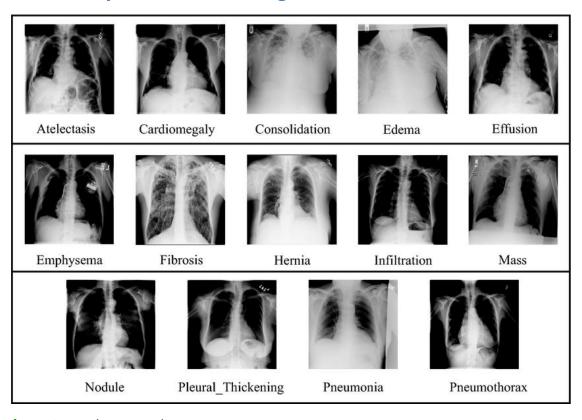
## **Chest X Ray Classification using DenseNet121 and Swin Transformer**



```
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import cv2
import seaborn as sns
import os
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
import torchvision.models as models
import torchvision.transforms as transforms
from torch.utils.data import DataLoader, Dataset
from torch.cuda.amp import autocast, GradScaler
from sklearn.metrics import roc auc score, roc curve
from sklearn.model selection import train test split
from pathlib import Path
from scipy.optimize import differential evolution, LinearConstraint
import timm
import warnings
warnings.filterwarnings("ignore")
```

```
class CFG:
    CLASS NAMES = [
        "Atelectasis", "Cardiomegaly", "Effusion", "Infiltration", "Mass",
        "Nodule", "Pneumonia", "Pneumothorax", "Consolidation", "Edema",
        "Emphysema", "Fibrosis", "Pleural_Thickening", "Hernia"
    BASE PATH = Path("/kaggle/input/nih-chest-x-ray-14-224x224-
resized/images-224/images-224")
    DATA PATH = Path("/kaggle/input/nih-chest-x-ray-14-224x224-resized")
    OUTPUT PATH = Path("/kaggle/working")
    BEST_MODEL_PATH = "models/best_model.pt"
    EPOCHS = 5
    BATCH SIZE = 16
    DEVICE = torch.device("cuda" if torch.cuda.is available() else "cpu")
    COLOR MODE = 'rgb'
    TARGET_SIZE = (224, 224)
    CHECKPOINT_PATH_DENSENET = 'model/DenseNet121_val_auc.pt'
    CHECKPOINT PATH SWIN = 'model/SwinTransformer val auc.pt'
    CHECKPOINT DIR = os.path.dirname(CHECKPOINT PATH DENSENET)
os.makedirs(CFG.OUTPUT_PATH / "model", exist_ok=True)
data entry df = pd.read csv(f'{CFG.DATA PATH}/Data Entry 2017.csv')
with open(f'{CFG.DATA_PATH}/train_val_list_NIH.txt', 'r') as f:
    train val list = [line.strip() for line in f]
with open(f'{CFG.DATA PATH}/test list NIH.txt', 'r') as f:
    test list = [line.strip() for line in f]
train val df = data entry df[data entry df['Image
Index'].isin(train val list)]
test_df = data_entry_df[data_entry_df['Image Index'].isin(test_list)]
train val df['full path'] = train val df['Image Index'].apply(lambda x:
str(CFG.BASE PATH / x))
test_df['full_path'] = test_df['Image Index'].apply(lambda x:
str(CFG.BASE PATH / x))
for cls in CFG.CLASS NAMES:
    train val df[cls] = train val df['Finding Labels'].apply(lambda x: 1 if
cls in x.split('|') else 0)
    test df[cls] = test df['Finding Labels'].apply(lambda x: 1 if cls in
x.split('|') else 0)
sampled dfs = []
for cls in CFG.CLASS NAMES:
    class df = train val df[train val df[cls] == 1]
    if len(class df) >= 100:
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sampled df = class df.sample(n=100, random state=42)
    else:
        sampled df = class df
    sampled dfs.append(sampled df)
train val df = pd.concat(sampled dfs).drop duplicates(subset='Image Index')
train val df = train val df[train val df['full path'].apply(os.path.exists)]
train df, val df = train test split(train val df, test size=0.125,
random state=42)
sampled test dfs = []
for cls in CFG.CLASS NAMES:
    class df = test df[test df[cls] == 1]
    if len(class df) >= 100:
        sampled_df = class_df.sample(n=100, random_state=42)
    else:
        sampled_df = class_df
    sampled test dfs.append(sampled df)
test df = pd.concat(sampled test dfs).drop duplicates(subset='Image Index')
test df = test df[test df['full path'].apply(os.path.exists)]
train df.to csv(f'{CFG.OUTPUT PATH}/train 100 per class.csv', index=False)
val_df.to_csv(f'{CFG.OUTPUT_PATH}/validation_100_per_class.csv', index=False)
test df.to csv(f'{CFG.OUTPUT PATH}/test.csv', index=False)
print(f"Train set size: {len(train df)} images")
print(f"Validation set size: {len(val_df)} images")
print(f"Test set size: {len(test_df)} images")
print("Train class distribution:")
print(train_df[CFG.CLASS_NAMES].sum())
class ChestXRayDataset(Dataset):
    def init (self, dataframe, transform=None):
        self.dataframe = dataframe
        self.transform = transform
        self.class_names = CFG.CLASS_NAMES
    def len_(self):
        return len(self.dataframe)
    def getitem (self, idx):
        img path = self.dataframe.iloc[idx]['full path']
        image = cv2.imread(img_path)
        image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
        image = apply clahe(image)
        image = (image / 255.0 - np.array([0.485, 0.456, 0.406])) /
np.array([0.229, 0.224, 0.225])
        image = image.transpose((2, 0, 1))
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image = torch.tensor(image, dtype=torch.float32)
        if self.transform:
            image = self.transform(image)
self.dataframe.iloc[idx][self.class names].values.astype(np.float32)
        return image, torch.tensor(labels, dtype=torch.float32), img path
def apply_clahe(image):
    if len(image.shape) == 3:
        gray = cv2.cvtColor(image, cv2.COLOR_RGB2GRAY)
    else:
        gray = image
    gray = np.uint8(gray)
    clahe = cv2.createCLAHE(clipLimit=2.0, tileGridSize=(8, 8))
    cl = clahe.apply(gray)
    if len(image.shape) == 3:
        clahe img = cv2.cvtColor(cl, cv2.COLOR GRAY2RGB)
