```
! pip install --upgrade git+https://github.com/keras-team/keras-cv -q Installing build dependencies ... ents to build wheel ... etadata (pyproject.toml) ...
```

```
import os
from tqdm.auto import tqdm
import xml.etree.ElementTree as ET
import matplotlib.pyplot as plt
import seaborn as sns
import matplotlib.image as mpimg
import tensorflow as tf
from tensorflow import keras
from keras_cv.losses import FocalLoss
import pandas as pd
import keras_cv
from keras_cv import bounding_box
from keras_cv import visualization
%matplotlib inline
```

Hyperparameters

```
# Try these modifications

LEARNING_RATE = 0.001  # Lower learning rate
BATCH_SIZE = 4  # Increase batch size if memory allows
WEIGHT_DECAY = 1e-5  # Adjust weight decay
GLOBAL_CLIPNORM = 1.0
SPLIT_RATIO=0.2
```

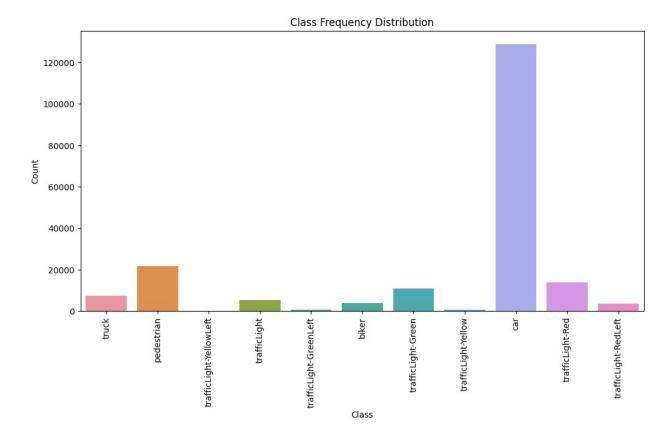
Path to images and annotations

```
path image="/kaggle/input/self-driving-car/export/"
annot path="/kaggle/input/self-driving-car/export/"
# Get all XML file paths in path annot and sort them
xml files = sorted(
        os.path.join(annot path, file name)
        for file name in os.listdir(annot path)
        if file name.endswith(".xml")
    ]
)
# Get all JPEG image file paths in path images and sort them
jpg_files = sorted(
        os.path.join(path image, file name)
        for file name in os.listdir(path image)
        if file name.endswith(".jpg")
    ]
)
class names = set()
# Function to parse XML annotations and extract class names
def extract class names(xml file):
    tree = ET.parse(xml file)
    root = tree.getroot()
    # Loop through each object in the XML and extract the class name
    for obj in root.iter("object"):
        class name = obj.find("name").text
        class names.add(class name)
# Loop through XML files and extract class names with tqdm for
progress
for xml_file in tqdm(xml_files, desc="Extracting class names",
```

```
unit="file"):
    extract class names(xml file)
# Print unique class names
print("Unique class names:")
print(class names)
{"model id": "ca8690c719134e72ab36742ae8c21bdd", "version major": 2, "vers
ion minor":0}
Unique class names:
{'truck', 'pedestrian', 'trafficLight-YellowLeft', 'trafficLight',
'trafficLight-GreenLeft', 'biker', 'trafficLight-Green', 'trafficLight-Yellow', 'car', 'trafficLight-Red', 'trafficLight-
RedLeft'}
rows, cols = 5, 5
fig, ax = plt.subplots(rows, cols, figsize=(15, 15))
axes = ax.flatten()
# Make sure the class names list has enough elements for the available
num images = min(len(jpg files), rows * cols)
class_names_list = list(class_names)[:num_images]
for i, ax in enumerate(axes[:num images]):
    img = mpimg.imread(jpg files[i])
    ax.imshow(img)
    ax.set title(f"Class: {class names list[i %
len(class_names_list)]}") # Cycle through class names if less than
images
    ax.axis('off')
# Hide any remaining axes
for j in range(num images, len(axes)):
    axes[i].axis('off')
plt.tight_layout()
plt.show()
```



```
class_count = {class_name: 0 for class_name in class_names}
def count classes in xml(xml file):
    tree = ET.parse(xml file)
    root = tree.getroot()
    for obj in root.iter("object"):
        class name = obj.find("name").text
        if class name in class count:
            class count[class name] += 1
for xml file in tqdm(xml_files, desc="Counting class occurrences",
unit="file"):
    count classes in xml(xml file)
class_count_df = pd.DataFrame(list(class count.items()),
columns=["Class", "Count"])
plt.figure(figsize=(12, 6))
sns.barplot(x="Class", y="Count", data=class_count_df)
plt.xticks(rotation=90)
plt.title("Class Frequency Distribution")
plt.show()
{"model_id": "3aeace96ff254091ac317e5c5e26531c", "version_major": 2, "vers
ion minor":0}
```



