

~~Лекция~~ Практика 2.

1) $\dot{x} = -\epsilon \sin(x)$; $x^* = ?$

$\dot{x} = 0$

$0 = -\epsilon \sin(x)$

1) $\epsilon = 0 \Rightarrow x(t) = \text{const}$

2) $x = \pi k, k \in \mathbb{Z}$

$\Gamma \neq k=0$

Анал. системы около $x^* = 0$

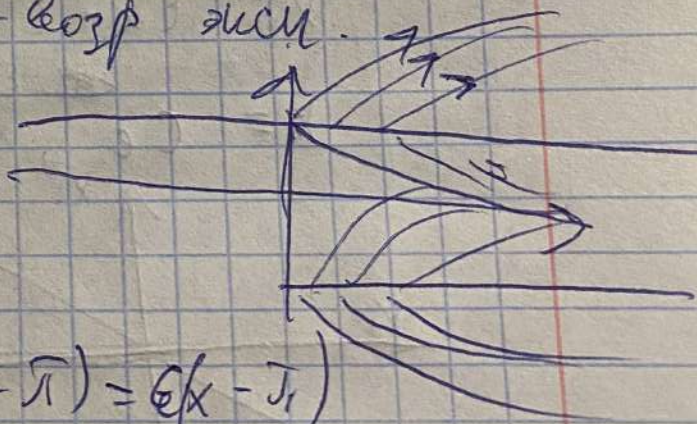
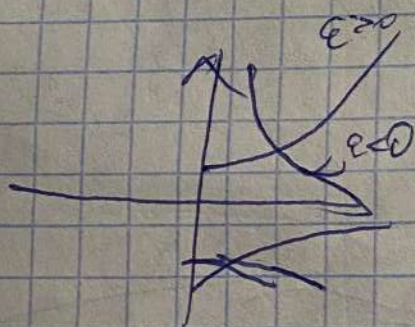
$$\dot{x} = \left. \frac{\partial F(\epsilon, x)}{\partial x} \right|_{x=x^*} \cdot (x - x^*) = -\epsilon \cdot \cos(0) \cdot (x - 0) = -\epsilon x$$

$\dot{x} = -\epsilon x$

~~Решение~~ $x = C e^{-\epsilon t}$

При $\epsilon > 0$ x убав. эксп.

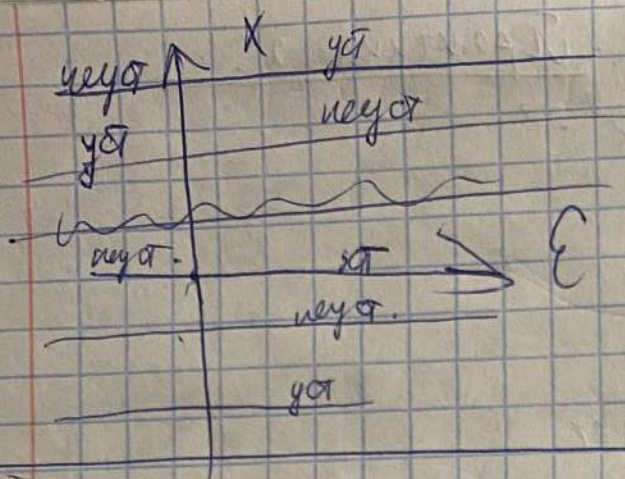
$\epsilon < 0$ x - возр. эксп.



II. $k=1 \Rightarrow \dot{x} = -\epsilon \cos \pi (x - \pi) = \epsilon (x - \pi)$

$x = C e^{\epsilon t} + \pi$ $\epsilon > 0$ x - возр. эксп.

$\epsilon < 0$, x - убав. экспонент



Биср. диаграмма

2. $\frac{dx}{dt} = \epsilon - x^2$ $\left| \begin{array}{l} x_1^* = 0 \\ x_2^* = \epsilon \end{array} \right.$