    else:
        clahe img = cl
    return clahe img
train_transform = transforms.Compose([
    transforms.ToPILImage(),
    transforms.RandomHorizontalFlip(p=0.5),
    transforms.RandomRotation(10),
    transforms.RandomAffine(degrees=0, translate=(0.1, 0.05), scale=(0.95,
1.05), shear=0.1),
   transforms.ToTensor()
1)
val transform = transforms.Compose([
    transforms.ToPILImage(),
    transforms.ToTensor()
1)
train dataset = ChestXRayDataset(train df, transform=train transform)
val dataset = ChestXRayDataset(val_df, transform=val_transform)
test_dataset = ChestXRayDataset(test_df, transform=val_transform)
train_loader = DataLoader(train_dataset, batch_size=CFG.BATCH_SIZE,
shuffle=True, drop last=True)
val loader = DataLoader(val dataset, batch size=CFG.BATCH SIZE,
shuffle=False)
test loader = DataLoader(test dataset, batch size=CFG.BATCH SIZE,
shuffle=False)
def compute class weights(df, class names):
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pos ratios = df[class names].mean()
    weights = torch.zeros(len(class names))
    for i, cls in enumerate(class names):
        rho = pos ratios[cls]
        weights[i] = torch.exp(torch.tensor(1 - rho))
    return weights.to(CFG.DEVICE)
class CombinedLoss(nn.Module):
    def init (self, gamma1=1.0, gamma2=4.0, margin=0.05):
        super(CombinedLoss, self).__init__()
        self.gamma1 = gamma1
        self.gamma2 = gamma2
        self.margin = margin
    def forward(self, inputs, targets, weights):
        if inputs.shape != targets.shape:
            raise ValueError(f"Inputs shape {inputs.shape} does not match
targets shape {targets.shape}")
        if inputs.shape[1] != len(CFG.CLASS_NAMES):
            raise ValueError(f"Expected {len(CFG.CLASS NAMES)} classes, got
{inputs.shape[1]}")
        inputs = torch.clamp(inputs, 0, 1)
        inputs m = torch.clamp(inputs - self.margin, min=0)
        loss = -torch.sum(
            weights[None, :] * (
                (1 - inputs) ** self.gamma1 * targets * torch.log(inputs +
1e-10) +
                inputs_m ** self.gamma2 * (1 - targets) * torch.log(1 -
inputs_m + 1e-10)
            ), dim=1
        return loss.mean()
class DenseNet121Model(nn.Module):
    def __init__(self, num_classes=len(CFG.CLASS_NAMES)):
        super(DenseNet121Model, self).__init__()
        self.densenet = models.densenet121(pretrained=True)
        num ftrs = self.densenet.classifier.in features
        self.densenet.classifier = nn.Linear(num_ftrs, num_classes)
        self.sigmoid = nn.Sigmoid()
    def forward(self, x, return features=False):
        features = self.densenet.features(x)
        out = F.relu(features, inplace=True)
        out = F.adaptive avg pool2d(out, (1, 1)).view(features.size(0), -1)
        out = self.densenet.classifier(out)
        out = self.sigmoid(out)
        if return features:
            return out, features
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class SwinTransformerModel(nn.Module):
    def init (self, num classes=len(CFG.CLASS NAMES)):
        super(SwinTransformerModel, self). init ()
        self.swin = timm.create model('swin base patch4 window7 224',
pretrained=True, num classes=0)
        self.head = nn.Linear(1024, num_classes)
        self.sigmoid = nn.Sigmoid()
    def forward(self, x, return features=False):
        features = self.swin(x)
        out = self.head(features)
        out = self.sigmoid(out)
        if return features:
            return out, features
        return out
densenet model =
DenseNet121Model(num classes=len(CFG.CLASS NAMES)).to(CFG.DEVICE)
swin model =
SwinTransformerModel(num classes=len(CFG.CLASS NAMES)).to(CFG.DEVICE)
criterion = CombinedLoss(gamma1=1.0, gamma2=4.0, margin=0.05)
optimizer densenet = optim.AdamW(densenet model.parameters(), lr=1e-4,
weight_decay=1e-4)
optimizer swin = optim.AdamW(swin model.parameters(), lr=1e-4,
weight decay=1e-4)
scaler = GradScaler()
class weights = compute class weights(train df, CFG.CLASS NAMES)
class EarlyStopping:
    def init (self, patience=5, delta=0):
        self.patience = patience
        self.delta = delta
        self.best score = None
        self.early stop = False
        self.counter = 0
        self.best loss = np.inf
    def __call__(self, val_loss):
        score = -val loss
        if self.best_score is None:
            self.best score = score
            self.best loss = val loss
        elif score < self.best score + self.delta:</pre>
            self.counter += 1
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if self.counter >= self.patience:
                self.early stop = True
        else:
            self.best score = score
            self.best_loss = val_loss
            self.counter = 0
def train_model(model, train_loader, val_loader, criterion, optimizer,
num epochs, checkpoint path, model name):
    early stopping = EarlyStopping(patience=5)
    best auc = 0.0
    scheduler = optim.lr scheduler.ReduceLROnPlateau(optimizer, mode='min',
factor=0.5, patience=2, verbose=True)
    for epoch in range(num_epochs):
        model.train()
        running loss = 0.0