- The function below reads the XML file and finds the image name and path, and then
 iterates over each object in the XML file to extract the bounding box coordinates and
 class labels for each object.
- The function returns three values: the image path, a list of bounding boxes (each represented as a list of four floats: xmin, ymin, xmax, ymax), and a list of class IDs (represented as integers) corresponding to each bounding box. The class IDs are obtained by mapping the class labels to integer values using a dictionary called class_mapping.

```
def parse_annotation(xml_file):
    tree = ET.parse(xml_file)
    root = tree.getroot()

image_name = root.find("filename").text
    image_path = os.path.join(path_image, image_name)

boxes = []
    classes = []
    for obj in root.iter("object"):
        cls = obj.find("name").text
        classes.append(cls)

    bbox = obj.find("bndbox")
```

```
xmin = float(bbox.find("xmin").text)
        ymin = float(bbox.find("ymin").text)
        xmax = float(bbox.find("xmax").text)
        ymax = float(bbox.find("ymax").text)
        boxes.append([xmin, ymin, xmax, ymax])
    class ids = [
        list(class mapping.keys())
[list(class mapping.values()).index(cls)]
        for cls in classes
    return image path, boxes, class ids
image paths = []
bbox = []
classes = []
for xml file in tqdm(xml files):
    image path, boxes, class ids = parse annotation(xml file)
    image paths.append(image path)
    bbox.append(boxes)
    classes.append(class ids)
{"model id": "8f489067b8db4680b04bd20fa2c79502", "version major": 2, "vers
ion minor":0}
bbox = tf.ragged.constant(bbox)
classes = tf.ragged.constant(classes)
image_paths = tf.ragged.constant(image paths)
data = tf.data.Dataset.from tensor slices((image paths, classes,
bbox))
```

split data from train & valid

```
# Determine the number of validation samples
num_val = int(len(xml_files) * SPLIT_RATIO)

# Split the dataset into train and validation sets
val_data = data.take(num_val)
train_data = data.skip(num_val)
```

• The dictionary has two keys, 'boxes' and 'classes', each of which maps to a TensorFlow RaggedTensor or Tensor object. The 'boxes' Tensor has a shape of [batch, num_boxes, 4], where batch is the number of images in the batch and num_boxes is the maximum number of bounding boxes in any image. The 4 represents the four values needed to define a bounding box: xmin, ymin, xmax, ymax.

• The 'classes' Tensor has a shape of [batch, num_boxes], where each element represents the class label for the corresponding bounding box in the 'boxes' Tensor. The num_boxes dimension may be ragged, which means that the number of boxes may vary across images in the batch.

Final dict should be:

```
def load image(image path):
    image = tf.io.read file(image path)
    image = tf.image.decode jpeg(image, channels=3)
    return image
def load dataset(image path, classes, bbox):
    # Read Image
    image = load image(image path)
    bounding boxes = {
        "classes": tf.cast(classes, dtype=tf.float32),
        "boxes": bbox,
    return {"images": tf.cast(image, tf.float32), "bounding boxes":
bounding boxes}
augmenter = keras.Sequential(
    layers=[
        keras cv.layers.RandomFlip(mode="horizontal",
bounding box format="xyxy"),
        keras_cv.layers.RandomShear(
            x factor=0.2, y factor=0.2, bounding box format="xyxy"
        keras cv.layers.JitteredResize(
            target size=(640,640), scale factor=(0.75, 1.3),
bounding box format="xyxy"
    ]
)
```

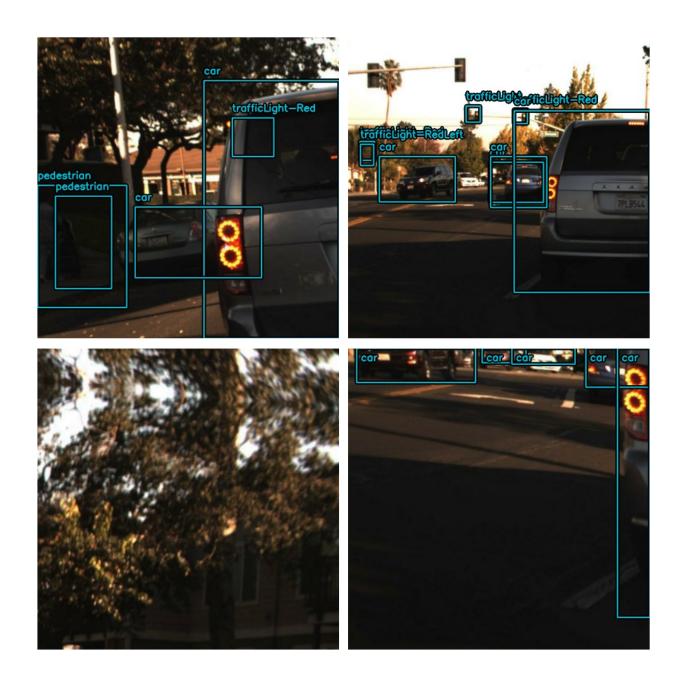
Creating Training Dataset

```
train_ds = train_data.map(load_dataset,
num_parallel_calls=tf.data.AUTOTUNE)
train_ds = train_ds.shuffle(BATCH_SIZE * 4)
train_ds = train_ds.ragged_batch(BATCH_SIZE, drop_remainder=True)
train_ds = train_ds.map(augmenter,
num_parallel_calls=tf.data.AUTOTUNE)
```