1) $x_1^* = 0$

$$\dot{x} = (\epsilon - 2x)x \Big|_{x=0} = \epsilon x$$

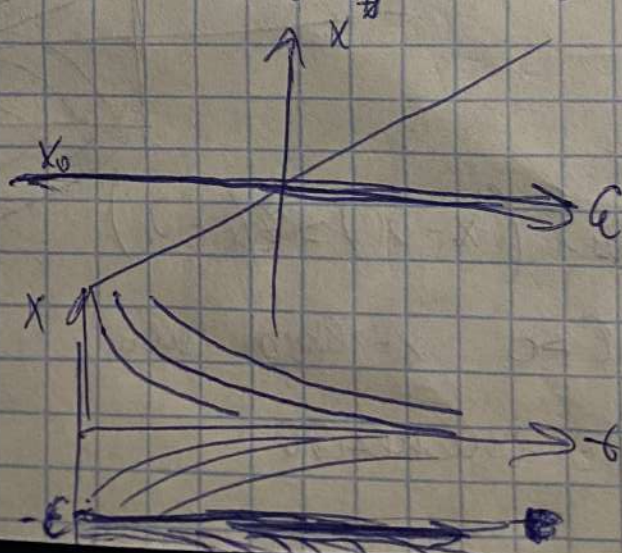
$$x = C e^{\epsilon t}$$

2) $x_2^* = \epsilon$

$$\dot{x} = (\epsilon - 2x^*) (x - x^*) = -\epsilon (x - \epsilon)$$

$$\dot{x} = -\epsilon x - \epsilon^2$$

$$x = C e^{-\epsilon t} + \epsilon$$



Биср. диаграмма

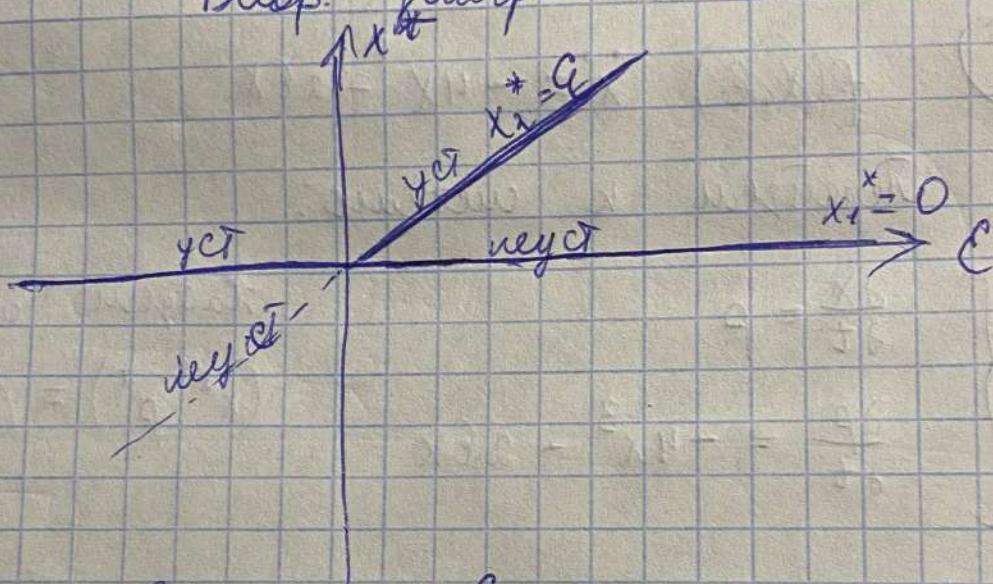
Биср.

$$\textcircled{3} \quad \frac{dx}{dt} = \epsilon x - x^2$$

Найдем особые точки:

$$x_1^* = \epsilon, \quad x_2^* = 0. \quad \text{Строим БД:}$$

Биф. диаграммы.



x_1^* устойчива при $\epsilon \geq 0$ и неуст. при $\epsilon < 0$

x_2^* устойчива при $\epsilon < 0$ и неуст. при $\epsilon \geq 0$

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$$\frac{\partial x}{\partial t} = \epsilon x - x^3$$

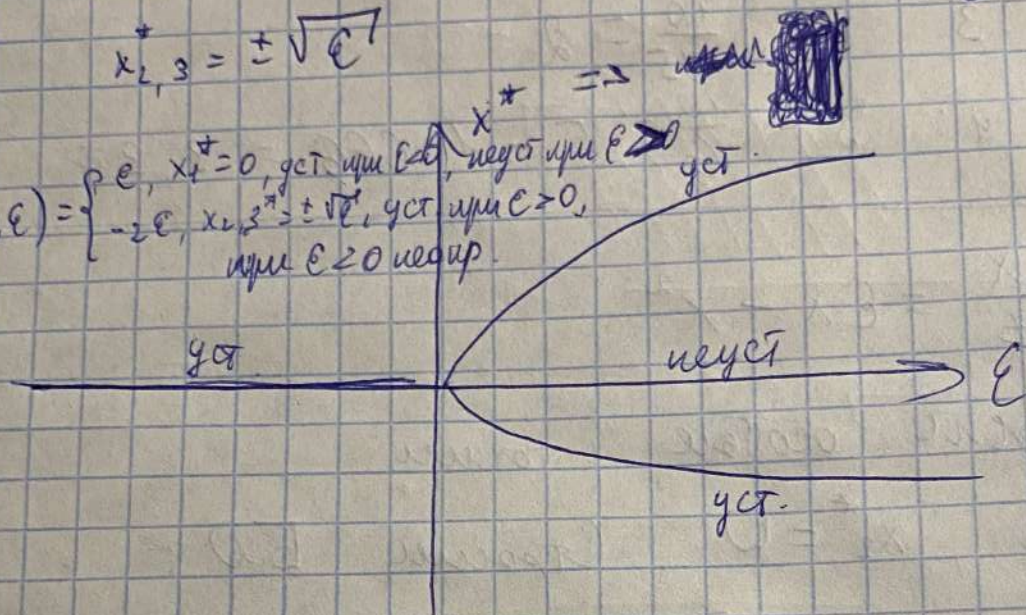
Найдём точки особые:

