$$\begin{split} m &= \rho \forall \\ \dot{\forall} &= \frac{\forall}{t} \\ q &= mc_p \Delta T \\ q &= -kA\frac{dT}{dt} \\ q &= hA\left(T_s - T_\infty\right) \\ q &= \varepsilon\sigma A\left(T_s^4 - T_{sur}^4\right) \\ \sigma &= 5.67 \times 10^{-8} \frac{W}{m^2 K^4} \\ \Delta E_{sys} &= \Sigma E_{in} - \Sigma E_{out} \\ \frac{dE_{sys}}{dt} &= \Sigma \dot{E}_{in} - \Sigma \dot{E}_{out} \\ q'' &= \frac{q}{A} \\ \hat{q}'' &= -k_x \frac{\partial T}{\partial x} \hat{\imath} - k_y \frac{\partial T}{\partial y} \hat{\jmath} - k_z \frac{\partial T}{\partial z} \hat{k} \\ k &= \frac{9\gamma - 5}{\pi c^2} \frac{c_v}{\pi c^2} \sqrt{\frac{M_w k_B T}{N_A \pi}} \\ k_B &= 1.381 \times 10^{-23} \frac{J}{K} \\ N_A &= 6.022 \times 10^{23} \\ \alpha &= \frac{k}{\rho c_p} \\ q_{x+dx} &= q_x + \frac{\partial q_x}{\partial x} dx \\ q_{y+dy} &= q_y + \frac{\partial q_y}{\partial y} dy \\ q_{z+dz} &= q_z + \frac{\partial q_z}{\partial z} dz \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x}\right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y}\right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial^2 T}{\partial x} &+ \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\dot{q}}{\dot{q}} &= \frac{1}{\alpha} \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial y}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial x}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{1}{r} \frac{\partial}{\partial r} \left(k r \frac{\partial T}{\partial r}\right) + \frac{1}{r^2} \frac{\partial}{\partial \phi} \left(k \frac{\partial T}{\partial \phi}\right) + \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{1}{r} \frac{\partial}{\partial r} \left(k r \frac{\partial T}{\partial r}\right) + \frac{1}{r^2} \frac{\partial}{\partial \phi} \left(k \frac{\partial T}{\partial \phi}\right) + \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{1}{r} \frac{\partial}{\partial r} \left(k r \frac{\partial T}{\partial z}\right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \phi^2} \left(k \frac{\partial T}{\partial \phi}\right) + \\ \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z}\right) + \dot{q} &= \rho c_p \frac{\partial T}{\partial t} \\ \frac{1}{r} \frac{\partial}{\partial r} \left(k r \frac{\partial T}{\partial z}\right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \phi^2} \left(k \frac{\partial T}{\partial \phi}\right) + \frac{1}{r^2} \frac{\partial}{\partial \phi} \left(k \frac{\partial T}{\partial z}\right) + \frac{1}{r^2} \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z}\right) + \frac{1}{r^2} \frac{\partial}{\partial z}$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(kr\frac{\partial T}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial z}\right) + \dot{q} = 0$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(kr\frac{\partial T}{\partial r}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2}\frac{\partial}{\partial \phi}\left(kr\frac{\partial T}{\partial r}\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial}{\partial \phi}\left(k\frac{\partial T}{\partial \phi}\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(\sin\theta\frac{\partial T}{\partial \theta}\right) + \dot{q} = \frac{1}{r^2\sin\theta}\frac{\partial T}{\partial \theta}$$

$$\frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$\frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(k\sin\theta\frac{\partial T}{\partial \theta}\right) + \dot{q} = \rho c_p\frac{\partial T}{\partial t}$$

$$T(0,t) = T_s$$

$$-k\frac{\partial T}{\partial x}\Big|_{x=0} = q''s$$

$$\frac{\partial T}{\partial x}\Big|_{x=0} = 0$$

$$-k\frac{\partial T}{\partial x}\Big|_{x=0} = h\left(T_{\infty} - T(0,t)\right)$$