create valid dataset

Visualization

```
def visualize dataset(inputs, value range, rows, cols,
bounding box format):
    inputs = next(iter(inputs.take(1)))
    images, bounding boxes = inputs["images"],
inputs["bounding boxes"]
    visualization.plot bounding box gallery(
        images,
        value range=value range,
        rows=rows,
        cols=cols,
        y true=bounding boxes,
        scale=5,
        font scale=0.7,
        bounding box format=bounding box format,
        class mapping=class mapping,
    )
visualize dataset(train ds, bounding box format="xyxy",
value_range=(0, 255), rows=2, cols=2)
```



visualize from valid dataset

```
def visualize_dataset(inputs, value_range, rows, cols,
bounding_box_format):
    inputs = next(iter(inputs.take(1)))
    images, bounding_boxes = inputs["images"],
inputs["bounding_boxes"]
    visualization.plot_bounding_box_gallery(
        images,
        value_range=value_range,
        rows=rows,
```

```
cols=cols,
    y_true=bounding_boxes,
    scale=5,
    font_scale=0.7,
    bounding_box_format=bounding_box_format,
    class_mapping=class_mapping,
)

visualize_dataset(val_ds, bounding_box_format="xyxy", value_range=(0, 255), rows=2, cols=2)
```



• We need to extract the inputs from the preprocessing dictionary and get them ready to be fed into the model.

Creating Model

- Next, let's build a YOLOV8 model using the YOLOV8Detector, which accepts a feature extractor as the backbone argument, a num_classes argument that specifies the number of object classes to detect based on the size of the class_mapping list, a bounding_box_format argument that informs the model of the format of the bbox in the dataset, and a finally, the feature pyramid network (FPN) depth is specified by the fpn_depth argument.
- It is simple to build a YOLOV8 using any of the aforementioned backbones thanks to KerasCV

```
# Reasonable starting point
lr schedule =
tf.keras.optimizers.schedules.CosineDecay(initial_learning_rate=LEARNI
NG RATE, decay steps=10000, alpha=0.01)
optimizer =
tf.keras.optimizers.AdamW(learning rate=lr schedule,weight decay=WEIGH
T DECAY, global clipnorm=GLOBAL CLIPNORM)
model.compile(optimizer=optimizer,
classification loss=FocalLoss(alpha=0.25, gamma=2.0), box loss="ciou")
model.summary()
Model: "yolov8 detector"
  Layer (type)
                            Output Shape
                                                             Param #
  Connected to
  input_layer_1
                            (None, None, None, 3)
  (InputLayer)
  functional (Functional)
                            [(None, None, None, 19,831,744
  input_layer_1[0][0]
                            256), (None, None,
                            None, 512), (None,
                            None, None, 512)]
  repeat (Repeat)
                            (None, None, None,
                                                                   0
  functional[0][2]
                            512)
```

(None, None, None,

(None, None, None,

512)

0

0

repeat_1 (Repeat)

repeat[0][0]

concatenate_5
repeat 1[0][0],

(Concatenate) functional[0][1]	1024)	
pa_fpn_p4p5_pre_conv concatenate_5[0][0] (Conv2D)	(None, None, None, 512)	524,288
pa_fpn_p4p5_pre_bn pa_fpn_p4p5_pre_conv[(BatchNormalization)	(None, None, None, 512)	2,048
pa_fpn_p4p5_pre pa_fpn_p4p5_pre_bn[0] (Activation)	(None, None, None, 512)	0
split_4 (Split) pa_fpn_p4p5_pre[0][0]	[(None, None, None, 256), (None, None, None, 256)]	0
pa_fpn_p4p5_pre_0_1_pad split_4[0][1] (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p4p5_pre_0_1_conv pa_fpn_p4p5_pre_0_1_p (Conv2D)	None, None, None,	589,824
pa_fpn_p4p5_pre_0_1_bn pa_fpn_p4p5_pre_0_1_c (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p4p5_pre_0_1	None, None, None,	0

