

LECTURE 8

Last Class: Dijkstra's algorithm for
shortest paths
→ Algorithm
→ Proof of Correctness.

DIJKSTRA's ALGORITHM

Let $S = \text{Set of explored/discovered nodes.}$ (For each vertex $u \in S$, we also store $d(u)$). $\rightarrow d(s, u)$

- ① $S = \{s\}$ and $d(s) = 0 \cdot d(v) = \infty \text{ if } v \neq s.$ $\} O(|V|)$
 $\text{parent}(v) = \phi \text{ if } v \in S$
 $\rightarrow d'(v) = \infty \text{ if } v \notin S$
- ② While $S \neq V$

W times

a For each vertex $v \notin S$
 takes $\leftarrow l$ set $d'(v) = \min \{ d(u) + l_{uv} : u \in S \text{ and } (u, v) \text{ is an edge} \}$

- b Find the vertex v with least $d'(v).$

(i) ADD v to $S.$

(ii) $d(v) = d'(v).$

- Step (a) of the while loop takes $\text{degree}(v)$ time for each vertex $v \notin S$.
- Total-time for step (a) would be $\sum_{v \notin S} \text{degree}(v) = O(|E|)$.
- Step(b): We have to pick the vertex v with least d' among all vertices not in S .
 - Takes $O(|V|)$ time.

Time for each iteration of the while loop is $O(|V| + |E|)$.

\Rightarrow Total run-time is $O(|V| \cdot (|V| + |E|))$.

-
- ① We don't have to recompute d' for every vertex after we update the set S .
→ You only have to update for neighbors of the newly added vertex.
 - ② We could use some "data structures" to compute \min efficiently.

You can use Heaps / Priority Queues
to get a run-time of
 $O(|V| + |E| \cdot \log |V|)$. (See [KT] if
curious ...).

- Greedy algorithms: You update solution gradually.
- Analyzing greedy algorithms: "Always stays ahead".

