

The Dataset

So far, we have introduced our simulator

The rest of our plan is as follows

- We learn an ML model
- We embed the model in a larger optimization problem
- We obtain a solution, i.e. a set of action to control the epidemics

But which data are we going to use for training?

The Dataset

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- We learn an ML model
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But which data are we going to use for training?

Since we have a simulator, we can build our dataset

- This means we can generate as much data as we wish
- ...But also that we are responsible for how to generate it

Building Our Dataset

We need to define the structure of the dataset

- We will focus on Non-Therapeutic Interventions (NPI)
 - E.g. mask mandates, social distancing...
- \blacksquare NPIs affect the β parameter in a SIR model
 - \blacksquare We will assume to have constant γ in our setup
- We will focus on making predictions at weekly intervals

Therefore, we can cover our needs with...

For the input part:

lacksquare The initial state (S,I,R) and the value of eta

For output part:

lacksquare The state after one week (S, I, R)

Given an input (S, I, R, β) , we can get the output via simulation

Building Our Dataset

Which input configurations should we generate?

A training set should be representative of the test distribution

- We do not have a fixed test distribution (no test set)
- ...But we know that the ML model will be used by an optimizer

The optimizer will seek to minimize the total infections So, we will need:

- High accuracy on the best configurations, so as to find them
- High accuracy on the worst configurations, so as to avoid them

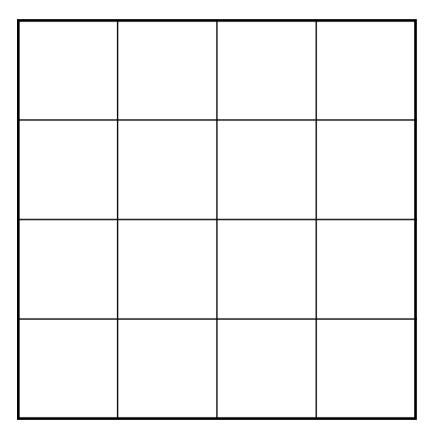
I.e. to be safe the model should work all across the board

Hence, we need a method that can cover well a given input space

- The simplest approach would be use use a regular grid
- ...But that approach does not scale well

The method we will use is called Latin Hypercube Sampling

Suppose we want to sample m points for n attributes with fixed ranges

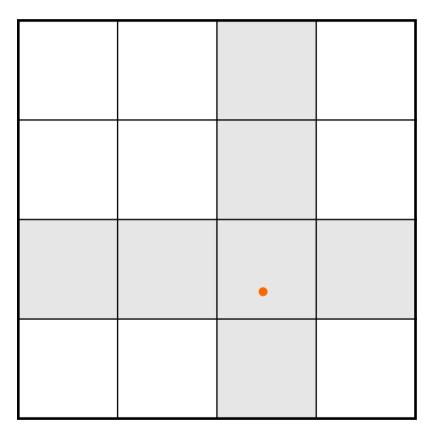


- We can view the sampling space as a hypercube
- \blacksquare ...Then we divide each dimension in n segments

In the example we want to sample 4 points for 2 attributes

The method we will use is called Latin Hypercube Sampling

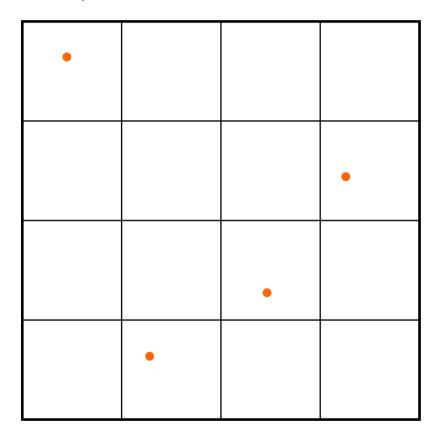
Suppose we want to sample m points for n attributes with fixed ranges



- We sample the first point uniformly at random
- ...Then we "cover" the row and column that contain the sample