        for images, labels, _ in train_loader:
            images, labels = images.to(CFG.DEVICE), labels.to(CFG.DEVICE)
            optimizer.zero grad()
            with autocast():
                outputs = model(images)
                loss = criterion(outputs, labels, class weights)
            scaler.scale(loss).backward()
            scaler.step(optimizer)
            scaler.update()
            running_loss += loss.item() * images.size(0)
        epoch loss = running loss / len(train loader.dataset)
        model.eval()
        val preds, val_labels = [], []
        val loss = 0.0
        with torch.no grad():
            for images, labels, _ in val_loader:
                images, labels = images.to(CFG.DEVICE), labels.to(CFG.DEVICE)
                with autocast():
                    outputs = model(images)
                    val_loss += criterion(outputs, labels,
class_weights).item() * images.size(0)
                val preds.append(outputs.cpu().numpy())
                val labels.append(labels.cpu().numpy())
        val_loss = val_loss / len(val_loader.dataset)
        val preds = np.concatenate(val preds)
        val_labels = np.concatenate(val_labels)
        auc scores = [roc auc score(val labels[:, i], val preds[:, i]) for i
in range(len(CFG.CLASS_NAMES))]
        mean_auc = np.mean(auc_scores)
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print(f'Epoch {epoch+1}/{num_epochs}, {model_name} - Train Loss:
{epoch_loss:.4f}, Val Loss: {val_loss:.4f}, Mean AUC: {mean auc:.4f}')
        if mean_auc > best_auc:
            best auc = mean auc
            torch.save(model.state dict(), checkpoint path)
        early_stopping(val_loss)
        scheduler.step(val_loss)
        if early stopping.early stop:
            print(f"Early stopping triggered for {model_name}")
            break
    torch.cuda.empty_cache()
def ensemble_predict(densenet_model, swin_model, loader, weights):
    densenet model.eval()
    swin model.eval()
    all preds, all labels = [], []
    with torch.no grad():
        for images, labels, _ in loader:
            images, labels = images.to(CFG.DEVICE), labels.to(CFG.DEVICE)
            with autocast():
                densenet preds = densenet model(images)
                swin preds = swin model(images)
                ensemble preds = weights[0] * densenet preds + weights[1] *
swin preds
            all_preds.append(ensemble_preds.cpu().numpy())
            all labels.append(labels.cpu().numpy())
    return np.concatenate(all preds), np.concatenate(all labels)
def objective function(weights, densenet model, swin model, val loader):
    weights = np.array(weights) / np.sum(weights)
    val preds, val labels = ensemble predict(densenet model, swin model,
val loader, weights)
    auc_scores = [roc_auc_score(val_labels[:, i], val_preds[:, i]) for i in
range(len(CFG.CLASS NAMES))]
    return -np.mean(auc scores)
train_model(densenet_model, train_loader, val_loader, criterion,
optimizer_densenet, CFG.EPOCHS, CFG.CHECKPOINT_PATH_DENSENET, "DenseNet121")
torch.cuda.empty_cache()
train_model(swin_model, train_loader, val_loader, criterion, optimizer_swin,
CFG.EPOCHS, CFG.CHECKPOINT PATH SWIN, "SwinTransformer")
densenet model.load state dict(torch.load(CFG.CHECKPOINT PATH DENSENET))
swin model.load state dict(torch.load(CFG.CHECKPOINT PATH SWIN))
```

```
bounds = [(0, 1), (0, 1)]
constraints = LinearConstraint(np.ones(2), lb=1, ub=1)
result = differential evolution(
    lambda w: objective function(w, densenet model, swin model, val loader),
    bounds.
    constraints=constraints,
    maxiter=100
optimal weights = result.x / np.sum(result.x)
print(f"Optimal ensemble weights: DenseNet={optimal weights[0]:.4f},
SwinTransformer={optimal_weights[1]:.4f}")
test preds, test labels = ensemble predict(densenet model, swin model,
test_loader, optimal_weights)
auc scores = [roc auc score(test labels[:, i], test preds[:, i]) for i in
range(len(CFG.CLASS NAMES))]
mean_auc = np.mean(auc_scores)
print(f"Test Mean AUC: {mean auc:.4f}")
for cls, auc in zip(CFG.CLASS NAMES, auc scores):
    print(f"{cls}: AUC = {auc:.4f}")
plt.figure(figsize=(10, 8))
for i, cls in enumerate(CFG.CLASS NAMES):
    fpr, tpr, = roc curve(test labels[:, i], test preds[:, i])
    plt.plot(fpr, tpr, label=f'{cls} (AUC = {auc_scores[i]:.4f})')
plt.xlabel('False Positive Rate')
plt.ylabel('True Positive Rate')
plt.title('ROC Curves for CheX-DS')
plt.legend()
plt.savefig(f'{CFG.OUTPUT_PATH}/roc_curves.png')
plt.show()
np.save(f'{CFG.OUTPUT_PATH}/test_predictions.npy', test_preds)
np.save(f'{CFG.OUTPUT_PATH}/test_labels.npy', test_labels)
Train set size: 1209 images
Validation set size: 173 images
Test set size: 1349 images
Train class distribution:
Atelectasis
                      268
Cardiomegaly
                      114
Effusion
                      283
Infiltration
                      338
Mass
                      182
Nodule
                      152
Pneumonia
                      96
Pneumothorax
                      124
Consolidation
                      150
Edema
                      119
Emphysema
                      114
```