pa_fpn_p4p5_pre_0_1_b (Activation)	256)	
pa_fpn_p4p5_pre_0_2_pad pa_fpn_p4p5_pre_0_1[0 (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p4p5_pre_0_2_conv pa_fpn_p4p5_pre_0_2_p (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p4p5_pre_0_2_bn pa_fpn_p4p5_pre_0_2_c (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p4p5_pre_0_2 pa_fpn_p4p5_pre_0_2_b (Activation)	(None, None, None, 256)	0
pa_fpn_p4p5_pre_1_1_pad pa_fpn_p4p5_pre_0_2[0 (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p4p5_pre_1_1_conv pa_fpn_p4p5_pre_1_1_p (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p4p5_pre_1_1_bn pa_fpn_p4p5_pre_1_1_c (BatchNormalization)	(None, None, None,	1,024
pa_fpn_p4p5_pre_1_1 pa_fpn_p4p5_pre_1_1_b	(None, None, None,	0

(Activation)	256) 	
pa_fpn_p4p5_pre_1_2_pad pa_fpn_p4p5_pre_1_1[0 (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p4p5_pre_1_2_conv pa_fpn_p4p5_pre_1_2_p (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p4p5_pre_1_2_bn pa_fpn_p4p5_pre_1_2_c (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p4p5_pre_1_2 pa_fpn_p4p5_pre_1_2_b (Activation)	(None, None, None, 256)	0
concatenate_6 split_4[0][0], (Concatenate) split_4[0][1],	(None, None, None, 1024)	 0
pa_fpn_p4p5_pre_0_2[0 pa_fpn_p4p5_pre_1_2[0		
pa_fpn_p4p5_output_conv concatenate_6[0][0] (Conv2D)	(None, None, None, 512)	524,288
pa_fpn_p4p5_output_bn pa_fpn_p4p5_output_co (BatchNormalization)	(None, None, None, 512)	2,048

pa_fpn_p4p5_output pa_fpn_p4p5_output_bn (Activation)	(None, None, None, 512)	0
repeat_2 (Repeat) pa_fpn_p4p5_output[0]	(None, None, None, 512)	0
repeat_3 (Repeat) repeat_2[0][0]	(None, None, None, 512)	9
concatenate_7 repeat_3[0][0], (Concatenate) functional[0][0]	(None, None, None, 768)	0
pa_fpn_p3p4p5_pre_conv concatenate_7[0][0] (Conv2D)	(None, None, None, 256)	196,608
pa_fpn_p3p4p5_pre_bn pa_fpn_p3p4p5_pre_con (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p3p4p5_pre pa_fpn_p3p4p5_pre_bn[(Activation)	(None, None, None,	9
split_5 (Split) pa_fpn_p3p4p5_pre[0][[(None, None, None, 128), (None, None, None, 128)]	9

pa_fpn_p3p4p5_pre_0_1_pad split_5[0][1] (ZeroPadding2D)	(None, None, None,	0
pa_fpn_p3p4p5_pre_0_1_co pa_fpn_p3p4p5_pre_0_1 (Conv2D)	(None, None, None,	147,456
pa_fpn_p3p4p5_pre_0_1_bn pa_fpn_p3p4p5_pre_0_1 (BatchNormalization)	(None, None, None,	512
pa_fpn_p3p4p5_pre_0_1 pa_fpn_p3p4p5_pre_0_1 (Activation)	None, None, None,	0
pa_fpn_p3p4p5_pre_0_2_pad pa_fpn_p3p4p5_pre_0_1 (ZeroPadding2D)	(None, None, None,	0
pa_fpn_p3p4p5_pre_0_2_co pa_fpn_p3p4p5_pre_0_2 (Conv2D)	(None, None, None,	147,456
pa_fpn_p3p4p5_pre_0_2_bn pa_fpn_p3p4p5_pre_0_2 (BatchNormalization)	(None, None, None,	512
pa_fpn_p3p4p5_pre_0_2 pa_fpn_p3p4p5_pre_0_2 (Activation)	(None, None, None,	0