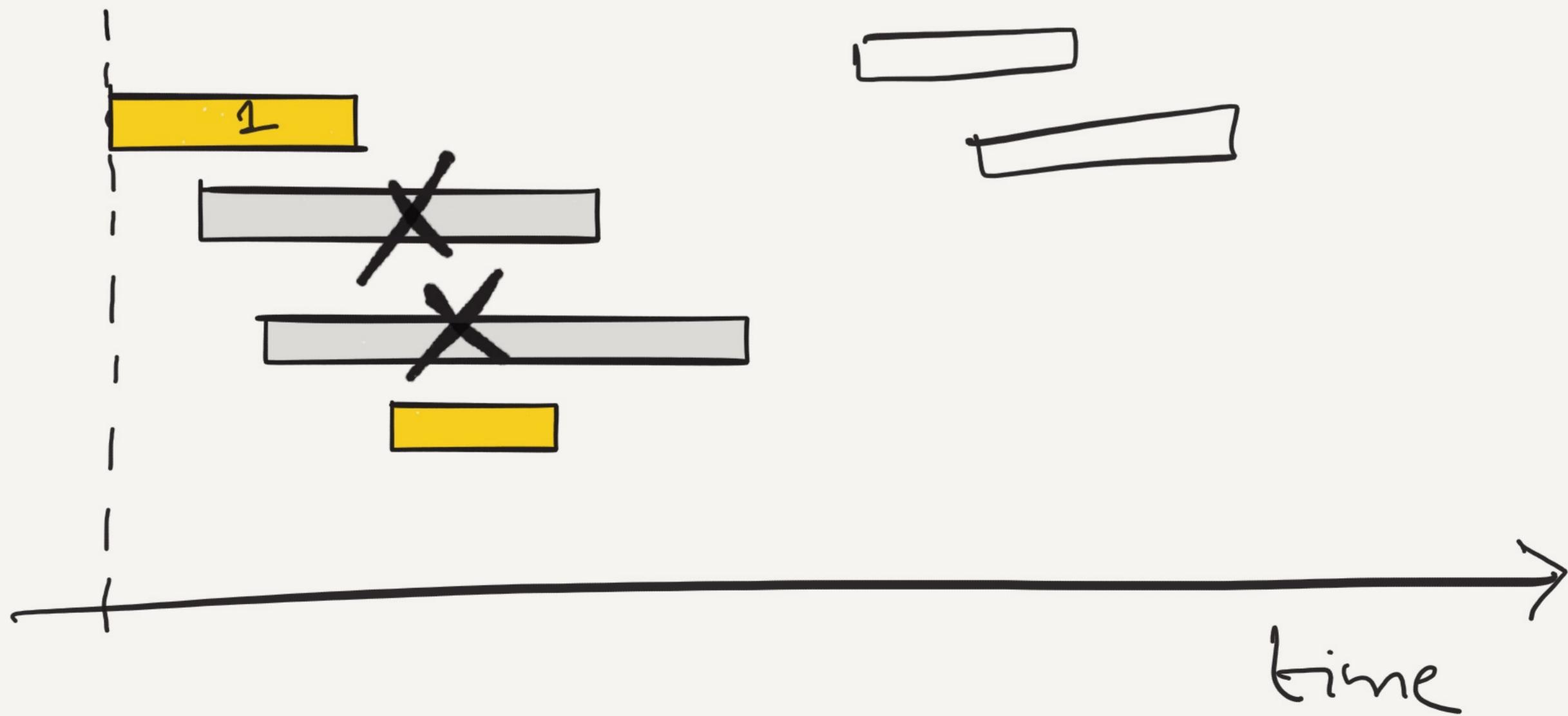
2nd Example of Greedy algorithms

Interval Scheduling:



← Requests for processing jobs
 $(s(i), f(i))$

Example:



Input: Sequence of jobs:
 $(s(1), f(1))$, $(s(2), f(2))$, ..., $(s(n), f(n))$

Output: Pick the maximum number of
"non-conflicting" jobs (requests).

How to solve?

- Use a Simple rule to select the first job
- Remove conflicting jobs
- Repeat until no more jobs left.

Which rule can we use??

①

Pick the job with least finish time

②

Pick " " that conflicts with the least number of ones.

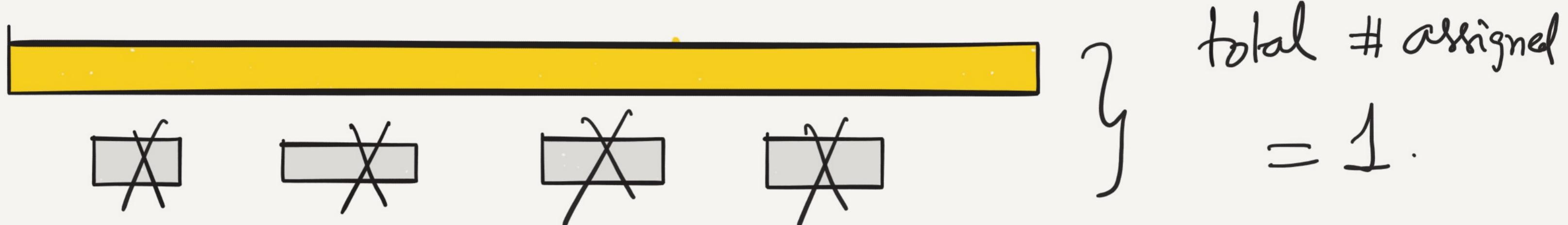
③

Pick the job with "least time".
 $\rightsquigarrow (f(i) - s(i))$.