$$x_1^* = 0$$

$$x_{2,3}^* = \pm \sqrt{\epsilon}$$

$$f'(x, \epsilon) = \epsilon - 3x^2 = \begin{cases} \epsilon, & x_1^* = 0 \\ -2\epsilon, & x_{2,3}^* = \pm \sqrt{\epsilon} \end{cases}$$

$$f'(x, \epsilon) = \begin{cases} \epsilon, & x_1^* = 0, \text{ уст. при } \epsilon < 0, \text{ неуст. при } \epsilon > 0 \\ -2\epsilon, & x_{2,3}^* = \pm \sqrt{\epsilon}, \text{ уст. при } \epsilon > 0, \\ & \text{или } \epsilon < 0 \text{ неуст.} \end{cases}$$



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$$\dot{x} = -4x^3 - 2\epsilon x$$

Перейдём к системе:

$$\begin{cases} \frac{\partial x}{\partial t} = p \\ \frac{\partial p}{\partial t} = -4x^3 - 2\epsilon x \end{cases}$$

Найдём особые точки

$$(x^*, p^*) = (0, 0)$$

Линеаризуем:

$$\begin{cases} \frac{\partial x}{\partial t} = p \\ \frac{\partial p}{\partial t} = (-12x^{*2} - 2\epsilon)(x - 0) \Big|_{x^*=0} = -2\epsilon x \end{cases}$$

$$\begin{cases} \frac{\partial x}{\partial t} = p \\ \frac{\partial p}{\partial t} = -2\epsilon x \end{cases}$$

Матрица системы:

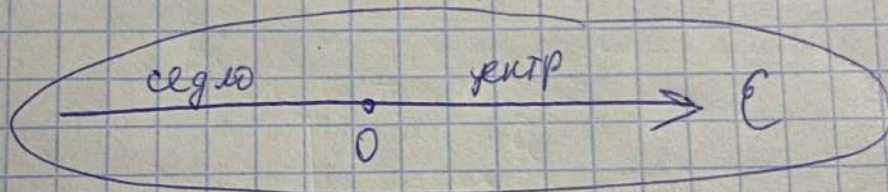
$$A = \begin{pmatrix} 0 & 1 \\ -2\epsilon & 0 \end{pmatrix} \Rightarrow \det(A - \lambda E) = 0$$

$$\begin{vmatrix} -\lambda & 1 \\ -2\epsilon & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 + 2\epsilon = 0$$

$$\lambda_{1,2} = \pm i\sqrt{2\epsilon}$$

~~матрица системы~~

~~сег~~



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$$\begin{cases} \frac{\partial x_1}{\partial t} = \epsilon x_1 \\ \frac{\partial x_2}{\partial t} = -x_2 \end{cases}$$

Запишем матрицу системы

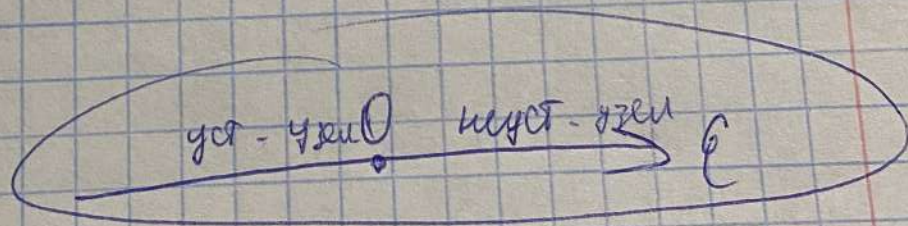
$$A = \begin{pmatrix} \epsilon & 0 \\ 0 & -1 \end{pmatrix}$$

$$\det(A - \lambda E) = \begin{vmatrix} \epsilon - \lambda & 0 \\ 0 & -1 - \lambda \end{vmatrix} = 0$$