(None, None, None, 128)	0
(None, None, None, 128)	147,456
(None, None, None, 128)	512
(None, None, None, 128)	0
(None, None, None, 128)	0
(None, None, None, 128)	147,456
(None, None, None, 128)	512
(None, None, None, 128)	0
	(None, None, None, 128) (None, None, None, 128)

concatenate_8 split_5[0][0], (Concatenate) split_5[0][1], pa_fpn_p3p4p5_pre_0_2 pa_fpn_p3p4p5_pre_1_2	(None, None, None, 512)	Θ
pa_fpn_p3p4p5_output_conv concatenate_8[0][0] (Conv2D)	(None, None, None, 256)	131,072
pa_fpn_p3p4p5_output_bn pa_fpn_p3p4p5_output (BatchNormalization)	(None, None, None,	1,024
pa_fpn_p3p4p5_output pa_fpn_p3p4p5_output (Activation)	(None, None, None, 256)	Θ
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_output[(ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p3p4p5_downsample1 pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	0

l		
concatenate_9 pa_fpn_p3p4p5_downsam (Concatenate) pa_fpn_p4p5_output[0]	(None, None, None,	0
pa_fpn_p3p4p5_downsample concatenate_9[0][0] (Conv2D)	(None, None, None, 512)	393,216
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None,	2,048
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None,	0
split_6 (Split) pa_fpn_p3p4p5_downsam	[(None, None, None, 256), (None, None, None, 256)]	0
pa_fpn_p3p4p5_downsample split_6[0][1] (ZeroPadding2D)	(None, None, None,	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None,	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam	(None, None, None,	1,024

(BatchNormalization)	256)	
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	1,024

pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	 0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None,	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None,	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None,	0
concatenate_10 split_6[0][0], (Concatenate) split_6[0][1],	(None, None, None,	 0
pa_fpn_p3p4p5_downsam		
pa_fpn_p3p4p5_downsam		
pa_fpn_p3p4p5_downsample concatenate_10[0][0] (Conv2D)	(None, None, None, 512)	524,288
pa_fpn_p3p4p5_downsample…	(None, None, None,	2,048

pa_fpn_p3p4p5_downsam (BatchNormalization)	512)	
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 512)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None, 512)	 0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None, 512)	2,359,296
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 512)	2,048
pa_fpn_p3p4p5_downsample2 pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 512)	 0
concatenate_11 pa_fpn_p3p4p5_downsam (Concatenate) functional[0][2]	(None, None, None,	0
pa_fpn_p3p4p5_downsample concatenate_11[0][0] (Conv2D)	(None, None, None,	524,288
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam	(None, None, None,	2,048

(BatchNormalization)	512)	
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 512)	0
split_7 (Split) pa_fpn_p3p4p5_downsam	[(None, None, None, 256), (None, None, None, 256)]	Θ
pa_fpn_p3p4p5_downsample split_7[0][1] (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	Θ
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample	(None, None, None,	589,824

pa_fpn_p3p4p5_downsam (Conv2D)	256)	
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	1,024
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Conv2D)	(None, None, None, 256)	589,824
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None,	1,024
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None,	0
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam	(None, None, None,	589,824

(Conv2D)	256)	
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 256)	 1,024
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 256)	0
concatenate_12 split_7[0][0], (Concatenate) split_7[0][1], pa_fpn_p3p4p5_downsam	(None, None, None,	0
pa_fpn_p3p4p5_downsam		
pa_fpn_p3p4p5_downsample concatenate_12[0][0] (Conv2D)	(None, None, None, 512)	524,288
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (BatchNormalization)	(None, None, None, 512)	2,048
pa_fpn_p3p4p5_downsample pa_fpn_p3p4p5_downsam (Activation)	(None, None, None, 512)	0
yolo_v8_head_1_class_1_p pa_fpn_p3p4p5_output[(ZeroPadding2D)	(None, None, None, 256)	0

yolo_v8_head_2_class_1_p pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None,	0
yolo_v8_head_3_class_1_p pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None,	0
yolo_v8_head_1_box_1_pad pa_fpn_p3p4p5_output[(ZeroPadding2D)	(None, None, None,	0
yolo_v8_head_1_class_1_c yolo_v8_head_1_class (Conv2D)	(None, None, None,	589,824
yolo_v8_head_2_box_1_pad pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None,	0
yolo_v8_head_2_class_1_c yolo_v8_head_2_class (Conv2D)	(None, None, None,	1,179,648
yolo_v8_head_3_box_1_pad pa_fpn_p3p4p5_downsam (ZeroPadding2D)	(None, None, None,	0
yolo_v8_head_3_class_1_c yolo_v8_head_3_class (Conv2D)	(None, None, None,	1,179,648