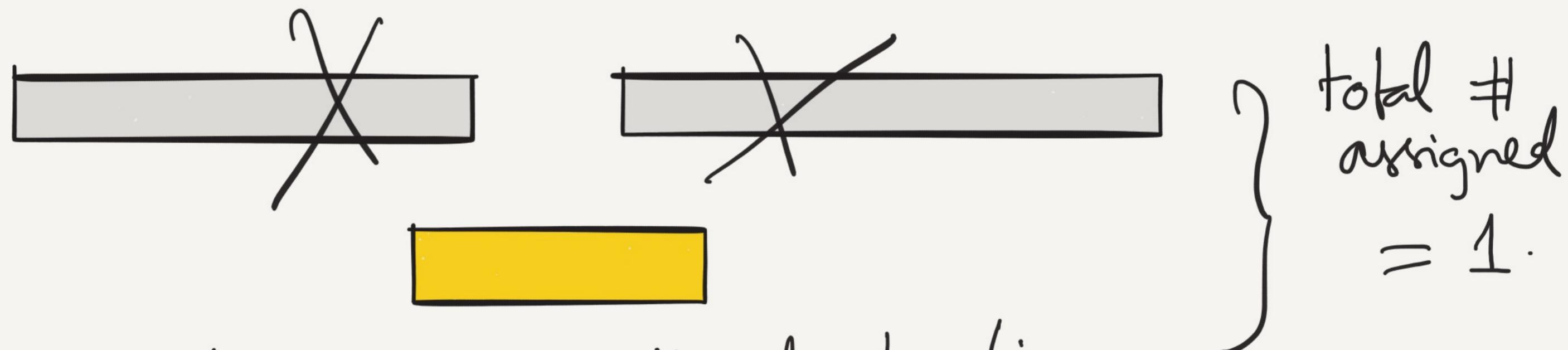
④

Pick the job with least start time.

~~④~~ Pick the one with least start time.

