$$\begin{split} m &= \rho \forall \\ \dot{\forall} &= \frac{\forall}{t} \\ q &= mc_p \Delta T \\ q &= -kA \frac{dT}{dt} \\ q &= hA \left(T_s - T_\infty \right) \\ q &= \varepsilon \sigma A \left(T_s^4 - T_{sur}^4 \right) \\ \sigma &= 5.67 \times 10^{-8} \frac{W}{m^2 K^4} \\ \Delta E_{sys} &= \Sigma E_{in} - \Sigma E_{out} \\ \frac{dE_{sys}}{dt} &= \Sigma \dot{E}_{in} - \Sigma \dot{E}_{out} \\ q'' &= \frac{q}{A} \\ \dot{q}'' &= -k_x \frac{\partial T}{\partial x} \hat{\imath} - k_y \frac{\partial T}{\partial y} \hat{\jmath} - k_z \frac{\partial T}{\partial z} \hat{k} \\ k &= \frac{9\gamma - 5}{\pi c^2} \frac{c_v}{\pi c^2} \sqrt{\frac{M_w k_B T}{N_A \pi}} \\ k_B &= 1.381 \times 10^{-23} \frac{J}{K} \\ N_A &= 6.022 \times 10^{23} \\ \alpha &= \frac{k}{\rho c_p} \\ q_{x+dx} &= q_x + \frac{\partial q_x}{\partial x} dx \\ q_{y+dy} &= q_y + \frac{\partial q_y}{\partial y} dy \\ q_{z+dz} &= q_z + \frac{\partial q_z}{\partial z} dz \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \\ \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \\ \dot{q} &= 0 \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial y} \right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial y} \right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial x} \right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{1}{r} \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial z^2} \left(k \frac{\partial T}{\partial z} \right) + \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial z^2} \left(k \frac{\partial T}{\partial z} \right) + \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial z^2} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) +$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(kr\frac{\partial T}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial r}\right) + \frac{1}{q} = 0$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(kr\frac{\partial T}{\partial r}\right) + \dot{q} = \rho c_p \frac{\partial T}{\partial t}$$

$$\frac{1}{r^2}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \dot{q} = \rho c_p \frac{\partial T}{\partial t}$$

$$\frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial z}\right) + \dot{q} = \rho c_p \frac{\partial T}{\partial t}$$

$$\frac{1}{r^2}\frac{\partial}{\partial r}\left(kr^2\frac{\partial T}{\partial r}\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\cos\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\cos\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\cos\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\sin\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\cos\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}{r^2\cos\theta}\frac{\partial T}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \frac{1}$$

$$R_{t,rad} = \frac{T_s - T_{sur}}{q} = \frac{1}{h_r A}$$

$$h_r = \varepsilon \sigma \left(T_s + T_{sur} \right) \left(T_s^2 + T_{sur}^2 \right)$$

$$q = U A \Delta T$$

$$U = \frac{1}{R_{tot} A}$$

$$R_{tot} = \Sigma R_t = \frac{1}{U A}$$

$$R_{t,c}^{"} = \frac{T_A - T_B}{q'}$$

$$q = \frac{k_{eff} A}{L} \left(T_1 - T_2 \right)$$

$$k_{eff,min} = \frac{1}{\frac{1-\varepsilon}{k_s} + \frac{\varepsilon}{k_f}}$$

$$k_{eff,max} = \varepsilon k_f + \left(1 - \varepsilon \right) k_s$$

$$R_{t,cond} = \frac{\ln \frac{r_2}{r_1}}{2\pi k L}$$

$$R_{t,conv} = \frac{1}{h2\pi r L}$$

$$\frac{d^2T}{dx^2} + \left(\frac{1}{A_c} \frac{dA_c}{dx} \right) \frac{dT}{dx} - \left(\frac{1}{A_c} \frac{h}{k} \frac{dA_s}{dx} \right) \left(T - T_\infty \right) = 0$$