$$\Delta U = N\left(V^{-} - V^{+}\right)$$

$$q = \frac{\Delta U}{\Delta t} = \frac{N}{\Delta t}\Delta V$$

$$q = -IV = \frac{-V^2}{R} = -I^2R$$

$$R = \frac{\rho L}{A} = \frac{L}{\sigma A}$$

$$S_{AB} = S_B - S_A = \frac{-\Delta V}{\Delta T}$$

$$C_1 = \frac{T_{s,2} - T_{s,1}}{L}$$

$$C_2 = T_{s,1}$$

$$T(x) = (T_{s,2} - T_{s,1})\frac{T}{L} + T_{s,1}$$

$$q = \frac{kA}{L}\left(T_{s,1} - T_{s,2}\right)$$

$$R_{t,cont} = \frac{T_{s,-1} - T_{s,2}}{q} = \frac{L}{kA}$$

$$R = \frac{V}{I}$$

$$R_{t,cont} = \frac{T_{s,-1} - T_{s,2}}{q} = \frac{1}{hA}$$

$$R_{t,rad} = \frac{T_s - T_{sur}}{q} = \frac{1}{h_r A}$$

$$h_r = \varepsilon \sigma \left(T_s + T_{sur} \right) \left(T_s^2 + T_{sur}^2 \right)$$

$$q = U A \Delta T$$

$$U = \frac{1}{R_{tot} A}$$

$$R_{tot} = \Sigma R_t = \frac{1}{U A}$$

$$R'_{t,c} = \frac{T_A - T_B}{q''}$$

$$q = \frac{k_{eff} A}{L} \left(T_1 - T_2 \right)$$

$$k_{eff,min} = \frac{1}{\frac{1-\varepsilon}{k_s} + \frac{\varepsilon}{k_f}}$$

$$k_{eff,max} = \varepsilon k_f + (1-\varepsilon) k_s$$

$$R_{t,cond} = \frac{\ln \frac{r_2}{r_1}}{2\pi k L}$$

$$R_{t,conv} = \frac{1}{h^2 \pi r L}$$

$$\frac{d^2 T}{dx^2} + \left(\frac{1}{A_c} \frac{dA_c}{dx} \right) \frac{dT}{dx} - \left(\frac{1}{A_c} \frac{h}{k} \frac{dA_s}{dx} \right) \left(T - T_\infty \right) = 0$$

$$A_s = Px$$

$$\frac{d^2 T}{dx^2} - \left(\frac{hP}{kA_c} \right) \left(T - T_\infty \right) = 0$$