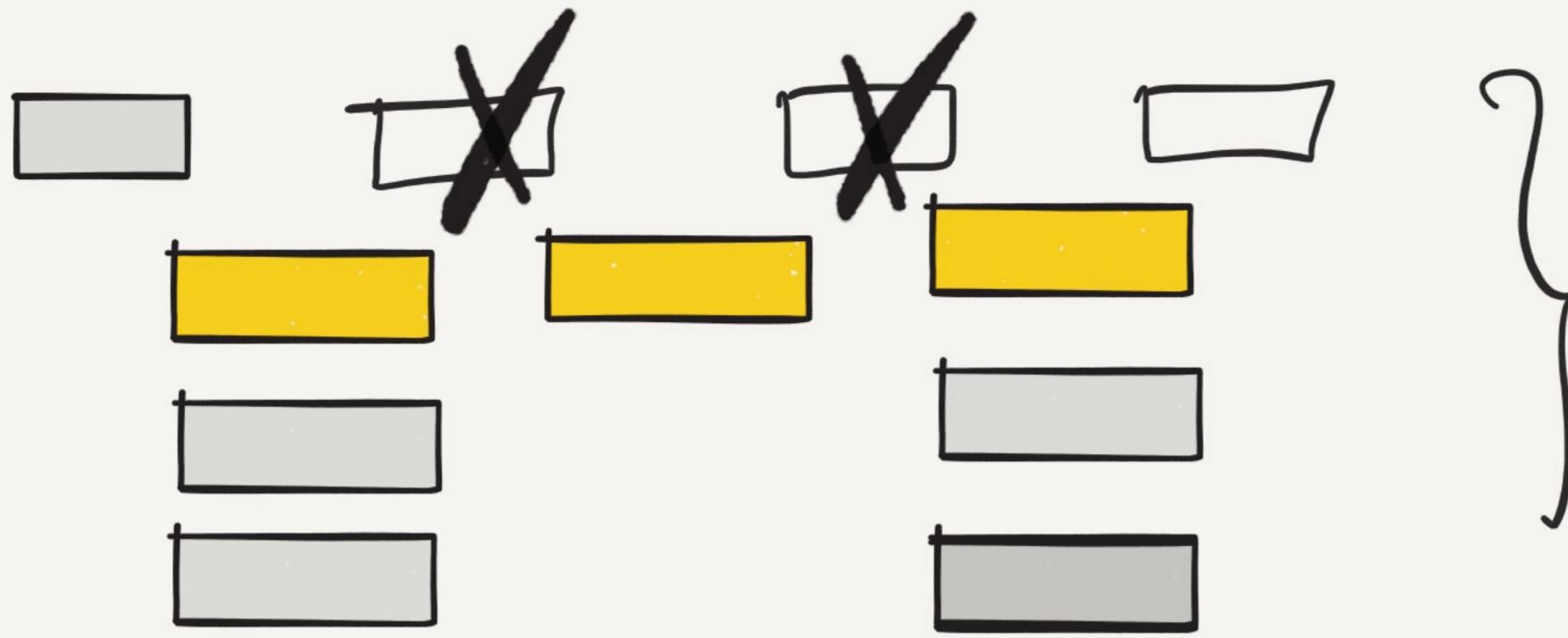


~~③~~



Pick the one with least time.

~~②~~ Pick the one with least # of conflicts,
solves the previous example.

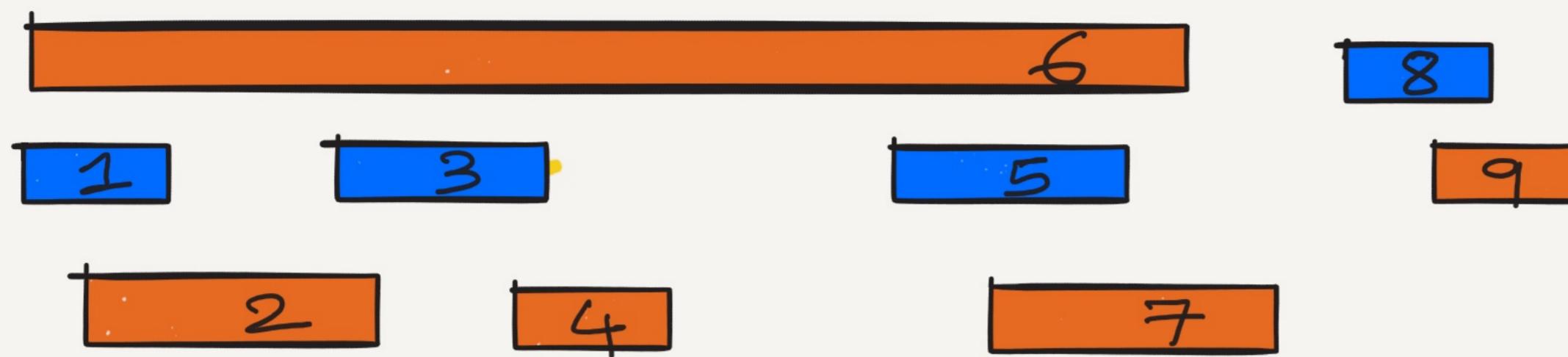


total # assigned
= 3.
Best is 4.

Earliest finish time works!!

Earliest Finish Time Algorithm:

- ① $R = \text{all jobs}$. $A = \emptyset$.
- ② While R is not empty
 - Pick request i with the least finish time from R .
 - Add i to A .
 - Remove all requests that conflict with i .



Output = jobs numbered 1, 3, 5, 8 in the figure.

How to analyze ??

"Greedy stays ahead"

"At any point in time, Our algorithm's performance is no worse than that of the optimal one"

Need a way to quantitatively compare our algorithm to the optimal set of jobs.

"Lemma": Our algorithm frees up sooner than the optimal one".

Suppose that $A = \{i_1, i_2, \dots, i_k\}$
 $f(i_1) < f(i_2) < \dots < f(i_k)$.

Suppose an optimal solution is

$$\Theta = \{j_1, j_2, \dots, j_m\}$$
$$f(j_1) < f(j_2) < \dots < f(j_m).$$

the jobs in Θ are ordered in increasing finish time.

Lemma: $\forall l \leq k, f(i_l) \leq f(j_l)$.