yolo_v8_head_1_box_1_conv yolo_v8_head_1_box_1 (Conv2D)	(None, None, None, 64)	147,456
yolo_v8_head_1_class_1_bn yolo_v8_head_1_class (BatchNormalization)	(None, None, None,	1,024
yolo_v8_head_2_box_1_conv yolo_v8_head_2_box_1 (Conv2D)	(None, None, None, 64)	294,912
yolo_v8_head_2_class_1_bn yolo_v8_head_2_class (BatchNormalization)	(None, None, None,	1,024
yolo_v8_head_3_box_1_conv yolo_v8_head_3_box_1 (Conv2D)	(None, None, None, 64)	294,912
yolo_v8_head_3_class_1_bn yolo_v8_head_3_class (BatchNormalization)	(None, None, None,	1,024
yolo_v8_head_1_box_1_bn yolo_v8_head_1_box_1 (BatchNormalization)	(None, None, None, 64)	256
yolo_v8_head_1_class_1 yolo_v8_head_1_class (Activation)	(None, None, None,	Θ
yolo_v8_head_2_box_1_bn	(None, None, None, 64)	256

yolo_v8_head_2_box_1 (BatchNormalization)		
yolo_v8_head_2_class_1 yolo_v8_head_2_class (Activation)	(None, None, None, 256)	0
yolo_v8_head_3_box_1_bn yolo_v8_head_3_box_1 (BatchNormalization)	(None, None, None, 64)	256
yolo_v8_head_3_class_1 yolo_v8_head_3_class (Activation)	(None, None, None, 256)	0
yolo_v8_head_1_box_1 yolo_v8_head_1_box_1 (Activation)	(None, None, None, 64)	0
yolo_v8_head_1_class_2_p yolo_v8_head_1_class (ZeroPadding2D)	(None, None, None,	0
yolo_v8_head_2_box_1 yolo_v8_head_2_box_1 (Activation)	(None, None, None, 64)	0
yolo_v8_head_2_class_2_p yolo_v8_head_2_class (ZeroPadding2D)	(None, None, None, 256)	0
yolo_v8_head_3_box_1 yolo_v8_head_3_box_1	(None, None, None, 64)	0

(Activation)		
yolo_v8_head_3_class_2_p yolo_v8_head_3_class (ZeroPadding2D)	(None, None, None,	Θ
yolo_v8_head_1_box_2_pad yolo_v8_head_1_box_1[(ZeroPadding2D)	(None, None, None, 64)	Θ
yolo_v8_head_1_class_2_c yolo_v8_head_1_class (Conv2D)	(None, None, None, 256)	589,824
yolo_v8_head_2_box_2_pad yolo_v8_head_2_box_1[(ZeroPadding2D)	(None, None, None, 64)	Θ
yolo_v8_head_2_class_2_c yolo_v8_head_2_class (Conv2D)	(None, None, None,	589,824
yolo_v8_head_3_box_2_pad yolo_v8_head_3_box_1[(ZeroPadding2D)	(None, None, None, 64)	Θ
yolo_v8_head_3_class_2_c yolo_v8_head_3_class (Conv2D)	(None, None, None, 256)	589,824
yolo_v8_head_1_box_2_conv yolo_v8_head_1_box_2 (Conv2D)	(None, None, None, 64)	36,864

yolo_v8_head_1_class_2_bn yolo_v8_head_1_class (BatchNormalization)	(None, None, None, 256)	1,024
yolo_v8_head_2_box_2_conv yolo_v8_head_2_box_2 (Conv2D)	(None, None, None, 64)	36,864
yolo_v8_head_2_class_2_bn yolo_v8_head_2_class (BatchNormalization)	(None, None, None, 256)	1,024
yolo_v8_head_3_box_2_conv yolo_v8_head_3_box_2 (Conv2D)	(None, None, None, 64)	36,864
yolo_v8_head_3_class_2_bn yolo_v8_head_3_class (BatchNormalization)	(None, None, None,	1,024
yolo_v8_head_1_box_2_bn yolo_v8_head_1_box_2 (BatchNormalization)	(None, None, None, 64)	256
yolo_v8_head_1_class_2 yolo_v8_head_1_class (Activation)	(None, None, None, 256)	Θ
yolo_v8_head_2_box_2_bn yolo_v8_head_2_box_2 (BatchNormalization)	(None, None, None, 64)	256

yolo_v8_head_2_class_2	(None, None, None,	0
yolo_v8_head_2_class (Activation)	256)	
yolo_v8_head_3_box_2_bn yolo_v8_head_3_box_2 (BatchNormalization)	(None, None, None, 64)	256
yolo_v8_head_3_class_2 yolo_v8_head_3_class (Activation)	(None, None, None,	0
(ACCIVACION)		
yolo_v8_head_1_box_2 yolo_v8_head_1_box_2 (Activation)	(None, None, None, 64)	0
yolo_v8_head_1_class_3_c yolo_v8_head_1_class (Conv2D)	(None, None, None, 11)	2,827
yolo_v8_head_2_box_2 yolo_v8_head_2_box_2 (Activation)	(None, None, None, 64)	0
yolo_v8_head_2_class_3_c yolo_v8_head_2_class (Conv2D)	(None, None, None, 11)	2,827
yolo_v8_head_3_box_2 yolo_v8_head_3_box_2 (Activation)	(None, None, None, 64)	0