Fibrosis 108 Pleural Thickening 148 94 Hernia dtype: int64 Epoch 1/5, DenseNet121 - Train Loss: 2.3531, Val Loss: 2.2826, Mean AUC: Epoch 2/5, DenseNet121 - Train Loss: 2.0696, Val Loss: 2.2544, Mean AUC: Epoch 3/5, DenseNet121 - Train Loss: 1.9548, Val Loss: 2.2879, Mean AUC: 0.5987 Epoch 4/5, DenseNet121 - Train Loss: 1.8423, Val Loss: 2.3280, Mean AUC: Epoch 5/5, DenseNet121 - Train Loss: 1.7293, Val Loss: 2.3448, Mean AUC: 0.6051 Epoch 1/5, SwinTransformer - Train Loss: 2.1966, Val Loss: 2.2037, Mean AUC: Epoch 2/5, SwinTransformer - Train Loss: 2.1437, Val Loss: 2.1586, Mean AUC: 0.6103 Epoch 3/5, SwinTransformer - Train Loss: 2.1312, Val Loss: 2.1350, Mean AUC: 0.6333 Epoch 4/5, SwinTransformer - Train Loss: 2.1137, Val Loss: 2.1473, Mean AUC: 0.6395 Epoch 5/5, SwinTransformer - Train Loss: 2.0771, Val Loss: 2.0997, Mean AUC:

Optimal ensemble weights: DenseNet=0.1202, SwinTransformer=0.8798

Test Mean AUC: 0.6624 Atelectasis: AUC = 0.6323 Cardiomegaly: AUC = 0.7392 Effusion: AUC = 0.6728Infiltration: AUC = 0.6334

Mass: AUC = 0.5849Nodule: AUC = 0.6103Pneumonia: AUC = 0.5596Pneumothorax: AUC = 0.6312 Consolidation: AUC = 0.6599

Edema: AUC = 0.7721Emphysema: AUC = 0.5607Fibrosis: AUC = 0.7209

Pleural Thickening: AUC = 0.6374

Hernia: AUC = 0.8592