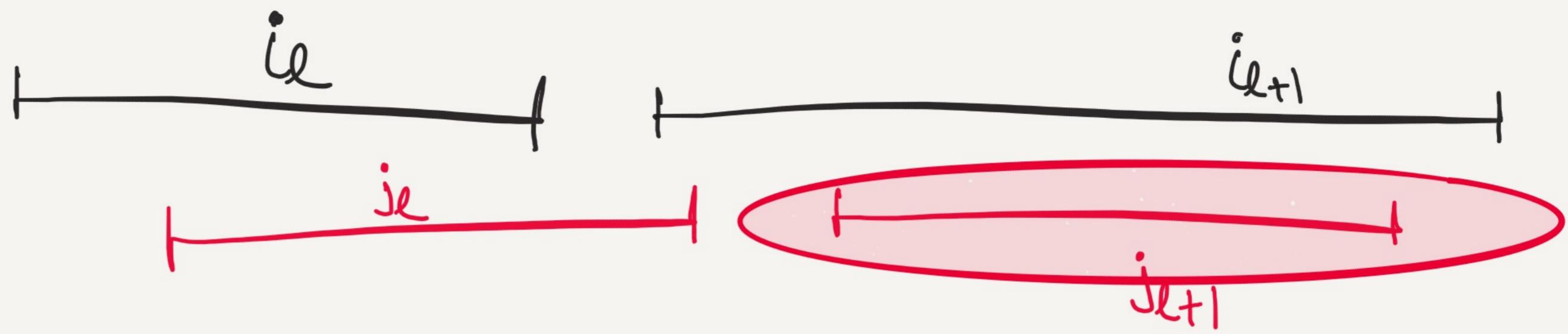
\downarrow

finish time of the
 l^{th} job under A . finish time of the
 l^{th} job under Θ .

Proof: Induction.

Base case: $l = 1$. True because $f(i_1)$ was the least finish time.

Induction step: Suppose claim is true for l . Want to show for $l+1$.



① When we picked i_{l+1} , j_{l+1} also belongs to the set R .

Why, $f(i_l) \leq f(j_l) \leq s(j_{l+1})$

$\Rightarrow j_{l+1}$ does not conflict with i_l .

\Rightarrow that the situation in figure
cannot occur.

\Rightarrow Lemma is true by induction.

Theorem: Earliest Finish First (EFF) finds an optimal set of jobs.

Proof: Suppose there exists $\Theta = \{j_1, j_2, \dots, j_m\}$ such that $m > k$. ($A = \{i_1, i_2, i_3, \dots, i_k\}$)

(Here as before $f(i_1) < f(i_2) < \dots < f(i_k)$)

$f(j_1) < f(j_2) < \dots < f(j_k) < \dots < f(j_m)$

By the lemma, $f(i_k) \leq f(j_k)$.

$\Rightarrow j_{k+1}$ does not conflict with the jobs in A .
EFF algorithm

$\Rightarrow j_{k+1}$ is not removed \Rightarrow would consider it & assign at least one more

Theorem: Earliest Finish First (EFF) finds an optimal set of jobs.

Proof: Suppose there exists $\Theta = \{j_1, j_2, \dots, j_m\}$ such that $m > k$. ($A = \{i_1, i_2, i_3, \dots, i_k\}$)

(Here as before $f(i_1) < f(i_2) < \dots < f(i_k)$)

