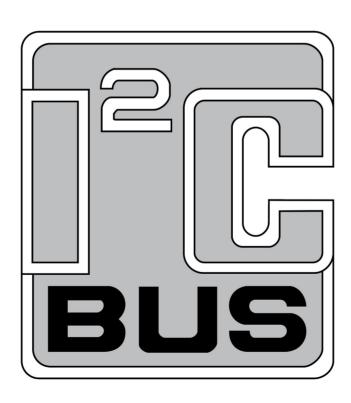
# Inter-Integrated Circuit Bus



### **Introduction**

- Inter-Integrated Circuit I2C or I<sup>2</sup>C
- Developed by Philips Semiconductors in 1982
- Synchronous, Multi-controller/multi-target, serial communication bus
- Sometimes is referred to as System Management Bus (SMBus)
  - Different, Intel developing SMBus in 1995
  - SMBus is a subset of I2C
- Current Standard

# **Basics**

- Controller Host device, historically known as master
- Target or peripheral Device that the controller talks with, historically known as slave
- Several different transfer modes
  - Original 1982 mode 100 kHz
  - Fast-mode 400 kHz
  - Fast-mode plus 1 MHz
  - High-speed mode 3.4 MHz
  - Ultra-fast mode 5 MHz
- Standard allows for any speed from 0 kHz to 5 MHz

# **Basics (cont.)**

- Targets are identified by unique address
- CONTROLLER

  GND

  VCC

  SDA

  SCL

  FULL UP

  RESISTORS

  SDA

  SCL

  TARGET

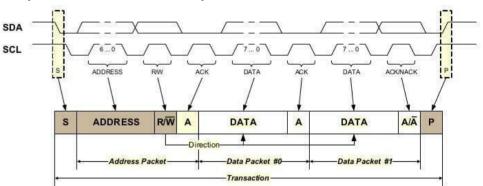
  GND

  VCC

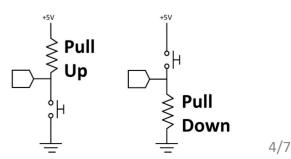
  ADDRESS

  0x??

  SCL
- Original standard allowed for 7-bit address (128 addresses, 112 available)
- Current standard allows for 10-bit address (1024 addresses)
- 7-bit addressing is still very common
- Requires two lines
  - SDA <u>Serial</u> <u>DA</u>ta
  - SCL <u>Serial</u> <u>Cl</u>ock

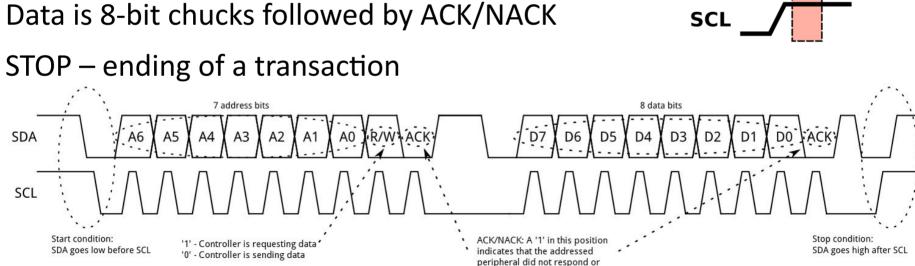


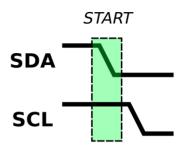
- Data is sent via transactions. More complex than UARTs.
- Open drain, pull-up resistors are required.
  - Open drain means they can pull line low but not high

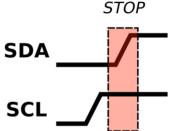


#### **Transaction**

- START beginning of a transaction
- Address is 7-bits big endian (MSB first)
- ACK/NACK Acknowledge/Not Acknowledge
  - Sent after each byte of data
- STOP ending of a transaction







was unable to process the request.

# **Pull-Up Resistors**

- Pull up to logic voltage level (5V or 3.3V), not power voltage (Vin)
- Rule of thumb: Start at 4.7 k $\Omega$  and then go down if need be
  - Depends on cable length
  - I2C intended for short distances (2-3 feet of cable max)
- Some controller devices have internal pull-up resistors
  - Arduino  $1.5 \text{ k}\Omega$
  - ESP32 45 kΩ with max 75  $\mu$ A (i.e., ~0.25 mW)
- Some target devices have pull-up resistors.
- Only need one each for SDA and SCL on entire bus.

# **Closing Remarks**

- Some have standardized connector for I2C
  - Sparkfun Qwiic
  - Adafruit STEMMA/STEMMA QT
- For long runs of I2C cabling, a bus extender may be used.
  - Uses RJ-45 connector (i.e., ethernet connector)