$$\theta = T(x) - T_\infty$$

$$m^2 = \frac{hP}{kA_c}$$

$$P = 2w + 2t$$

$$A_c = wt$$

$$P = \pi D$$

$$A_c = \frac{\pi}{4} D^2$$

$$\theta(x) = C_1 e^{mx} + C_2 e^{-mx}$$

$$\theta_b = T_b - T_\infty$$

$$M = \sqrt{hPKA_c} \theta_b$$

$$\varepsilon_f = \frac{q_f}{hA_{c,b}\theta_b}$$

$$\varepsilon_f = \sqrt{\frac{kP}{hA_c}}$$

$$R_{t,f} = \frac{q_f}{\theta_b}$$

$$R_{t,f} = \frac{q_f}{q_{max}}$$

$$R_{t,f} = \frac{q_f}{q_f}$$

$$R_{t,b} = \frac{1}{hA_t\theta_b}$$

$$\eta_o = \frac{q_t}{q_{max}} = \frac{q_t}{hA_t\theta_b}$$

$$A_t = NA_f + A_b$$

$$q_t = N\eta_f h A_f \theta_b + h A_b \theta_b$$

$$\begin{array}{c} \eta_{o} = 1 - \frac{NA_{f}}{A_{f}} (1 - \eta_{f}) \\ R_{t,o} = \frac{1}{w} = \frac{1}{\eta_{b} h A_{i}} \\ \hline \\ \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{g^{2}}{\frac{g^{2}}{w_{i} + \frac{1}{2} - N^{2}}} \frac{g^{2}}{w_{i} - \frac{1}{2} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{g^{2}}{\frac{g^{2}}{w_{i} + \frac{1}{2} - N^{2}}} \frac{g^{2}}{w_{i} - \frac{1}{2} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{g^{2}T}{m_{i} - 1} - \frac{1}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{g^{2}T}{m_{i} - N^{2}} - \frac{g^{2}T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{m_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{g}}|_{m,n} \approx \frac{T}{m_{i} - N^{2}} + \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}{g_{i} - N^{2}} - \frac{T}{g_{i} - N^{2}} \\ \hline \frac{g^{2}T}$$

Isothermal Flat Plate $rac{\delta}{\delta_t}pprox Pr^{1/3}$ Laminar:

$$\overline{Nu}_D = \frac{\overline{h}D}{k} = CRe_D^m Pr^{1/3}$$

$$(Pr \gtrsim 0.7)$$

See Table 6

Sphere

$$A_s = \pi D^2$$

$$C_D = \frac{25}{Re_D}$$

 $(Re_D \lesssim 0.5)$

$$\overline{Nu}_D = 2 + \left(0.4 Re_D^{1/2} + 0.06 Re_D^{2/3}\right) P r^{0.4} \left(\frac{\mu}{\mu_s}\right)^{1/4}$$

$$(0.71 \lesssim Pr \lesssim 380)$$

$$(3.5 \lesssim Re_D \lesssim 7.6 \times 10^4)$$

$$\left(1.0 \lesssim \frac{\mu}{\mu_s} \lesssim 3.2\right)$$

$$m = \rho u_m A_c$$

$$Re_D = \frac{\rho u_m D}{\mu} = \frac{u_m D}{\nu}$$

$$\left(\frac{x_{fd,t}}{D}\right) \approx 0.05 Re_D Pr$$

$$f = \frac{-\frac{dP}{dx}D}{\rho \frac{u_m^2}{2}}$$
$$f = \frac{64}{Re_D}$$

$$\frac{1}{\sqrt{f}} = -2.0 \log \left[\frac{e/D}{3.7} + \frac{2.51}{Re_D \sqrt{f}} \right]$$

$$dq_{conv} = mc_p \left[(T_m + dT_m) - T_m \right] =$$

$$mc_p dT_m$$

$$dq_{conv} = q_s^{"} P dx$$

$$\frac{dT_m}{dx} = \frac{q_s''P}{mc_p} = \frac{P}{mc_p}h\left(T_s - T_m\right)$$

$$T_m(x) = T_{m,i} + \frac{q_s''P}{mc_p}x$$

$$\Delta T = T_s - T_m$$

$$\frac{d}{ds} = -\frac{d(\Delta T)}{ds} - \frac{P}{r} h \Delta r$$

$$\frac{dT_m}{dx} = -\frac{d(\Delta T)}{dx} = \frac{P}{mc_p} h \Delta T$$
$$\frac{T_s - T_m(x)}{T_s - T_{m,i}} = e^{-\frac{Px}{mc_p} \overline{h}}$$

$$\Delta T_{lm} = \frac{\Delta T_o - \Delta T_i}{\ln\left(\frac{\Delta T_o}{\Delta T_i}\right)}$$

$$\Delta T_o = T_s - T_{m,o}$$

$$\Delta T_i = T_s - T_{m,i}$$

$$q_{conv} = \overline{h} A_s \Delta T_{lm}$$

Circular Tubes

Fully dev. lam. w/
$$q'' = \mathbb{C}$$
:

$$Nu_D = 4.36$$

Fully dev. lam. w/
$$T_s = \mathbb{C}$$
:

$$Nu_D = 3.66$$

Fully dev. turb. w/ small ΔT :