$f(j_1) < f(j_2) < \dots < f(j_k) < \dots < f(j_m)$

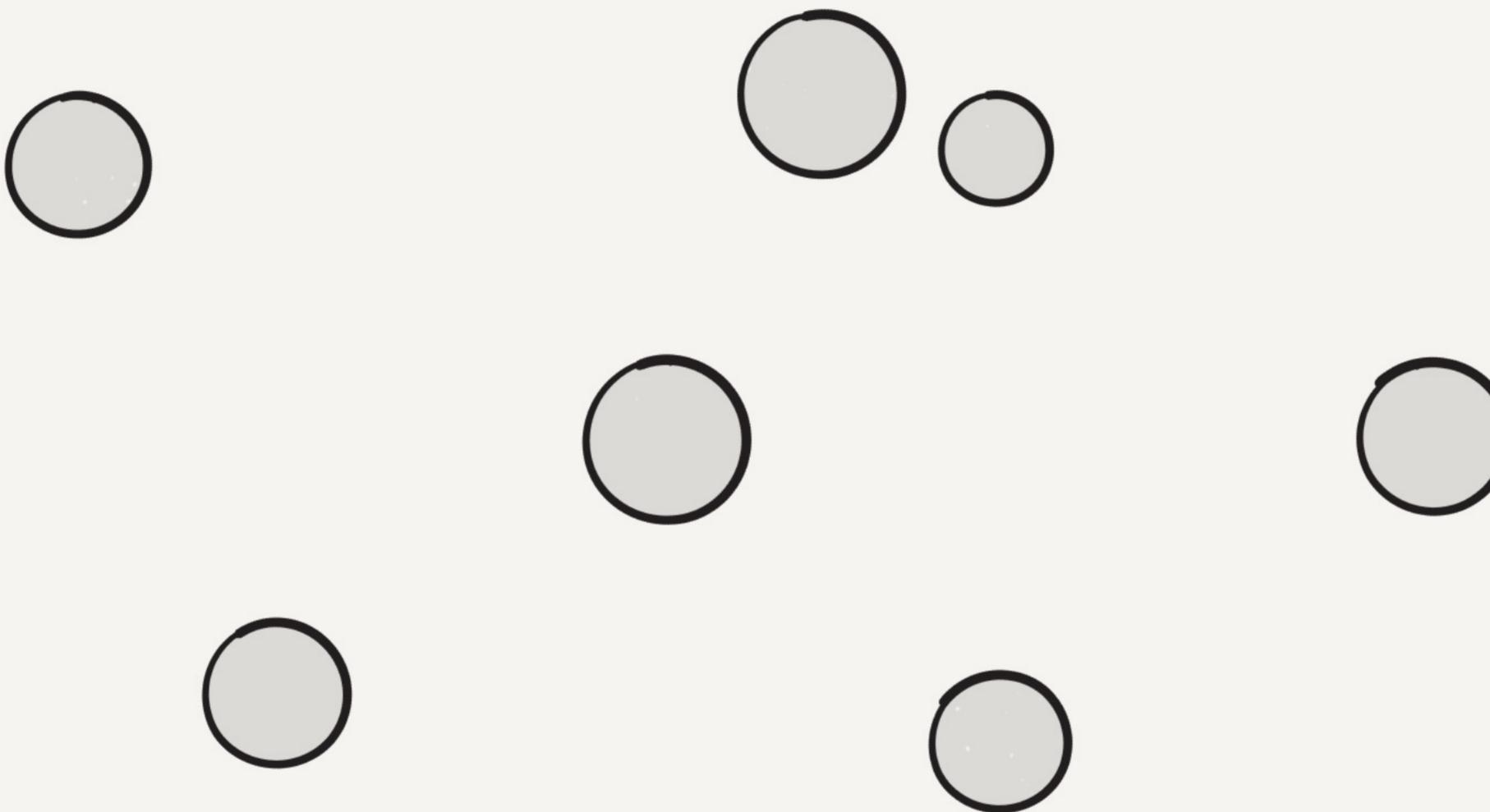
By the lemma, $f(i_k) \leq f(j_k)$.

$\Rightarrow j_{k+1}$ does not conflict with the jobs in A . the set R

$\Rightarrow j_{k+1}$ is not removed \Rightarrow is not empty.

Minimum Spanning Trees

(3rd example of Greedy algorithms).



fiber optic
cable.
Connections

Each pair (i,j) has a cost $c(i,j)$.

Goal: Connect the cities with least total cost.