$$A_s = Px$$

$$\frac{d^2T}{dx^2} - \left(\frac{hP}{kA_c} \right) \left(T - T_\infty \right) = 0$$

$$\theta = T \left(x \right) - T_\infty$$

$$m^2 = \frac{hP}{kA_c}$$

$$P = 2w + 2t$$

$$A_c = wt$$

$$P = \pi D$$

$$A_c = \frac{\pi}{4} D^2$$

$$\theta \left(x \right) = C_1 e^{mx} + C_2 e^{-mx}$$

$$\theta_b = T_b - T_\infty$$

$$M = \sqrt{hPKA_c} \theta_b$$

$$\varepsilon_f = \frac{q_f}{hA_{c,b}\theta_b}$$

$$\varepsilon_f = \sqrt{\frac{kP}{hA_c}}$$

$$R_{t,b} = \frac{1}{hA_{c,b}\theta_b}$$

$$\varepsilon_f = \frac{q_f}{R_{t,b}}$$

$$R_{t,b} = \frac{1}{hA_{t,b}\theta_b}$$

$$\eta_o = \frac{q_t}{q_{max}} = \frac{q_t}{hA_t\theta_b}$$

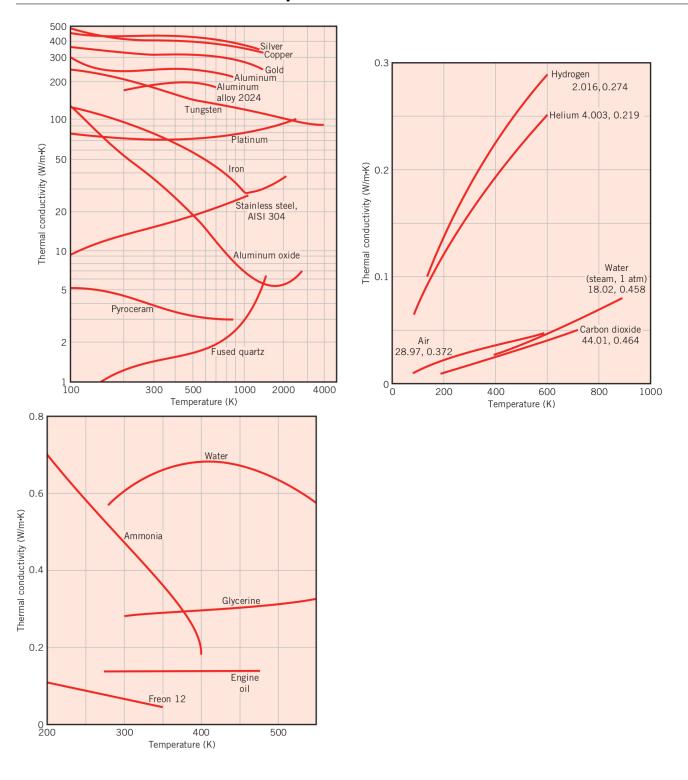
$$\eta_o = \frac{q_t}{q_{max}} = \frac{q_t}{hA_t\theta_b}$$

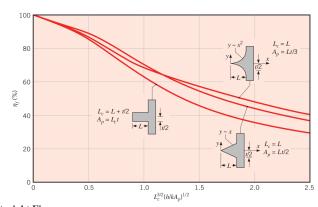
$$A_t = NA_f + A_b$$

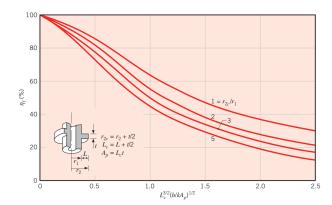
$$q_t = N\eta_f h A_f \theta_b + h A_b \theta_b$$