$$Nu_D = 0.023 Re_D^{4/5} Pr^n$$

$$n = 0.4, \quad T_s > T_m$$

$$n = 0.3, \quad T_s < T_m$$

$$(0.6 \lesssim Pr \lesssim 160)$$

$$(Re_D \gtrsim 10,000)$$

$$(L/D \gtrsim 10)$$

Fully dev. turb. w/ large ΔT :

$$Nu_D = 0.027 Re_D^{4/5} Pr^{1/3} \left(\frac{\mu}{\mu_s}\right)^{0.14}$$

$$(0.7 \lesssim Pr \lesssim 16,700)$$

$$(Re_D \gtrsim 10,000)$$

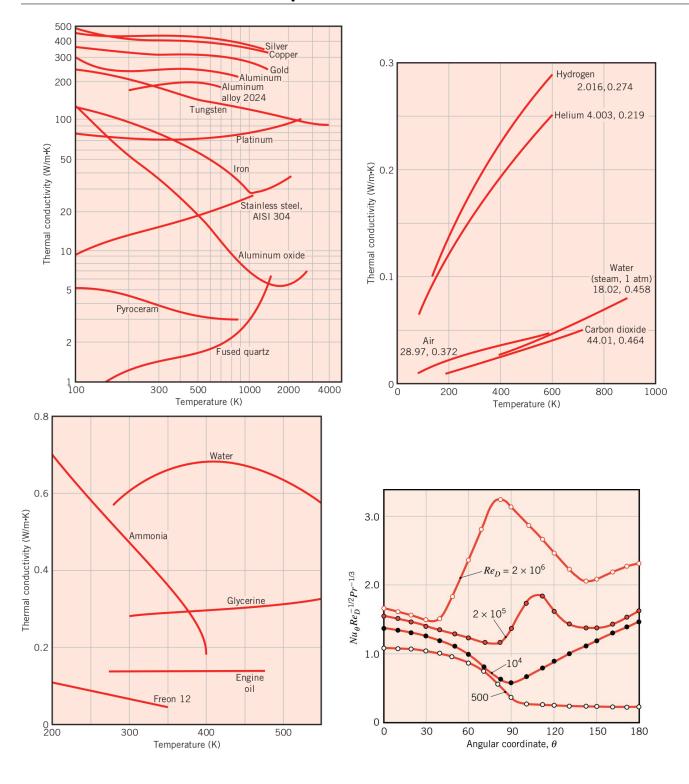
$$(L/D \gtrsim 10)$$

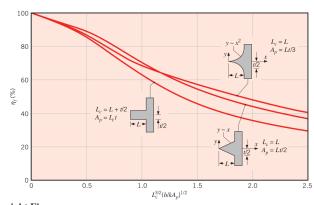
Noncircular Tubes

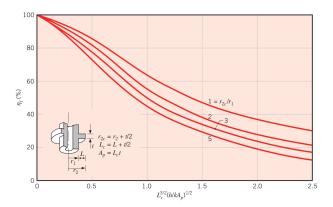
$$D_h = \frac{4A_c}{P}$$

$$Nu_D = \frac{hD_h}{k}$$

See Table 7







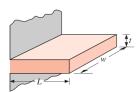
Straight Fins

Rectangular

$$A_f = 2wL_c$$

$$L_c = L + (t/2)$$

 $A_p = tL$

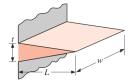


$$\eta_f = \frac{\tanh mL_c}{mL_c}$$

Triangular

$$A_f = 2w[L^2 + (t/2)^2]^{1/2}$$

 $A_p = (t/2)L$



$$\eta_f = \frac{1}{mL} \frac{I_1(2mL)}{I_0(2mL)}$$

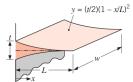
Parabolic

$$A_f = w[C_1L +$$

$$(L^2/t)\ln\left(t/L+C_1\right)]$$

$$C_1 - [1 + (u_1 + v_2)]$$

 $C_1 = [1 + (t/L)^2]^{1/2}$ $A_p = (t/3)L$



$$\eta_f = \frac{2}{[4(mL)^2 + 1]^{1/2} + 1}$$

Pin Fins