$$(\epsilon - \lambda)(-1 - \lambda) = 0$$

$$\lambda_1 = \epsilon$$

$$\lambda_2 = -1$$



$$\begin{cases} \dot{x} = \epsilon x - y - x(x^2 + y^2) \\ \dot{y} = x + \epsilon y - y(x^2 + y^2) \end{cases}$$

$$\{x(t); y(t)\} \rightarrow \{r(t), \varphi(t)\}$$

$$x(t) = r(t) \cdot \cos(\varphi)$$

$$y(t) = r(t) \cdot \sin(\varphi)$$

$$\dot{x}(t) = \dot{r}(t) \cdot \cos \varphi - r(t) \cdot \sin \varphi \cdot \dot{\varphi}(t)$$

$$\dot{y}(t) = \dot{r}(t) \sin \varphi + r(t) \cos \varphi \cdot \dot{\varphi}(t)$$

$$\sin \varphi \left\{ \begin{aligned} \dot{r} - \cos \varphi - r \sin \varphi \cdot \dot{\varphi} &= \epsilon r \cos \varphi - r \sin \varphi - r \cos \varphi \cdot r^2 \end{aligned} \right.$$

$$\cos \varphi \left\{ \begin{aligned} \dot{r} \sin \varphi + r \cos \varphi \cdot \dot{\varphi} &= r \cos \varphi + \epsilon r \sin \varphi - r \sin \varphi \cdot r^2 \end{aligned} \right.$$

$$P \quad \dot{r} = Q(r, \varphi)$$

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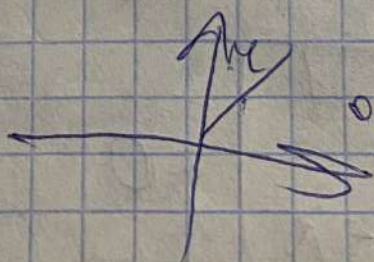
$$1) \cdot \sin \varphi - \cos \varphi \text{ и наоборот}$$

$$2) \cdot \cos \varphi \cdot \sin \varphi \text{ и наоборот}$$

$$\begin{cases} \dot{r} = \epsilon r - r^3 \\ -r \dot{\varphi} = -r \end{cases} \rightarrow \begin{cases} \dot{r} = \epsilon r - r^3 \\ \dot{\varphi} = 1 \end{cases} \quad \begin{cases} r_1^* = 0 \\ r_{2,3}^* = \sqrt{\epsilon} \end{cases}$$

$$r \geq 0$$

$$\dot{r} = (\epsilon - 2r^2)(r - r^*)$$



$$0 < \varphi < 2\pi$$

$$r^* = 0$$

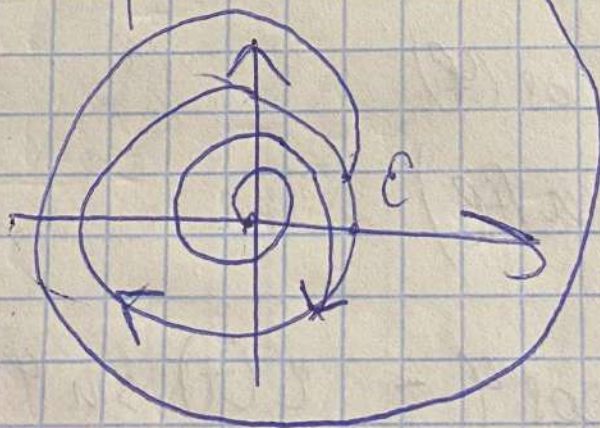
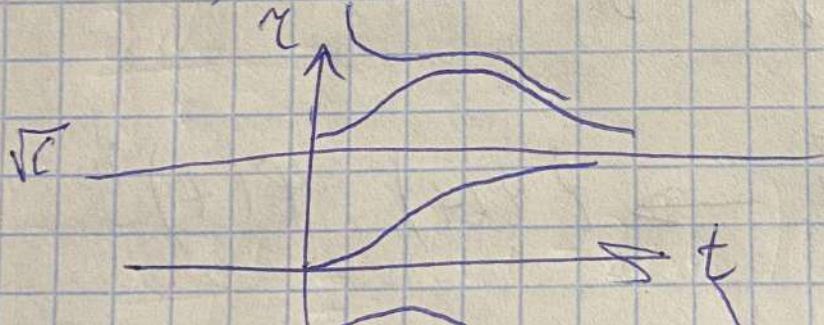
$$\dot{r} = \epsilon r$$

$$r^* = \sqrt{\epsilon}$$

$$\dot{r} = -2\epsilon(r - \sqrt{\epsilon})$$

$$u_1(t) = C_1 e^{\epsilon t}$$

$$u_2(t) = C_2 e^{-2\epsilon t} + \epsilon$$



Требуемые условия