$$\eta_o = 1 - \frac{NA_f}{A_t} (1 - \eta_f)$$

$$R_{t,o} = \frac{\theta_b}{q_t} = \frac{1}{\eta_o h A_t}$$







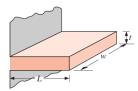
Straight Fins

Rectangular

$$A_f = 2wL_c$$

$$L_c = L + (t/2)$$

$$A_p = tL$$

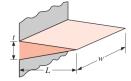


$$\eta_f = \frac{\tanh mL_c}{mL_c}$$

Triangular

$$A_f = 2w[L^2 + (t/2)^2]^{1/2}$$

$$A_p = (t/2)L$$



$$\eta_f = \frac{1}{mL} \frac{I_1(2mL)}{I_0(2mL)}$$

Parabolic

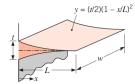
$$A_f = w[C_1L +$$

$$(L^2/t)\ln(t/L + C_1)$$

$$C_1 = [1 + (t/L)^2]^{1/2}$$

 $A_p = (t/3)L$

$$A = (t/3)L$$



$$\eta_f = \frac{2}{[4(mL)^2 + 1]^{1/2} + 1}$$

Pin Fins

Rectangular

$$A_f = \pi D L_c$$

$$L_c = L + (D/4)$$

$$V = (\pi D^2/4)L$$



$$\eta_f = \frac{\tanh mL_c}{mL_c}$$

Triangular

$$A_f = \frac{\pi D}{2} \left[L^2 + (D/2)^2 \right]^{1/2}$$

$$V = (\pi/12)D^2L$$



$$\eta_f = \frac{2}{mL} \frac{I_2(2mL)}{I_1(2mL)}$$

Parabolic

$$\begin{split} A_f &= \frac{\pi L^3}{8D} \left\{ C_3 C_4 - \frac{L}{2D} \ln \left[(2DC_4/L) + C_3 \right] \right\} \end{split}$$

$$C_3 = 1 + 2(D/L)^2$$

$$C_4 = [1 + (D/L)^2]^{1/2}$$

$$V = (\pi/20)D^2 L$$

$$y = (D/2)(1 - x/L)^2$$

$$\eta_f = \frac{2}{[4/9(mL)^2 + 1]^{1/2} + 1}$$

Table 1: Contact Resistance for vacuum interfaces, $R_{t,c}^{''}\times 10^4\left(\frac{m^2K}{W}\right)$

Material	100 (kPa)	10,000 (kPa)
Stainless Steel	6-25	0.7-4.0
Copper	1-10	0.1 - 0.5
Magnesium	1.5 - 3.5	0.2-0.4
Aluminum	1.5 - 5.0	0.2-0.4

Table 2: Contact Resistance for aluminum ($10\mu m$ surface roughness, 10kPa contact pressure)

Interfacial Fluid	$R_{t,c}^{"} \times 10^4 \left(\frac{m^2 K}{W}\right)$
Air	2.75
Helium	1.05
Hydrogen	0.720
Silicone Oil	0.525
Glycerine	0.265

Table 3: Fin Tip Conditions

Case	Tip Condition	Temperature Distribution $\frac{\theta}{\theta_b}$	Fin Heat Transfer Rate q_f
A	Convection	$\frac{\cosh m(L-x) + \left(\frac{h}{mk}\right) \sinh m(L-x)}{\cosh mL + \left(\frac{h}{mK}\right) \sinh mL}$	$M \frac{\sinh mL + \left(\frac{h}{mk}\right) \cosh mL}{\cosh mL + \left(\frac{h}{mk}\right) \sinh mL}$
В	Adiabatic	$\frac{\cosh m(L-x)}{\cosh mL}$	M anh mL
C	Constant Temperature	$\frac{\left(\frac{\theta_L}{\theta_b}\right)\sinh mx + \sinh m(L-x)}{\sinh mL}$	$M \frac{\cosh mL - \frac{\theta_L}{\theta_b}}{\sinh mL}$
D	Infinite Fin $(L \to \infty)$	e^{-mx}	M