The method we will use is called Latin Hypercube Sampling

Suppose we want to sample m points for n attributes with fixed ranges

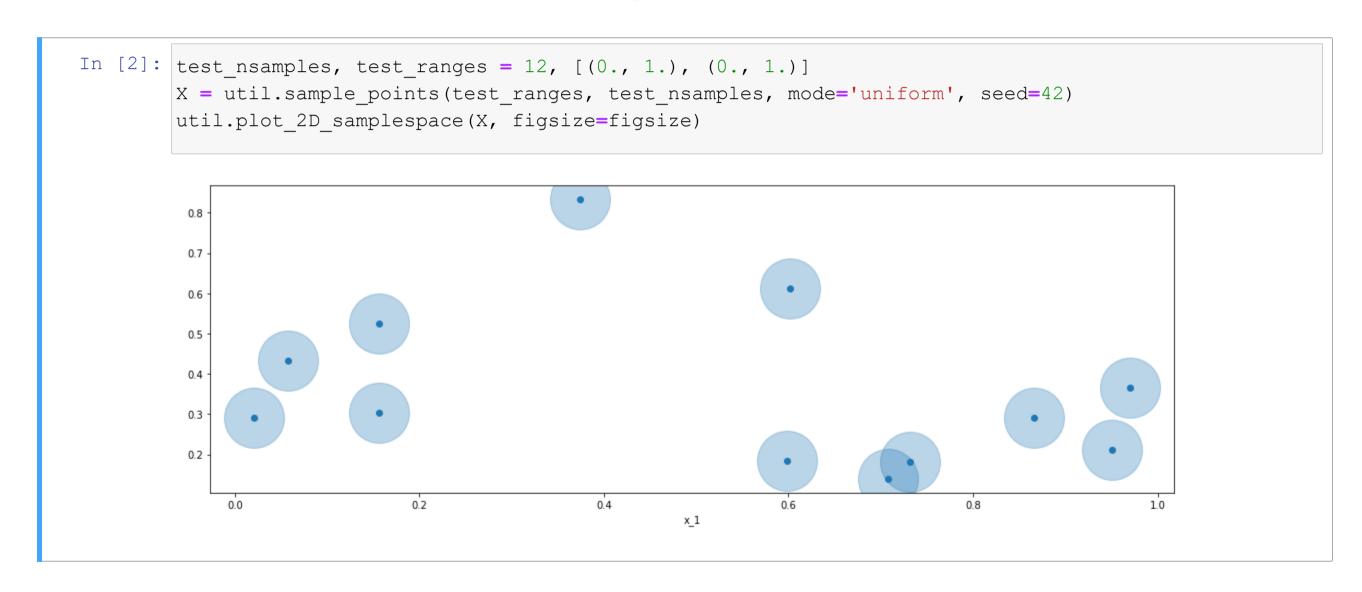


- When we take additional samples, we exclude all covered row/columns
- ...So we end up with a pattern similar to that of the figure

LHS can cover quite uniformly a given space with relatively few samples

Let's see a practical example

Here is the result of uniform sampling, for reference



Let's see a practical example

...And here is the result of classical LHS:

```
In [3]: test_nsamples, test_ranges = 12, [(0., 1.), (0., 1.)]
        X = util.sample points(test ranges, test nsamples, mode='lhs', seed=42)
        util.plot 2D samplespace(X, figsize=figsize)
         0.8
         0.6
         0.2
                             0.2
                                               0.4
                                                                0.6
                                                      x_1
```

The process can be further improved

E.g. after sampling we can try to maximize the minimum distance

```
In [4]: test nsamples, test_ranges = 12, [(0., 1.), (0., 1.)]
        X = util.sample points(test ranges, test nsamples, mode='max min', seed=42)
        util.plot_2D_samplespace(X, figsize=figsize)
          0.8
          0.6
          0.4
          0.2
                           0.2
                                             0.4
                                                               0.6
                                                                                 0.8
                                                                                                   1.0
                                                        x_1
```

Dataset Input

We are now ready to generate our dataset input

- We sample S, I, R, β from $[0, 1]^4$
- lacksquare ...Then S, I, R are normalized so that their sum is 1

This will reduce in some redundancy in the dataset

Dataset Output

We obtain the corresponding output via simulation

```
In [6]: %%time
        qamma = 1/14
        sir tr out = util.generate_SIR_output(sir_tr_in, gamma, 7)
        sir ts out = util.generate SIR output(sir ts in, gamma, 7)
        sir tr out.head()
         CPU times: user 7.13 s, sys: 13 ms, total: 7.14 s
         Wall time: 7.16 s
Out[6]:
         0 0.201814 0.425756 0.372430
         1 0.115945 0.474359 0.409696
         2 0.019150 0.511369 0.469481
          3 0.078295 0.196566 0.725139
         4 0.453265 0.148189 0.398546
```

- We picked $\gamma = 1/14$ (this will be fixed in our use case)
- We simulate one week

Training a Model

We try with Linear Regression

```
In [14]: nn0 = util.build ml model(input size=4, output size=3, hidden=[], name='LR')
         history0 = util.train ml model(nn0, sir tr in, sir tr out, verbose=0, epochs=100)
         util.plot training history(history0, figsize=figsize)
         util.print ml metrics(nn0, sir tr in, sir tr out, 'training')
         util.print ml metrics(nn0, sir ts in, sir ts out, 'test')
          0.08
          0.06
          0.04
          0.02
          0.00
                                             10
                                                           15
                                                                         20
                                                      epochs
         R2: 0.95, MAE: 0.023, RMSE: 0.03 (training)
         R2: 0.94, MAE: 0.024, RMSE: 0.04 (test)
```

Training a Model

...And with a shallow Neural Network

```
In [13]: nn1 = util.build ml model(input_size=4, output_size=3, hidden=[8], name='MLP')
         history1 = util.train ml model(nn1, sir tr in, sir tr out, verbose=0, epochs=100)
         util.plot training history(history1, figsize=figsize)
         util.print ml metrics(nn1, sir tr in, sir tr out, 'training')
         util.print ml metrics(nn1, sir ts in, sir ts out, 'test')
          0.08
          0.06
          0.04
          0.02
          0.00
                                 20
                                                                  60
                                                      epochs
         R2: 0.99, MAE: 0.0084, RMSE: 0.01 (training)
         R2: 0.99, MAE: 0.0086, RMSE: 0.01 (test)
```

Considerations and Next Steps

We will save both models for later

```
In [15]: util.save_ml_model(nn0, 'nn0')
  util.save_ml_model(nn1, 'nn1')
```

- The network is much better in terms of accuracy
- ...But the Linear Regressor is simpler!

Hence, the approaches provide different trade offs

We are halfway there

We now have our ML model(s)!

- We need to understand how they can be embedded in an optimization model
- ...And we need to define our optimization model itself