yolo_v8_head_3_class_3_c yolo_v8_head_3_class (Conv2D)	(None, None, None, 11)	2,827
yolo_v8_head_1_box_3_conv yolo_v8_head_1_box_2[(Conv2D)	(None, None, None, 64)	4,160
yolo_v8_head_1_classifier yolo_v8_head_1_class (Activation)	(None, None, None, 11)	Θ
yolo_v8_head_2_box_3_conv yolo_v8_head_2_box_2[(Conv2D)	(None, None, None, 64)	4,160
yolo_v8_head_2_classifier yolo_v8_head_2_class (Activation)	(None, None, None, 11)	Θ
yolo_v8_head_3_box_3_conv yolo_v8_head_3_box_2[(Conv2D)	(None, None, None, 64)	4,160
yolo_v8_head_3_classifier yolo_v8_head_3_class (Activation)	(None, None, None, 11)	Θ
concatenate_13 yolo_v8_head_1_box_3 (Concatenate) yolo_v8_head_1_classi	(None, None, None, 75)	Θ
concatenate_14	(None, None, None, 75)	Θ

yolo_v8_head_2_box_3 (Concatenate) yolo_v8_head_2_classi		
concatenate_15 yolo_v8_head_3_box_3 (Concatenate) yolo_v8_head_3_classi	(None, None, None, 75)	Θ
yolo_v8_head_1_output_re concatenate_13[0][0] (Reshape)	(None, None, 75)	Θ
yolo_v8_head_2_output_re concatenate_14[0][0] (Reshape)	(None, None, 75)	Θ
yolo_v8_head_3_output_re concatenate_15[0][0] (Reshape)	(None, None, 75)	0
concatenate_16 yolo_v8_head_1_output (Concatenate) yolo_v8_head_2_output yolo_v8_head_3_output	(None, None, 75)	Θ
box_outputs (Activation) concatenate_16[0][0]	(None, None, 75)	0
get_item (GetItem) box_outputs[0][0]	(None, None, 64)	0
get_item_1 (GetItem) box_outputs[0][0]	(None, None, 11)	0

COCO Metric Callback

```
class EvaluateCOCOMetricsCallback(keras.callbacks.Callback):
    def init (self, data, save path):
        super().__init__()
        self.data = data
        self.metrics = keras cv.metrics.BoxCOCOMetrics(
            bounding box format="xyxy",
            evaluate freq=1e9,
        self.save path = save path
        self.best map = -1.0
    def on epoch end(self, epoch, logs):
        self.metrics.reset state()
        for batch in self.data:
            images, y true = batch[0], batch[1]
            y pred = self.model.predict(images, verbose=0)
            self.metrics.update state(y true, y pred)
        metrics = self.metrics.result(force=True)
        logs.update(metrics)
        current map = metrics["MaP"]
        if current map > self.best map:
            self.best map = current map
            self.model.save(self.save path) # Save the model when mAP
improves
        return logs
```

```
history = model.fit(
            train ds,
            validation data=val ds,
            epochs=3.
            callbacks=[EvaluateCOCOMetricsCallback(val ds,
"model.h5"), tf.keras.callbacks.EarlyStopping(patience=5,
restore best weights=True)])
Epoch 1/3
                      _____ 293s 2s/step - box_loss: 2.7060 -
100/100 -
class loss: 0.2422 - loss: 2.9482 - val box loss: 0.0492 -
val_class_loss: 0.0461 - val_loss: 0.0953 - MaP: 0.0000e+00 -
MaP@[IoU=50]: 0.0000e+00 - MaP@[IoU=75]: 0.0000e+00 -
MaP@[area=small]: 0.0000e+00 - MaP@[area=medium]: 0.0000e+00 -
MaP@[area=large]: 0.0000e+00 - Recall@[max detections=1]: 0.0000e+00 -
Recall@[max detections=10]: 0.0000e+00 - Recall@[max detections=100]:
0.0000e+00 - Recall@[area=small]: 0.0000e+00 - Recall@[area=medium]:
0.0000e+00 - Recall@[area=large]: 0.0000e+00
Epoch 2/3
                     ------ 167s 2s/step - box loss: 2.6770 -
100/100 -
class_loss: 0.0063 - loss: 2.6834 - val_box_loss: 1.0912 -
val class loss: 0.0011 - val loss: 1.0924 - MaP: 0.0000e+00 -
MaP@[IoU=50]: 0.0000e+00 - MaP@[IoU=75]: 0.0000e+00 -
MaP@[area=small]: 0.0000e+00 - MaP@[area=medium]: 0.0000e+00 -
MaP@[area=large]: 0.0000e+00 - Recall@[max detections=1]: 0.0000e+00 -
Recall@[max_detections=10]: 0.0000e+00 - Recall@[max_detections=100]:
0.0000e+00 - Recall@[area=small]: 0.0000e+00 - Recall@[area=medium]:
0.0000e+00 - Recall@[area=large]: 0.0000e+00
Epoch 3/3
                      ------ 165s 2s/step - box loss: 2.9708 -
100/100 -
class loss: 0.0022 - loss: 2.9730 - val box loss: 1.7389 -
val class loss: 5.6286e-04 - val loss: 1.7395 - MaP: 1.9426e-07 -
MaP@[IoU=\overline{50}]: 1.2951e-06 - MaP@[\overline{1oU}=75]: 0.0000e+00 -
MaP@[area=small]: 0.0000e+00 - MaP@[area=medium]: 1.5360e-07 -
MaP@[area=large]: 1.1380e-06 - Recall@[max detections=1]: 0.0000e+00 -
Recall@[max detections=10]: 3.5282e-05 - Recall@[max detections=100]:
3.5282e-05 - Recall@[area=small]: 0.0000e+00 - Recall@[area=medium]:
3.8197e-05 - Recall@[area=large]: 1.1299e-04
```