Rectangular

$$A_f = \pi D L_c$$

$$L_c = L + (D/4)$$

 $V = (\pi D^2/4)L$



$$\eta_f = \frac{\tanh mL_c}{mL_c}$$

Triangular

$$A_f = \frac{\pi D}{2} \left[L^2 + (D/2)^2 \right]^{1/2}$$

 $V = (\pi/12)D^2L$



$$\eta_f = \frac{2}{mL} \frac{I_2(2mL)}{I_1(2mL)}$$

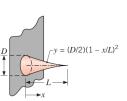
Parabolic

$$\begin{split} A_f &= \frac{\pi L^3}{8D} \left\{ C_3 C_4 - \frac{L}{2D} \ln \left[(2DC_4/L) + C_3 \right] \right\} \end{split}$$

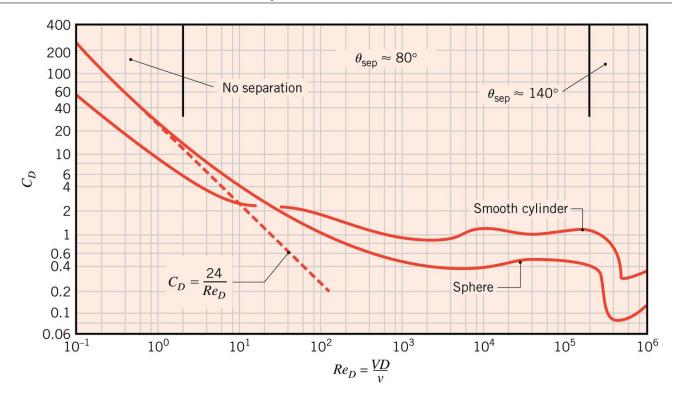
$$C_3 = 1 + 2(D/L)^2$$

$$C_4 = [1 + (D/L)^2]^{1/2}$$

 $V = (\pi/20)D^2 L$



$$\eta_f = \frac{2}{[4/9(mL)^2 + 1]^{1/2} + 1}$$



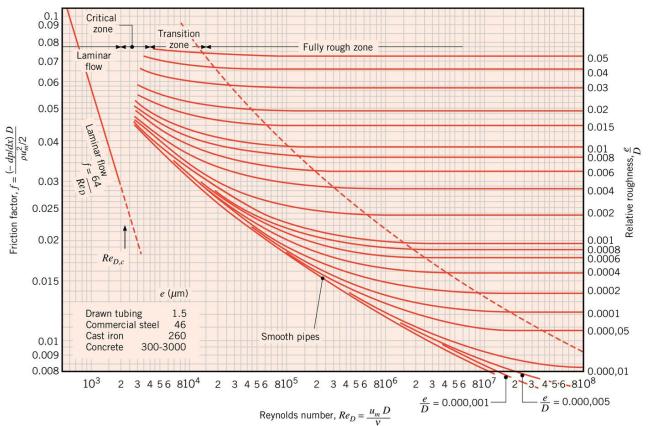


Table 1: Contact Resistance for vacuum interfaces, $R_{t,c}^{''}\times 10^4\left(\frac{m^2K}{W}\right)$

Material	100 (kPa)	10,000 (kPa)
Stainless Steel	6-25	0.7-4.0
Copper	1-10	0.1 - 0.5
Magnesium	1.5-3.5	0.2-0.4
Aluminum	1.5 - 5.0	0.2-0.4

Table 2: Contact Resistance for aluminum ($10\mu m$ surface roughness, 10kPa contact pressure)

Interfacial Fluid	$R_{t,c}^{"} \times 10^4 \left(\frac{m^2 K}{W}\right)$
Air	2.75
Helium	1.05
Hydrogen	0.720
Silicone Oil	0.525
Glycerine	0.265