$G = (V, E)$

↓ ↓
Vertices Edges

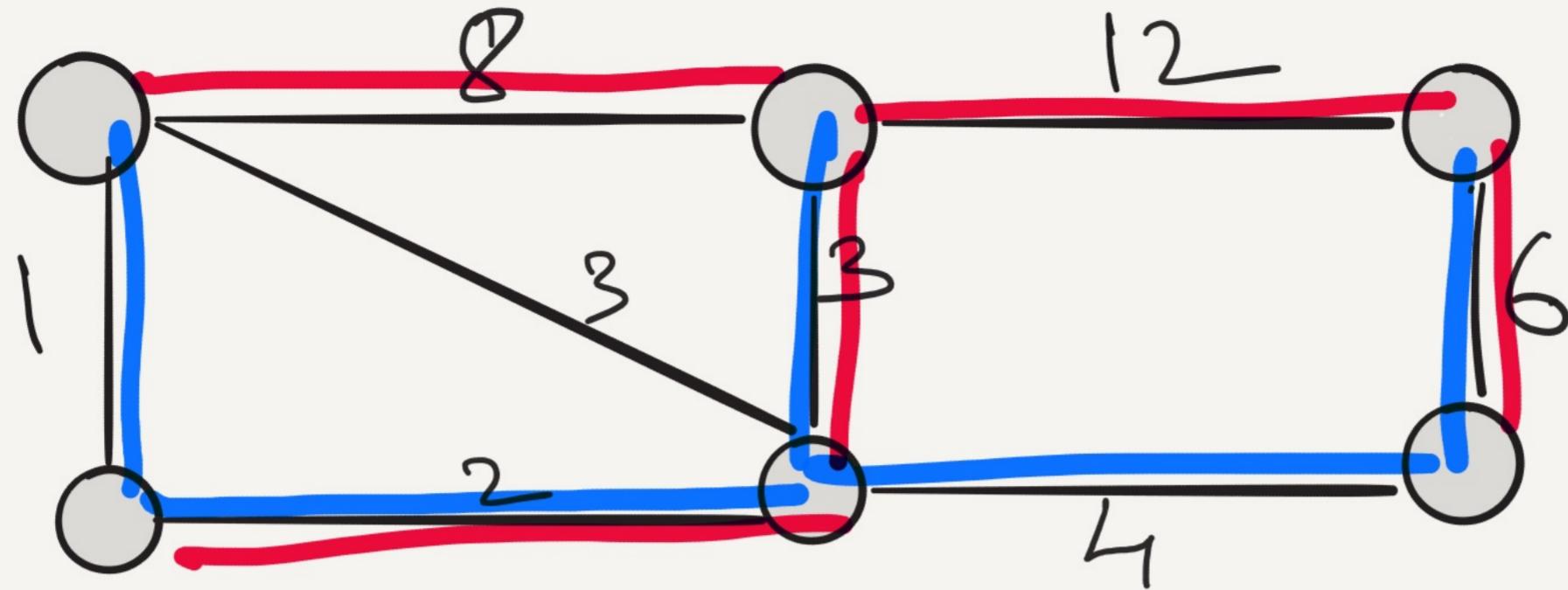
Each edge has an associated weight.

Undirected weighted graphs

Spanning Tree: A spanning tree is a sub-graph of

G so that

- Ⓐ the edges form a tree
- Ⓑ they cover/hit all the vertices of V .



$$\text{wt(blue)} = 16$$

$$\text{wt(red)} = 31$$

Minimum Spanning Tree (MST):
 → Spanning tree with least total weight.

INPUT: $G = (V, E)$ undirected weighted graph

OUTPUT: Compute a minimum Spanning tree (MST).

Applications:

- fiber optic cables / electricity grids / hydraulic
- Ethernet protocols
- Important primitive for approximation algorithms

Greedy algorithms for computing a MST.

- ① Find the "closest" city/vertex that is not "Covered" and "add" it. → PRIM's Algorithm
- ② Find the edge with least weight that does not create a cycle and add that edge.
→ Kruskal's algorithm.