will find B_1 as a solution, and the lower bound is attained. \square



Rado-Edmonds theorem

4 Greedy algorithms

Theorem (Rado 1957, Edmonds 1971)

An independence system (E, \mathcal{F}) is a matroid if and only if the BEST-IN-GREEDY finds an optimum solution for the MAXIMIZATION PROBLEM for (E, \mathcal{F}, c) for all cost functions $c : E \mapsto \mathbb{R}^+$.

This is one of the rare cases where we can define a structure by its algorithmic behaviour.



Quality of the solution for the minimization problem

4 Greedy algorithms

Theorem

Korte and Monma 1979 Let (E, \mathcal{F}) be an independence system. For $c : E \mapsto \mathbb{R}^+$ let $G(E, \mathcal{F}, c)$ denote a solution found by Worst-Out-Greedy for the Minimization problem. Then

$$1 \leq \frac{G(E, \mathcal{F}, c)}{OPT(E, \mathcal{F}, c)} \leq \max_{F \subseteq E} \frac{|F| - \rho^*(F)}{|F| - r^*(F)}$$

for all $c : E \mapsto \mathbb{R}^+$, where ρ^ and r^* are the rank functions of the dual independence system (E, \mathcal{F}^*) . There is a cost function where the upper bound is attained.*



Proof We use the same notation as in the previous proof. At each step, the partial solution will be $(E \setminus E_j) \cup G_j$, by construction contains a basis of E . Its complement $E_j \setminus G_j$, like G_j in Best-In-Greedy is a basis for E_j in the dual \mathcal{F}^* , thus:

$$|E_j| - |G_j| \geq \rho^*(E_j)$$

Likewise, the complement of the solution $E_j \setminus O_j$ is independent in \mathcal{F}^* , thus:

$$|E_j| - |O_j| \leq r^*(E_j)$$



We now use the same trick to compute the cost of the solution G_n :

$$\begin{aligned} c(G_n) &= \sum_{j=1}^n (|G_j| - |G_{j-1}|) c(e_j) \\ &= \sum_{j=1}^n |G_j| d_j \\ &\leq \sum_{j=1}^n |E_j| - \rho^*(E_j) d_j \end{aligned}$$



$$\begin{aligned} &= \sum_{j=1}^n (|E_j| - \rho^*(E_j)) \frac{|E_j| - r^*(E_j)}{|E_j| - r^*(E_j)} d_j \\ &\leq \max_{F \subseteq E} \frac{|F| - \rho^*(F)}{|F| - r^*(F)} \sum_{j=1}^n |O_j| d_j \\ &= \max_{F \subseteq E} \frac{|F| - \rho^*(F)}{|F| - r^*(F)} \sum_{j=1}^n (|O_j| - |O_{j-1}|) c(e_j) \\ &= \max_{F \subseteq E} \frac{|F| - \rho^*(F)}{|F| - r^*(F)} c(O_n) \end{aligned}$$

□

To prove that the upper bound is tight we can use the same strategy as in the Edmons-Rado theorem. □



Remarks

4 Greedy algorithms

We have shown that using **Best-In-Greedy** for maximization problems on matroids will always find the best solution, likewise **Worst-Out-Greedy** for minimization problems.



Remarks

4 Greedy algorithms

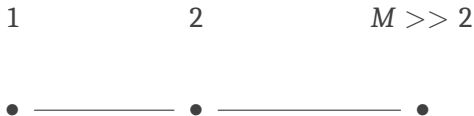
We have shown that using **Best-In-Greedy** for maximization problems on matroids will always find the best solution, likewise **Worst-Out-Greedy** for minimization problems. If we apply the **Worst-Out-Greedy** to the maximization problem or the **Best-In-Greedy** to the minimization problems, **there is no positive lower/finite upper bound for $\frac{G}{OPT}$.**



Remarks

4 Greedy algorithms

We have shown that using **Best-In-Greedy for maximization problems** on matroids will always find the best solution, likewise **Worst-Out-Greedy for minimization problems**. If we apply the **Worst-Out-Greedy** to the maximization problem or the **Best-In-Greedy** to the minimization problems, **there is no positive lower/finite upper bound for $\frac{G}{OPT}$** . To see this try finding a minimal vertex cover of maximum weight or a maximal stable set of minimum weight in this simple graph:





Remarks

4 Greedy algorithms

However in the case of matroids, it does not matter whether we use the Best-In-Greedy or the Worst-Out-Greedy: since all bases have the same cardinality, the minimization problem for (E, \mathcal{F}, c) is equivalent to the maximization problem for (E, \mathcal{F}, c') , where

$$\begin{aligned}c'(e) &:= M - c(e) && \forall e \in E \\ M &:= 1 + \max\{c(e) : e \in E\}\end{aligned}$$

Therefore

Corollary

Kruskal's algorithm solves the MST problem optimally.



Matroids and combinatorial optimization

Thank you for listening!