Visualize Predictions

```
import tensorflow as tf
from keras_cv import visualization, bounding_box

def visualize_detections(model, dataset, bounding_box_format,
    class_mapping, conf_threshold=0.5, max_detections=5):
    images, y_true = next(iter(dataset.take(1)))
    y_pred = model.predict(images)
```

```
# Extract boxes from y pred
    if isinstance(y_pred, dict):
        y pred boxes = y pred["boxes"] # Shape: (batch size, 100, 4)
        y_pred_classes = y_pred["classes"] # Shape: (batch size, 100)
        y_pred_confidence = y_pred["confidence"] # Shape:
(batch size, 1\overline{0}0)
    else:
        raise ValueError("y pred must be a dictionary with 'boxes',
'classes', and 'confidence'")
    # Filter and trim predictions
    y pred boxes trimmed = []
    y pred classes trimmed = []
    for i in range(len(images)):
        conf = y_pred_confidence[i]
        boxes = y pred boxes[i]
        classes = y pred classes[i]
        # Filter by confidence threshold
        mask = conf > conf threshold
        filtered conf = conf[mask]
        filtered boxes = boxes[mask]
        filtered classes = classes[mask]
        # Sort by confidence and take top max detections
        if tf.shape(filtered conf)[0] > 0:
            top indices = tf.argsort(filtered conf,
direction="DESCENDING")[:max detections]
            filtered boxes = tf.gather(filtered boxes, top indices)
            filtered classes = tf.gather(filtered classes,
top indices)
        else:
            filtered_boxes = tf.zeros((0, 4), dtype=tf.float32)
            filtered classes = tf.zeros((0,), dtype=tf.int32)
        # Pad to max detections
        num detections = tf.shape(filtered boxes)[0]
        padding = [[0, max detections - num detections], [0, 0]]
        padded_boxes = tf.pad(filtered_boxes, padding,
constant values=-1) # Pad with -1 for invalid boxes
        padded classes = tf.pad(filtered_classes, [[0, max_detections]
- num detections]], constant values=-1)
        y pred boxes trimmed.append(padded boxes)
        y pred classes trimmed.append(padded classes)
    # Stack into fixed-size tensors
    y_pred_boxes_padded = tf.stack(y_pred_boxes_trimmed, axis=0) #
```

```
Shape: (batch size, max detections, 4)
    y_pred_classes_padded = tf.stack(y_pred_classes_trimmed, axis=0)
# Shape: (batch_size, max_detections)
    # Combine into a dictionary
    y pred formatted = {
        "boxes": y_pred_boxes_padded,
        "classes": y pred classes padded
    }
    # Visualize
    visualization.plot bounding box gallery(
        images,
        value range=(0, 255),
        bounding box format=bounding box format,
        y_true=y_true,
        y pred=y pred formatted,
        scale=8,
        rows=2,
        cols=2,
        show=True,
        font scale=0.7,
        class mapping=class mapping,
    )
# Run the function
visualize detections(
    model,
    dataset=val ds,
    bounding box format="xyxy",
    class_mapping=class_mapping, # Assuming defined elsewhere
    conf threshold=0.5,
    max detections=5
)
1/1 -
                        0s 154ms/step
```