Table 3: Fin Tip Conditions

Case	Tip Condition	Temperature Distribution $\frac{\theta}{\theta_b}$	Fin Heat Transfer Rate q_f
A	Convection	$\frac{\cosh m(L-x) + \left(\frac{h}{mk}\right) \sinh m(L-x)}{\cosh mL + \left(\frac{h}{mK}\right) \sinh mL}$	$M \frac{\sinh mL + \left(\frac{h}{mk}\right) \cosh mL}{\cosh mL + \left(\frac{h}{mk}\right) \sinh mL}$
В	Adiabatic	$\frac{\cosh m(L-x)}{\cosh mL}$	M anh mL
C	Constant Temperature	$\frac{\left(\frac{\theta_L}{\theta_b}\right)\sinh mx + \sinh m(L-x)}{\sinh mL}$	$M \frac{\cosh mL - \frac{\theta_L}{\theta_b}}{\sinh mL}$
D	Infinite Fin $(L \to \infty)$	e^{-mx}	M

Table 4: Energy Balance Method Case Summary

Case	Diagram	Equation
1	$m, n+1$ Δy m, n $m+1, n$ $-\Delta x \longrightarrow m, n-1$	$T_{m,n+1} + T_{m,n-1} + T_{m+1,n} + T_{m-1,n} - 4T_{m,n} = 0$
2	m-1, n m , $n+1$ $m+1$, n m , $n-1$	$2\left(T_{m-1,n} - T_{m,n+1}\right) + \left(T_{m+1,n} + T_{m,n-1}\right) + 2\frac{h\Delta x}{k}T_{\infty} - 2\left(3 + \frac{h\Delta x}{k}\right)T_{m,n} = 0$
3	m, n + 1 $m - 1, n$ $m, n + 1$ $m, n + 1$ $m, n + 1$ $m, n + 1$	$(2T_{m-1,n} + T_{m,n+1} + T_{m,n-1}) + 2\frac{h\Delta x}{k}T_{\infty} - 2\left(2 + \frac{h\Delta x}{k}\right)T_{m,n} = 0$
4	$m-1, n$ m, n Δy $m, n-1$ $M, n-1$	$(T_{m,n-1} + T_{m-1,n}) + 2\frac{h\Delta x}{k}T_{\infty} - 2\left(1 + \frac{h\Delta x}{k}\right)T_{m,n} = 0$

Table 5: Cylinder In Cross Flow

Re_D	C	m
0.4 - 4	0.989	0.330
4 - 40	0.911	0.385
40 - 4000	0.683	0.466
4000 - 40,000	0.193	0.618
40,000 - 400,000	0.027	0.805

Table 6: Various Geometries In Cross Flow

Geometry	Re_D	C	m
$V \rightarrow \bigcirc \qquad \stackrel{\overline{\downarrow}}{\bigcirc} \qquad \qquad$	6000 - 60,000	0.304	0.59
$V \longrightarrow $	5000 - 60,000	0.158	0.66
$V \rightarrow \bigcirc \qquad \stackrel{\uparrow}{D}$	5200 - 20,400 20,400 - 105,000	0.164 0.039	0.638 0.78
$V \longrightarrow \begin{array}{ c c c c c c c c c c c c c c c c c c c$	4500 - 90,700	0.150	0.638
$V \longrightarrow \begin{bmatrix} & \overline{A} & \text{Front} \\ D & \text{Back} \end{bmatrix}$	10,000 - 50,000 7,000 - 80,000	$0.667 \\ 0.191$	$0.500 \\ 0.667$

Table 7: Noncircular Tubes

Cross Section	$\frac{b}{a}$	Uniform $q_s^{''}$	Uniform T_s	fRe_{D_h}
		4.36	3.66	64
a	1.0	3.61	2.98	57
a	1.43	3.73	3.08	59
ab	2.0	4.12	3.39	62
<i>a b</i>	3.0	4.79	3.96	69
ab	4.0	5.33	4.44	73
Heated	∞	8.23	7.54	96
(ASSA) (A	∞	5.39	4.86	96
\triangle		3.11	2.49	53